Independent Domination: Reductions from Circular- and Triad-Convex Bipartite Graphs to Convex Bipartite Graphs^{*}

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Abstract. An independent dominating set in a graph is a subset of vertices, such that no edge has both ends in the subset, and each vertex either itself is in the subset or has a neighbor in the subset. In a convex bipartite (circular convex bipartite, triad convex bipartite, respectively) graph, there is a linear ordering (a circular ordering, a triad, respectively) defined on one class of vertices, such that for every vertex in the other class, the neighborhood of this vertex is an interval (a circular arc, a subtree, respectively), where a triad is three paths with a common end. The problem of finding a minimum independent dominating set, called independent domination, is known \mathcal{NP} -complete for bipartite graphs and tractable for convex bipartite graphs. In this paper, we make polynomial time reductions for independent domination from triad- and circular convex bipartite graphs to convex bipartite graphs.

Keywords: Independent domination, circular convex bipartite graph, triad convex bipartite graph, polynomial time reduction.

1 Introduction

An independent dominating set in a graph is a subset of vertices, such that the subset is an independent set, and every vertex in the graph either itself is in the subset or has a neighbor in the subset. The problem of finding a minimum independent dominating set, called *independent domination*, is \mathcal{NP} -complete for *chordal bipartite* graphs, but polynomial time solvable for *convex bipartite* graphs [3]. In a *convex bipartite* graph [7,3,2], there is a linear ordering defined on one class of vertices, such that for every vertex in another class, the neighborhood of this vertex is an interval. In a *chordal bipartite* graph [6], every cycle of length at least *six* has a chord, where a *chord* of a cycle on a graph is an edge between two vertices of the cycle but the edge itself is not a part of the cycle.

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Beside convex bipartite graphs and chordal bipartite graphs, there are other interesting bipartite graph classes, such as *circular convex bipartite* graphs [11] and *triad convex bipartite* [10,9] graphs, etc, see Figure 1.



Fig. 1. Various bipartite graph classes and their inclusions

In a *circular convex bipartite* graph [11], there is a circular ordering defined on one class of vertices, such that for every vertex in another class, the neighborhood of this vertex is a circular arc. Circular convex bipartite graphs are natural models for scheduling problems. For example, the available working hours of a worker is usually a consecutive period of hours. A group of workers and their available hours can be modeled by a circular convex bipartite graphs [11]. For a long time, complexity results for circular convex bipartite graphs are scarce. Maximum matching and Hamiltonian cycle and path are known linear time solvable for circular-convex bipartite graphs [11]. The complexity of independent domination for circular-convex bipartite graphs is unknown before. In this paper, we show that independent domination is *polynomial time* solvable for *circular convex bipartite* graphs.

In a tree convex bipartite graph [8,9], there is a tree defined on one class of vertices, such that for every vertex in another class, the neighborhood of this vertex is a subtree. When the tree is a star (a triad, respectively), the graph is called *star convex bipartite* [8,9] (*triad convex bipartite* [10,9], respectively), where a *triad* is three pathes with a common end. It is known that independent domination is \mathcal{NP} -complete for star convex bipartite graphs, but tractable for triad convex bipartite graphs in [14]. In this paper, we simplify the tractability proof in [14].

Our main contributions are making two explicit reductions for independent domination from circular- and triad-convex bipartite graphs respectively to convex bipartite graphs, instead of running modified algorithms such as in [14]. In fact, the second reduction can be viewed as a detailed proof for the correctness of the algorithm in [14], easier to understand with a better modularity. Moreover, our reductions are Cook reductions (i.e. polynomial time Turing reductions) [5], which call the known polynomial time algorithms of independent domination for convex bipartite graphs [3] many times, and also work for *weighted* circular- and triad-convex bipartite graphs, though the original algorithm in [3] only works for unweighted bipartite graphs. Before our works, only Karp reduction (i.e. polynomial many-one reduction) [5] from circular convex bipartite graphs to circular-arc graphs is used [11]. Thus, our methods may be of use to show more problems tractable for circular- and triad-convex bipartite graphs.

This paper is structured as follows. After introducing necessary definitions and notations mainly from graph theory (Section 2), polynomial time reductions for independent domination from circular-convex bipartite graphs (Section 3) and triad-convex bipartite graphs (Section 4) to convex bipartite graphs are shown respectively. Concluding remarks are at the last section (Section 5).

