

New Research in Nature Inspired Algorithms for Mobility Management in GSM Networks

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Abstract. Mobile Location Management (MLM) is an important and complex telecommunication problem found in mobile cellular GSM networks. Basically, this problem consists in optimizing the number and location of paging cells to find the lowest location management cost. There is a need to develop techniques capable of operating with this complexity and used to solve a wide range of location management scenarios. Nature inspired algorithms are useful in this context since they have proved to be able to manage large combinatorial search spaces efficiently. The aim of this study is to assess the performance of two different nature inspired algorithms when tackling this problem. The first technique is a recent version of Particle Swarm Optimization based on geometric ideas. This approach is customized for the MLM problem by using the concept of Hamming spaces. The second algorithm consists of a combination of the Hopfield Neural Network coupled with a Ball Dropping technique. The location management cost of a network is embedded into the parameters of the Hopfield Neural Network. Both algorithms are evaluated and compared using a series of test instances based on realistic scenarios. The results are very encouraging for current applications, and show that the proposed techniques outperform existing methods in the literature.

Keywords: Mobile Location Management, GSM Cellular Networks, Geometric Particle Swarm Optimization, Hopfield Neural Network.

1 Introduction

Mobility Management becomes a crucial issue when designing infrastructure for wireless mobile networks. In order to route incoming calls to appropriate mobile terminals, the network must keep track of the location of each mobile terminal. Mobility management requests are often initiated either by a mobile terminal movement (crossing a cell boundary) or by deterioration of the quality of a received signal in a currently allocated channel. Due to the expected increase in the usage of wireless services in the future, the next generation of mobile networks should be able to support a huge number of users and their bandwidth requirements [1,4].

Several strategies for Mobility Management have been used in the literature being the location area (LA) scheme one of the most popular [6,11]. An analogous strategy is the *Reporting Cells* (RC) scheme suggested in [3]. In RC, a subset of cells in the network is designated as reporting cells. Each mobile terminal performs a location update only when it enters one of these reporting cells. When a call arrives, the search is confined to the reporting cell the user last reported and the neighboring bounded nonreporting cells. It was shown in [3] that finding an optimal set of reporting cells, such that the location management cost is minimized, is an NP-complete problem. For this reason, bioinspired algorithms have been commonly used to solve this problem [7,10].

In this work, we use two nature inspired algorithms to assign the reporting cells of a network following the RC scheme. The first algorithm, called Geometric Particle Swarm Optimization (GPSO), is a generalization of the Particle Swarm Optimization for virtually any solution representation, which works according to a geometric framework. The second technique combines a Hopfield Neural Network with a Ball Dropping (HNN+BD) mechanism. Our contributions are both to perform better with respect to existing works and to introduce the GPSO algorithm for solving Telecommunications problems. In addition, these two techniques are experimentally assessed and compared from different points of view such as quality of the solutions, the robustness and design issues.

The remaining of the paper is organized as follows: Section 2 briefly explains the Mobility Management problem. The two algorithms, GPSO and HNN+BD, are described in sections 3 and 4 respectively. After that, Section 5 presents a number of experiments and results that show the applicability of the proposed approaches to this problem. Finally, conclusions are drawn in Section 6.

2 The Mobility Management Problem

Basically, the Mobility (location) Management problem consists in reducing the total cost of managing a mobile cellular network. Two factors take part when calculating the total cost: the updating cost and the paging cost. The updating cost is the portion of the total cost due to location updates performed by roaming mobile terminals in the network. The paging cost is caused by the network during a location inquiry when the network tries to locate a user¹.

According to the reporting cells scheme, there are two types of cells: reporting cells (RC) and non-reporting cells (nRC). A neighborhood is assigned to each reporting cell, which consists of all nRC that must also page the user in case of an incoming call. For both RC and nRC, a *vicinity* factor is calculated representing the maximum number of reporting neighbors for each cell that must page the user (including the cell itself) in case of an incoming call. Obviously, the vicinity factor of each RC is the number of neighbors it has (see Fig. 1).

¹ Other costs like the cost of database management to register user's locations or the cost of the wired network (backbone) that connects the base stations to each other were not considered here, since these costs are assumed to be the same for all location management strategies and hence aren't contemplated in comparisons.

