

On the Strong Convergence of the Orthogonal Series-Type Kernel Regression Neural Networks in a Non-stationary Environment

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Abstract. Strong convergence of general regression neural networks is proved assuming non-stationary noise. The network is based on the orthogonal series-type kernel. Simulation results are discussed in details.

1 Introduction

In this paper we consider the following model

$$Y_i = \phi(X_i) + Z_i, \quad i = 1, \dots, n, \quad (1)$$

where X_1, \dots, X_n are independent random variables with a probability density $f(\cdot)$, Z_i are random variables such that

$$E(Z_i) = 0, \quad EZ_i^2 = d_i, \quad i = 1, \dots, n, \quad (2)$$

and $\phi(\cdot)$ is an unknown function. We assume that function $f(\cdot)$ has the representation

$$f(x) \sim \sum_{j=0}^{\infty} a_j g_j(x), \quad (3)$$

where

$$a_j = \int_A f(x) g_j(x) dx = E g_j(X_i). \quad (4)$$

and $\{g_j(\cdot)\}$, $j = 0, 1, 2, \dots$ is a complete orthonormal series (see e.g. [1]) defined on $A \subset R^p$. Then the estimator of density $f(x)$ takes the form

$$\hat{f}_n(x) = \sum_{j=0}^{N(n)} \hat{a}_j g_j(x), \quad (5)$$

where $N(n) \xrightarrow{n} \infty$ and

$$\hat{a}_j = \frac{1}{n} \sum_{k=0}^n g_j(X_k) \quad (6)$$

Let us define

$$\hat{R}(x) = f(x)\phi(x). \tag{7}$$

We assume that function $R(\cdot)$ has the representation

$$R(x) \sim \sum_{j=0}^{\infty} b_j g_j(x), \tag{8}$$

where

$$b_j = \int_A \phi(x) f(x) g_j(x) dx = E(Y_k g_j(X_k)) \tag{9}$$

We estimate function $R(\cdot)$ using

$$\hat{R}_n(x) = \sum_{j=0}^{M(n)} \hat{b}_j g_j(x), \tag{10}$$

where $M(n) \xrightarrow{n} \infty$ and

$$\hat{b}_j = \frac{1}{n} \sum_{k=0}^n Y_k g_j(X_k). \tag{11}$$

Then the estimator of the regression function is of the following form

$$\hat{\phi}_n(x) = \frac{\hat{R}_n(x)}{\hat{f}_n(x)} = \frac{\sum_{i=1}^n \sum_{j=0}^{M(n)} Y_i g_j(X_i) g_j(x)}{\sum_{i=1}^n \sum_{j=0}^{N(n)} g_j(X_i) g_j(x)} \tag{12}$$

This algorithm creates a so-called general regression neural network [37]. Figure 1 shows block diagram for $M(n) = N(n)$. There are many papers in literature

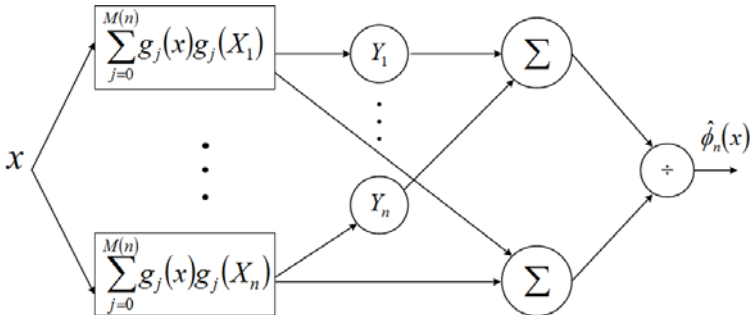


Fig. 1. Regression neural network

where nonparametric regression estimates were studied in a stationary environment e.g. [4], [5],[7], [11], [13] - [17], [23] - [25], [28] - [31] and in a non-stationary environment e.g. [6], [18] -[22], [26], [27]. For excellent overviews on these techniques the reader is referred to [8] and [9].

