A Framework for Data-Driven Workflow Management: Modeling, Verification and Execution

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Abstract. In recent years, many data-driven workflow modeling approaches has been developed, but none of them can insure data integration, process verification and automatic data-driven execution in a comprehensive way. Based on these needs, we introduced, in previous works, a data-driven approach for workflow modeling and execution. In this paper, we extend our approach to ensure a correct definition and execution of our workflow model, and we implement this extension in our Framework *Opus*.

Keywords: Data-driven workflow management Framework, Petri nets, Relational algebra, Workflow analysis and verification, Soundness property.

1 [In](#page-13-0)troduction

In a competitive environment continually ev[olv](#page-13-1)ing, companies are recognized the need to manage their business processes in order to align their information systems, more and more quickly, in a process-oriented way. In this context, workflow management systems (WMS) offer promising perspectives for modeling, processing and controlling processes. In the most common WMS, only the control flow 1 is completely included [1]. In Fact, during process execution, a process-oriented view (e.g. worklists) is provided to end-users. However, [th](#page-13-2)[e](#page-13-3) behavior of an activity during its execution is out of the control of the WMS [2]. As almost all processes are related to data, such as the c[ost](#page-13-4)[s](#page-13-5) of the ordered products, the addresses information for delivery, etc., the main goal from using a WMS is to automate, as possible, the manipulation of data in business processes, and to restrict as possible the manual tasks performed by hum[an](#page-13-0) actors.

Regarding the existing literature, the need for modeling processes that combine data and control flow has bee[n](#page-14-0) [w](#page-14-0)idely studied. Most of them are inspired from Petri nets (P-nets) formalism, such as the approaches proposed in [3–7]. Thus, to enhance earlier approaches that have mainly focused on process activities and largely overlooked the data, we previously extended, in [8,9], the P-nets

¹ Control flow: is a set of synchronized activities representing the business process functions, and a set of ordering constraints defining their execution sequence [1].

H. Decker et al. (Eds.): DEXA 2013, Part I, LNCS 8055, pp. 239–253, 2013.

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formalism by data operations inspired from the relational algebra to model datadriven workflows. This extension improves the generation [of](#page-2-0) business functions from the process definition, without the need for a programmer, and provides advanced abilities for the information system [\(I](#page-7-0)S) and the users' integration. In this paper, we extend the modeling method of the proposed approach [8, 9] by some rules, to ensure the consis[te](#page-13-6)ncy of the process model during runtime. We also provide a technique to verify a released notion of the classical soundness property.

The remainder of the paper is organized as follows: we present the related work in Sect. 2 and we continue by introducing our workflow model in Sect. 3. In Sect. 4, we present the definition of the firing rules that ensure a uniform [exe](#page-13-7)[cut](#page-13-8)ion of all the process activities. [The](#page-13-8)n we discuss, in Sect. 5, the technique provided to ensure the analysis and the verification of our workflow model. In Sect. 6, we present our Framework Opus. Section 7 concludes.

2 Related [Wo](#page-13-1)rk

The need for modeling processes integrating data has been recognized by several authors [3–7, 10, 11]. The Case Handling Paradigm [11] aims to coordinate activities which are presented as forms in [rel](#page-13-9)ation to atomic data elements. The problem here is that data may be omitted or activities are unwittingly ignored or executed many times. In addition, more than one user can handle the same case simultaneously, which damages the data coherence.

The PHILharmonicFlows system [2] provides a comprehensive approach that combines object behavior based on states with da[ta-d](#page-13-7)riven process execution. In fact, it allows the control of activities by presenting them as form-based 2 and black-box activities 3 . The proper execution as well as termination of processes at runtime is further ensured by a set of correctness rules [12]. But, the execution of form-[bas](#page-13-10)ed activities increases the rate of errors that may be caused by the manual seizure performed by human actors, even if the seized data values respect the data types requested by the form' input fields.

Many extensions of P-nets in which tokens carry data have been defined in the literature. The workflow nets based on colored P-nets (WFCP-nets) [10] consider a P-net color as an abstraction of data objects and flow control variants. The execution of a WFCP-net depends on the interpretation of its arc expressions and guard expressions, [wh](#page-13-1)ich describe the business rules. Besides, the verification methods of workflow nets [13] are adapted to WFCP-nets. The weakness of this approach is that the process specification consists of a graphical part and a WF script part. The latter is a hard-coding process logic that describes the data elements and the behavior of activities. So, resulting applications are both complex to design and costly to deploy, and even simple process changes require

² Form-based activities: provide input fields for writing and data fields for reading selected attributes of data object instances [2].

