

# $\alpha_1, \beta_1, \beta_2$ - root characteristics of multiply possible theoretical solutions of steady Mach reflections in perfect diatomic gases

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**Summary.** The existence of the jump in  $\beta_1=\beta_2$  double roots in the three-shock theoretical solutions of steady Mach reflections on the  $(\theta_1, M_0)$  plane is determined for the first time,  $\theta_1$  is flow deflection behind the incident shock,  $M_0$  is the incident shock Mach number. This jump behavior of  $\beta_1=\beta_2$  double roots explains the occurrence of newly found  $\alpha_1=\beta_2$  double roots of multiple theoretical solutions of steady MR in perfect diatomic and triatomic gases. The critical condition determining the location of  $M_0$  of this jump, for gas specific heats ratio of 1.4, is obtained to occur at  $\alpha_1 = \beta_1 = \beta_2$  triple roots where  $M_0=3.41485$ . There are two findings closely associated with this jump behavior of  $\beta_1=\beta_2$  double roots: 1, the  $\alpha_1$  solutions cease to become physically meaningful for  $M_0 > 3.41485$ ; 2,  $\alpha_1=\beta_2$  double roots do not exist for  $M_0 < 3.41485$ .

## 1 Introduction

This work is an extension of Liu [1-3] and Liu et al. [4] reporting on multiplicity regimes of three-shock theoretical solutions of steady Mach reflections (MR) in perfect diatomic and triatomic gases. The existence and basic characteristics of newly found  $\alpha_1 = \beta_2$  double roots of three-shock solutions of steady MR are verified and analyzed in perfect diatomic and triatomic gases [3,4]. As noted earlier [1], the problem of three-shock confluences of MR phenomena in steady flow is important both theoretically and practically. Academically, the problem of weak pseudo-steady MR has attracted attentions of researchers in areas of physics, mathematics, and engineering for more than half of century. A change of coordinates from laboratory to self-similarly propagating triple-point makes pseudo-steady MR equivalent to steady MR in the vicinity of the triple-point. Henderson [5] showed that the equation of motion of a confluence of perfect-gas three-shock waves (i.e. steady MR) could be reduced to a single polynomial equation of tenth degree with the pressure ratio across the Mach stem as the variable. Henderson [5] then gave the maps of the multiplicity of theoretical three-shock solutions on the  $(\theta_1, M_0)$  plane for  $\gamma = 1.1, 9/7, 7/5$  and  $5/3$  where  $m = 0, 1, 2$  for the former two gases and  $m = 0, 1, 2, 3$  for the latter two ( $m$ , the number of physically significant roots). Liu [1,2], on the other hand, pointed out that there exist regimes of  $m = 3$  for  $\gamma = 1.1$  and  $9/7$ , and there are erratum in Henderson's multiplicity map for  $\gamma = 7/5$ . The reason for these mistakes are incorrectness in computed  $\beta_1=\beta_2$  double-root lines. Henderson [5] reported that the  $\beta_1=\beta_2$  double-root line and triple-root (II) curve coincide over the entire  $M_0$  range considered for  $\gamma=1.1$ , and they merge for  $M_0 > 3$  for  $\gamma = 7/5$ . Liu [1,2], however, showed that these two lines coincide only at  $M_0 = 2.41$  and  $3.117$  for  $\gamma = 9/7$  and  $7/5$ , respectively. We show here that these two lines affect the map of the multiplicity of three-shock theoretical solutions of steady MR significantly. Needless to say, the newly found  $\alpha_1=\beta_2$  double roots not only change the  $\beta_1=\beta_2$  double-root line, but dramatically alter the multiplicity

map of steady MR. Liu [3] remarked that the occurrence of  $\alpha_1=\beta_2$  roots implies the existence of a possible discontinuity behavior in the  $\beta_1=\beta_2$  double-root line. The aim of this work is the determination of the location of the jump in  $\beta_1=\beta_2$  double-root line of theoretical solutions of steady MR on the  $(\theta_1, M_0)$  plane. Another motivation of this work stems from the above-mentioned link between theoretical solutions of a steady MR, where exact solutions are available, and those of a pseudo-steady MR. Henderson's 1987 work [6] on pseudo-steady MR, which was based on his 1964 work [5] on steady MR, is the most frequently referred theoretical analysis for describing the problem of the von Neumann paradox of weak pseudo-steady MR. However, are these two Henderson's works correct?