2 Main Result

Let us assume that

$$\max_x |g_j| < G_j. \tag{13}$$

Theorem 1. *Let us denote:*

$$s_i = d_i + \int_A \phi^2(u)f(u)du. < \infty \tag{14}$$

If the following conditions hold

$$\sum_{n=1}^{\infty} \frac{s_n}{n^2} \left(\sum_{j=0}^{M(n)} G_j^2 \right)^2 < \infty, \quad M(n) \xrightarrow{n} \infty \tag{15}$$

$$\sum_{n=1}^{\infty} \frac{1}{n^2} \left(\sum_{j=0}^{N(n)} G_j^2 \right)^2 < \infty, \quad N(n) \xrightarrow{n} \infty \tag{16}$$

then

$$\hat{\phi}_n(x) \xrightarrow{n} \phi(x) \quad \text{with probability 1,} \tag{17}$$

at every point $x \in A$ at which series (3) and (8) converge to $f(x)$ and $R(x)$ respectively.

Proof. It is sufficient to show that:

$$\hat{R}_n(x) - E[\hat{R}_n(x)] \xrightarrow{n} 0 \tag{18}$$

$$\hat{f}_n(x) - E[\hat{f}_n(x)] \xrightarrow{n} 0, \tag{19}$$

with probability one, at every point $x \in A$, at which series (3) and (8) are convergent to $f(x)$ and $R(x)$ respectively. Denote

$$T_i = \sum_{j=0}^{M(i)} (g_j(X_i)Y_i - b_j)g_j(x) \tag{20}$$

Observe that

$$\hat{R}_n(x) - E\hat{R}_n(x) = \frac{1}{n} \sum_{i=1}^n T_i \tag{21}$$

Using Cauchy's inequality:

$$ET_n^2 \leq \left(\int_A \phi^2(u) f(u) du + d_n \right) \left(\sum_{j=0}^{M(n)} G_j^2 \right)^2 \quad (22)$$

Applying Kolmogorov's strong law we obtain

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n (T_i - ET_i) = 0 \quad (23)$$

with probability one.

Similarly, for $T_i = \sum_{j=0}^{N(n)} (g_j(X_i) - a_j) g_j(x)$

$$\hat{f}_n(x) - E\hat{f}_n(x) = \frac{1}{n} \sum_{i=1}^n T_i \quad (24)$$

we obtain

$$ET_n^2 \leq \left(\sum_{j=0}^{N(n)} G_j^2 \right)^2 \quad (25)$$

which implies that

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n (T_i - ET_i) = 0 \quad (26)$$

with probability one. This concludes the proof.

Example. Let assume that

$$M(n) = [c_1 n^{q_M}] \quad N(n) = [c_2 n^{q_N}] \quad d_n = c_3 n^\alpha \quad G_j = c_4 j^d, \quad (27)$$

where q_m, q_n and α are positive numbers. It is easily seen that if

$$4dq_M + 2q_M + \alpha < 1, \quad 4dq_N + 2q_N < 1 \quad (28)$$

then Theorem 1 holds. It should be noted that $d = -\frac{1}{12}$ for the Hermite system, $d = -\frac{1}{4}$ for the Laguerre system, $d = 0$ for the Fourier system, $d = \frac{1}{2}$ for the Legendre and Haar systems (see [35]).

3 Experimental Results

For computer simulations we will use synthetic data. Distribution of random variables X_i is uniform on interval $[0; 3]$, for $i = 1, \dots, n$. Consider the following model