 3 Black-box activities: allow the integration of advanced functionalities (e.g. sending e-mails) [2].

costly code adaptations and testing efforts. Another extension of P-nets is the workflow nets with data (WFD-nets) [7], in which transitions can read from or write to some data elements. This extension does not provide a support for executing process models. However, it defines algorithms to verify a soundness property that guarantees the proper termination of a WFD-net and that only certain transitions are not dead.

None of the existent approaches considers data integration, process verification and data-driven execution issues in a comprehensive way. Thus, in this area a comprehensive approach for supporting these three issues is still missing.

3 Our Data-Driven Workflow Model

As described by the most modeling approaches, a process is defined, in a higher level of abstraction, as a set of synchronized activities performed by roles according to the available data. If we stop at this level, we will not be able to generate the process functions from the process model definition, and activities will behave as a black box in which data are managed by invoked application components. To attempt the lowest level of abstraction, we propose to split each activity, in a process, to tasks applied on data. Each task consumes data to produce others. Thus, each activity is presented as a set of data-driven tasks. Each task consumed data provenance can be either the IS, or data produced by other tasks. But, in some cases, to complete the processing of a task, data can be seized by a role. Accordingly, to enable tasks to generate new data from old ones and import data from the IS, data have to be well structured. We introduced this approach in [8,9], in a formal way, as a data-driven modeling approach based on combination between structured tokens P-nets and relational algebra.

3.1 Data Structure

According to [8, 9], we define each handled data as a data structure; i.e, a pair $s = (C, D)$, where C is a list of attributes and D is a list of data tuples. Each tuple is an ordered list of attributes values, formally defined by:

 $C = (c_1, c_2 \ldots c_n), D = \{(d_{1_1}, d_{1_2} \ldots d_{1_n}), (d_{2_1}, d_{2_2} \ldots d_{2_n}) \ldots (d_{m_1}, d_{m_2} \ldots d_{m_n})\}.$

Where n (resp. m) is the number of attributes (resp. tuples) in s .

Each attribute $c_j = (\alpha_j, \beta_j)$ is a pair characterized by an attribute identifier α_j and an attribute type β_j , such as: $\forall j \in \{1, 2...n\}$, $\beta_j \in \{Int, \; float, \; Char,$ String, Date, Boolean...}, and $\forall i \in \{1,2...m\}$, an attribute value d_{i_j} is a specific valid value for the type β_i of the attribute c_i .

At modeling step, the designer has just to define the data structure attributes and the values types put up with each one. At runtime, the different data structure tuples comprise varying values according to each attribute type.

3.2 Process Structure

The workflow process is defined as a P-net representing the work, where a place corresponds to a data structure that contains structured tokens (tuples)

and a transition corresponds to a task. A workflow is then a quadruplet $[8, 9]$ $WF = (S, T, Pre, Post)$, where:

 $S = \{s_1, s_2 \dots s_{|S|}\}\$ is a finite set of data structures,

 $T = \{t_1, t_2, \ldots t_{|T|}\}\$ is a finite set of tasks inspired from the relational algebra, $Pre: S \times T \to \mathbb{N}$ is the pre-incidence matrix, such as, $\forall i \in \{1, 2... |S|\}$ and

 $j \in \{1, 2...|T|\}, \ Pre(s_i, t_j), \text{ is the edge between a data structure } s_i \text{ and a}$ task t_j weight, representing the number of tokens consumed by t_j in order to be firable, i.e. executable.

Post : $T \times S \rightarrow \mathbb{N}$ is the post-incidence matrix. Due to the dynamic of the relational algebra, we cannot be limited to a static post-incidence matrix thus, $\forall i \in \{1, 2...|S|\}$ and $j \in \{1, 2...|T|\}$, $Post(t_j, s_i) \in [Post_{Min}(t_j, s_i),$

 $Post_{Max}(t_j, s_i)$. Where: $Post_{Min}(t_j, s_i)$ (resp. $Post_{Max}(t_j, s_i)$), is the edge between a task t_i and a data structure s_i mini[ma](#page-13-5)l (resp. maximal) weight, representing the minimal (resp. maximal) number of t_i produced tokens.

3.3 Data Operations

A task can be viewed as a data ope[rat](#page-13-5)ion applied on data structure tokens to produce others. Therefore, we have inspired from the relational algebra to define the behavior of operations. We presented these operations in [9]. So, in this paper, we detail in Appendix A , only operations that we will use to demonstrate the new extensions of the model. Noting that the definition of the *Add Tuples* operation, presented in Table 1, is an extended version of its definition in [9]. In fact, in this version, we allow to inserts a[ll](#page-4-0) a data structure tuples in another data structure, instead of inserting only a single tuple [9].

