

Characterizing the Existence of Potential Functions in Weighted Congestion Games

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Abstract. Since the pioneering paper of Rosenthal a lot of work has been done in order to determine classes of games that admit a potential. First, we study the existence of potential functions for weighted congestion games. Let C be an arbitrary set of locally bounded functions and let $\mathcal{G}(C)$ be the set of weighted congestion games with cost functions in C . We show that every weighted congestion game $G \in \mathcal{G}(C)$ admits an exact potential if and only if C contains only affine functions. We also give a similar characterization for weighted potentials with the difference that here C consists either of affine functions or of certain exponential functions. We finally extend our characterizations to weighted congestion games with facility-dependent demands and elastic demands, respectively.

1 Introduction

In many situations, the state of a system is determined by a large number of independent agents, each pursuing selfish goals optimizing an individual objective function. A natural framework for analyzing such decentralized systems are noncooperative games. It is well known that an equilibrium point in pure strategies (if it exists) need not optimize the social welfare as individual incentives are not always compatible with social objectives. Fundamental goals in algorithmic game theory are to decide whether a Nash equilibrium in pure strategies (PNE for short) exists, how efficient it is in the worst case, and how fast an algorithm (or protocol) converges to an equilibrium.

One of the most successful approaches in accomplishing these goals is the potential function approach initiated by Rosenthal [24] and generalized by Monderer and Shapley in [22]: one defines a function P on the set of possible strategies of the game and shows that every strictly improving move by one defecting player strictly reduces (increases) the value of P . Since the set of outcomes of such a game is finite, every sequence of improving moves reaches a PNE. In particular, the global minimum (maximum) of P is a PNE. A function P with the property above is called a *potential function* of the game. If one can associate a weight w_i to each player such that $w_i P$ decreases about the same value as the private cost of the defecting player i , then P is called a *weighted potential*. If, in addition, $w_i = 1$ for each player, then P is called an *exact potential*.

1.1 Framework

The first part of this paper studies the existence of potential functions in weighted congestion games (Definition 4). Congestion games, as introduced by Rosenthal [24],

model the interaction of a finite set of strategic agents that compete over a finite set of facilities. A pure strategy of each player is a set of facilities. We consider cost minimization games. Here, the cost of facility f is given by a real-valued cost function c_f that depends on the number of players using f and the private cost of every player equals the sum of the costs of the facilities in the strategy that she chooses.¹ Rosenthal [24] proved in a seminal paper that such congestion games always admit a PNE by showing these games possess an exact potential function.

In a *weighted congestion game*, every player has a demand $d_i \in \mathbb{R}_+$ that she places on the chosen facilities. The cost of a facility is a function of the total demand of the facility. In contrast to unweighted congestion games, weighted congestion games, even with two players, do not always admit a PNE, see the examples given by Fotakis et al. [11], Goemans et al. [14], and Libman and Orda [18].

On the positive side, Fotakis et al. [11,12] proved that every weighted congestion game with affine cost functions possesses an exact potential function and thus, a PNE. Panagopoulou and Spirakis [23] proved existence of a weighted potential function for the set of exponential cost functions.

The results of [11,12] and [23] are particularly appealing as they establish existence of a potential function *independent* of the underlying game structure, that is, *independent* of the underlying strategy set, demand vector, and number of players, respectively. To further stress this independence property, we rephrase the result of Fotakis et al. as follows: Let C be a set of affine cost functions and let $\mathcal{G}(C)$ be the set of *all* weighted congestion games with cost functions in C . Then, *every* game in $\mathcal{G}(C)$ possesses an exact potential.

A natural open question is to decide whether there are further functions guaranteeing the existence of an exact or weighted potential. We thus investigate the following question: How large is the class C of (continuous) cost functions such that every game in the set of weighted congestion games $\mathcal{G}(C)$ with cost functions in C does admit a potential function and hence a PNE?

Before we outline our results we present related work and explain, why it is important to characterize weighted congestion games admitting a potential function.

1.2 Related Work

Fundamental issues in algorithmic game theory are the computability of Nash equilibria and the design of distributed dynamics (for instance best-response) that provably converge in reasonable time to a Nash equilibrium (in pure or mixed strategies).

Monderer and Shapley [22] formalized Rosenthal's approach of using potential functions to determine the existence of PNE. Furthermore, they show that one-side better response dynamics always converge to a PNE provided the game is finite and admits a potential. In addition, they proved that weighted potential games have other desirable properties, e.g., the Fictitious Play Process converges to a PNE [21]. For recent progress on convergence towards approximate Nash equilibria using potential functions, see Awerbuch et al. [4] and Fotakis et al. [10].

