# A Framework for Data-Driven Workflow Management: Modeling, Verification and Execution

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**Abstract.** In recent years, many data-driven workflow modeling approaches has been developed, but none of them can insure data integration, process verification and automatic data-driven execution in a comprehensive way. Based on these needs, we introduced, in previous works, a data-driven approach for workflow modeling and execution. In this paper, we extend our approach to ensure a correct definition and execution of our workflow model, and we implement this extension in our Framework *Opus*.

**Keywords:** Data-driven workflow management Framework, Petri nets, Relational algebra, Workflow analysis and verification, Soundness property.

### 1 Introduction

In a competitive environment continually evolving, companies are recognized the need to manage their business processes in order to align their information systems, more and more quickly, in a process-oriented way. In this context, workflow management systems (WMS) offer promising perspectives for modeling, processing and controlling processes. In the most common WMS, only the control flow <sup>1</sup> is completely included [1]. In Fact, during process execution, a process-oriented view (e.g. worklists) is provided to end-users. However, the behavior of an activity during its execution is out of the control of the WMS [2]. As almost all processes are related to data, such as the costs of the ordered products, the addresses information for delivery, etc., the main goal from using a WMS is to automate, as possible, the manipulation of data in business processes, and to restrict as possible the manual tasks performed by human actors.

Regarding the existing literature, the need for modeling processes that combine data and control flow has been widely studied. Most of them are inspired from Petri nets (P-nets) formalism, such as the approaches proposed in [3–7]. Thus, to enhance earlier approaches that have mainly focused on process activities and largely overlooked the data, we previously extended, in [8,9], the P-nets

<sup>&</sup>lt;sup>1</sup> Control flow: is a set of synchronized activities representing the business process functions, and a set of ordering constraints defining their execution sequence [1].

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formalism by data operations inspired from the relational algebra to model datadriven workflows. This extension improves the generation of business functions from the process definition, without the need for a programmer, and provides advanced abilities for the information system (IS) and the users' integration. In this paper, we extend the modeling method of the proposed approach [8,9] by some rules, to ensure the consistency of the process model during runtime. We also provide a technique to verify a released notion of the classical soundness property.

The remainder of the paper is organized as follows: we present the related work in Sect. 2 and we continue by introducing our workflow model in Sect. 3. In Sect. 4, we present the definition of the firing rules that ensure a uniform execution of all the process activities. Then we discuss, in Sect. 5, the technique provided to ensure the analysis and the verification of our workflow model. In Sect. 6, we present our Framework *Opus*. Section 7 concludes.

# 2 Related Work

The need for modeling processes integrating data has been recognized by several authors [3–7, 10, 11]. The Case Handling Paradigm [11] aims to coordinate activities which are presented as forms in relation to atomic data elements. The problem here is that data may be omitted or activities are unwittingly ignored or executed many times. In addition, more than one user can handle the same case simultaneously, which damages the data coherence.

The PHILharmonicFlows system [2] provides a comprehensive approach that combines object behavior based on states with data-driven process execution. In fact, it allows the control of activities by presenting them as form-based  $^2$  and black-box activities  $^3$ . The proper execution as well as termination of processes at runtime is further ensured by a set of correctness rules [12]. But, the execution of form-based activities increases the rate of errors that may be caused by the manual seizure performed by human actors, even if the seized data values respect the data types requested by the form' input fields.

Many extensions of P-nets in which tokens carry data have been defined in the literature. The workflow nets based on colored P-nets (WFCP-nets) [10] consider a P-net color as an abstraction of data objects and flow control variants. The execution of a WFCP-net depends on the interpretation of its arc expressions and guard expressions, which describe the business rules. Besides, the verification methods of workflow nets [13] are adapted to WFCP-nets. The weakness of this approach is that the process specification consists of a graphical part and a WF script part. The latter is a hard-coding process logic that describes the data elements and the behavior of activities. So, resulting applications are both complex to design and costly to deploy, and even simple process changes require

<sup>&</sup>lt;sup>2</sup> Form-based activities: provide input fields for writing and data fields for reading selected attributes of data object instances [2].

<sup>&</sup>lt;sup>3</sup> Black-box activities: allow the integration of advanced functionalities (e.g. sending e-mails) [2].

costly code adaptations and testing efforts. Another extension of P-nets is the workflow nets with data (WFD-nets) [7], in which transitions can read from or write to some data elements. This extension does not provide a support for executing process models. However, it defines algorithms to verify a soundness property that guarantees the proper termination of a WFD-net and that only certain transitions are not dead.

None of the existent approaches considers data integration, process verification and data-driven execution issues in a comprehensive way. Thus, in this area a comprehensive approach for supporting these three issues is still missing.

# 3 Our Data-Driven Workflow Model

As described by the most modeling approaches, a process is defined, in a higher level of abstraction, as a set of synchronized activities performed by roles according to the available data. If we stop at this level, we will not be able to generate the process functions from the process model definition, and activities will behave as a black box in which data are managed by invoked application components. To attempt the lowest level of abstraction, we propose to split each activity, in a process, to tasks applied on data. Each task consumes data to produce others. Thus, each activity is presented as a set of data-driven tasks. Each task consumed data provenance can be either the IS, or data produced by other tasks. But, in some cases, to complete the processing of a task, data can be seized by a role. Accordingly, to enable tasks to generate new data from old ones and import data from the IS, data have to be well structured. We introduced this approach in [8,9], in a formal way, as a data-driven modeling approach based on combination between structured tokens P-nets and relational algebra.