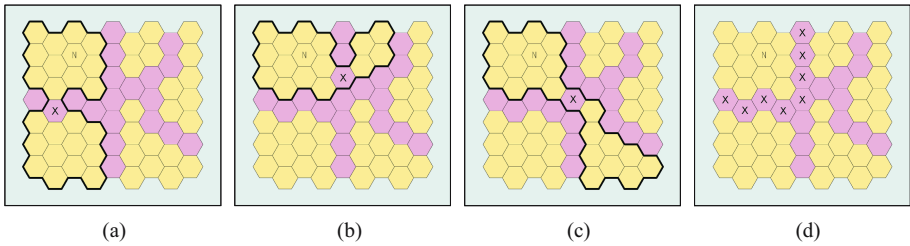


Fig. 1. Cells marked as ‘N’ belong to the neighborhoods of at least three RCs (grey cells). For example, the number of neighbors for cell ‘X’ is 25, 17, and 22 for (a), (b) and (c) respectively (25 to consider the worst case). However, if a nRC belongs to more than two neighborhoods the calculation must be done for all of them, and then, the maximum number is considered as the vicinity factor for this nRC. For example, the nRC marked as ‘N’ is a part of the neighborhood of all cells marked as ‘X’ in (d).

For nRC, the vicinity factor is calculated based on the fact that each nRC might be in the neighborhood of more than one RC, the maximum number of paging neighbors that contains such a cell is considered its vicinity factor.

Therefore, to calculate the total cost of the network location management, the general cost function is formulated as:

$$Cost = \beta \times \sum_{i \in S} N_{LU}(i) + \sum_{i=0}^N N_P(i) \times V(i) \quad (1)$$

where, $N_{LU}(i)$ is the number of location updates for reporting cell number i , $N_P(i)$ is the number of arrived calls for cell i , $V(i)$ is the vicinity factor for cell i , S is the set of cells defined as reporting cells, and N is the total number of cells in the network. β is a constant representing the cost ratio of a location update to a paging transaction in the network (typically $\beta = 10$). This function is used either as *fitness function* by the GPSO or *energy function* by the HNN.

3 Geometric Particle Swarm Optimization

The recent Geometric Particle Swarm Optimization (GPSO) [5,2], enables us to generalize PSO to virtually any solution representation in a natural and straightforward way, extending the search to richer spaces, such as combinatorial ones. This property was demonstrated for the cases of Euclidean, Manhattan and Hamming spaces in the referenced work.

The key issue in this approach consists of using a multi-parental recombination of particles which leads to the generalization of a *mask-based crossover* operation, proving that it respects four requirements for being a *convex combination* in a certain space (see [5] for a complete explanation). This way, the mask-based crossover operation substitutes the classical *movement* in PSO, based on the *velocity* and *position update* operations, only suited for continuous spaces.

For Hamming spaces, which is the focus of this work, a *three-parent mask-based crossover* (3PMBCX) was defined in a straightforward way:

Definition 1. Given three parents a , b and c in $\{0,1\}^n$, generate randomly a crossover mask of length n with symbols from the alphabet $\{a,b,c\}$. Build the offspring o filling each position with the bit from the parent appearing in the crossover mask at the position.

In a convex combination, the weights w_a , w_b and w_c indicate for each position in the crossover mask the probability of having the symbols a , b or c .

The pseudocode of the GPSO algorithm for Hamming spaces is illustrated in Algorithm 1. For a given particle i , three parents take part in the 3PMBCX operator (line 13): the current position x_i , the social best position g_i and the historical best position found h_i (of this particle). The weight values w_a , w_b and w_c indicate for each element in the crossover mask the probability of having values from the parents x_i , g_i or h_i respectively. A constriction of the geometric crossover forces w_a , w_b and w_c to be non-negative and add up to one.