3.4 Workflow Example

The customer solvency check role (SCRole) evaluates the received orders, and sends them to the inventory check. After the evaluation, either an order is rejected, or sent to shipping and billing. As illustrated by Fig. 1, considering that s_8 , s_{13} , and s_{19} present tables from the IS, we restrict our example to the inventory check role (ICRole) sub-process, which performs the following activities:

Select the ordered products: t_7 extends s_8 (which contains all the products data) by the *ord qtity* attribute, in order to allow the ICRole to enter the ordered quantities. Then, t_8 selects from s_9 only tuples having an ordered quantity value higher than zero and lower than the stocked product quantity.

Verify the products availability: t_9 checks s_{10} content. If it contains one or more tokens, t_9 will reproduce s_{11} token in s_{12} , otherwise, it will end the process.

Create a new order: according to the decision of $t₉$, if there are available products, t_{10} will add a new order in s_{13} .

Create the new order lines: the ICRole enters the new order identifier and t_{13} saves it in s_{17} . Then, t_{14} will create the new order lines and finally, t_{15} will save the resulting structured s_{18} tokens in s_{19} .

Fig. 1. The inventory check role sub-process [9] (modified version)

We deduce the Pre and $Post$ matrix of the example in Fig. 1.

Following the definition of tasks in Appendix A, the number of tokens produced by each task in Fig. 1, are defined as follows: $x_5 \in [0, 1]$, $x_6 = 1$ (i.e. there by each task in Fig. 1, are defined as follows: $x_5 \in [0, 1]$, $x_6 = 1$ (i.e. there is only a single customer identifier), $x_7 = |D_{13}| + x_6$, $x_9 = x_8$, $x_{11} \in [0, x_{10}]$, is only a single customer identifier), $x_7 = |D_{13}| + x_6$, $x_9 = x_8$, $x_{11} \in [0, x_{10}]$,
 $x_{13} \in [0, x_{12}]$, $x_{15} \in [0, x_{14}]$, $x_{17} = |D_{17}| + 1 = 1$ (because $D_{17} = \emptyset$), $x_{19} = x_{16} \times x_{18}$, $x_{21} = |D_{19}| + x_{20}$. Accordingly, the *Post* matrix is defined by:

3.5 Marking

The marking $M^{[\theta]}$ defines the state of the process described by WF at a given time $\theta \in \{0, 1, 2...\}$. Thus, $\forall i \in \{1, 2...|S|\} : M^{[\theta]} = (m_1^{[\theta]} m_2^{[\theta]} ... m_{|S|}^{[\theta]}),$ where $m_i^{[\theta]} \in \mathbb{N}$ is the number of tuples in s_i .

The initial marking $M^{[0]}$ defines the state of WF at time $\theta = 0$, in which only root nodes of a WF process can be initiated by a finite number of tokens. The evolution of the markings, in the other nodes, results due to the firing of WF tasks. A valid initial marking must follow (1) $[8, 9]$.

$$
\forall j \in \{1, 2...|S|\}, m_j^{[0]} = \begin{cases} \max_{k \in \{1, 2...|T|\}} Pre(s_j, t_k) \\ \text{if } \forall l \in \{1, 2...|T|\} Post_{Max}(s_j, t_l) = 0, \\ 0 \text{ otherwise.} \end{cases}
$$
(1)

3.6 Synthesis

Our proposed data-driven approach allows for a comprehensive integration between data flow and control flow, which ensures a successful data driven execution of the workflow. Indeed, data integration is granted through data structures that can handle various data elements types. Furthermore, data manipulation is enable through data operations that can read, write and generate new data elements without any risk of simulating a WF process in which data can be lost. This is granted through the dynamic behavior of the relational data operations, which entails a generalization of the static post-incidence matrix of the classical P-net[s.](#page-13-4) [In](#page-13-5) the next section, we present how we improve our approach by the application of some firing rules. These latter grant a uniform definition of a WF process and introduce the basic notions of our verification method, that ensures a valid WF process execution.

4 Firing Rules

To ensure the process consistency during runtime, we improve the modeling approach described in $[8, 9]$ by adding some firing rules. The latter indicate under which conditions a task may fire, and what the effect of the firing on the marking is.