#### 3.1 Data Structure

According to [8,9], we define each handled data as a data structure; i.e, a pair s = (C, D), where C is a list of attributes and D is a list of data tuples. Each tuple is an ordered list of attributes values, formally defined by:

$$C = (c_1, c_2 \dots c_n), D = \{ (d_{1_1}, d_{1_2} \dots d_{1_n}), (d_{2_1}, d_{2_2} \dots d_{2_n}) \dots (d_{m_1}, d_{m_2} \dots d_{m_n}) \}.$$

Where n (resp. m) is the number of attributes (resp. tuples) in s.

Each attribute  $c_j = (\alpha_j, \beta_j)$  is a pair characterized by an attribute identifier  $\alpha_j$  and an attribute type  $\beta_j$ , such as:  $\forall j \in \{1, 2...n\}, \beta_j \in \{Int, Float, Char, String, Date, Boolean...\}$ , and  $\forall i \in \{1, 2...m\}$ , an attribute value  $d_{i_j}$  is a specific valid value for the type  $\beta_j$  of the attribute  $c_j$ .

At modeling step, the designer has just to define the data structure attributes and the values types put up with each one. At runtime, the different data structure tuples comprise varying values according to each attribute type.

#### 3.2 Process Structure

The workflow process is defined as a P-net representing the work, where a place corresponds to a *data structure* that contains *structured tokens* (tuples)

and a transition corresponds to a *task*. A workflow is then a quadruplet [8,9] WF = (S, T, Pre, Post), where:

 $S = \{s_1, s_2 \dots s_{|S|}\}$  is a finite set of data structures,

 $T = \{t_1, t_2 \dots t_{|T|}\}$  is a finite set of tasks inspired from the relational algebra,  $Pre: S \times T \to \mathbb{N}$  is the pre-incidence matrix, such as,  $\forall i \in \{1, 2 \dots |S|\}$  and

 $j \in \{1, 2... |T|\}$ ,  $Pre(s_i, t_j)$ , is the edge between a data structure  $s_i$  and a task  $t_j$  weight, representing the number of tokens consumed by  $t_j$  in order to be firable, i.e. executable.

*Post*:  $T \times S \rightarrow \mathbb{N}$  is the post-incidence matrix. Due to the dynamic of the relational algebra, we cannot be limited to a static post-incidence matrix thus,  $\forall i \in \{1, 2..., |S|\}$  and  $j \in \{1, 2..., |T|\}$ ,  $Post(t_j, s_i) \in [Post_{Min}(t_j, s_i),$ 

 $Post_{Max}(t_j, s_i)$ ]. Where:  $Post_{Min}(t_j, s_i)$  (resp.  $Post_{Max}(t_j, s_i)$ ), is the edge between a task  $t_j$  and a data structure  $s_i$  minimal (resp. maximal) weight, representing the minimal (resp. maximal) number of  $t_j$  produced tokens.

#### 3.3 Data Operations

A task can be viewed as a data operation applied on data structure tokens to produce others. Therefore, we have inspired from the relational algebra to define the behavior of operations. We presented these operations in [9]. So, in this paper, we detail in Appendix A, only operations that we will use to demonstrate the new extensions of the model. Noting that the definition of the  $Add\_Tuples$  operation, presented in Table 1, is an extended version of its definition in [9]. In fact, in this version, we allow to inserts all a data structure tuples in another data structure, instead of inserting only a single tuple [9].

#### 3.4 Workflow Example

The customer solvency check role (SCRole) evaluates the received orders, and sends them to the inventory check. After the evaluation, either an order is rejected, or sent to shipping and billing. As illustrated by Fig. 1, considering that  $s_8$ ,  $s_{13}$ , and  $s_{19}$  present tables from the IS, we restrict our example to the inventory check role (ICRole) sub-process, which performs the following activities:

Select the ordered products:  $t_7$  extends  $s_8$  (which contains all the products data) by the ord\_qtity attribute, in order to allow the ICRole to enter the ordered quantities. Then,  $t_8$  selects from  $s_9$  only tuples having an ordered quantity value higher than zero and lower than the stocked product quantity.

Verify the products availability:  $t_9$  checks  $s_{10}$  content. If it contains one or more tokens,  $t_9$  will reproduce  $s_{11}$  token in  $s_{12}$ , otherwise, it will end the process.

Create a new order: according to the decision of  $t_9$ , if there are available products,  $t_{10}$  will add a new order in  $s_{13}$ .

Create the new order lines: the ICRole enters the new order identifier and  $t_{13}$  saves it in  $s_{17}$ . Then,  $t_{14}$  will create the new order lines and finally,  $t_{15}$  will save the resulting structured  $s_{18}$  tokens in  $s_{19}$ .



Fig. 1. The inventory check role sub-process [9] (modified version)

We deduce the *Pre* and *Post* matrix of the example in Fig. 1.

		$t_7$	$t_8$	$t_9$	$t_{10}$	$t_{11}$	$t_{12}$	$t_{13}$	$t_{14}$	$t_{15}$
Pre =	$s_8$	$\int x_8$	0	0	0	0	0	0	0	0)
	$s_9$	0	$x_{10}$	0	0	0	0	0	0	0
	$s_{10}$	0	0	$x_{12}$	0	$x_{12}$	0	0	0	0
	$s_{11}$	0	0	1	0	0	0	0	0	0
	$s_{12}$	0	0	0	$x_6$	0	0	0	0	0
	$s_{13}$	0	0	0	0	0	0	0	0	0
	$-s_{14}$	0	0	0	0	0	$x_{14}$	0	0	0
	$s_{15}$	0	0	0	0	0	0	0	$x_{16}$	0
	$s_{16}$	0	0	0	0	0	0	1	0	0
	$s_{17}$	0	0	0	0	0	0	0	$x_{18}$	0
	$s_{18}$	0	0	0	0	0	0	0	0	$x_{20}$
	$s_{19}$	0	0	0	0	0	0	0	0	0 /