Algorithm 1. GPSO for Hamming spaces

```

1:  $S \leftarrow \text{SwarmInitialization}()$ 
2: while not stop condition do
3:   for each particle  $x_i$  of the swarm  $S$  do
4:     evaluate( $x_i$ )
5:     if  $\text{fitness}(x_i)$  is better than  $\text{fitness}(h_i)$  then
6:        $h_i \leftarrow x_i$ 
7:     end if
8:     if  $\text{fitness}(h_i)$  is better than  $\text{fitness}(g_i)$  then
9:        $g_i \leftarrow h_i$ 
10:    end if
11:   end for
12:   for each particle  $x_i$  of the swarm  $S$  do
13:      $x_i \leftarrow \text{3PMBCX}((x_i, w_a), (g_i, w_b), (h_i, w_c))$ 
14:     mutate( $x_i$ )
15:   end for
16: end while
17: Output: best solution found

```

Since the GPSO for Mobility Management was developed for Hamming space, each particle i of the swarm consists of a binary vector $x_i = (x_{i1}, x_{i2}, \dots, x_{in})$ representing a reporting cell configuration, where each element x_{ij} represents a cell of the network; x_{ij} can have a value of either “0”, representing a nRC, or “1”, representing a RC. For example, in an 6×6 network, the particle position will have a length (n) of 36.

4 Hopfield Neural Network with Ball Dropping

In this approach, the Ball Dropping technique is used as the backbone of the algorithm that employs the HNN as its optimizer, and is inspired by the natural behavior of individual balls when they are dropped onto a non-even plate (a plate with troughs and crests). As can be expected, the balls will spontaneously move to the concave areas of the plate, and in a natural process, find the minimum of the plate. A predefined number of balls are dropped onto several random positions on the plate, which is equivalent to the random addition of a predefined number of paging cells to the current paging cell configuration of the network.

As a result, after dropping a number of balls on the plate the energy value of the network increases suddenly and the HNN optimizer tries to reduce it by moving the balls around. The following procedure summarizes the basic form of this algorithm.

Algorithm 2. Ball Dropping Mechanism

- 1: Drop a predefined number of balls onto random positions
 - 2: **repeat**
 - 3: Shake the plate
 - 4: Remove unnecessary balls
 - 5: **until** location of balls does not lead to any better configuration
 - 6: **Output:** best solution found
-

In relation to Equation 1, the state vector of the HNN, ‘X’, is considered to have two different components for location updates and call arrival as follows:

$$X = [x_0 \ x_1 \ \wedge \ x_{N-1} \ x_N \ x_{N+1} \ \wedge \ x_{2N-1}]^T \quad (2)$$

where x_0 to x_{N-1} is the location updates part, x_N to x_{2N-1} is the call arrival part and ‘N’ is the total number of cells in the network. This HNN model is designed to represent a RC configuration network, and then, tries to modify its RCs in order to reduce the total cost gradually. To summarize this explanation, we refer the reader to [8] where other aspects like generating a initial solution generation, definition of function to modify the state vector and reduction of the number of variations are given completely.

5 Simulation Results

In this section we present the experiments conducted to evaluate and compare the proposed GPSO and HNN+BD. We firstly give some details of the test network instances used. The experiments with both algorithms are presented and analyzed afterwards. We have made 10 independent runs for each algorithm and instance. Comparisons are made from different points of view such as the performance, robustness, quality of solutions and even design issues concerning the two algorithms. Finally, comparisons with other optimizers found in the literature are encouraging since our algorithms obtain competitive solutions which even beat traditional metaheuristic techniques in the previous state of the art.

5.1 Test GSM Network Instances

In almost all of the previous research in the literature, the cell attributes of the network are generated randomly. In general, two independent attributes for each cell are considered: the number of call arrivals (NP) and the number of location updates (NLU), which are set at random according to a normal distribution. However, these numbers are highly correlated in real world scenarios. Therefore, in this work, a more robust and realistic approach is used to seed the initial solutions, and consequently, the network attributes of each cell [9]. This makes the configuration of the solutions obtained in this work to be more realistic.

Therefore, a benchmark of twelve different instances were generated here to be used for testing GPSON and HNN+BD. The numeric values shaping the test networks configurations are given in tables below² for future reproduction of our results.