1. Assuming that t_i , $t_j \in T$, are two successive tasks in a WF , and $s \in S$ is an output data structure of t_i and an input data structure to t_j . Thus, tokens produced by t_i will be automatically consumed by t_i :

$$
\forall t_i, t_j \in T, \exists s \in S \mid \Rightarrow pre(t_j, s) = post(t_i, s).
$$
 (2)

2. Assuming that δ is the function calculating the possible markings resulting of Assuming that *o* is the function calculating the possible markings resulting of the firing of a task $t_i \in T$ from a marking M. So, $\forall M \in \mathbb{N}^{|S|}, t_1, t_2, \ldots t_k \in T$:

$$
\delta(\{M_1, M_2 \dots M_n\}, t_1 t_2 \dots t_k) = \bigcup_{M \in \{M_1, M_2 \dots M_n\}} \delta(\{M\}, t_1 t_2 \dots t_k)
$$
\n(3)

Where:
$$
\delta({M}, t_1 t_2 ... t_k) = \delta(\delta({M}, t_1), t_2 ... t_k)
$$

= $\delta(\delta(\delta({M}, t_1), t_2), t_3 ... t_k)$
= ...

The function $\delta({M}, t_i)$ is defined as follows:

$$
\delta({M}, t_i) = \begin{cases} \varnothing \text{ if } M < Pre(., t_i), \\ \{M - Pre(., t_i) + x\} \text{ otherwise.} \end{cases} \tag{4}
$$

Where $x \in [Post_{Min}(., t_i), Post_{Max}(., t_i)],$ and $\delta(\emptyset, t_i) = \emptyset$. We apply (3) and (4) on the example illustrated in Fig. 1, and we calculate the possible markings resulting from the firing sequence of tasks < **t₈ t₁₁ t₁₂ t₁₃ t₁₄ t₁₅ >:**

- ${M^{[0]}} = {(x_8 0 0 0 0 0 0 0 0 0 0), (x_8 0 0 1 0 0 0 0 0 0), (x_8 0 0 0 0 0 0 0 1 0 0 0)},$ $(x_8 0 0 1 0 0 0 0 1 0 0 0)$, $(0 0 0 1 0 0 0 0 0 0 0)$, $(0 0 0 1 0 0 0 0 1 0 0 0)$, (0000000001000) , (0000000000000) }
- $\delta({M^{[0]}}), t_7 \ t_8 \ t_{11} \ t_{12} \ t_{13} \ t_{14} \ t_{15}) = \delta(\delta({M^{[0]}}), t_7), t_8 \ t_{11} \ t_{12} \ t_{13} \ t_{14} \ t_{15})$
	- $= \delta({\{(0 x_8 0 0 0 0 0 0 0 0 0 0), (0 x_8 0 1 0 0 0 0 0 0 0), (0 x_8 0 0 0 0 0 0 1 0 0 0)},$ $(0 \ x_8 \ 0\ 1\ 0\ 0\ 0\ 1\ 0\ 0\ 0)$ }, \varnothing , \varnothing , \varnothing , \varnothing }, $t_8 \ t_{11} \ t_{12} \ t_{13} \ t_{14} \ t_{15})$
	- $= \delta(\delta({\{(0 x_8 0 0 0 0 0 0 0 0 0 0), (0 x_8 0 1 0 0 0 0 0 0 0), (0 x_8 0 0 0 0 0 0 1 0 0 0)},$ $(0 \ x_8 \ 0 \ 1 \ 0 \ 0 \ 0 \ 0 \ 1 \ 0 \ 0 \ 0)$ }, \varnothing }, t_8), $t_{11} \ t_{12} \ t_{13} \ t_{14} \ t_{15})$
	- $= \delta({\{ (0 \ 0 \ [0, x_{10}] \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0)}, (0 \ 0 \ [0, x_{10}] \ 1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0)},$
	- $(0 0 0 0, x_{10}] 0 0 0 0 0 1 0 0 0, (0 0 0, x_{10}] 1 0 0 0 0 1 0 0 0), \emptyset$, $t_{11} t_{12} t_{13} t_{14} t_{15}$ $= \ldots$ = {{(0 0 0 0 0 0 0 0 0 0 0 |D₁₉| + x₂₀), (0 0 0 1 0 0 0 0 0 0 0 |D₁₉| + x₂₀)}, ∅}
- 3. According to (1) , any loop in a WF model will cause a blocking state. In fact, if a task t_i is waiting for a data structure s tuples, and if these tuples are produced by a task t_i , which will never be executed in certain conditions: if his input data structures are not root nodes, and if $t_j \in \langle t_1, t_2, \ldots, t_i \rangle$, i.e. the firing sequence leading to execute t_i , this case is [id](#page-6-0)entified as a deadlock. In addition, even if the input data structures of t_i are root nodes, the occured cycle may cause a livelock (i.e. a loop without progress). Thus, we require that each task $t \in T$ is fired, at most once, in a sequence of tasks starting from a marking M.

$$
\forall i_1, i_2 \dots i_k \in \{1, 2 \dots |T|\}, \ \delta(\{M\}, t \ t_{i_1} \ t_{i_2} \dots \ t_{i_k} \ t) = \varnothing \ . \tag{5}
$$

We explain this rule through the example illustrated through Fig. 3.