Following the definition of tasks in Appendix A, the number of tokens produced by each task in Fig. 1, are defined as follows:  $x_5 \in [0, 1]$ ,  $x_6 = 1$  (i.e. there is only a single customer identifier),  $x_7 = |D_{13}| + x_6$ ,  $x_9 = x_8$ ,  $x_{11} \in [0, x_{10}]$ ,  $x_{13} \in [0, x_{12}]$ ,  $x_{15} \in [0, x_{14}]$ ,  $x_{17} = |D_{17}| + 1 = 1$  (because  $D_{17} = \emptyset$ ),  $x_{19} = x_{16} \times x_{18}$ ,  $x_{21} = |D_{19}| + x_{20}$ . Accordingly, the *Post* matrix is defined by:

	$t_7$	$t_8$	$t_9$	$t_{10}$	$t_{11}$	$t_{12}$	$t_{13}$	$t_{14}$	$t_{15}$
$s_8$	10	0	0	0	0	0	0	0	0 )
$s_9$	$x_8$	0	0	0	0	0	0	0	0
$s_{10}$	0	$[0, x_{10}]$	0	0	0	0	0	0	0
$s_{11}$	0	0	0	0	0	0	0	0	0
$s_{12}$	0	0	[0, 1]	0	0	0	0	0	0
Deed \$13	0	0	0	$ D_{13}  + x_6$	0	0	0	0	0
$Post = \frac{s_{14}}{s_{14}}$	0	0	0	0	$[0, x_{12}]$	0	0	0	0
$s_{15}$	0	0	0	0	0	$[0, x_{14}]$	0	0	0
$s_{16}$	0	0	0	0	0	0	0	0	0
$s_{17}$	0	0	0	0	0	0	1	0	0
$s_{18}$	0	0	0	0	0	0	0	$x_{16} \times x_{18}$	0
$s_{19}$	0	0	0	0	0	0	0	0	$ D_{19}  + x_{20}$

#### 3.5 Marking

The marking  $M^{[\theta]}$  defines the state of the process described by WF at a given time  $\theta \in \{0, 1, 2...\}$ . Thus,  $\forall i \in \{1, 2...|S|\} : M^{[\theta]} = \left(m_1^{[\theta]} m_2^{[\theta]} \ldots m_{|S|}^{[\theta]}\right)$ , where  $m_i^{[\theta]} \in \mathbb{N}$  is the number of tuples in  $s_i$ .

The initial marking  $M^{[0]}$  defines the state of WF at time  $\theta = 0$ , in which only root nodes of a WF process can be initiated by a finite number of tokens. The evolution of the markings, in the other nodes, results due to the firing of WFtasks. A valid initial marking must follow (1) [8,9].

$$\forall j \in \{1, 2... |S|\}, m_j^{[0]} = \begin{cases} \max_{k \in \{1, 2... |T|\}} Pre(s_j, t_k) \\ if \ \forall l \in \{1, 2... |T|\} Post_{Max}(s_j, t_l) = 0, \\ 0 \text{ otherwise.} \end{cases}$$
(1)

#### 3.6 Synthesis

Our proposed data-driven approach allows for a comprehensive integration between data flow and control flow, which ensures a successful data driven execution of the workflow. Indeed, data integration is granted through data structures that can handle various data elements types. Furthermore, data manipulation is enable through data operations that can read, write and generate new data elements without any risk of simulating a WF process in which data can be lost. This is granted through the dynamic behavior of the relational data operations, which entails a generalization of the static post-incidence matrix of the classical P-nets. In the next section, we present how we improve our approach by the application of some firing rules. These latter grant a uniform definition of a WFprocess and introduce the basic notions of our verification method, that ensures a valid WF process execution.

#### 4 Firing Rules

To ensure the process consistency during runtime, we improve the modeling approach described in [8, 9] by adding some firing rules. The latter indicate under which conditions a task may fire, and what the effect of the firing on the marking is.

1. Assuming that  $t_i, t_j \in T$ , are two successive tasks in a WF, and  $s \in S$  is an output data structure of  $t_i$  and an input data structure to  $t_j$ . Thus, tokens produced by  $t_i$  will be automatically consumed by  $t_j$ :

$$\forall t_i, t_j \in T, \exists s \in S \mid \langle t_i, t_j \rangle \Rightarrow pre(t_j, s) = post(t_i, s) .$$
(2)

2. Assuming that  $\delta$  is the function calculating the possible markings resulting of the firing of a task  $t_i \in T$  from a marking M. So,  $\forall M \in \mathbb{N}^{|S|}$ ,  $t_1, t_2 \dots t_k \in T$ :

$$\delta(\{M_1, M_2 \dots M_n\}, t_1 t_2 \dots t_k) = \bigcup_{M \in \{M_1, M_2 \dots M_n\}} \delta(\{M\}, t_1 t_2 \dots t_k)$$
(3)

Where: 
$$\delta(\{M\}, t_1 t_2 \dots t_k) = \delta(\delta(\{M\}, t_1), t_2 \dots t_k)$$
  
=  $\delta(\delta(\delta(\{M\}, t_1), t_2), t_3 \dots t_k)$   
= ...

The function  $\delta(\{M\}, t_i)$  is defined as follows:

$$\delta(\{M\}, t_i) = \begin{cases} \emptyset \text{ if } M < Pre(., t_i), \\ \{M - Pre(., t_i) + x\} \text{ otherwise.} \end{cases}$$
(4)

Where  $x \in [Post_{Min}(., t_i), Post_{Max}(., t_i)]$ , and  $\delta(\emptyset, t_i) = \emptyset$ .