¹ Since we allow the cost of a facility to be positive or negative, we also cover maximization games.

Fabrikant et al. [9] proved that one can efficiently compute a PNE for symmetric network congestion games with nondecreasing cost functions. Their proof uses a potential function argument, similar to Rosenthal [24]. Fotakis et al. [11] proved that one can compute a PNE for weighted network games with affine cost (with nonnegative coefficients) in pseudo-polynomial time (again using a potential function).

Milchtaich [20] introduced weighted congestion games with player-specific cost functions. Among other results, he presented a game on 3 parallel links with 3 players, which does not possess a PNE. On the other hand, he proved that such games with 2 players do possess a PNE. Ackermann et al. [1] characterized conditions on the strategy space in weighted congestion games that guarantee the existence of PNE. They also considered the case of player-specific cost functions.

Gairing et al. [13] derive a potential function for the case of weighted congestion games with player-specific linear latency functions (without a constant term). Mavronicolas et al. [19] prove that every unweighted congestion game with player-specific (additive or multiplicative) constants on parallel links has an ordinal potential. Even-Dar et al. [8] consider a variety of load balancing games with makespan objectives and prove among other results that games on unrelated machines possess a generalized ordinal potential function. For related results, see the survey by Vöcking [25] and references therein.

Potential functions also play a central role in Shapley cost sharing games with weighted players, which are special cases of weighted congestion games, see Anshelevich et al. [3] and Albers et al. [2]. In the variant with weighted players, each player i has a demand d_i that she wishes to place on each facility of an allowable subset of facilities (e.g., a path in a network connecting her source node s_i to her terminal node t_i). When facility $f \in F$ is stressed with a load of $\ell_f(x)$ in strategy profile x , it causes a cost of $k_f(\ell_f(x))$. Under Shapley cost sharing, this cost is shared linearly with respect to the demands among the users. Thus the cost of player i for using facility f is defined as $c_{i,f}(x) = k_f(\ell_f(x))d_i/\ell_f(x)$ and clearly, the private cost of player i in strategy profile x is given as $\pi_i(x) = \sum_{f \in x_i} c_{i,f}(x)$. For the unweighted case ($d_i = 1, i \in N$), Anshelevich et al. [3] proved existence of PNE and derived bounds on the price of stability using a potential function argument. This argument fails in general for games with weighted players, see the counterexamples given by Chen and Roughgarden [5]. Determining subclasses of Shapley cost sharing games with weighted players that admit a potential, however, is an open problem that we address in this paper.

1.3 Our Results for Weighted Congestion Games

Our first two results provide a characterization of the existence of exact and weighted potential functions for the set of weighted congestion games with locally bounded and continuous cost functions, respectively. Let C be an arbitrary set of locally bounded functions and let $\mathcal{G}(C)$ be the set of weighted congestion games with cost functions in C . We show that every weighted congestion game $G \in \mathcal{G}(C)$ admits an exact potential if and only if C contains only affine functions. For an arbitrary set C of continuous functions, we show that every weighted congestion game $G \in \mathcal{G}(C)$ possesses a weighted potential if and only if exactly one of the following cases hold: (i) C contains only affine

functions; (ii) C contains only exponential functions such that $c(\ell) = a_c e^{\phi \ell} + b_c$ for some $a_c, b_c, \phi \in \mathbb{R}$, where a_c and b_c may depend on c , while ϕ must be equal for every $c \in C$.

We additionally show that the above characterizations for exact and weighted potentials are valid even if we restrict the set $\mathcal{G}(C)$ to two-player games (three-player games for weighted potentials), three-facility games (four-facility games for weighted potentials), games with symmetric strategies, games with singleton strategies, games with integral demands. Moreover, we derive a result for weighted congestion games where each facility is contained in the strategy set of at most two players, showing that every such game with cost functions in C admits a weighted potential if $C = \{(c : \mathbb{R}_+ \rightarrow \mathbb{R}) : c(x) = af(x) + b, a, b \in \mathbb{R}\}$, where $f : \mathbb{R}_+ \rightarrow \mathbb{R}$ is a strictly monotonic function.

Our results have a series of consequences. First, using a result of Monderer and Shapley [22, Lemma 2.10], our characterization of weighted potentials in weighted congestion games carries over to the mixed extension of weighted congestion games.