2 Preliminaries

A graph G = (V, E) consists of a vertex set V and an edge set E. Each edge e in E is *incident* to two vertices, called its ends, and these two ends are called *adjacent* to each other. For each vertex v, its *neighborhood* $N(v) = \{u|v \text{ is adjacent to } u\}$, its *closed neighborhood* $N[v] = N(v) \cup \{v\}$. For a subset V' of vertices, $N(V') = \bigcup_{v \in V'} N(v)$. A path in a graph is a sequence of different vertices $v_{i_1}, v_{i_2}, \ldots, v_{i_k}$, such that each two consecutive vertices are adjacent to each other. A cycle is a path where v_{i_1} and v_{i_k} are also adjacent to each other. A graph is *connected* if every two vertices are connected by a path. A tree is a connected graph without any cycle. For a subset V' of vertices, the *induced subgraph* G[V'] = (V', E'), where $V' \subseteq V$ and $E' = \{e \in E | e$ has both ends in $V'\}$. An *independent set* is a subset of vertices whose induced subgraph has no edge.

In a weighted graph G = (V, E, w), there is a function w defined on V, such that each vertex v has a weight w(v). The weight of a vertex subset V' is $w(V') = \sum_{v \in V'} w(v)$. When w(v) = 1 for all vertices v, the graph is called *unweighted*. In a *finite* graph, both V and E are finite sets. A *simple* graph has no loop and no parallel edges, where a loop has the same one vertex as its ends, and two parallel edges are incident to the same two ends. In a *bipartite* graph, denoted by G = (A, B, E), the vertex set V is divided into two classes A and B, such that each edge is incident to a vertex in A and a vertex in B respectively. In this paper, we only consider finite simple bipartite graphs.

The cardinality of a set X, i.e. the number of elements in X, is denoted by |X|. The difference of two sets X and Y is denoted by $X \setminus Y = \{x \mid x \in X \text{ and } x \notin Y\}$. The empty set is denoted by \emptyset . An arbitrary ordering on a set is denoted by \prec .

Definition 1. (Independent Dominating Set) In a graph G = (V, E), an independent dominating set D is a subset of V, such that D is an independent set, and for each vertex v in V, either $v \in D$ or $N(v) \cap D \neq \emptyset$.

Definition 2. (Triad) $A \ G = (V, E)$ is called a triad, if the vertex set V can be partitioned into four parts, $V_1, V_2, V_3, \{v_0\}$, such that for $i = 1, 2, 3, V_i \cup \{v_0\}$ induces a path. The vertex v_0 is called center.

Definition 3. (Circular Convex Bipartite Graphs [11]) A bipartite graph G = (A, B, E) is called circular convex bipartite, if there is a circular ordering \prec

defined on $A = \{a_1, \ldots, a_n\}$, $a_1 \prec a_2 \prec \cdots \prec a_n \prec a_1$, such that for each vertex b in B, its neighborhood N(b) is a circular arc under this circular ordering, that is, there are two (possibly equal) vertices a_i and a_j , where $1 \leq i \leq j \leq n$, such that $N(b) = \{a_i, a_{i+1}, \ldots, a_j\}$ or $N(b) = \{a_j, a_{j+1}, \ldots, a_n, a_1, \ldots, a_i\}$.

Definition 4. (Triad Convex Bipartite Graphs [8,9]) A bipartite graph G = (A, B, E) is called triad convex bipartite, if these is a triad T = (A, F) defined on A, such that for each vertex b in B, its neighborhood N(b) is a subtree of T.

Remark 1. The adjacent matrices of circular convex (convex, respectively) bipartite graphs have the so-called *circular* (*consecutive*, respectively) *ones property*, which are recognizable in *linear* time [4]. Tree convex bipartite graphs are also recognizable in *linear* time [1]. The associated circular orderings (trees, respectively) are all constructible in *linear* time, thus can safely be assumed as part of the inputs. Chordal bipartite graphs are recognizable in *square* time.

We refer to [5] for the notions of *polynomial time*, *reductions*, and \mathcal{NP} -completeness.

3 Reduction from Circular-Convex Bipartite Graphs

In this section, we show that independent domination is polynomial time solvable for circular-convex bipartite graphs, by a polynomial time reduction for this problem from circular-convex bipartite graphs to convex bipartite graphs.