4. To keep the coherency of a WF process at runtime, whatever the firing sequence, starting from a marking M , the fi[na](#page-4-0)l marking has to be the same. Formally: $\forall i_1, i_2 \dots i_k \in \{1, 2 \dots |T|\}$ and $\forall j_1, j_2 \dots j_k \in \{1, 2 \dots |T|\}$, if $δ({M}, t_{i_1} t_{i_2} ... t_{i_k}) = ∅$ (resp. $δ({M}, t_{i_1} t_{i_2} ... t_{i_k}) = ∅$) then: $\delta({M}, t_{i_1}, t_{i_2} \ldots t_{i_{k-1}}) \neq \emptyset$ (resp. $\delta({M}, t_{i_1}, t_{i_2} \ldots t_{i_{k-1}}) \neq \emptyset$) is the final

marking. In such case we have to get:

$$
\delta({M}, t_{i_1}, t_{i_2} \dots t_{i_{k-1}}) = \delta({M}, t_{j_1}, t_{j_2} \dots t_{j_{k-1}}) .
$$
 (6)

We elucidate this rule through the example illustrated in Fig. 1.

Fig. 2. Process model (a) with deadlock

So, we calculate the possible markings resulting from the firing sequence of tasks $\langle t_7 \, t_8 \, t_{11} \, t_{12} \, t_{13} \, t_{14} \, t_{15} \, t_1 \rangle$, such as t. refers to any task $\in T$ that is not in the above firing sequence:

$$
\delta({M^{[0]}}), t_7 t_8 t_{11} t_{12} t_{13} t_{14} t_{15} t.) = \delta(\delta({M^{[0]}}), t_7), t_8 t_{11} t_{12} t_{13} t_{14} t_{15} t.)
$$

=...

= δ({{(00000000000 ∣D19∣ + x20), (00010000000 ∣D19∣ + x20)}, ∅}, t**.**)=∅ \Rightarrow {{(0 0 0 0 0 0 0 0 0 0 0 |D₁₉| + x₂₀), (0 0 0 1 0 0 0 0 0 0 0 |D₁₉| + x₂₀}}, ∅} is the final marking. We also calculate the possible markings resulting from the firing sequence of tasks $\langle t_7 \, t_8 \, t_{11} \, t_{13} \, t_{12} \, t_{14} \, t_{15} \, t_{\bullet} \rangle$:

 $\delta({M^{[0]}}), t_7 t_8 t_{11} t_{13} t_{12} t_{14} t_{15} t.) = \delta(\delta({M^{[0]}}), t_7), t_8 t_{11} t_{13} t_{12} t_{14} t_{15} t.)$ $=$...

= δ({{(00000000000 ∣D19∣ + x20), (00010000000 ∣D19∣ + x20)}, ∅}, t**.**)=∅ \Rightarrow {{(000000000000|D₁₉| + x₂₀), (00010000000|D₁₉| + x₂₀}}, ∅} is the final marking. So, as t_{12} and t_{13} are two parallel tasks: marking. So, as t_{12} and t_{13} are two parallel tasks:
 $\delta({M^{[0]}}), t_7 \ t_8 \ t_{11} \ t_{12} \ t_{13} \ t_{14} \ t_{15}) = \delta({M^{[0]}}), t_7 \ t_8 \ t_{11} \ t_{13} \ t_{12} \ t_{14} \ t_{15}).$

5. When the final marking has been reached, a WF process needs to be revived in order to be executed again. In other words, we have to ensure that $\forall M$ m order to be executed again. In
 $\mathbb{N}^{|S|}, i_1, i_2 \ldots i_k \in \{1, 2 \ldots |T|\}$:

$$
\delta({M^{[0]}}), t_{i_1} t_{i_2} \dots t_{i_k} t_{i_1}) = \varnothing . \tag{7}
$$

To do so, we extend WF by a restitution task $t_r \notin T$, i.e. t_r is not a data operation, it is a simple transition used to return from all the final states to the initial states. In such case:

$$
\delta(\emptyset, t_r) = \{M^{[0]}\} \tag{8}
$$

5 Workflow Analysis

As introduced in [13], the classical soundness property grants that a process has always the possibility to terminate and all its tasks are coverable (i.e., can potentially be executed). Termination ensures that the workflow can, during its execution, neither get stuck (i.e., it is deadlock free) nor enter a loop that

cann[ot b](#page-14-1)e left (i.e., it is livelocks free), whereas coverable excludes dead tasks in the workflow. But, to ensure these criteria, the soundness property needs, to be verified, that the process has a single source place i and a single final place o .