$$\phi(x) = 8e^{-x^2}, \quad (29)$$

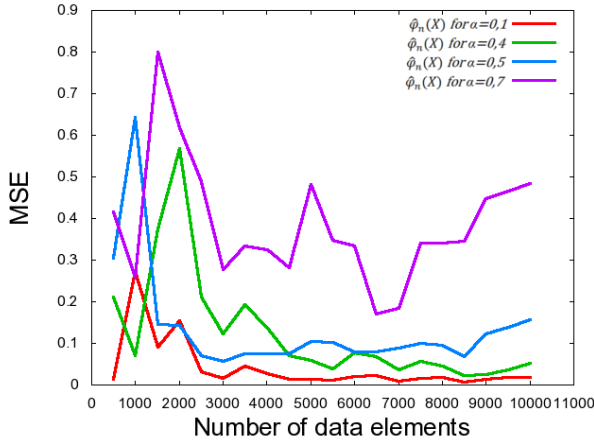


Fig. 2. The MSE as a function of n

with Z_i which are realizations of random variables $N(0, d_i)$, $d_i = i^\alpha$, $\alpha > 0$. Constants c_1, c_2 in (27) are equal to 2 and $c_3 = 1$. Parameters q_M and q_N are both equal to 0,4. The Laguerre orthonormal system is chosen to perform calculations. Number of data set is taken from the interval $[500; 10000]$ and parameter α is tested in the interval $[\frac{1}{10}, \frac{12}{10}]$.

Figure 2 shows how the MSE (Mean Square Error) changes with the number of data elements n for different values of parameter α . For parameter $\alpha \in [0, 1; 0, 4]$ we can see that, when n goes to infinity, the MSE goes to 0. For $\alpha = 0, 5$ or $\alpha = 0, 7$ this trend is not maintained. Moreover, for $\alpha = 0, 7$, value of the MSE is much bigger than for lower values of parameter α . Experimental results show that for higher values of α the MSE is growing. For $\alpha = 1, 2$ and $n = 10^4$, the MSE is equal to 19,18.

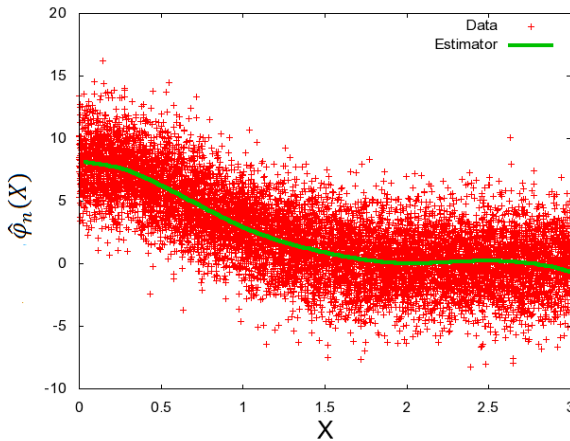


Fig. 3. Training set and obtained estimator

In Figure 3 input data and the result of estimation for $n = 10^4$ and $\alpha = 0, 2$ is indicated. As we can see the estimator found in the appropriate manner center of data and maintained its trend.

Figure 4 shows the course of the function given by (29) and estimators obtained for $n = 10^4$, with parameters α equal to 0, 2 and 1, 2.

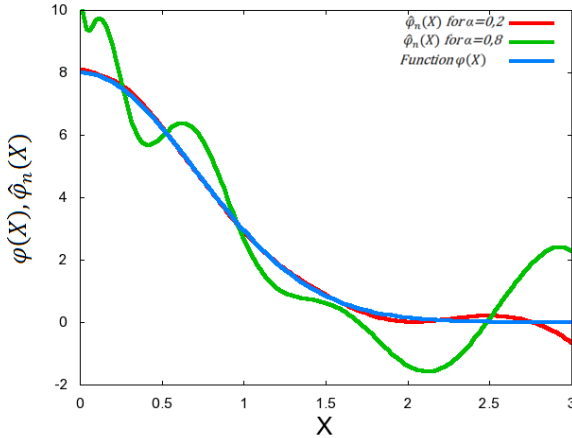


Fig. 4. Function $\phi(\cdot)$ and its estimators for different values of parameter α

4 Conclusions

In this paper we studied general regression neural networks based on the orthogonal series-type kernel. We established the strong convergence assuming non-stationary noise. Further research will focus on how to adopt methods based on unsupervised and unsupervised training algorithms for neural networks [2], [3], [12] and neurofuzzy structures [10], [32] - [34], [36], [38], [39] to handle non-stationary noise.

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