Theorem 1. For circular convex bipartite graphs G = (A, B, E) with a circular ordering on A, independent domination is $O(|A|(|A| + |B|)^3)$ time solvable.

Proof. Without loss of generality, we assume that G contains no isolated vertex, since isolated vertices are trivially in every independent dominating set.



Fig. 2. Removing vertices in N[a] from graph G results in graph G_a

First, for each vertex a in A, we define a graph G_a as follows, see Figure 2.

$$G_a = (A_a, B_a, E_a)$$
, where $A_a = A \setminus \{a\}, B_a = B \setminus N(a)$, and $E_a = \{e \in E \mid e \text{ is not incident to any vertex in } N[a]\}.$

Lemma 1. For each $a \in A$, G_a is convex bipartite.

Proof. We prove by definition of convex bipartite graphs. After removing $\{a\} \cup N(a)$ and the incident edges from G, no vertex in $B_a = B \setminus N(a)$ is adjacent to vertex a. Since G is circular convex bipartite, for each vertex in B_a , its neighborhood is a circular arc contained in $A_a = A \setminus \{a\}$. Thus, we can restrict the circular ordering on A to a linear ordering on A_a , such that for each vertex in B_a , its neighborhood is an interval under this linear ordering.

Lemma 2. For each $a \in A$, if D is an independent dominating set of G containing a, then $D \setminus \{a\}$ is an independent dominating set of G_a .

Proof. We prove by definition of independent dominating sets. Since $a \in D$, $N(a) \cap D = \emptyset$. For each vertex $a' \in A_a$, either $a' \in D$ or $N(a') \cap D \neq \emptyset$. Since $a \notin N[a']$, either $a' \in D \setminus \{a\}$ or $N(a') \cap (D \setminus \{a\}) \neq \emptyset$. For each vertex $b' \in B_a$, either $b' \in D$ or $N(b') \cap D \neq \emptyset$. Since $a \notin N[b']$, either $b' \in D \setminus \{a\}$ or $N(b') \cap (D \setminus \{a\}) \neq \emptyset$.

Lemma 3. For each $a \in A$, if D' is an independent dominating set of G_a , then $D' \cup \{a\}$ is an independent dominating set of G.

Proof. We prove again by definition. Since G_a is resulted by removing N[a] from G, a is not adjacent to any vertex in G', $D' \cup \{a\}$ is an independent set. Since D' is an independent dominating set of G_a and each vertex in N(a) is adjacent to $a, D' \cup \{a\}$ is an independent dominating set of G.

Next, we define a set S as follows.

 $\mathcal{S} = \{B\} \cup \{D_a \cup \{a\} \mid a \in A \text{ and } D_a \text{ is a minimum independent} \\ \text{dominating set in } G_a\}.$

Remark 2. For each a, G_a is unique, but for each G_a , D_a may not be unique. For our purpose, however, for each a, we only need one such D_a in S, see proof of Lemma 5 below.

Lemma 4. S contains a minimum independent dominating set of G.

Proof. Let D be a minimum independent dominating set of G. We consider the following two cases.

Case 1: $D \cap A = \emptyset$.

Since D is an independent dominating set, for each vertex b in B, either $b \in D$ or $N(b) \cap D \neq \emptyset$. Since $D \cap A = \emptyset$, G is bipartite and $N(b) \subseteq A$, we have $N(b) \cap D = \emptyset$ and thus $b \in D$. So in Case 1 we have D = B and thus $D \in S$.

Case 2: $D \cap A \neq \emptyset$.

Assume that $a \in D \cap A$. For any minimum independent dominating set D_a of G_a , by Lemma 2, $|D_a| \leq |D| - 1$, and by Lemma 3, $|D| \leq |D_a| + 1$, thus $|D| = |D_a| + 1 = |D_a \cup \{a\}|$. By Lemma 3 and the minimality of D in G, $D_a \cup \{a\}$ is a *minimum* independent dominating set of G.

Lemma 5. S is computable in $O(|A|(|A|+|B|)^3)$ time.

Proof. By Lemmm 1, for each $a \in A$, G_a is convex bipartite, thus we can compute a minimum independent dominating set D_a of G_a by the known $O\left((|A| + |B|)^3\right)$ time algorithm in [3]. As remarked in Remark 2, for each a, we only need one such D_a in S. Thus, by an *enumeration* of all |A| vertices a in A, we can compute S in $O\left(|A|(|A| + |B|)^3\right)$ time. \Box

Finally, by Lemmas 4 and 5, we can find a minimum independent dominating set of G in $O(|A|(|A| + |B|)^3)$ time.