Nevertheless, to reflect the reality of business processes, we allow a WF model to present initial and final states as needed and accordingly, it is not possible to de[te](#page-13-4)[ct](#page-13-5) this classical soundness property. So, we propose a released notion of soundness which ensures that there are no livelocks, or deadlocks, or dead tasks in a WF . In other words, we will verify the well-formedness property of a WF process. According to [14], a P-net is well-formed if it is live and bounded. We adopt this rule to WF , thus, the first step is to verify its liveness property.

5.1 Verification of the Liveness Propert[y](#page-13-4)

W[e](#page-8-0) [t](#page-8-0)ackle [this](#page-8-1) issue in $[8, 9]$, but by analyzing other process cases, we have been aware that the proposed technique is not enough to ensure the liveness property of a WF model. So, we improve it as follows:

a *W* F model. So, we improve it as follows:
Assuming that $\{M^{[0]}\}$ is the set of the possible initial markings, a WF model Assuming that $\{M^{t-1}\}\$ is the set of the possible initial markings, a W F model
is live if and only if: $\forall t \in T$, $\exists t_1, t_2...t_n \in T \mid \delta(M^{[0]}, t_1, t_2...t_n, t) \neq \emptyset \Rightarrow$ t is live.

To ensure the verification of this property, we proposed in [8, 9] a simple algorithm based on (9) and (10), which are defined as the following:

$$
Findb = \bigwedge_{i \in \{1, 2...|S|\}}\text{Expectedb}(s_i).
$$
\n
$$
Pre(s_i, t) \neq 0
$$
\n
$$
(9)
$$

$$
\text{Expectedble}(s) = \begin{cases} \text{true if } \forall i \in \{1, 2 \dots |T|\}, \; Post_{Max}(s, \; t_i) = 0 \; .\\ \text{Findble}(t_i) \; \text{if } \exists \; i \in \{1, 2 \dots |T|\}, \; \text{ where } Post_{Max}(s, \; t_i) \neq 0 \; . \end{cases} \tag{10}
$$

We elucidate (9) and (10) through the example illustrated in Fig. 1. $\text{Firable}(t_{15}) =$ *i* ∈ {8*,* 9 *...* 19} $Pre(s_i, t_{15}) \neq 0$ Expectable(s_i)= Expectable(s_{18})= Firable(t_{14}) $=$ Expec[tabl](#page-8-1)e(s_{15}) \land Expectable(s_{17})= Firable(t_{12}) \land Firable(t_{13})= Expectable(s_{14}) \land

 $\text{Expectedble}(s_{16}) = \text{Findble}(t_{11}) \land \text{true} = \text{Findble}(t_{11}) = \text{Expectedble}(s_{10})$ $=$ Firable(t_8) = Expectable(s_9) = Firable(t_7) = Expectable(s_8) = true

By using (9) and (10) , we can verify that every task in a WF process is firable if its expected tokens can be provided by the evolution of the marking. However, this is not sufficient to verify its liveness proverty. In fact, if a WF model contains structural conflicts, there will be a part in the workflow that may not be executed. So, before applying (9) and (10), we have to start by verifying that the workflow does not contains structural conflicts.

Conflict Resolution: we assume that a WF model has a structural conflict, if it contains at least two tasks t_i and t_j having the same input data structure s_k , e.g., t_2 and t_5 sharing s_2 in the Role 1 sub-process, t_9 and t_{11} sharing s_{10}

in the Role 2 sub-process. To resolve such conflicts $[8, 9]$ $[8, 9]$ $[8, 9]$, we extend the model by adding extra tasks T^* = $\{t_{clone_1},\ t_{clone_2}\dots t_{clone_l}\}$ such as l is the number of conflict tasks, and t_{clone} is a *clone* operation formally defined as follows: whether $\text{conmetric} \text{ tasks, and } t_{clone} \text{ is a } \text{clone} \text{ operation form} \ s_k = (C_k, D_k), t_{clone}(s_k, l) = \{s_{k_1}, s_{k_2} \ldots s_{k_l}\}\;.$

 $T = (C_k, D_k), t_{clone}(s_k, t) = \{s_{k_1}, s_{k_2}...s_{k_l}\}$.
The extended model $WF_+ = (S_+, T_+, Pre_+, Post_+)$ such as: $S_+ = S$, T_{+} = $T \cup T^{*}$, Pre_{+} = $S \times T_{+}$, and $Post_{+}$ = $T_{+} \times S$.