Second, we obtain the following characterizations for Shapley cost sharing games. Let \mathcal{K} be a set of continuous functions. Then, the set $\mathcal{S}(\mathcal{K})$ of Shapley cost sharing games with weighted players and construction cost functions in \mathcal{K} are weighted potential games if and only if \mathcal{K} contains either quadratic construction cost functions ($k(\ell) = a_k \ell^2 + b_k \ell$) or functions of type $k(\ell) = a_k e^{\phi \ell} \ell + b_k \ell$ for some $a_k, b_k, \phi \in \mathbb{R}$, where a_k and b_k may depend on k , while ϕ must be equal for every $k \in \mathcal{K}$. Notice that these results hold for arbitrary coefficients $a_k, b_k, \phi \in \mathbb{R}$. Thus, we obtain the existence of PNE for a family of games with nondecreasing and strictly concave construction costs modeling the effect of economies of scale.

1.4 Our Results for Extended Models

In the second part of this paper, we introduce two non-trivial extensions of weighted congestion games.

First, we study weighted congestion games with *facility-dependent* demands, that is, the demand $d_{i,f}$ of player i depends on the facility f . These games contain, among others, scheduling games on identical, restricted, related and unrelated machines. In contrast to classical load balancing games, we do not consider makespan objectives. In our model, the private cost of a player is a function of the machine load multiplied with the demand of the player.

We show the following: Let C be a set of continuous functions and let $\mathcal{G}^{fd}(C)$ denote the set of weighted congestion games with facility-dependent demands and cost functions in C . Every $G \in \mathcal{G}^{fd}(C)$ has a weighted potential if and only if C contains only affine functions. In this case the weighted potential is an exact potential. To the best of our knowledge, our characterization establishes for the first time the existence of an exact potential function (and hence the existence of a PNE) for affine cost functions and *arbitrary* strategy sets and demands, respectively.

Second, we study weighted congestion games with *elastic* demands. Here, each player i is allowed to choose both a subset of the set of facilities and her demand d_i out of a compact set $D_i \subset \mathbb{R}_+$ of demands that are allowable for her. This congestion model can be interpreted as a generalization of Cournot games [7], where multiple producers strategically determine quantities they will produce. The cost of a producer is

given by her offered quantity multiplied with the market price, which is usually a decreasing function of the total quantity offered by all producers. Weighted congestion games with elastic demands generalize Cournot games in the sense that there are multiple markets (facilities) and each player may offer her quantity on allowable subsets of these markets.

Weighted congestion games with elastic demands have several more natural applications: they model, e.g., routing problems in the Internet, where each user wants to route data along a path in the network and adjusts the injected data rate according to the level of congestion in the network. Most mathematical models for routing and congestion control rely on fractional routing, see Kelly [17] and Cole et al. [6]. In practice, however, routing protocols use single path routing, see, e.g., the current TCP/IP protocol. Weighted congestion games with elastic demands model both congestion control and unsplitable routing. Yet another application is that of Shapley cost sharing games with players that may vary their requested demand.

Let $\mathcal{G}^e(C)$ be the set of weighted congestion games with elastic demands where each player may choose her demand out of a compact space and where the cost of each facility is determined by a function in C . Our main contribution is to show that all games $G \in \mathcal{G}^e(C)$ are weighted potential games if and only if C contains only affine functions. For this important class of games, our result also establishes for the first time the existence of PNE.

Proofs of our results can be found in [15]. In a follow up paper [16] we characterize strong Nash equilibria for weighted congestion games with bottleneck objectives.

2 Preliminaries

Definition 1 (Finite game). *A finite strategic game is a tuple $G = (N, X, \pi)$ where $N = \{1, \dots, n\}$ is the non-empty finite set of players, $X = \times_{i \in N} X_i$ where X_i is the finite and non-empty set of strategies of player i , and $\pi : X \rightarrow \mathbb{R}^n$ is the combined private cost function.*

We will call an element $x \in X$ a strategy profile. For $S \subset N$, $-S$ denotes the complementary set of S , and we define for convenience of notation $X_S = \times_{j \in S} X_j$. Instead of $X_{-(i)}$ we will write X_{-i} , and with a slight abuse of notation we will write sometimes a strategy profile as $x = (x_i, x_{-i})$ meaning that $x_i \in X_i$ and $x_{-i} \in X_{-i}$.