This finishes the proof of Theorem 1.

Remark 3. The above reduction also works for weighted independent domination. The only change is in replacing $|D| = |D_a| + 1$ by $w(D) = w(D_a) + w(a)$ in proof of Lemma 4. However, the known polynomial time algorithm in [3] only works for *unweighted* independent domination.

4 Reduction from Triad-Convex Bipartite Graphs

In this section, we show that independent domination is polynomial time solvable for triad-convex bipartite graphs, by a polynomial time reduction for this problem from triad-convex bipartite graphs to convex bipartite graphs. Due to space limitation, we omit some details in this section.

Theorem 2. For triad convex bipartite graphs G = (A, B, E) with a triad T defined on A, independent domination is $O(|A|^3(|A| + |B|)^3)$ time solvable.

Proof. Without loss of generality, we assume that G contains no isolated vertex, since isolated vertices are trivially in every independent dominating set.

We assume that A is divided into four parts, $A_1, A_2, A_3, \{a_0\}$, such that for $i = 1, 2, 3, A_i \cup \{a_0\}$ induces a path of T. To be specific, we assume that $A_i = \{a_{i,1}, a_{i,2}, \ldots, a_{i,n_i}\}$, where $\sum_{i=1}^{3} n_i = |A| - 1$ and $a_0 a_{i,1} a_{i,2} \cdots a_{i,n_i}$ are three paths of T with a common end a_0 .



Fig. 3. Removing vertices in $N[a_0]$ from graph G results in three graphs G_1, G_2, G_3



Fig. 4. Removing vertices in $\bigcup_{i=1}^{3} (\{a_i\} \cup N(a_i))$ from graph G results in four graphs $G_{a_1}, G_{a_2}, G_{a_3}$ and $G_{(a_1, a_2, a_3)}$

First, we define three graphs G_1, G_2, G_3 as follows, see Figure 3.

$$G_i = (A_i, N(A_i) \setminus N(a_0), E_i), \text{ for } i = 1, 2, 3, \text{ where}$$
$$E_i = \{e \in E \mid e \text{ is incident to a vertex in } A_i \text{ but not incident to a vertex in } N(a_0)\},$$

For i = 1, 2, 3, for each vertex $a_i = a_{i,j_i}$ in A_i , we define four graphs $G_{a_1}, G_{a_2}, G_{a_3}, G_{(a_1,a_2,a_3)}$ as follows, see Figure 4.

$$G_{a_i} = (A_{a_i}, B_{a_i}, E_{a_i}), \text{ where}$$

$$A_{a_i} = \{a_{i,j_i+1}, \dots, a_{i,n_i}\}, B_{a_i} = N(A_{a_i}) \setminus N(a_i),$$

$$E_{a_i} = \{e \in E \mid e \text{ is incident to a vertex in } B_{a_i}\}, \text{ and}$$

$$\begin{aligned} G_{(a_1,a_2,a_3)} &= (A_{(a_1,a_2,a_3)}, B_{(a_1,a_2,a_3)}, E_{(a_1,a_2,a_3)}), \text{ where} \\ A_{(a_1,a_2,a_3)} &= A \setminus \bigcup_{i=1}^3 (A_{a_i} \cup \{a_i\}), B_{(a_1,a_2,a_3)} = B \setminus \bigcup_{i=1}^3 (B_{a_i} \cup \{N(a_i)\}), \text{ and} \\ E_{(a_1,a_2,a_3)} &= \{e \in E \mid e \text{ is incident to a vertex in } B_{(a_1,a_2,a_3)}\}. \end{aligned}$$

We define graphs $G_{(a_1,a_2,*)}$ as follows, $G_{(*,a_2,a_3)}, G_{(a_1,*,a_3)}$ are similar.

$$G_{(a_1,a_2,*)} = (A_{(a_1,a_2,*)}, B_{(a_1,a_2,*)}, E_{(a_1,a_2,*)}),$$
 where

$$A_{(a_1,a_2,*)} = A \setminus \bigcup_{i \in \{1,2\}} (A_{a_i} \cup \{a_i\}), B_{(a_1,a_2,*)} = B \setminus \left(N(a_i) \bigcup_{i \in \{1,2\}} B_{a_i} \right), \text{ and}$$