We apply (3) and (4) on the example illustrated in Fig. 1, and we calculate the possible markings resulting from the firing sequence of tasks  $< t_7 t_8 t_{11} t_{12} t_{13} t_{14} t_{15} >$ :

- $\delta(\{M^{[0]}\}, t_7 t_8 t_{11} t_{12} t_{13} t_{14} t_{15}) = \delta(\delta(\{M^{[0]}\}, t_7), t_8 t_{11} t_{12} t_{13} t_{14} t_{15})$
- 3. According to (1), any loop in a WF model will cause a blocking state. In fact, if a task  $t_j$  is waiting for a data structure *s* tuples, and if these tuples are produced by a task  $t_i$ , which will never be executed in certain conditions: if his input data structures are not root nodes, and if  $t_j \in \langle t_1 t_2 \dots t_i \rangle$ , i.e. the firing sequence leading to execute  $t_i$ , this case is identified as a deadlock. In addition, even if the input data structures of  $t_j$  are root nodes, the occured cycle may cause a livelock (i.e. a loop without progress). Thus, we require that each task  $t \in T$  is fired, at most once, in a sequence of tasks starting from a marking M.

$$\forall i_1, \ i_2 \dots i_k \in \{1, \ 2 \dots |T|\}, \ \delta(\{M\}, t \ t_{i_1} \ t_{i_2} \dots \ t_{i_k} \ t) = \emptyset \ . \tag{5}$$

We explain this rule through the example illustrated through Fig. 3.

4. To keep the coherency of a WF process at runtime, whatever the firing sequence, starting from a marking M, the final marking has to be the same. Formally:  $\forall i_1, i_2 \dots i_k \in \{1, 2 \dots |T|\}$  and  $\forall j_1, j_2 \dots j_k \in \{1, 2 \dots |T|\}$ , if  $\delta(\{M\}, t_{i_1}, t_{i_2} \dots t_{i_k}) = \emptyset$  (resp.  $\delta(\{M\}, t_{j_1}, t_{j_2} \dots t_{j_k}) = \emptyset$ ) then:

 $\delta(\{M\}, t_{i_1}, t_{i_2}, \dots, t_{i_{k-1}}) \neq \emptyset$  (resp.  $\delta(\{M\}, t_{j_1}, t_{j_2}, \dots, t_{j_{k-1}}) \neq \emptyset$ ) is the final marking. In such case we have to get:

$$\delta(\{M\}, t_{i_1} t_{i_2} \dots t_{i_{k-1}}) = \delta(\{M\}, t_{j_1} t_{j_2} \dots t_{j_{k-1}}) .$$
(6)

We elucidate this rule through the example illustrated in Fig. 1.



Fig. 2. Process model (a) with deadlock

So, we calculate the possible markings resulting from the firing sequence of tasks  $\langle t_7 t_8 t_{11} t_{12} t_{13} t_{14} t_{15} t$ . >, such as t. refers to any task  $\in T$  that is not in the above firing sequence:

 $\delta(\{M^{[0]}\}, t_7 t_8 t_{11} t_{12} t_{13} t_{14} t_{15} t_{\cdot}) = \delta(\delta(\{M^{[0]}\}, t_7), t_8 t_{11} t_{12} t_{13} t_{14} t_{15} t_{\cdot}) = \dots$ 

 $\delta(\{M^{[0]}\}, t_7 t_8 t_{11} t_{13} t_{12} t_{14} t_{15} t_{\cdot}) = \delta(\delta(\{M^{[0]}\}, t_7), t_8 t_{11} t_{13} t_{12} t_{14} t_{15} t_{\cdot}) = \dots$ 

 $\delta(\{M^{[0]}\}, t_7 \ t_8 \ t_{11} \ t_{12} \ t_{13} \ t_{14} \ t_{15}) = \delta(\{M^{[0]}\}, t_7 \ t_8 \ t_{11} \ t_{13} \ t_{12} \ t_{14} \ t_{15}).$ 

5. When the final marking has been reached, a WF process needs to be revived in order to be executed again. In other words, we have to ensure that  $\forall M \in \mathbb{N}^{|S|}$ ,  $i_1, i_2 \dots i_k \in \{1, 2 \dots |T|\}$ :

$$\delta(\{M^{[0]}\}, t_{i_1} t_{i_2} \dots t_{i_k} t_{i_1}) = \emptyset .$$
(7)

To do so, we extend WF by a restitution task  $t_r \notin T$ , i.e.  $t_r$  is not a data operation, it is a simple transition used to return from all the final states to the initial states. In such case:

$$\delta(\emptyset, t_r) = \{M^{[0]}\} . \tag{8}$$

### 5 Workflow Analysis

As introduced in [13], the classical soundness property grants that a process has always the possibility to terminate and all its tasks are coverable (i.e., can potentially be executed). Termination ensures that the workflow can, during its execution, neither get stuck (i.e., it is deadlock free) nor enter a loop that cannot be left (i.e., it is livelocks free), whereas coverable excludes dead tasks in the workflow. But, to ensure these criteria, the soundness property needs, to be verified, that the process has a single source place i and a single final place o.

Nevertheless, to reflect the reality of business processes, we allow a WF model to present initial and final states as needed and accordingly, it is not possible to detect this classical soundness property. So, we propose a released notion of soundness which ensures that there are no livelocks, or deadlocks, or dead tasks in a WF. In other words, we will verify the well-formedness property of a WFprocess. According to [14], a P-net is well-formed if it is live and bounded. We adopt this rule to WF, thus, the first step is to verify its liveness property.

#### 5.1 Verification of the Liveness Property

We tackle this issue in [8,9], but by analyzing other process cases, we have been aware that the proposed technique is not enough to ensure the liveness property of a WF model. So, we improve it as follows:

Assuming that  $\{M^{[0]}\}$  is the set of the possible initial markings, a WF model is live if and only if:  $\forall t \in T, \exists t_1, t_2 \dots t_n \in T \mid \delta(M^{[0]}, t_1 t_2 \dots t_n t) \neq \emptyset \Rightarrow t$  is live.