Definition 2 (Weighted potential game, exact potential game). *A strategic game $G = (N, X, \pi)$ is called weighted potential game if there is a vector $w = (w_i)_{i \in N}$ of positive weights and a real-valued function $P : X \rightarrow \mathbb{R}$ such that $\pi_i(x_i, x_{-i}) - \pi_i(y_i, x_{-i}) = w_i(P(x_i, x_{-i}) - P(y_i, x_{-i}))$ for all players $i \in N$ and for all $x_{-i} \in X_{-i}$ and all $x_i, y_i \in X_i$. The function P together with the vector w is then called a weighted potential of the game G . The function P is called an exact potential if $w_i = 1$ for all $i \in N$.*

We sometimes call a weighted potential function P a $(w_i)_{i \in N}$ -potential.

Monderer and Shapley [22, Theorem 2.8] have shown that one can characterize exact potentials in a very convenient way. For this, let a finite strategic game $G = (N, X, \pi)$ be given. A *path* in X is a sequence $\gamma = (x^0, x^1, \dots, x^m)$ with $x^k \in X$, $k = 0, \dots, m$, such that

for all $k \in \{1, \dots, m\}$ there exists a unique player $i_k \in N$ such that $x^k = (x_{i_k}^k, x_{-i_k}^{k-1})$ for some $x_{i_k}^k \neq x_{i_k}^{k-1}$, $x_{i_k}^k \in X_i$. A path is called closed if $x^0 = x^m$ and is called simple if $x^k \neq x^l$ for $k \neq l$. The length of a closed path is defined as the number of its distinct elements. For a set of strategy profiles X let $\Gamma(X)$ denote the set of all simple closed paths in X that have length 4. For a finite path $\gamma = (x^0, x^1, \dots, x^m)$ let the discrete path integral of π along γ be defined as $I(\gamma, \pi) = \sum_{k=1}^m (\pi_{i_k}(x^k) - \pi_{i_k}(x^{k-1}))$ where i_k is the deviator at step k in γ , that is $x_{i_k}^k \neq x_{i_k}^{k-1}$.

Theorem 1 (Monderer and Shapley). *Let $G = (N, X, \pi)$ be a finite strategic game. Then, G is an exact potential game if and only if $I(\gamma, \pi) = 0$ for all $\gamma \in \Gamma(X)$.*

In the following, we will use this characterization in order to study the existence of potentials in weighted congestion games.

3 Weighted Congestion Games

Definition 3 (Congestion model). *A tuple $\mathcal{M} = (N, F, X = \prod_{i \in N} X_i, (c_f)_{f \in F})$ is called a congestion model, where $N = \{1, \dots, n\}$ is a non-empty, finite set of players, F is a non-empty, finite set of facilities, for each player $i \in N$, her collection of pure strategies X_i is a non-empty, finite set of subsets of F and $(c_f)_{f \in F}$ is a set of cost functions.*

In the following, we will define weighted congestion games similar to Goemans et al. [14].

Definition 4 (Weighted congestion game). *Let $\mathcal{M} = (N, F, X, (c_f)_{f \in F})$ be a congestion model and $(d_i)_{i \in N}$ be a vector of demands $d_i \in \mathbb{R}_+$. The corresponding weighted congestion game is the strategic game $G(\mathcal{M}) = (N, X, \pi)$, where π is defined as $\pi = \prod_{i \in N} \pi_i$, $\pi_i(x) = \sum_{f \in x_i} d_i c_f(\ell_f(x))$ and $\ell_f(x) = \sum_{j \in N: f \in x_j} d_j$.*

We call $\ell_f(x)$ the *load* on facility f in strategy x . In case there is no confusion on the underlying congestion model, we will write G instead of $G(\mathcal{M})$.

A slightly different class of games has been considered by (among others) Fotakis et al. [11,12], Gairing et al. [13] and Mavronicolas et al. [19]. They considered games that almost coincide with Definition 4 except that the private cost of every player is not scaled by her demands. We call such games *normalized* if they comply with Definition 4 except that the private costs are defined as $\bar{\pi}_i(x) = \sum_{f \in x_i} c_f(\ell_f(x))$ for all $i \in N$.

Fotakis et al. [11] show that there are normalized weighted congestion games with $c_f(\ell) = \ell$ for all $f \in F$ that are not exact potential games. They also show that any normalized weighted congestion game with linear costs on the facilities admits a weighted potential.