 $E_{(a_1,a_2,*)} = \{ e \in E \mid e \text{ is incident to a vertex in } A_{(a_1,a_2,*)} \\ \text{and a vertex in } B_{(a_1,a_2,*)} \}.$

We define graphs $G_{(a_1,*,*)}$ as follows, $G_{(*,a_2,*)}, G_{(*,*,a_3)}$ are similar.

$$G_{(a_1,*,*)} = (A_{(a_1,*,*)}, B_{(a_1,*,*)}, E_{(a_1,*,*)}),$$
 where

$$\begin{aligned} A_{(a_1,*,*)} &= A \setminus (A_{a_1} \cup \{a_1\}), B_{(a_1,*,*)} = B \setminus (N(a_1) \cap B_{a_1}), \text{ and} \\ E_{(a_1,*,*)} &= \{e \in E \mid e \text{ is incident to a vertex in } A_{(a_1,*,*)} \\ &\text{ and a vertex in } B_{(a_1,*,*)}\}. \end{aligned}$$

Definition 5. For i = 1, 2, 3 and for each $a_i \in A_i$, a triple (a_1, a_2, a_3) is called good, if $B_{(a_1, a_2, a_3)}$ is an independent dominating set of $G_{(a_1, a_2, a_3)}$. Similarly for $(a_1, a_2, *)$, $(a_1, *, a_3)$, $(*, a_2, a_3)$, $(a_1, *, *)$, $(*, a_2, *)$, $(*, *, a_3)$.

Remark 4. A triple (a_1, a_2, a_3) is good, if and only if there is an independent dominating set D of G, such that D contains $\{a_1, a_2, a_3\}$ and a_i is the first vertex of D on the path $a_0a_{i,1}\cdots a_{i,n_i}$ of the triad T for i = 1, 2, 3. Similarly for $(a_1, a_2, *)$, $(a_1, *, a_3)$, $(*, a_2, a_3)$, $(a_1, *, *)$, $(*, a_2, *)$, $(*, *, a_3)$. A star * on the *i*-th place of a triple means that no vertex in $\{a_0\} \cup A_i$ is in D for i = 1, 2, 3.

Lemma 6. For i = 1, 2, 3 and for each $a_i \in A_i$, G_i and G_{a_i} are convex bipartite.

Proof. We prove by definition of convex bipartite graphs for G_{a_i} , the proof for G_i is similar and thus omitted. After removing $N(a_i)$ and the incident edges from G, no vertex in $B_{a_i} = N(A_{a_i}) \setminus N(a_i)$ is adjacent to vertex a_i . Since G is triad convex bipartite, for each vertex in B_{a_i} , its neighborhood is a path of T on $A_{a_i} = \{a_{i,j_i+1}, \ldots, a_{i,j_n}\}$. Thus, we can define a linear ordering \prec_i on A_{a_i} , $a_{i,j_i+1} \prec_i \cdots \prec_i a_{i,j_n}$, such that for each vertex in B_{a_i} , its neighborhood is an interval under this linear ordering \prec_i .

Lemma 7. For each triple (a_1, a_2, a_3) , if D is an independent dominating set of G containing a_i for i = 1, 2, 3, then $D \cap (A_{a_i} \cup B_{a_i})$ is an independent dominating set of G_{a_i} for i = 1, 2, 3. Similarly for $(a_1, a_2, *)$, $(a_1, *, a_3)$, $(*, a_2, a_3)$, $(a_1, *, *)$, $(*, a_2, *)$, $(*, *, a_3)$.

Proof. We prove by definition of independent dominating sets. Since $a_i \in D$, $N(a_i) \cap D = \emptyset$. For each vertex $a' \in A_{a_i}$, either $a' \in D$ or $N(a') \cap D \neq \emptyset$. Since $a_i \notin \{a'\} \cup N(a')$, either $a' \in D \cap A_{a_i}$ or $N(a') \cap (D \cap B_{a_i}) \neq \emptyset$. For each vertex $b' \in B_{a_i}$, either $b' \in D$ or $N(b') \cap D \neq \emptyset$. Since $a_i \notin \{b'\} \cup N(b')$, either $b' \in D \cap B_{a_i}$ or $N(b') \cap (D \cap A_{a_i}) \neq \emptyset$. Similarly for $(a_1, a_2, *), (a_1, *, a_3), (*, a_2, a_3), (a_1, *, *), (*, a_2, *), (*, *, a_3).$