Test-Network 4				Test-Network 5				Test-Network 6				Test-Network 1				Test-Network 2				Test-Network 3									
Cell	MLU	NP	Cell	MLU	NP	Cell	MLU	NP	Cell	MLU	NP	Cell	MLU	NP	Cell	MLU	NP	Cell	MLU	NP	Cell	MLU	NP	Cell	MLU	NP	Cell	MLU	NP
0	339	97	0	373	86	0	859	659	0	452	484	0	280	353	0	488	455	0	785	209	0	785	209	0	785	209	0	785	209
1	944	105	1	968	155	1	1561	621	1	767	377	1	762	438	1	762	438	1	762	438	1	762	438	1	762	438	1	762	438
2	588	103	2	284	99	2	450	93	2	960	294	2	686	589	2	686	589	2	686	589	2	686	589	2	686	589	2	686	589
3	1478	500	3	571	119	3	599	98	3	548	518	3	617	503	3	617	503	3	617	503	3	617	503	3	617	503	3	617	503
4	899	545	4	431	132	4	535	151	4	591	365	4	447	403	4	447	403	4	447	403	4	447	403	4	447	403	4	447	403
5	793	495	5	451	97	5	425	138	5	1451	1355	5	978	560	5	978	560	5	978	560	5	978	560	5	978	560	5	978	560
6	646	127	6	693	153	6	1219	590	6	816	438	6	1349	648	6	1349	648	6	1349	648	6	1349	648	6	1349	648	6	1349	648
7	1159	119	7	1256	149	7	1638	137	7	574	415	7	552	431	7	552	431	7	552	431	7	552	431	7	552	431	7	552	431
8	1184	115	8	847	112	8	991	114	8	647	366	8	608	412	8	608	412	8	608	412	8	608	412	8	608	412	8	608	412
9	854	95	9	1412	173	9	646	72	9	889	435	9	1305	681	9	1305	681	9	1305	681	9	1305	681	9	1305	681	9	1305	681
10	1503	526	10	1350	163	10	587	97	10	1105	510	10	966	508	10	966	508	10	966	508	10	966	508	10	966	508	10	966	508
11	753	140	11	711	135	11	361	84	11	736	501	11	466	408	11	466	408	11	466	408	11	466	408	11	466	408	11	466	408
12	744	120	12	356	81	12	559	101	12	528	470	12	654	503	12	654	503	12	654	503	12	654	503	12	654	503	12	654	503
13	819	103	13	951	171	13	787	110	13	423	376	13	710	530	13	710	530	13	710	530	13	710	530	13	710	530	13	710	530
14	542	61	14	2282	1016	14	1738	191	14	1058	569	14	746	473	14	746	473	14	746	473	14	746	473	14	746	473	14	746	473
15	476	103	15	2276	1067	15	1433	165	15	434	361	15	282	336	15	282	336	15	282	336	15	282	336	15	282	336	15	282	336
16	937	117	16	1217	139	16	562	87	16	208	90	16	338	64	16	338	64	16	338	64	16	338	64	16	338	64	16	338	64
17	803	89	17	341	96	17	404	63	17	393	112	17	438	89	17	438	89	17	438	89	17	438	89	17	438	89	17	438	89
18	817	181	18	337	87	18	342	78	18	152	46	18	186	93	18	186	93	18	186	93	18	186	93	18	186	93	18	186	93
19	888	102	19	1210	121	19	595	97	19	271	84	19	247	80	19	247	80	19	247	80	19	247	80	19	247	80	19	247	80
20	452	103	20	2428	979	20	1312	164	20	1304	591	20	665	584	20	665	584	20	665	584	20	665	584	20	665	584	20	665	584
21	581	86	21	1104	171	21	1129	92	21	523	201	21	554	201	21	554	201	21	554	201	21	554	201	21	554	201	21	554	201
22	773	86	22	718	99	22	884	102	22	266	85	22	449	89	22	449	89	22	449	89	22	449	89	22	449	89	22	449	89
23	741	123	23	362	103	23	630	138	23	137	100	23	172	91	23	172	91	23	172	91	23	172	91	23	172	91	23	172	91
24	693	131	24	669	119	24	306	80	24	208	90	24	338	64	24	338	64	24	338	64	24	338	64	24	338	64	24	338	64
25	1535	576	25	1189	158	25	893	87	25	127	79	25	601	93	25	601	93	25	601	93	25	601	93	25	601	93	25	601	93
26	921	128	26	1032	157	26	803	82	26	393	112	26	438	89	26	438	89	26	438	89	26	438	89	26	438	89	26	438	89
27	1225	73	27	620	93	27	977	136	27	152	46	27	186	93	27	186	93	27	186	93	27	186	93	27	186	93	27	186	93
28	1199	163	28	1350	163	28	1350	163	28	152	46	28	186	93	28	186	93	28	186	93	28	186	93	28	186	93	28	186	93
29	710	139	29	596	112	29	1225	641	29	187	116	29	144	64	29	144	64	29	144	64	29	144	64	29	144	64	29	144	64
30	782	484	30	367	74	30	421	158	30	265	82	30	342	103	30	342	103	30	342	103	30	342	103	30	342	103	30	342	103
31	879	477	31	369	108	31	684	163	31	552	99	31	603	515	31	603	515	31	603	515	31	603	515	31	603	515	31	603	515
32	1553	532	32	418	120	32	689	99	32	565	83	32	884	528	32	884	528	32	884	528	32	884	528	32	884	528	32	884	528
33	613	68	33	220	102	33	569	115	33	487	95	33	652	16	33	652	16	33	652	16	33	652	16	33	652	16	33	652	16
34	1044	121	34	759	120	34	1554	314	34	277	114	34	388	62	34	388	62	34	388	62	34	388	62	34	388	62	34	388	62
35	400	148	35	344	117	35	733	534	35	444	109	35	384	68	35	384	68	35	384	68	35	384	68	35	384	68	35	384	68