We state the following trivial relations between weighted congestion games and normalized weighted congestion games: Let $G = (N, X, \pi)$ and $\bar{G} = (N, X, \bar{\pi})$ be a weighted congestion game and a normalized weighted congestion game with demands $(d_i)_{i \in N}$, respectively. Moreover, let them share the same congestion model and the same demands. Then G and \bar{G} coincide in the following sense: (i) A strategy profile $x \in X$ is a PNE in G if and only if x is a PNE in \bar{G} ; (ii) A real-valued function $P : X \rightarrow \mathbb{R}$ is a $(w_i/d_i)_{i \in N}$ -potential for G if and only if P is a $(w_i)_{i \in N}$ -potential for \bar{G} ; (iii) A real-valued function

$P : X \rightarrow \mathbb{R}$ is an ordinal potential for G (see [22] for a definition) if and only if P is an ordinal potential for \bar{G} ; (iv) The real-valued function $P : X \rightarrow \mathbb{R}$ is an exact potential for G if and only if P is a $(d_i)_{i \in N}$ -potential for \bar{G} ; (v) The real-valued function $P : X \rightarrow \mathbb{R}$ is an exact potential for \bar{G} if and only if P is a $(1/d_i)_{i \in N}$ -potential for G . All proofs rely on the simple observation that $\pi_i(x) = d_i \bar{\pi}_i(x)$ for all $i \in N, x \in X$.

3.1 Characterizing the Existence of an Exact Potential

In the following, we will examine necessary and sufficient conditions for a weighted congestion game G to be a potential game. The criterion in Theorem 1 states that the existence of an exact potential for $G = (N, X, \pi)$ is equivalent to the fact that $I(\gamma, \pi) = 0$ for all $\gamma \in \Gamma(X)$. In such paths, either one or two players deviate. It is easy to verify that $I(\gamma, \pi) = 0$ for all paths γ with only one deviating player. Considering a path γ with two deviating players, say i and j , each of them uses two different strategies, say $x_i, y_i \in X_i$ and $x_j, y_j \in X_j$. We denote by $z_{-\{i,j\}} \in X_{-\{i,j\}}$ the strategy profile of all players except i and j that remains constant in γ . Then, a generic path $\gamma \in \Gamma(X)$ can be written as $\gamma = ((x_i, x_j, z_{-\{i,j\}}), (y_i, x_j, z_{-\{i,j\}}), (y_i, y_j, z_{-\{i,j\}}), (x_i, y_j, z_{-\{i,j\}}), (x_i, x_j, z_{-\{i,j\}}))$. The following lemma provides an explicit formula for the calculation of $I(\gamma, \pi)$ for such a path.

Lemma 1. *Let $\mathcal{M} = (N, F, X, (c_f)_{f \in F})$ be a congestion model and $G(\mathcal{M})$ a corresponding weighted congestion game with demands $(d_i)_{i \in N}$. Moreover, let $\gamma = ((x_i, x_j, z_{-\{i,j\}}), (y_i, x_j, z_{-\{i,j\}}), (y_i, y_j, z_{-\{i,j\}}), (x_i, y_j, z_{-\{i,j\}}), (x_i, x_j, z_{-\{i,j\}}))$ be an arbitrary path in $\Gamma(X)$ with two deviating players. Then,*

$$\begin{aligned}
 I(\gamma, \pi) = & \sum_{f \in F_1 \cup F_{11}} (d_j - d_i) c_f (d_i + d_j + r_f) - d_j c_f (d_j + r_f) + d_i c_f (d_i + r_f) \\
 & + \sum_{f \in F_3 \cup F_9} (d_i - d_j) c_f (d_i + d_j + r_f) - d_i c_f (d_i + r_f) + d_j c_f (d_j + r_f), \quad (1)
 \end{aligned}$$

where $F_1 = (x_i \setminus y_i) \cap (x_j \setminus y_j)$, $F_3 = (x_i \setminus y_i) \cap (y_j \setminus x_j)$, $F_9 = (y_i \setminus x_i) \cap (x_j \setminus y_j)$, and $F_{11} = (y_i \setminus x_i) \cap (y_j \setminus x_j)$.

Using Lemma 1, we can derive a sufficient condition on the existence of an exact potential in a weighted congestion game.