## 2 Analysis

The tenth degree polynomial equation of perfect-gas three-shock confluences given by Henderson [5] is of the form:  $R_i T_i = 0$  ( $i=1,2,\dots,9$ ), where  $R_i$  and  $T_i$  are algebraic polynomials of degree 6. The tenth degree polynomial equation obtained by Liu [1] is of the form  $\sum_{n=0}^{10} C_n x^n = 0$ , where  $C_n$ 's are too lengthy to be given here. For example, the numbers of different terms in coefficients  $C_3$  and  $C_4$  are 748 and 778, respectively. This tenth degree polynomial equation is used for calculating all possible three-shock theoretical solutions for a given condition of a steady MR. An intermediate form of this equation is given in [1].

According to Henderson [5], a physically significant solution of a steady MR requires that the pressure behind the Mach stem be larger than that behind the incident shock. There exist double incident Mach line degeneracies,  $D_1$ , double reflected Mach line degeneracies,  $D_2$ , a physically possible  $\alpha_1$  solution, a physically impossible  $\alpha_2$  solution. This gives a total of six roots with two pairs of complex roots left. He used symbols  $\beta_1, \beta_2$  to represent a second and third appearances of physically possible solutions when one of the two pairs becomes real. In the following, we explain nomenclature used in obtaining multiple three-shock solutions by applying it to a steady MR of  $M_0 = 4.015$ ,  $P_1 = 6.215$ ,  $\gamma = 1.4$ . Figure 1(a) shows  $(p - \theta)$  shock polar diagrams illustrating multiply possible three-shock solutions for this steady MR, where  $m = 2$ . There is one regular reflection solution RR (weak), one backward-facing reflected shock solution  $\beta_1$ , one forward-facing reflected shock solution  $\beta_2$ . The  $\alpha_1$  root is not physically realizable in this case. The physical plane corresponding to  $\beta_1$  is shown in Fig. 1(b). The wave configuration is drawn according to calculated results of the  $\beta_1$  solution, and it agrees reasonably well with that of the actual experiment of this case reported in JFM (2002, 459). Note the vast differences among  $\beta_1, \beta_2$  and  $\alpha_1$  solutions, and not all intersection solutions lead to physically meaningful results. Liu et al. [4] reported the link between the occurrence of  $\alpha_1=\beta_2$  roots and a possible jump behavior in  $\beta_1=\beta_2$  root-line. More specifically, possible jump behaviors of  $\beta_1=\beta_2$  root-line were found to be located in narrow ranges near  $M_0=3.5$  and 2.3 for  $\gamma = 7/5$  and  $9/7$ , respectively. Searching for the exact location of the jump of the  $\beta_1=\beta_2$  double-root line on the  $(\theta_1, M_0)$  plane are carried out by systematically examining multiply possible solutions at different  $M_0$ 's by varying  $\theta_1$  from upper forbidden sonic conditions to their minimum incident Mach angle conditions. Three series of sequential solutions of  $M_0 = 3.4, 3.41484$  and  $3.45$  are reported.

### 3 Locating the jump of $\beta_1=\beta_2$ double roots line by examining theoretical solutions of steady MR at different $M_0$ 's