To ensure the verification of this property, we proposed in [8, 9] a simple algorithm based on (9) and (10), which are defined as the following:

$$Firable(t) = \bigwedge_{\substack{i \in \{1, 2... |S|\}\\ Pre(s_i, t) \neq 0}} Expectable(s_i) .$$
(9)

$$\operatorname{Expectable}(s) = \begin{cases} \operatorname{true if } \forall i \in \{1, \ 2 \dots |T|\}, \ \operatorname{Post}_{Max}(s, \ t_i) = 0 \ . \\ \operatorname{Firable}(t_i) \ \text{if } \exists \ i \in \{1, \ 2 \dots |T|\}, \ \text{where } \operatorname{Post}_{Max}(s, \ t_i) \neq 0 \ . \end{cases}$$
(10)

We elucidate (9) and (10) through the example illustrated in Fig. 1. Firable( $t_{15}$ ) =  $\land$  Expectable( $s_i$ ) = Expectable( $s_{18}$ ) = Firable( $t_{14}$ )  $i \in \{8, 9...19\}$   $Pre(s_i, t_{15}) \neq 0$ = Expectable( $s_{15}$ )  $\land$  Expectable( $s_{17}$ ) = Firable( $t_{12}$ )  $\land$  Firable( $t_{13}$ ) = Expectable( $s_{14}$ )  $\land$ Expectable( $s_{16}$ ) = Firable( $t_{11}$ )  $\land$  true = Firable( $t_{11}$ ) = Expectable( $s_{10}$ )

= Firable
$$(t_8)$$
 = Expectable $(s_9)$  = Firable $(t_7)$  = Expectable $(s_8)$  = true

By using (9) and (10), we can verify that every task in a WF process is firable if its expected tokens can be provided by the evolution of the marking. However, this is not sufficient to verify its liveness proverty. In fact, if a WF model contains structural conflicts, there will be a part in the workflow that may not be executed. So, before applying (9) and (10), we have to start by verifying that the workflow does not contains structural conflicts.

**Conflict Resolution:** we assume that a WF model has a structural conflict, if it contains at least two tasks  $t_i$  and  $t_j$  having the same input data structure  $s_k$ , e.g.,  $t_2$  and  $t_5$  sharing  $s_2$  in the Role 1 sub-process,  $t_9$  and  $t_{11}$  sharing  $s_{10}$ 

in the Role 2 sub-process. To resolve such conflicts [8,9], we extend the model by adding extra tasks  $T^* = \{t_{clone_1}, t_{clone_2} \dots t_{clone_l}\}$  such as l is the number of conflict tasks, and  $t_{clone}$  is a *clone* operation formally defined as follows: whether  $s_k = (C_k, D_k), t_{clone}(s_k, l) = \{s_{k_1}, s_{k_2} \dots s_{k_l}\}$ .

The extended model  $WF_+ = (S_+, T_+, Pre_+, Post_+)$  such as:  $S_+ = S$ ,  $T_+ = T \cup T^*$ ,  $Pre_+ = S \times T_+$ , and  $Post_+ = T_+ \times S$ .

**Blocking State Resolution:** after extending WF, the process has to be verified to ensure that there are no deadlocks or livelocks. In fact, if we apply (9) and (10) directly on a  $WF_+$ , which contains deadlocks or livelocks, the equations will enter in an infinite loop, as the case of model (a) presented in Fig. 2:

 $Firable(t_2) = \bigwedge_{\substack{i \in \{1, 2, 3\}\\ Pre(s_i, t_2) \neq 0}} Expectable(s_i) = Expectable(s_2) \land Expectable(s_3)$ 

= Firable $(t_1)$   $\wedge$  Firable $(t_2)$  = Expectable $(s_1)$   $\wedge$  Expectable $(s_2)$   $\wedge$  Expectable $(s_3)$ 

= true  $\land$  Firable $(t_1)$   $\land$  Firable $(t_2)$  = Firable $(t_1)$   $\land$  Firable $(t_2)$  = Expectable $(s_1)$   $\land$  Expectable $(s_2)$   $\land$  Expectable $(s_3)$  = true  $\land$  Firable $(t_1)$   $\land$  Firable $(t_2)$  = ...

The verification of deadlocks or livelocks is ensured by (5) defined by the firing rule 3, which prohibits the existence of loops in a WF model. If this rule is not verified, it means that the model contains deadlocks or livelocks and accordingly, it is not live.

### 5.2 Verification of the Boundedness Property

As we extended WF to  $WF_+$ , the boundedness property will be verified relatively to the extended model. If  $WF_+$  is not bounded, it means that the workflow will contain at least one data structure having a number of tokens increasing infinitely with the evolution of the marking. To verify the boundedness property of a WF, we assume that if its  $WF_+$  has no loop, it will be bounded. We prove this idea as follows: According to (2):  $\forall t_i, t_j \in T, \exists s \in S \mid \langle t_i, t_j \rangle$ ,  $pre(t_j, s) = post(t_i, s)$ , which ensures that the number of tokens produced by a task, in its output data structure, will be automatically consumed by the next task having, as input, the same data structure. Besides, according to (5):  $\forall i \in \{1, 2 \dots |T|\}, M \in \{M_1, M_2 \dots M_n\}, \delta(\{M\}, t t_{i_1} t_{i_2} \dots t_{i_k} t) = \emptyset$ , which means that, there is no cycle in a WF model.

Consequently,  $\{i \in \{1, 2..., |T|\}, M > Pre(., t_i)\} = \emptyset$ , and accordingly, in any case, the marking of a data structure will never be higher then the number of tuples requested by the task consuming this data structure tuples. Thus,  $|\bigcup_{\theta=0}^{+\infty} \delta(M^{[\theta]}, t_i)| < +\infty$ , which means that, the set of possible markings  $\delta(\{M^{[\theta]}\}, t_i)$  is a finite set  $\forall t_i \in T$ , and consequently,  $WF_+$  is bounded.