Proposition 1. *Let $\mathcal{M} = (N, F, X, (c_f)_{f \in F})$ be a congestion model and $G(\mathcal{M})$ a corresponding weighted congestion game with demands $(d_i)_{i \in N}$. For each facility $f \in F$ we denote by $N^f = \{i \in N : (\exists x_i \in X_i : f \in x_i)\}$ the set of players potentially using f , and by $\mathcal{R}_{-\{i,j\}}^f = \{\sum_{k \in P} d_k : P \subseteq N^f \setminus \{i, j\}\}$ the set of possible residual demands by all players except i and j . If for all $f \in F$ and all $i, j \in N^f$ it holds that*

$$(d_j - d_i) c_f (d_i + d_j + r_f) - d_j c_f (d_j + r_f) + d_i c_f (d_i + r_f) = 0 \quad \forall r_f \in \mathcal{R}_{-\{i,j\}}^f, \quad (2)$$

then G admits an exact potential.

It is a useful observation that we can write the condition of Proposition 1 as

$$\frac{c_f (d_i + d_j + r_f) - c_f (d_j + r_f)}{d_i} = \frac{c_f (d_j + r_f) - c_f (d_i + r_f)}{d_j - d_i} \quad (3)$$

for all $i, j \in N^f$ and $r_f \in \mathcal{R}_{-[i,j]}^f$. Thus, the difference quotients of c_f between the points $d_i + r_f$ and $d_j + r_f$ as well as $d_j + r_f$ and $d_i + d_j + r_f$ must have the same value. It follows easily that the above condition is satisfied if all demands are equal (this corresponds to unweighted congestion games, see Rosenthal's potential [24]). For *arbitrary* demands (weighted congestion games) and *affine* cost functions, one can check that the above condition is also satisfied, see the positive result of Fotakis et al. [11].

There is, however, an important question left: Are there non-affine cost functions that give rise to an exact potential in *all* weighted congestion games? Under mild assumptions on feasible cost functions, we will give in Theorem 2 a negative answer to this question. First, we derive the following lemma from Theorem 1.

Lemma 2. *Let C be a set of functions and let $\mathcal{G}(C)$ be the set of all weighted congestion games with cost functions in C . Every $G \in \mathcal{G}(C)$ has an exact potential if and only if for all $c \in C$*

$$(x - y)c(x + y + z) - xc(x + z) + yc(y + z) = 0 \tag{4}$$

for all $x, y \in \mathbb{R}_+$ and $z \in \mathbb{R}_+^0$.

We will now solve the functional equation (4) in order to characterize all cost functions that guarantee an exact potential in all weighted congestion games. We require the following property: A function $c : \mathbb{R}_+ \rightarrow \mathbb{R}$ is *locally bounded*, if for every compact set $K \subset \mathbb{R}_+$, $|c(x)| < M_K$ for all $x \in K$ and a constant $M_K \in \mathbb{R}_+$ potentially depending on K .

Theorem 2. *Let C be a set of locally bounded functions and let $\mathcal{G}(C)$ be the set of weighted congestion games with cost functions in C . Then every $G \in \mathcal{G}(C)$ admits an exact potential function if and only if C contains affine functions only, that is, every $c \in C$ can be written as $c(\ell) = a_c \ell + b_c$ for some $a_c, b_c \in \mathbb{R}$.*

3.2 Characterizing the Existence of a Weighted Potential

Our next aim is to determine whether weaker notions of potential functions will enrich the class of cost functions giving rise to a potential game. The idea of a weighted potential allows a player specific scaling of the private cost π_i by a strictly positive w_i . It is a useful observation that the existence of a weighted potential function is equivalent to the existence of a strictly positive-valued vector $w = (w_i)_{i \in N}$ such that the game G^w with private costs $\bar{\pi} := \times_{i \in N} \pi_i / w_i$ has an exact potential.

Using this equivalent formulation and Theorem 1 it follows that the existence of an exact potential function for the game $G^w = (N, X, \bar{\pi})$ is equivalent to $I(\gamma, \bar{\pi}) = 0$ for all $\gamma \in \Gamma(X)$ suggesting that G^w has an exact potential if and only if there are $w_i, w_j \in \mathbb{R}_+$ such that

$$\left(\frac{d_i}{w_i} - \frac{d_j}{w_j} \right) c_f(d_i + d_j + r_f) = \frac{d_i}{w_i} c_f(d_i + r_f) - \frac{d_j}{w_j} c_f(d_j + r_f)$$

for all $i, j \in N$ and all $r_f \in \mathcal{R}_{-i,j}$. In particular it is necessary that either $c_f(d_i + d_j + r_f) = c_f(d_j + r_f) = c_f(d_i + r_f)$ or the value $\alpha(d_i, d_j)$ defined as

$$\alpha(d_i, d_j) = \frac{w_i}{w_j} = \frac{d_i}{d_j} \cdot \frac{c_f(d_i + d_j + r_f) - c_f(d_i + r_f)}{c_f(d_i + d_j + r_f) - c_f(d_j + r_f)} \tag{5}$$

is strictly positive and independent of both f and r_f .