Blocking State Resolution: after extending WF, the process has to be verified to ensure that there are no deadlocks or livelocks. In fact, if we apply (9) and (10) directly on a WF_{+} , which contains deadlocks or livelocks, the equations will enter in an infinite loop, as the case o[f](#page-6-0) [m](#page-6-0)odel (a) presented in Fig. 2:

 $\text{Firable}(t_2) =$ *i* ∈ {1, 2, 3} Expectable (s_i) =Expectable (s_2) ∧ Expectable (s_3)

$$
Pre(s_i, t_2) \neq 0
$$

- $=$ Firable(t_1) ∧ Firable(t_2) $=$ Expectable(s_1) ∧ Expectable(s_2) ∧ Expectable(s_3)
- $=$ true ∧ Firable(t_1) ∧ Firable(t_2)= Firable(t_1) ∧ Firable(t_2)= Expectable(s_1) ∧ Expectable(s_2) ∧ Expectable(s_3)= true ∧ Firable(t_1) ∧ Firable(t_2)= ...

The verification of deadlocks or livelocks is ensured by (5) defined by the firing rule 3, which prohibits the existence of loops in a WF model. If this rule is not verified, it means that the model contains deadlocks or livelocks and accordingly, it is not live.

5.2 Verification of the Boundedness Property

As we extended WF to WF_+ , the boundedness property will be verified relatively to the extended model. If WF_{+} is not bounded, it means that the workflow will contain at least one data structure having a number of tokens increasing infinitely with the evolution of the marking. To verify the boundedness property of a WF , we assume that if its WF ₊ has no loop, it will be bounded. We prove this idea as follows: According to (2): $\forall t_i, t_j \in T$, $\exists s \in S \mid < t_i, t_j >$, $pre(t_j, s) = post(t_i, s)$, which ensures that the number of tokens produced by a task, in its output data structure, will be automatically consumed by the next task having, as input, the same data structure. Besides, according to (5): $\forall i \in \{1, 2 \ldots |T|\}, M \in \{M_1, M_2 \ldots M_n\}, \delta(\{M\}, t \; t_{i_1} \; t_{i_2} \ldots \; t_{i_k} \; t) = \emptyset,$ which means that, there is no cycle in a WF model.

Consequently, $\{i \in \{1, 2...|T|\}, M > Pre(., t_i)\} = \emptyset$, and accordingly, in any case, the marking of a data structure will never be higher then the number of tuples requested by the task consuming this data structure tuples. Thus, $\bigcup_{\theta=0}^{+\infty}$ $\delta(M^{[\theta]}, t_i)| < +\infty$, which means that, the set of possible markings $\delta({M^{[\theta]}}), t_i)$ is a finite set $\forall t_i \in T$, and consequently, WF_{+} is bounded.

6 Opus Framework

Opus Framework is implemented using Java Swing language with a set of Java library, namely, JGraph, UMLGraph, JTable. . . It consists of a number of components including a modeling editor, a workflow engine, and a verification module.

6.1 Opus Editor

The graphical modeling of workflow processes is ensured using *Opus editor*. The latter is equipped with a set of graphical interfaces to create profiles of roles performing the work, define data flow interactions between roles and the IS (e.g. ICRole receives the data structure $Customer_Inf$ from SCRole and saves Order Table a[nd](#page-7-0) Order Line Table tokens in the IS), and finally, define the sub-process model related to each role work. It also p[rov](#page-10-0)ides to the designer a customized assistant for each operation in the process m[od](#page-10-1)el, in order to help him to model the process structure.

6.2 Verification of the Workflow Model

 $Opus$ system is equipped with a *verification module* which ensures the analyses and the verification of the conceived workflow models, as described in Sect. 5. The verification result of the ICRole sub-process is illustrated in Fig. 3. We illustrate also the verification of model (a) (defined in Fig. 2), through Fig. 4.