# 6 Opus Framework

*Opus* Framework is implemented using Java Swing language with a set of Java library, namely, JGraph, UMLGraph, JTable... It consists of a number of components including a modeling editor, a workflow engine, and a verification module.

### 6.1 Opus Editor

The graphical modeling of workflow processes is ensured using *Opus editor*. The latter is equipped with a set of graphical interfaces to create profiles of roles performing the work, define data flow interactions between roles and the IS (e.g. ICRole receives the data structure *Customer\_Inf* from SCRole and saves *Order\_Table* and *Order\_Line\_Table* tokens in the IS), and finally, define the sub-process model related to each role work. It also provides to the designer a customized assistant for each operation in the process model, in order to help him to model the process structure.

### 6.2 Verification of the Workflow Model

*Opus* system is equipped with a *verification module* which ensures the analyses and the verification of the conceived workflow models, as described in Sect. 5. The verification result of the ICRole sub-process is illustrated in Fig. 3. We illustrate also the verification of model (a) (defined in Fig. 2), through Fig. 4.

Well-formedness Verification:	Well-formedness Verification:
Liveness Verification	
Task T7 is live.	Linear and Mariffer Alan
Task T8 is live.	Liveness verification
Task T11 is live.	Task T1 is live
Task T9 is live.	
Task T10 is live.	Task T2 is not live.
Task T13 is live.	
Task T12 is live.	Boundness Verification
Task T14 is live.	
Task T15 is live.	The model is not bounded.
Boundness Verification	
The model is bounded.	
OK Cancel	OK Cancel

**Fig. 3.** ICRole sub-process verification (processing time 1.37 sec)

**Fig. 4.** Model (a) verification (processing time 0.24 sec)

### 6.3 Opus Engine

Opus engine follows up the data flow routing, simulates the processing of tasks according to its formal definition, considering the firing rules defined in Sect. 4, and invites each role to perform its tasks according to its feasibility and urgency. Furthermore, tokens of workflow initial states may be imported from the IS. And in the same way, tokens of final states may be stored in. For this purpose, Opus engine is equipped with the IS Integration Module that provides the Import tool (which imports tuples from a definite IS table to a definite data structure [9]), the ImportId tool (which imports the identifier of the last tuple inserted in a definite IS table, instead of being entered by a role), and the Insert

tool (which stores a data structure tuples in a definite IS table. It is considered as an Add\_Tuples operation such as  $t_{10}$  and  $t_{15}$  in Fig 1). We detail all the actions, performed either by the ICRole or by *Opus* engine, through Fig. 5.

 $A_1$ . Starting the ICRole sub-process: when the ICRole launches his process, the engine will present to him the data structure Customer\_Inf received from SCRole and will ask him to instantiate the data structure Product\_Table.

 $A_2$ . Alimentation of the data structure Product\_Table from the IS: the ICRole imports tuples to Product\_Table from the IS using the Import tool, and validates its tokens in order to execute  $t_7$  (see Step 1).

 $A_3$ . Seizure of the ordered quantities: the ICRole seizes the ordered quantities relatively to the ordered products (OrdPs), in the resulting data structure of  $t_7$ , and validates his seizures (see Step 2).

 $A_4$ . Select the OrdPs: during the execution of  $t_8$ , the engine invites the *ICRole* to enter the selection property in order to select the OrdPs (see Step 3). Then, the *ICRole* saves the selection property for the next executions of  $t_8$ .

A<sub>5</sub>. Verify the availability of the OrdPs: in this runtime example,  $s_{10} \neq \emptyset$ , so,  $t_{11}$  decides to send  $s_{14}$  to  $t_{12}$ , also  $t_9$  decides to send  $s_{11}$  to  $t_{10}$ .

 $A_6$ . Insert a new order:  $t_{10}$  uses the Insert tool to insert a new order in the IS Orders Table (see Steps 5, 5.1, 5.2).

 $A_7$ . Create the new order lines: in parallel with  $t_9$ ,  $t_{11}$  then  $t_{12}$  will be automatically executed to produce  $s_{15}$  (see Step 4-2). Then,  $t_{14}$  will be waiting for  $s_{17}$  to be executed. In this case, the *ICRole* has to launch the execution of  $t_{13}$ .

 $A_8$ . Import the identifier of the last inserted order from the IS: the ICRole launches the execution of  $t_{13}$  (see Step 6-1). The latter receives the empty data structure  $S16\_Order\_Id$  as an input, and instead of seizing the new order identifier,  $t_{13}$  will import its value using the ImportId tool (see Step 6-2).

 $A_9$ . Wake a waiting task: at this level, the *ICRole* can turn to wake  $t_{14}$  by validating  $s_{15}$  tokens, and the engine will launch its execution (see Step 7).

 $A_{10}$ . Complete the creation of the new order lines: the engine executes  $t_{14}$  to produce  $s_{18}$  tokens (see Step 8).

 $A_{11}$ . Insert the new order lines: the engine executes  $t_{15}$  and asks the *ICRole* to choose the suitable IS table for the insertion (see Step 9-1), and to perform the matching between the data structure  $s_{18}$  and the chosen table (see Step 9-2). If these two steps are well done, the engine will properly end the workflow.