Earlier works of one of the authors [1-4] have explained mathematical and physical meanings for the occurrences of possible theoretical  $\alpha_1, \beta_1, \beta_2, D_2, D_1$  and  $\alpha_2$  solutions of perfect-gas steady MR. Owing to the usefulness of (p -  $\theta$ ) shock polar representation of theoretical MR solutions, the results illustrating in Figs. 2-4 are self-explanatory. In particular, solutions of the upper sonic forbidden condition are marked as  $M_1=1, D_2=\alpha_1$ , marked as Triple-root (I),  $D_2=\beta_1$  as Triple-root (I) or (II),  $D_2=\beta_2$  as Triple-root (II). Solutions of forward- and backward-strong/weak separating, forward- and backward-sonic, forward/backward separating, von Neumann and limiting incident shock Mach angle conditions,  $\beta_1=\beta_2, \alpha_1=\beta_2$  are correspondingly marked. Therefore, only brief descriptions regarding main features of multiply possible solutions are provided for  $M_0 = 3.4$  and 3.45. Detailed discussions on behaviors of  $\alpha_1, \beta_1$  and  $\beta_2$  solutions are given for  $M_0 = 3.41485$ , where the jump in  $\beta_1=\beta_2$  is located. Figures 2 and 4 give systematic shock polar solutions for  $M_0 = 3.4$  and 3.45, respectively. There are similarities and differences in these two series theoretical solutions. Similarities are  $\theta_1$  locations of the solutions of triple-root (I) and (II), forward/backward separating, forward- and backward- sonic and von Neumann conditions. However, significant differences are  $\theta_1$  locations of  $\beta_1=\beta_2$  double roots. Particularly,  $\alpha_1=\beta_2$  double roots, which occur twice in  $M_0 = 3.45$ , do not exist in  $M_0 = 3.4$ . The reason for this apparently large difference in  $\theta_1$  location in such a narrow variation of  $M_0$  and the occurrence of  $\alpha_1=\beta_2$  may be understood when one compares calculated solutions of  $M_0 = 3.4$  and 3.5 with those of  $M_0 = 3.41485$ . The critical condition for occurring the jump in  $\beta_1=\beta_2$  double roots is now found to be the  $\alpha_1=\beta_1=\beta_2$  triple-root condition at  $M_0=3.41485, \theta_1=36.4344$ , shown in Fig. 3(b). One observes that the  $\alpha_1$  solutions cease to become physically realistic, for they are unable to move above  $D_2$  for  $M_0 > 3.41485$ . After the occurrence of  $\alpha_1=\beta_1=\beta_2, \alpha_1$  and  $\beta_2$  disappear immediately, and the  $\beta_1$  moves towards the forward-facing, then backward-facing branches of the reflected shock polar. From the incident polar viewpoint, the  $\beta_1$  moves from the weak to the strong branches. As for the various specific MR solutions, they are marked in Fig. 3. Most interesting cases are  $\alpha_1=\beta_2$  roots whose first appearance is the merge of the  $\alpha_1$  and  $\beta_2$  roots and their second appearance is the separation of these two roots, when  $M_0 > 3.41485$ . Finally, this obtained jump behavior of  $\beta_1=\beta_2$  double-root line, occurring at  $M_0=3.41485, 29.8438^\circ \leq \theta_1 \leq 36.4344^\circ$ , is added to the map of the multiplicity of theoretical three-shock solutions of steady MR of perfect diatomic gases on the ( $\theta_1, M_0$ ) plane. This is shown in Fig. 5(a). Important locations delineating different regimes of multiplicities of steady MR are marked as points a to k. Their definitions are given accordingly there. Locally enlarged view near the  $\beta_1=\beta_2$  jump of 5(a) illustrating various separating or limiting properties of steady MR solution curves are shown in Fig. 5(b).

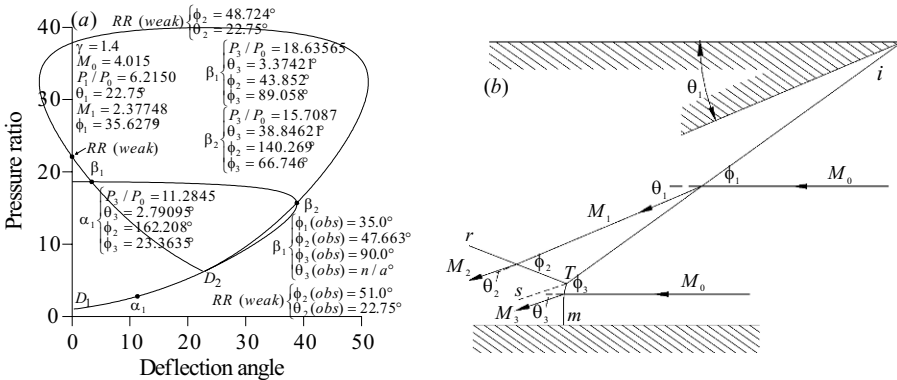
### 4 Conclusions

The existence of the jump in  $\beta_1=\beta_2$  double roots in the three-shock theoretical solutions of steady Mach reflections on the ( $\theta_1, M_0$ ) plane is determined for the first time,  $\theta_1$  is flow reflection behind the incident shock,  $M_0$  is the incident shock Mach number. This jump behavior of  $\beta_1=\beta_2$  double roots explains the occurrence of newly found  $\alpha_1=\beta_2$  double

roots of multiple three-shock theoretical solutions of steady MR in perfect diatomic and triatomic gases. The critical condition determining the location of  $M_0$  of this jump, for gas specific heats ratio of 1.4, is obtained to occur at  $\alpha_1 = \beta_1 = \beta_2$  triple roots where  $M_0 = 3.41485$ . There are two findings closely associated with this jump behavior of  $\beta_1 = \beta_2$  double roots: 1, the  $\alpha_1$  solutions cease to become physically meaningful for  $M_0 > 3.41485$ ; 2,  $\alpha_1 = \beta_2$  double roots do not exist for  $M_0 < 3.41485$ .