Test-Network 10				Test-Network 11				Test-Network 12						
Cell	MLU	NP	Cell	MLU	NP	Cell	MLU	NP	Cell	MLU	NP	Cell	MLU	NP
0	144	83	0	233	85	0	233	85	0	144	83	0	144	83
1	304	98	1	665	584	1	665	584	1	304	98	1	304	98
2	201	66	2	554	201	2	554	201	2	201	66	2	201	66
3	266	85	3	449	89	3	449	89	3	266	85	3	266	85
4	137	100	4	172	91	4	172	91	4	137	100	4	137	100
5	208	90	5	338	64	5	338	64	5	208	90	5	208	90
6	127	79	6	201	93	6	201	93	6	127	79	6	127	79
7	393	112	7	438	89	7	438	89	7	393	112	7	393	112
8	152	46	8	186	93	8	186	93	8	152	46	8	152	46
9	187	116	9	144	64	9	144	64	9	187	116	9	187	116
10	265	82	10	342	103	10	342	103	10	265	82	10	265	82
11	552	99	11	603	515	11	603	515	11	552	99	11	552	99
12	565	83	12	884	528	12	884	528	12	565	83	12	565	83
13	487	95	13	652	16	13	652	16	13	487	95	13	487	95
14	277	114	14	388	62	14	388	62	14	277	114	14	277	114
15	444	109	15	384	68	15	384	68	15	444	109	15	444	109
16	387	95	16	417	77	16	417	77	16	387	95	16	387	95
17	752	83	17	559	95	17	559	95	17	752	83	17	752	83
18	457	76	18	403	70	18	403	70	18	457	76	18	457	76
19	271	84	19	247	80	19	247	80	19	271	84	19	271	84
20	249	80	20	233	79	20	233	79	20	249	80	20	249	80
21	468	90	21	408	86	21	408	86	21	468	90	21	468	90
22	469	74	22	550	83	22	550	83	22	469	74	22	469	74
23	612	103	23	538	93	23	538	93	23	612	103	23	612	103
24	571	114	24	431	97	24	431	97	24	571	114	24	571	114
25	1335	678	25	604	99	25	604	99	25	1335	678	25	1335	678
26	802	112	26	347	65	26	347	65	26	802	112	26	802	112
27	656	87	27	404	91	27	404	91	27	656	87	27	656	87
28	731	124	28	538	75	28	538	75	28	731	124	28	731	124
29	274	89	29	290	84	29	290	84	29	274	89	29		

5.2 Experimental Results

We have conducted different experiments with several configurations of GPSO and HNN+BD depending on the test network used. Since the two algorithms perform quite different operations, we have set the parameters (Table 1) after preliminary executions of the two algorithms (with each instance) where the computational effort in terms of time and number of evaluations was balanced.

Table 1. Parameter settings for HNN+BD and GPSO. The columns indicate: the number of dropping balls ($N.DroppBalls$) and the number of trials ($N.Trials$) for HNN+BD. For GPSO are reported: the number of particles ($N.Particles$), the crossover probability (P_{cross}), the mutation probability (P_{mut}) and the weighted values (w_a , w_b and w_c).