Lemma 8. For each good triple (a_1, a_2, a_3) , if D_{a_i} is an independent dominating set of G_{a_i} for i = 1, 2, 3, then $B_{(a_1, a_2, a_3)} \cup \bigcup_{i=1}^3 (D_{a_i} \cup \{a_i\})$ is an independent dominating set of G. Similarly for $(a_1, a_2, *)$, $(a_1, *, a_3)$, $(*, a_2, a_3)$, $(a_1, *, *)$, $(*, a_2, *)$, $(*, *, a_3)$.

Proof. We prove by definition. Since for $i = 1, 2, 3, G_{a_i}$ is resulted by removing $\{a_i\} \cup N(a_i)$ from G, a_i is not adjacent to any vertex in G_{a_i} and $G_{(a_1,a_2,a_3)}$, $B_{(a_1,a_2,a_3)} \cup \bigcup_{i=1}^3 (D_{a_i} \cup \{a_i\})$ is an independent set. Since the triple (a_1, a_2, a_3) is good, B_{a_1,a_2,a_3} is an independent dominating set of $G_{(a_1,a_2,a_3)}$. Since D_{a_i} is an independent dominating set of $G_{(a_1,a_2,a_3)}$. Since D_{a_i} is an independent dominating set of $G_{(a_1,a_2,a_3)}$. Since D_{a_i} is an independent dominating set of $G_{(a_1,a_2,a_3)} \cup \bigcup_{i=1}^3 (D_{a_i} \cup \{a_i\})$ is an independent dominating set of G. Similarly for $(a_1, a_2, *), (a_1, *, a_3), (*, a_2, a_3), (a_1, *, *), (*, a_2, *), (*, *, a_3)$.

Next, we define a set $S = \{B, \{a_0\} \cup D_1 \cup D_2 \cup D_3\} \cup S_1 \cup S_2 \cup S_3$ as follows.

$$\begin{split} \mathcal{S}_{1} &= \{B_{(a_{1},*,*)} \cup D_{a_{1}} \cup \{a_{1}\}, B_{(*,a_{2},*)} \cup D_{a_{2}} \cup \{a_{2}\}, B_{(*,*,a_{3})} \cup D_{a_{3}} \cup \{a_{3}\} \mid \\ &a_{i} \in A_{i} \text{ and } D_{a_{i}} \text{ is a minimum independent dominating set in } G_{a_{i}} \\ &\text{for } i = 1, 2, 3\}, \\ \mathcal{S}_{2} &= \{B_{(a_{1},a_{2},*)} \cup \bigcup_{i \in \{1,2\}} (D_{a_{i}} \cup \{a_{i}\}), B_{(*,a_{2},a_{3})} \cup \bigcup_{i \in \{2,3\}} (D_{a_{i}} \cup \{a_{i}\}), \\ &B_{(a_{1},*,a_{3})} \cup \bigcup_{i \in \{1,3\}} (D_{a_{i}} \cup \{a_{i}\}) \mid a_{i} \in A_{i} \text{ and } D_{a_{i}} \text{ is a minimum} \\ &\text{independent dominating set in } G_{a_{i}} \text{ for } i = 1, 2, 3\}, \end{split}$$

$$\mathcal{S}_3 = \{ B_{(a_1, a_2, a_3)} \cup \bigcup_{i \in \{1, 2, 3\}} (D_{a_i} \cup \{a_i\}) \mid (a_1, a_2, a_3) \text{ is good and } D_{a_i} \text{ is a} \}$$

minimum independent dominating set in G_{a_i} for i = 1, 2, 3,

where for i = 1, 2, 3, D_i is a minimum dominating set of G_i and G_i is resulted by removing $N[a_0]$ from G.

Remark 5. For each triple (a_1, a_2, a_3) , G_{a_i} is unique, but for each G_{a_i} , D_{a_i} may not be unique. For our purpose, however, for each (a_1, a_2, a_3) , we only need one triple $(D_{a_1}, D_{a_2}, D_{a_3})$ in S, see proof of Lemma 10 below. Similarly for $(a_1, a_2, *)$, $(a_1, *, a_3)$, $(*, a_2, a_3)$, $(a_1, *, *)$, $(*, a_2, *)$, $(*, *, a_3)$.