## References

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**Fig. 1.** Steady MR shock polar diagram (a) showing multiple solutions and the physical plane of the  $\beta_1$  solution for  $M_0 = 4.015$ ,  $\theta_1 = 22.75^\circ$ ,  $\gamma = 1.4$ , where i, incident shock; r, reflected shock; m, Mach stem; s, slipstream. (0), (1), (2), (3), respectively, are flow regions as defined,  $\phi_n$ , wave angles,  $\theta_n$ , deflection angles, T, triple-point,  $\chi$ , triple-point angle,  $M_s$ , incident shock Mach number,  $\theta_w$ , wedge angle,  $M_n$ , flow Mach number.

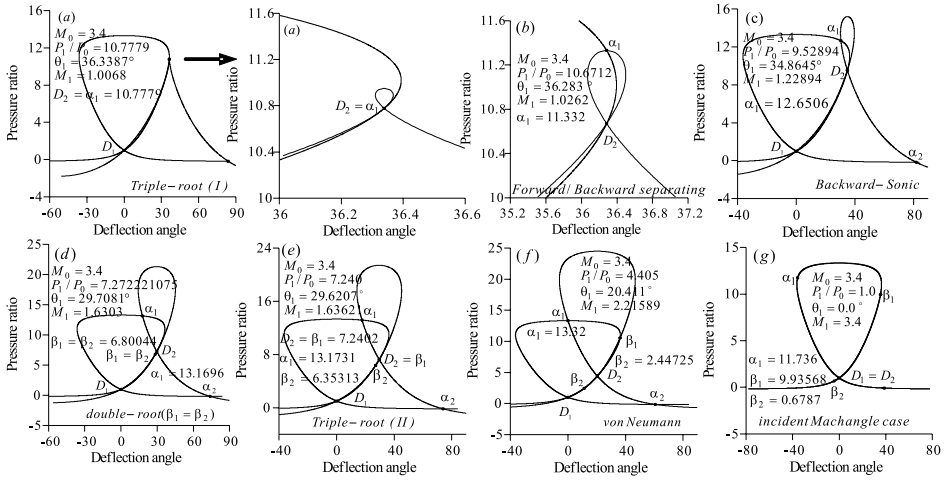


Fig. 2. Sequential  $(p-\theta)$  shock polar solutions of steady MR of  $M_0 = 3.4$

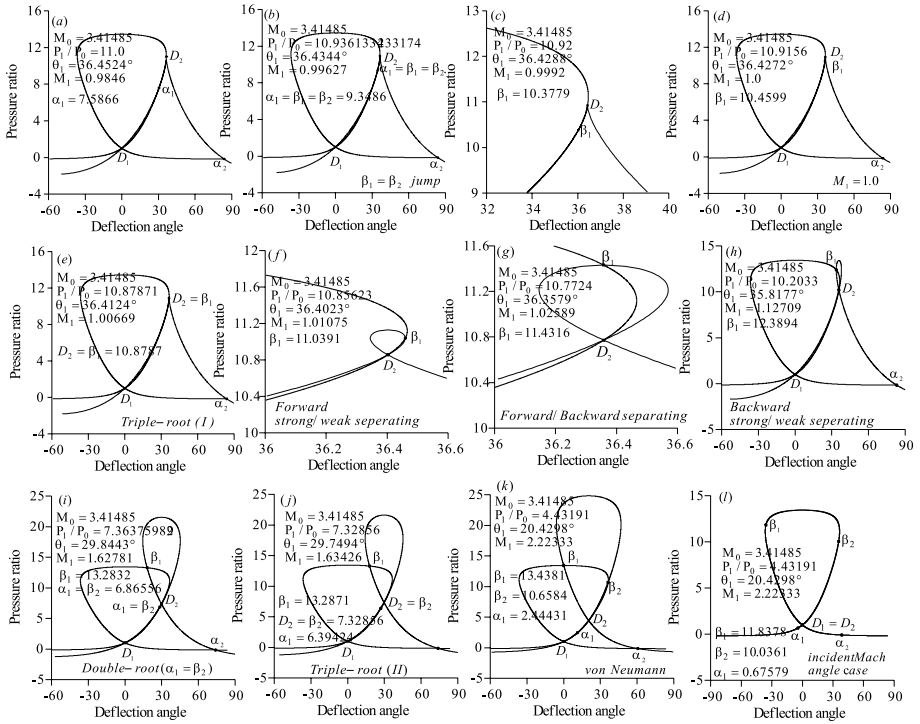


Fig. 3. Sequential  $(p-\theta)$  shock polar solutions of steady MR of  $M_0 = 3.41485$