Lemma 3. *Let C be a set of functions. Let $\mathcal{G}(C)$ be the set of weighted congestion games with cost functions in C . Every $G \in \mathcal{G}(C)$ has a weighted potential if and only if for all $x, y \in \mathbb{R}_+$ there exists an $\alpha(x, y) \in \mathbb{R}_+$ such that*

$$\alpha(x, y) = \frac{x}{y} \cdot \frac{c(x+y+z) - c(x+z)}{c(x+y+z) - c(y+z)} \quad (6)$$

for all $z \in \mathbb{R}_+^0$ and non-constant $c \in C$.

Although this condition seems to be similar to the functional equation (4) characterizing the existence of an exact potential, it is not possible to proceed using differential equations as in the proof of Theorem 2. As $\alpha(x, y)$ need not be bounded it is not possible to prove continuity and differentiability of c . Instead, we will use the discrete counterpart of differential equations, that is, difference equations.

Theorem 3. *Let C be a set of continuous functions. Let $\mathcal{G}(C)$ be the set of weighted congestion games with cost functions in C . Then every $G \in \mathcal{G}(C)$ admits a weighted potential if and only if exactly one of the following cases holds:*

1. C contains only affine functions,
2. C contains only exponential functions $c(\ell) = a_c e^{\phi \ell} + b_c$ for some $a_c, b_c, \phi \in \mathbb{R}$, where a_c and b_c may depend on c , while ϕ must be equal for every $c \in C$.

3.3 Implications of Our Characterizations

It is natural to ask whether these results remain valid if additional restrictions on the set $\mathcal{G}(C)$ are made. A natural restriction is to assume that all players have an integral demand. As we used infinitesimally small demands in the proof of Lemma 2, our results for exact potentials do not apply directly to integer demands. With a slight variation of the proof of Theorem 3 where only the case $\alpha(\cdot, \cdot) = 1$ is considered, however, we still obtain the same result provided that C contains only continuous functions.

Another natural restriction on $\mathcal{G}(C)$ are games with symmetric sets of strategies or games with a bounded number of players or facilities. Since the proofs of Lemma 2 and 3 and Theorems 2 and 3 rely on mild assumptions, we can strengthen our characterizations as follows.

Corollary 1. *Let C be a set of continuous functions. Let $\mathcal{G}(C)$ be the set of weighted congestion games with cost functions in C satisfying one or more of the following properties*

1. Each game $G = (N, X, \pi) \in \mathcal{G}(C)$ has two (three) players.
2. Each game $G = (N, X, \pi) \in \mathcal{G}(C)$ has three (five) facilities.
3. For each game $G = (N, X, \pi) \in \mathcal{G}(C)$ and each player $i \in N$ the set of her strategies X_i contains a single facility only.
4. Each game $G = (N, X, \pi) \in \mathcal{G}(C)$ has symmetric strategies, that is $X_i = X_j$ for all $i, j \in N$.
5. In each game $G = (N, X, \pi) \in \mathcal{G}(C)$ the demands of all players are integral.

Then, every $G = (N, X, \pi) \in \mathcal{G}(C)$ has an exact (a weighted) potential if and only if C contains only affine functions (only affine functions or only exponential functions as in Theorem 3).

Yet, we are able to deduce an interesting result concerning the existence of weighted potentials in weighted congestion games where each facility can be chosen by at most two players. As we can set $z = 0$ in (6), the conditions of Lemma 3 are fulfilled by more than affine or exponential functions.

Theorem 4. *Let $m(x)$ be a strictly monotonic function and $C_m = \{am(x) + b : a, b \in \mathbb{R}\}$. Let $\mathcal{G}^2(C_m)$ be the set of games such that cost functions are in C_m and every facility is contained in the set of strategies of at most two players. Then, every $G \in \mathcal{G}^2(C_m)$ possesses a weighted potential.*

This result generalizes a result of Anshelevich et al. in [3], who showed that a weighted congestion game with two players and $c_f(\ell) = b_f/\ell$ for a constant $b_f \in \mathbb{R}_+$ has a potential. Moreover, this result shows that the characterization of Corollary 1 is tight in the sense that weighted congestion games with two players admit a weighted potential even if cost functions are neither affine nor exponential.