Fig. 3. ICRole sub-process verification (processing time 1.37 sec)

Fig. 4. Model (a) verification (processing time 0.24 sec)

6.3 Opus Engine

Opus engine follows up the data flow routing, simulates the processing of tasks according to its formal definition, considering the firing rules defined in Sect. 4, and invites each role to perform its tasks according to its feasibility and urgency. Furthermore, tokens of workflow initial states may be imported from the IS. And in the same way, tokens of final states may be stored in. For this purpose, *Opus* engine is equipped with the IS Integration Module that provides the *Import tool* (which imports tuples from a definite IS table to a definite data structure [9]), the *ImportId tool* (which imports the identifier of the last tuple inserted in a definite IS table, instead of being entered by a role), and the *Insert*

tool (which stores a data structure tuples in a definite IS table. It is considered as an *Add* Tuples operation such as t_{10} and t_{15} in Fig 1). We detail all the actions, performed either by the ICRole or by *Opus* engine, through Fig. 5.

A1. *Starting the* ICRole *sub-process:* when the ICRole launches his process, the engine will present to him the data structure $Customer_Inf$ received from $SCRole$ and will ask him to instantiate the data structure $Product_Table$.

A₂. Alimentation of the data structure Product_Table from the IS: the ICRole imports tuples to *Product Table* from the IS using the *Import* tool, and validates its tokens in order to execute t_7 (see Step 1).

A3. *Seizure of the ordered quantities:* the ICRole seizes the ordered quantities relatively to the ordered products (OrdPs), in the resulting data structure of t_7 , and validates his seizures (see Step 2).

 A_4 . Select the OrdPs: during the execution of t_8 , the engine invites the ICRole to enter the selection property in order to select the OrdPs (see Step 3). Then, the ICRole saves the selection property for the next executions of t_8 .

A₅. *Verify the availability of the OrdPs:* in this runtime example, $s_{10} \neq \emptyset$, so, t_{11} decides to send s_{14} to t_{12} , also t_9 decides to send s_{11} to t_{10} .

A₆. *Insert a new order:* t_{10} uses the *Insert tool* to insert a new order in the IS Orders Table (see Steps 5, 5.1, 5.2).

 A_7 . Create the new order lines: in parallel with t_9 , t_{11} then t_{12} will be automatically executed to produce s_{15} (see Step 4-2). Then, t_{14} will be waiting for s_{17} to be executed. In this case, the *ICRole* has to launch the execution of t_{13} .

A8. *Import the identifier of the last inserted order from the IS:* the ICRole launches the execution of t_{13} (see Step 6-1). The latter receives the empty data structure S16 Order Id as an input, and instead of seizing the new order identifier, t_{13} will import its value using the *ImportId* tool (see Step 6-2).

A₉. *Wake a waiting task:* at this level, the *ICRole* can turn to wake t_{14} by validating s¹⁵ tokens, and the engine will launch its execution (see Step 7).

 A_{10} . *Complete the creation of the new order lines:* the engine executes t_{14} to produce s_{18} tokens (see Step 8).

 A_{11} . *Insert the new order lines:* the engine executes t_{15} and asks the *ICRole* to choose the suitable IS table for the insertion (see Step 9-1), and to perform the matching between the data structure s_{18} and the chosen table (see Step 9-2). If these two steps are well done, the engine will properly end the workflow.

We can deduce, from the execution details, the presence of four types of actions: 9.1% of actions are based on *manual tasks* (i.e. tasks that are performed only by a role without the intervention of the engine, such as A_3), 27.27% of actions are based on *automatic tasks* (i.e. tasks that are performed only by the engine without the intervention of a role, such as A_5 , A_7 and A_{10}), 18.18% of actions are based on *semi-automatic tasks* (i.e. tasks that are performed by the engine under control of a role, such as A_1 and A_9), and 45.45% of actions are based on *semi-automatic tasks only in the first execution (SA-FE)* (i.e. tasks that are semi-automatic tasks only in their first executions, but during their next executions, they will migrate to be automatic tasks, such as A_2 , A_4 , A_6 , A_8 and A_{11}).

Fig. 5. Executing the ICRole sub-process

7 Conclusions a[nd](#page-5-0) Future Work

According to the execution of the ICRole sub-process, manual tasks are extremely reduced. Other tasks are either purely executed by the engine, or executed by the engine under supervising of a human actor. That demonstrates the success of the modeling approach in execution issue. In fact, thanks to the detailed definition of the workflow model, Opus engine can interpret, automatically, the process operational functions and perform a data-driven execution based on the firing rules defined in Sect. 4. These latter ensure the consistency of data, during runtime, and grant, together with the verification method, presented in Sect. 5, the proper termination of the workflow process. However, this Framework must be completed by a module for documents generation (invoice, purchase order...): the system can manage the content but not the container.

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Appendix A: Data Operations Definition

Table 1. Operations definition