We can deduce, from the execution details, the presence of four types of actions: 9.1% of actions are based on manual tasks (i.e. tasks that are performed only by a role without the intervention of the engine, such as  $A_3$ ), 27.27% of actions are based on automatic tasks (i.e. tasks that are performed only by the engine without the intervention of a role, such as  $A_5$ ,  $A_7$  and  $A_{10}$ ), 18.18% of actions are based on semi-automatic tasks (i.e. tasks that are performed by the engine under control of a role, such as  $A_1$  and  $A_9$ ), and 45.45% of actions are based on semi-automatic tasks only in the first execution (SA-FE) (i.e. tasks that are semi-automatic tasks only in their first executions, but during their next executions, they will migrate to be automatic tasks, such as  $A_2$ ,  $A_4$ ,  $A_6$ ,  $A_8$  and  $A_{11}$ ).

id_p	e to Role?						
	name	price	stock			Structure Customer_Inf to Role2	
Dess	art Plate 15	.5	1000			id_c	
Servic	e Plate 30	.0	3000			1	
Glass	8.9	3	5000			Save Validate	
New Row	Import Data	Save	Validate				
ep 2: ICRole sel	zes the orde	red quantitie:	s relatively to the o	ordered products	Step 4-1:	CRole validates the received structure to o	execute <b>t</b>
🛎 Structure for Role2				Step 5	5: executing	t 10 which insert a new order in the IS Ta	ble Ordei
id_p	name p	price sto	ock ord_qtity	Ste	ep 5-1 : IC	Role chooses the IS table where the data v	will be ins
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4 Glass	8.9	5000	200			Insert data in table:	
	Va	didate				⊖ Bills	
Step 3: Invitin	a ICRoleto s	elze the sele	tion property for 1	8		Customers	
Step Standa	g renore to s	eize ure serev				◯ Order_Lines	
erme selection						Orders	
Attributes ord_qtity: Bet	ween 💌 🕻	J	stock			O Products	
Save the selection pr	opery	ОК	Cancel			OK Cancel	
				r -			
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γ 4-2; in paral	er with step!	>-1, u11 and 1	€12 WIII be automa	ucally		You have to make the matching between the attributes of b	oth structure
Cuted to produce	rdered Products (	o Role2	<u>र्</u> ज 🛛			S12_Customer_Id TABLE_Orders	
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2		200					0
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					(i) 1 inse	erted line(s) in Table Orders	T
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(i) T14 is 1	s available	CRole can we	ake 114 by validati	ng \$15			
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Fig. 5. Executing the ICRole sub-process

### 7 Conclusions and Future Work

According to the execution of the ICRole sub-process, manual tasks are extremely reduced. Other tasks are either purely executed by the engine, or executed by the engine under supervising of a human actor. That demonstrates the success of the modeling approach in execution issue. In fact, thanks to the detailed definition of the workflow model, *Opus* engine can interpret, automatically, the process operational functions and perform a data-driven execution based on the firing rules defined in Sect. 4. These latter ensure the consistency of data, during runtime, and grant, together with the verification method, presented in Sect. 5, the proper termination of the workflow process. However, this Framework must be completed by a module for documents generation (invoice, purchase order...): the system can manage the content but not the container.

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# Appendix A: Data Operations Definition