4 Extensions of the Model

In the last section, we developed a new technique to characterize the set of functions that give rise to a potential in weighted congestion games. In this section, we will introduce two generalizations of weighted congestion games and investigate the set of cost functions that assure the existence of potential functions.

Definition 5 (Weighted congestion game with facility-dependent demands). *Let $\mathcal{M} = (N, F, X, (c_f)_{f \in F})$ be a congestion model and let $(d_{i,f})_{i \in N, f \in F}$ be a matrix of facility-dependent demands. The corresponding weighted congestion game with facility-dependent demands is the strategic game $G(\mathcal{M}) = (N, X, u)$, where u is defined as $u = \times_{i \in N} \pi_i$, $\pi_i(x) = \sum_{f \in x_i} d_{i,f} c_f(\ell_f(x))$ and $\ell_f(x) = \sum_{j \in N: f \in x_j} d_{j,f}$.*

Restricting the strategy sets to singletons, we obtain scheduling games. In a scheduling game, players are jobs that have machine-dependent demands and can be scheduled on a set of admissible machines (restricted scheduling on unrelated machines). In contrast to the classical approach, where each job strives to minimize its makespan, we consider a different private cost function: Machines charge a price per unit given by a load-dependent cost function c_f and each job minimizes its cost defined as the price of the chosen machine multiplied with its machine-dependent demand.

Theorem 5. *Let C be a set of continuous functions and let $\mathcal{G}^{fd}(C)$ be the set of weighted congestion games with facility-dependent demands and cost functions in C . Then, every $G \in \mathcal{G}^{fd}(C)$ admits a weighted potential if and only if C contains only affine functions, that is, every $c \in C$ can be written as $c(\ell) = a_c \ell + b_c$ for some $a_c, b_c \in \mathbb{R}$. For a game G with affine cost functions, the potential function is given by $P(x) = \sum_{i \in N} \sum_{f \in x_i} c_f \left(\sum_{j \in \{1, \dots, i\}: f \in x_j} d_{j,f} \right) d_{i,f}$.*

We will now introduce an extension to weighted congestion games allowing players to also choose their demand.

Definition 6 (Weighted congestion game with elastic demands). Let $\mathcal{M} = (N, F, X, (c_f)_{f \in F})$ be a congestion model. Together with $D = \times_{i \in N} D_i$, where $D_i \subset \mathbb{R}_+$ are compact for all $i \in N$, we define the weighted congestion game with elastic demands as the strategic game $G(\mathcal{M}) = (N, \tilde{X}, \pi)$ with $\tilde{X} := (X, D)$, $\pi = \times_{i \in N} \pi_i$, and $\pi_i(\bar{x}) = \sum_{f \in x_i} d_i c_f(\ell_f(\bar{x}))$ and $\ell_f(\bar{x}) = \sum_{j \in N: f \in x_j} d_j$.

In our definition of weighted congestion games with elastic demands, we explicitly allow for positive and negative, and for increasing and decreasing cost functions. Thus, an increase in the demand may increase or decrease the player's private cost. Note that in weighted congestion games with elastic demands, the strategy sets are topological spaces and are in general infinite. By restricting the sets D_i to singletons $D_i = \{d_i\}$, $i \in N$, we obtain weighted congestion games as a special case of weighted congestion games with elastic demands. The proof of the following result is similar to the case of facility-dependent demands.

Theorem 6. Let C be a set of continuous functions and let $\mathcal{G}^e(C)$ be the set of weighted congestion games with elastic demands and cost functions in C . Then, every $G \in \mathcal{G}^e(C)$ admits a weighted potential function if and only if C contains only affine functions. For a game G with affine cost functions, the potential function is given by $P(\bar{x}) = \sum_{i \in N} \sum_{f \in x_i} c_f \left(\sum_{j \in \{1, \dots, i\}: f \in x_j} d_j \right) d_i$.

As an immediate consequence, we obtain the existence of a PNE if cost functions are affine. Note that the existence of a potential is not sufficient for proving existence of a PNE as we are considering infinite games. However, as \tilde{X} is compact and P is continuous, P has a minimum $\bar{x}^* \in \tilde{X}$ and \bar{x}^* is a PNE.

Corollary 2. Let C be a set of affine functions and let $\mathcal{G}^e(C)$ be the set of weighted congestion games with elastic demands and cost functions in C . Then every $G \in \mathcal{G}^e(C)$ admits a PNE.

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