Test Network	HNN+BD		GPSO			
$Dim.$	$N.DroppBalls$	$N.Trials$	$N.Particles$	P_{cross}	P_{mut}	$w_a + w_b + w_c$
(4 × 4)	7	3	20	0.9	0.1	0.33+0.33+0.33
(6 × 6)	10	5	50			
(8 × 8)	15	5	100			
(10 × 10)	15	5	120			

After the initial experimentation, several results were obtained; they are shown in Table 2. The first column contains the number and dimension (in parenthesis) of each test network. Three values are presented for each evaluated algorithm: the best cost (out of 10 runs), the average cost ($Aver.$) of all the solutions, and the deviation ($Dev.$) percentage from the best cost.

As it can be seen from the results, the two algorithms have similar performance in almost all of the instances, although there are a few differences for the large test networks. For example, GPSO obtains better solutions in Test-Network 7 and 10, while, HNN+BD obtains a better solution in Test-Network 11. In addition, it can be noticed that the deviation percentage from the best cost is generally lower in GPSO than in HNN+BD, specially for the smaller test networks. This behavior leads us to believe that the GPSO approach is more robust than HNN+BD, but just slightly.

Table 2. Results for Test Networks obtained by HNN+BD and GPSO

Test Network	HNN+BD			GPSO		
	$No.(Dim.)$	$Best$	$Aver.$	$Dev.$	$Best$	$Aver.$
1 (4 × 4)	98,535	98,627	0.09%	98,535	98,535	0.00%
2 (4 × 4)	97,156	97,655	0.51%	97,156	97,156	0.00%
3 (4 × 4)	95,038	95,751	0.75%	95,038	95,038	0.00%
4 (6 × 6)	173,701	174,690	0.56%	173,701	174,090	0.22%
5 (6 × 6)	182,331	182,430	0.05%	182,331	182,331	0.00%
6 (6 × 6)	174,519	176,050	0.87%	174,519	175,080	0.32%
7 (8 × 8)	308,929	311,351	0.78%	308,401	310,062	0.53%
8 (8 × 8)	287,149	287,149	0.00%	287,149	287,805	0.22%
9 (8 × 8)	264,204	264,695	0.18%	264,204	264,475	0.10%
10 (10 × 10)	386,351	387,820	0.38%	385,972	387,825	0.48%
11 (10 × 10)	358,167	359,036	0.24%	359,191	359,928	0.20%
12 (10 × 10)	370,868	374,205	0.89%	370,868	373,722	0.76%

Another obvious difference between HNN+BD and GPSO lies in the behavior of each algorithm. This can be observed in Fig. 2, where we show a graphical representation of algorithm runs for the different evaluated networks. Each graph, corresponding to one of the twelve test networks, plots a representative trace of the execution of each algorithm tracking the best solution obtained versus the number of iterations. On the one hand, GPSO shows a typical behavior in evolutionary metaheuristics, that is, it tends to converge from the solutions in the initial population to an optimal reporting cell arrangement. Graphically, the GPSO operation is represented by a monotonous decreasing (minimization) curve. On the other hand, HNN+BD carries out a different searching strategy, as from the initialization, it provokes frequent shaking scenarios in the population with the purpose of gradually diversifying and intensifying the search. These “shakes” are carried out by means of the Ball Dropping technique (Section 4) when no improvement in the overall condition of the network is detected, so the frequency of this operation is variable.