Lemma 9. S contains a minimum independent dominating set of G.

Proof. Let D be a minimum independent dominating set of G. We consider the following *five* cases.

Case 1: $D \cap A = \emptyset$. In this case we have D = B, which is in \mathcal{S} .

Case 2: $a_0 \in D$. In this case, similar to the reasoning process in Case 5 below, we have $|D| = |\{a_0\} \cup \bigcup_{i \in \{1,2,3\}} D_i|$, thus $\{a_0\} \cup \bigcup_{i \in \{1,2,3\}} D_i$ is a minimum independent dominating set of G, which is in S.

Case 3: $D \cap A_i \neq \emptyset$ for some $i \in \{1, 2, 3\}$ but $D \cap (\{a_0\} \cup A_j) = \emptyset$ for $j \neq i$. In this case, similar to Case 5 below, a minimum dominating set of G is in S_1 .

Case 4: $D \cap (\{a_0\} \cup A_i) = \emptyset$ for some $i \in \{1, 2, 3\}$ but $D \cap A_j \neq \emptyset$ for $j \neq i$. In this case, similar to Case 5 below, a minimum dominating set of G is in S_2 .

Case 5: $D \cap A_i \neq \emptyset$ for i = 1, 2, 3. Assume that $a_i \in D \cap A_i$ for i = 1, 2, 3and the triple (a_1, a_2, a_3) is good. For any minimum independent dominating sets D_{a_i} of G_{a_i} for i = 1, 2, 3, by Lemma 7, $\sum_{i=1}^3 |D_{a_i}| \leq |D| - |B_{(a_1, a_2, a_3)}| - 3$, and by Lemma 8, $|D| \leq \sum_{i=1}^3 |D_{a_i}| + |B_{(a_1, a_2, a_3)}| + 3$, thus $|D| = \sum_{i=1}^3 |D_{a_i}| + |B_{(a_1, a_2, a_3)}| + 3 = |B_{(a_1, a_2, a_3)} \cup \bigcup_{i=1}^3 (D_{a_i} \cup \{a_i\})|$. By Lemma 8 and the minimality of D in G, $B_{(a_1, a_2, a_3)} \cup \bigcup_{i \in \{1, 2, 3\}} (D_{a_i} \cup \{a_i\})$ is a minimum independent dominating set of G, which is in S_3 .

Lemma 10. S is computable in $O(|A|^3(|A|+|B|)^3)$ time.

Proof. By Lemmm 6, for i = 1, 2, 3 and for each $a_i \in A_i$, G_{a_i} is convex bipartite, thus we can compute a minimum independent dominating set D_{a_i} of G_{a_i} by the

known $O\left((|A|+|B|)^3\right)$ time algorithm in [3]. As remarked in Remark 5, for each good triple (a_1, a_2, a_3) , we only need one such triple $(D_{a_1}, D_{a_2}, D_{a_3})$ in \mathcal{S} . Thus, by an *enumeration* of all $|A_1||A_2||A_3|$ triples (a_1, a_2, a_3) , we can compute \mathcal{S}_3 in $O\left(|A|^3(|A|+|B|)^3\right)$ time. Similarly for \mathcal{S}_1 and \mathcal{S}_2 .

Finally, by Lemmas 9 and 10, we can find a minimum independent dominating set of G in $O(|A|^3(|A| + |B|)^3)$ time.

This finishes the proof of Theorem 2.

Remark 6. The above reduction also works for weighted independent domination. The only changes are in replacing $|D| = \sum_{i=1}^{3} |D_{a_i}| + |B_{(a_1,a_2,a_3)}| + 3$ by $w(D) = \sum_{i=1}^{3} (w(D_{a_i}) + w(a_i)) + w(B_{(a_1,a_2,a_3)})$ and so on in proof of Lemma 9.

5 Concluding Remarks

We have shown that independent domination is polynomial time reducible from circular- and triad-convex bipartite graphs to convex bipartite graphs. As in [12], we make Cook reductions from circular convex bipartite graphs to convex bipartite graphs. Our methods may be of use to show more problems tractable for circular- and triad-convex bipartite graphs. It would be interesting to find real applications of these results.

Recently, maximum non-crossing matching for convex bipartite graphs is studied [2]. Whether the results in [2] carry over for circular- and triad-convex bipartite graphs is still unknown.

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