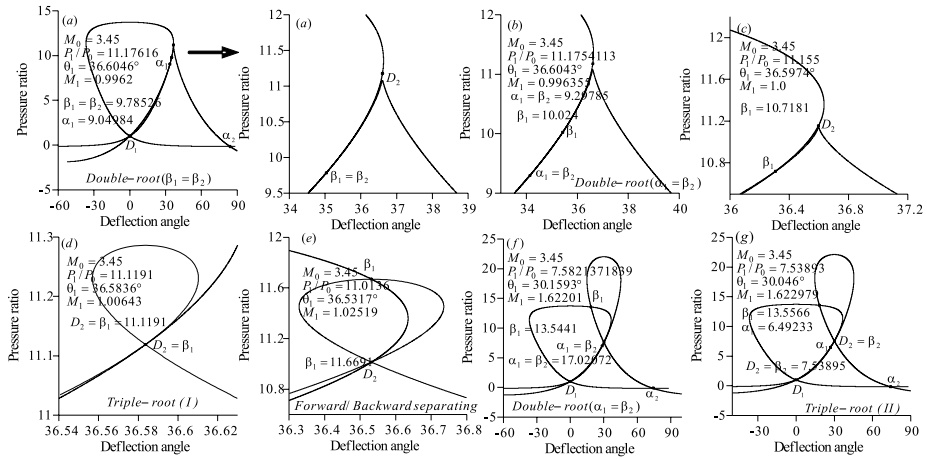


Fig. 4. Sequential (p-θ) shock polar solutions of steady MR of  $M_0 = 3.45$

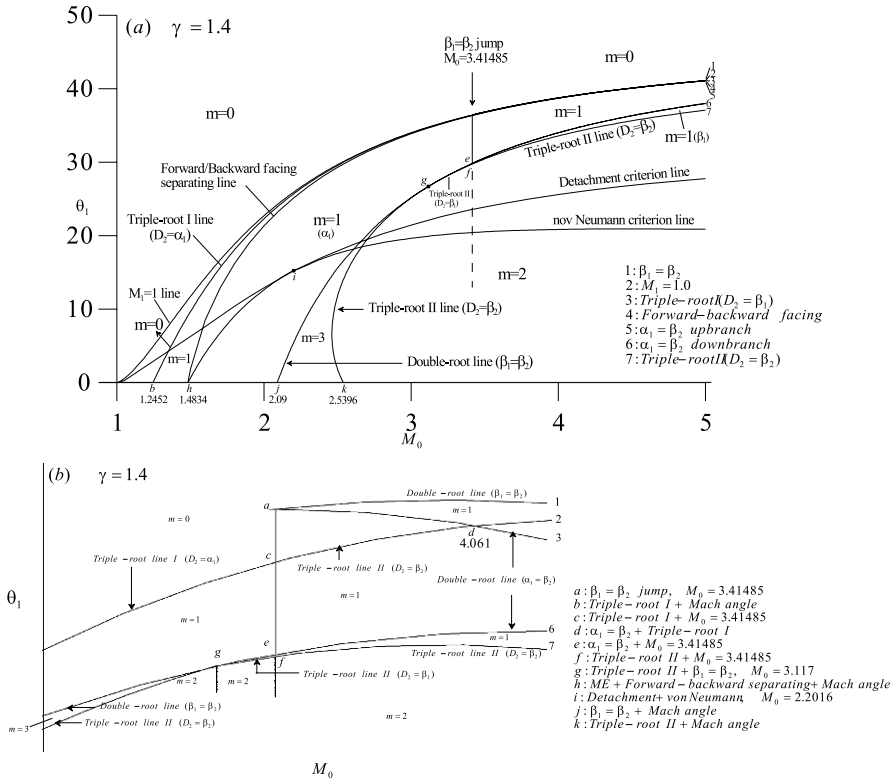


Fig. 5. The map of multiplicity of theoretical three-shock solutions of steady MR in perfect diatomic gases on the  $(\theta_1, M_0)$  plane. (b) Locally enlarged view (not in proportional to actual curves) near the  $\beta_1 = \beta_2$  jump showing solution curves of  $\beta_1 = \beta_2$  jump and various separating and limiting conditions of different regimes of (a).