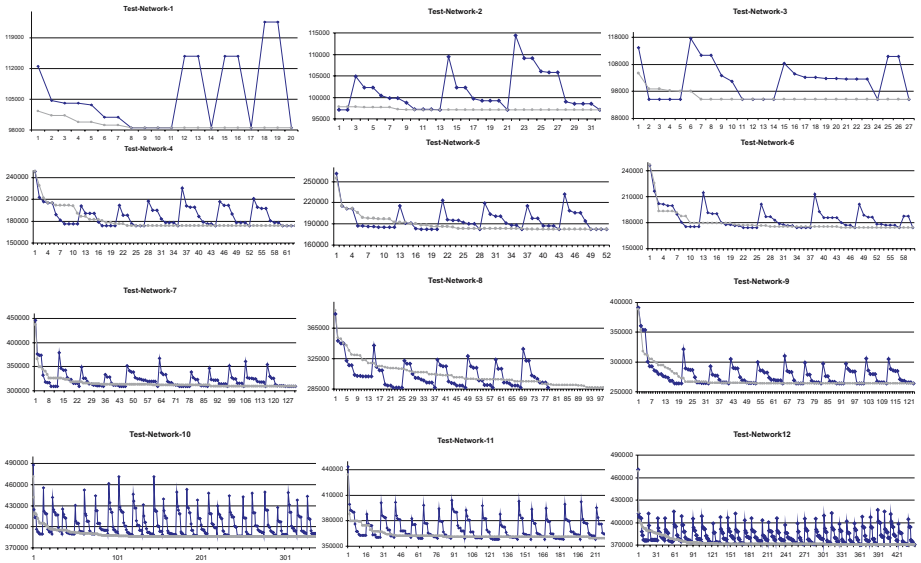


Fig. 2. Cost values level (Y axis) versus iterations (X axis) of all the test networks. Each graphic plots the energy level obtained, we track the evolution of the HNN+BD algorithm (black line with peaks and valleys), and the fitness level in the evolution of the GPSO algorithm (concave grey curve).

Evidently, as Fig. 2 shows, the number of drops in larger test networks is higher than in smaller ones, since the number of iterations required here to converge is also higher. Graphically, this behavior produces intermittent peaks and valleys in the evolution line.

From the point of view of the quality of solutions, as expected, optimal reporting cell configurations for all test networks split the network into smaller sub-networks by clustering the full area. This property can be seen in the large instances in a much clearer way than in the short ones (Fig. 3).

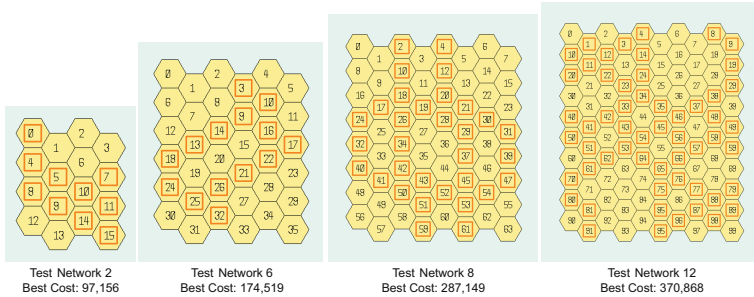


Fig. 3. Paging Cells (with squares) configurations obtained as solutions by the two algorithms (the same solutions) in Test Network 2, Test Network 6, Test Network 8 and Test Network 12. Neighborhood area clusters are easily visible in larger instances. All the legends show the Best Cost found by both algorithms.

5.3 Comparison with Other Optimizers

To the best of our knowledge a Genetic Algorithm (GA) is the only algorithm that can be compared against in this work. The modeling of the problem, the quality of the initial population, and the number of iterations are the main design issues that can affect the performance of the GA. When comparing the proposed approaches with a GA implementation given in [7], one can observe two advantages in terms of convergence and quality of solution in our two new approaches.

Despite the general good behavior of the GA, our two approaches generate a better solution when solving the Test-Network-2 (6×6 instance provided in [7]) in additional experiments. The energy value obtained by the GA is 229,556 with a total of 26 paging cells in the network, while, the cost obtained by HNN+BD in this work is 211,278 with 24 paging cells, and the GPSO obtained a cost of 214,313 with 23 paging cells. With respect to HNN+BD, a reasonable explanation for this difference could be due to the setup parameters used for the GA in [7]. However, our GPSO uses a similar setup parameters compared to the GA, providing a better solution with a smaller number of paging cells.

6 Conclusions

This paper addresses the use of two nature inspired approaches to solve the Mobile Location Management problem found in telecommunications: a new binary Particle Swarm Optimization algorithm called GPSO, and an algorithm based on a Hopfield Neural Network hybridized with the Balls Dropping Technique.

The problem is described and tackled following the Reporting Cells Scheme. In addition, the design and operation of HNN+BD and GPSO are discussed. Twelve test networks of different dimensions, generated following realistic scenarios of mobile networks, were for the first time used in this work. In addition, a comparison of the algorithms is carried out focusing on the performance, robustness, and design issues.

In conclusion, simulation results are very encouraging and show that the proposed algorithms outperform existing methods. Both approaches prove themselves as very powerful optimizers providing fast and good quality solutions.

This work has been carried out as a continuation of previous works where metaheuristics techniques were applied to solve the Mobile Location Management problem. For further work, we are interested in evaluating new test networks under different conditions of topology and dimension. In addition, new experiments will be carried out using different location area schemes.

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