Operation	Formal definition
	$\forall s_j = (C_j, D_j), s_k = (C_k, D_k), C_j = (c_{j_1}, c_{j_2} \dots c_{j_{n_j}}),$
Inner Product: performs the combination	$C_k = (c_{k_1}, c_{k_2} \dots c_{k_{n_i}}), s_i = s_i \times s_k = ((c_{i_1} \dots c_{i_{n_i}}, c_{k_1} \dots c_{k_{n_i}}), D_i)$
of a data structure tuples with those of	Where: $D_i = \bigcup \{ (d_{i,1} \dots d_{i,n_i}, d_{i_{k-1}} \dots d_{i_{k-n_k}}) \}$
another data structure.	$l \in \{1 \dots n_j\}  ((j_l) = j_l \neq k_p = k_p \neq k_p)$
Noted: ×	$p \in \{1 \dots n_k\}$
	Resulted tokens number: $ D_i  =  D_j  \times  D_k $
	Whether P is the selection property, $\forall s_j = (C_j, D_j), s_i = \sigma_P s_j$
Selection: selects the tuples of a data	$\Leftrightarrow s_i = (C_j, \bigcup_{i \in D} \{e\})$
structure that meet the desired criteria.	$e \in D_j$
Noted: 0	$\frac{I(c)}{[0, D_{c}]}$
	$s_i = (C_i \ D_i) \ \forall (b_1 \ b_n) \in \{0, 1\}^n \ s_i = (C_i \ D_i) = \div (b_i \ b_i) s_i$
	Where $c_i$ is a selected (resp. not selected) attribute, if $b_i = 1$ (resp. $b_i = 0$ ).
	$\Leftrightarrow C_i = (c_{i,i}, c_{i,i}, \dots, c_{i,i}), D_i = \{(d_{i_1}, d_{i_1}, \dots, d_{i_{i-1}}), d_{i_{i-1}}\}$
Projection: selects the values of specific	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
attributes in a data structure.	$(a_{j_{2_{j_{1}}'}}, a_{j_{2_{j_{2}'}}} \dots a_{j_{2_{j_{d}'}}}) \dots (a_{j_{m_{j_{j_{1}}'}}}, a_{j_{m_{j_{j_{2}}'}}} \dots a_{j_{m_{j_{j_{d}'}}}})\}$
Noted: -	Such as: $q = \sum_{k=1}^{n} b_k$ : is the number of attributes in the structure result,
	$j'_k = \min_{l=\{1,2,,n\}} l$ : refers to the projection attributes indices.
	$\sum_{i=1}^{l} b_{i} = k$
	Resulted tokens number: $ D_i  \in [0,  D_j ]$
Substitution: changes the name of	$\forall a = (C, D) = B(a, a, a) = ((a, a, a, a, a, b, D))$
an attribute in a data structure.	$v_{sj} = (C_j, D_j), s_i = \Box(C_{j_k}, c, s_j) = ((C_{j_1} \dots C_{j_k-1}, c, C_{j_k+1} \dots C_{j_n}), D_j)$ Besulted tokens number: $ D_i  =  D_i $
Noted:	$ D_{i}  =  D_{j} $
D	$\forall s_i = (C_i, D_i), s_i = (s_i, k, l), \text{ such as: } k, l \in \{1, 2n\}, k < l,$
Permutation: allows to permute two	$C_i = \begin{pmatrix} c_i & c_i & c_i & c_i & c_i & c_i \\ c_i & c_i & c_i & c_i & c_i & c_i \end{pmatrix}$
columns in a data structure.	$D_{i} = \{(d_{1i}, \dots, d_{1i}, \dots,$
Noted:	$(d_{mi_1} \dots d_{mi_{k-1}}, d_{mi_1}, d_{mi_{k+1}} \dots d_{mi_{k-1}}, d_{mi_{k+1}} \dots d_{mi_{k-1}}, d_{mi_{k-1}}, d_{mi_{k-1}}, d_{mi_{k-1}}, d_{mi_{k-1}})\}.$
	Resulted tokens number: $ D_i  =  D_j $
Extension: Extends a structure scheme	$\forall s_j = (C_j, D_j), s_i = \neg (s_j, c, f), \text{ such as:}$
by adding an attribute $c = (n, t)$ and	$C_{i} = ((c_{j_{1}}, c_{j_{2}} \dots c_{j_{n}}, c), D_{i} = \{(d_{j_{1_{1}}}, d_{j_{1_{2}}} \dots d_{j_{1_{n}}}, f(d_{j_{1_{1}}}, d_{j_{1_{2}}} \dots d_{j_{1_{n}}}, d_$
applying a function f.	$D_j))\dots(d_{j_{m_1}}, d_{j_{m_2}}\dots d_{j_{m_n}}, f(d_{j_{m_1}}, d_{j_{m_2}}\dots d_{j_{m_n}}, D_j))\})$
Noted: -	Resulted tokens number: $ D_i  =  D_j $
	$\forall s_j = (C_j, D_j), \ s_k = (C_k, D_k),$
	$D_{j} = \{(a_{j_{1_{1}}}, a_{j_{1_{2}}} \dots a_{j_{1_{n}}}), (a_{j_{2_{1}}}, a_{j_{2_{2}}} \dots a_{j_{2_{n}}}) \dots (a_{j_{m_{1}}}, a_{j_{m_{2}}} \dots a_{j_{m_{n}}})\}$
	$D_k = \{(a_{k11}, a_{k12} \dots a_{k1_h}), (a_{k21}, a_{k22} \dots a_{k2_h}) \dots (a_{kl_1}, a_{k22} \dots a_{kl_h})\},$
	$b_1, b_2, \dots, b_h \in \{1, 2, \dots, n\}$ . refers to the positions of the added values in the resulting data structure $s_i = \pm (s_i, (b_1, b_2, \dots, b_i))$
	if $h < n$ then: $s_i = ((c_1, c_2 \dots c_n), \{(d_{i_1}, d_{i_1} \dots d_{i_n}), (d_{i_2}, d_{i_2} \dots d_{i_n})\}$
Add_Tuples: inserts the tuples of a data	$(d_{i_1}, d_{i_2}, \dots, d_{i_m}), (d_{k_1}, d_{k_2}, \dots, d_{k_n}), (d_{k_n}, d_{k_1}, \dots, d_{k_n}),$
Noted: +	$(J_{m_1}, J_{m_2}, J_{m_n}, (h_{b_1}, h_{b_2}, h_{b_h}, h_{a_1}, J_{a_1}))$
Totolar	$(a_{k_{2_{b_{1}}}}, a_{k_{2_{b_{2}}}} \dots a_{k_{2_{b_{h}}}} \dots a_{k_{2_{n}}}) \dots (a_{k_{l_{b_{1}}}}, a_{k_{l_{b_{2}}}} \dots a_{k_{l_{b_{h}}}}))$
	if $h = n$ then: $s_j = ((c_1, c_2 \dots c_n), \{(d_{j_{1_1}}, d_{j_{1_2}} \dots d_{j_{1_n}}), (d_{j_{2_1}}, d_{j_{2_2}} \dots d_{j_{2_n}})$
	$\dots (d_{j_{m_1}}, d_{j_{m_2}} \dots d_{j_{m_n}}), (d_{k_{1_{b_1}}}, d_{k_{1_{b_2}}} \dots d_{k_{1_n}}),$
	$(d_{k_{2_{1}}}, d_{k_{2_{1}}}, \dots, d_{k_{2_{n}}}) \dots (d_{k_{l_{1}}}, d_{k_{l_{1}}}, \dots, d_{k_{l_{n}}})))$
	Resulted tokens number: $ D_i  =  D_i  +  D_k $
Control 1: Decides to continue or not	Condition 1: if $s_i$ is the data structure expected by the next task,
the information flow routing, according to	and $s_i$ is the controlled data structure, then: $s_i = s_{i_i} + s_j = \begin{cases} s_k & \text{if } s_j = \emptyset \end{cases}$
condition1. Noted: ±	$[\square i j = i ] [\square i ] [$
	Resulted tokens number: $[D_i] \in [0, [D_k]]$
Control 2: Decides to continue or not	Condition 2. If $s_i$ is the data structure expected by the next task, $\left(s_i, if s_i \pm \alpha\right)$
the information flow routing, according to	and $s_j$ is the controlled data structure, then: $s_i = s_k \mp s_j = \begin{cases} s_k & j & s_j \neq \wp \\ \emptyset & otherwise \end{cases}$ ,
condition 2. Noted: Ŧ	Resulted tokens number: $ D_i  \in [0,  D_k ]$