Constructing Physically Consistent Subgrid-Scale Models for Large-Eddy Simulation of Incompressible Turbulent Flows

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Abstract We studied the construction of subgrid-scale models for large-eddy simulation of incompressible turbulent flows, focusing on consistency with important mathematical and physical properties. In particular, we considered the symmetries of the Navier-Stokes equations, and the near-wall scaling and dissipation behavior of the turbulent stresses. After showing that existing models do not all satisfy the desired properties, we discussed a general class of subgrid-scale models based on the local filtered velocity gradient. We provided examples of models from this class that preserve several of the symmetries of the Navier-Stokes equations and exhibit the same near-wall scaling behavior as the turbulent stresses. Furthermore, these models are capable of describing nondissipative effects.

1 Introduction

It is well known that the governing equations of fluid dynamics, the Navier-Stokes equations, are form invariant under transformations like instantaneous rotations of the coordinate system and the Galilean transformation [13]. Such transformations, also referred to as symmetries, play an important physical role, because they make sure that the description of fluids is the same in all inertial frames of reference. Furthermore, they relate to conservation and scaling laws [14]. To ensure physical consistency it is desirable that the basic equations of large-eddy simulation, which are used to study the large-scale behavior of turbulent flows, satisfy the same principles. Speziale [17] was the first to emphasize the importance of Galilean invariance of subgrid-scale models for large-eddy simulation. Later, Oberlack [10] formulated

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requirements to make subgrid-scale models compatible with all the symmetries of the Navier-Stokes equations. Aside from preserving symmetries, it is desirable that subgrid-scale models share some basic properties with the turbulent stresses, such as the observed near-wall scaling [2] and the dissipation behavior [20]. In the current work we aim to construct subgrid-scale models that preserve these and other properties of the Navier-Stokes equations and the turbulent stresses.

In Sect. 2 we will outline several model requirements, after which, in Sect. 3, we analyze the properties of existing subgrid-scale models. Section 4 is devoted to the construction of new subgrid-scale models. Conclusions are presented in Sect. 5.

2 Model Constraints

In large-eddy simulation, the large-scale behavior of incompressible turbulent flows is described by the filtered Navier-Stokes equations, [15]

$$\frac{\partial \bar{u}_i}{\partial x_i} = 0 , \qquad \frac{\partial \bar{u}_i}{\partial t} + \bar{u}_j \frac{\partial \bar{u}_i}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{u}_i}{\partial x_j \partial x_j} - \frac{\partial}{\partial x_j} \tau_{ij} . \tag{1}$$

The turbulent stresses, $\tau_{ij} = \overline{u_i u_j} - \overline{u}_i \overline{u}_j$, are not solely expressed in terms of the filtered velocity field and therefore have to be modeled. In what follows we will discuss requirements that make sure that specific properties of the Navier-Stokes equations and the turbulent stresses are preserved in this modeling process.

2.1 Symmetry Requirements

We would like to ensure that the basic equations of large-eddy simulation, (1) with a subgrid-scale model in place of the turbulent stresses, admit the same symmetries as the unfiltered Navier-Stokes equations. Assuming that the filtering operation does not destroy symmetry properties, we need the following transformation behavior for the modeled subgrid-scale stresses, τ^{mod} [10].

$$\hat{\tau}_{ii}^{\text{mod}} = \tau_{ii}^{\text{mod}} , \qquad (2)$$

$$\hat{\tau}_{ij}^{\text{mod}} = Q_{im} Q_{jn} \tau_{mn}^{\text{mod}} , \qquad (3)$$

$$\hat{\tau}_{ij}^{\text{mod}} = e^{-2a+2b} \tau_{ij}^{\text{mod}} , \qquad (4)$$

$$\hat{\tau}_{ij}^{\text{mod}} = R_{im}(t)R_{jn}(t)\tau_{mn}^{\text{mod}} \,. \tag{5}$$

In (2) the hat indicates the time (S1) or pressure translation (S2), or the generalized Galilean transformation (S3). Conditions (3) and (4) ensure invariance under, respectively, instantaneous rotations and reflections (S4), and scaling transformation (S5),

for an orthogonal matrix Q, and real a and b. Material frame-indifference in the limit of a two-component flow (S6) holds when (5) is satisfied for a constant-in-rate rotation about an axis perpendicular to the flow directions, described by R(t). In principle, (2) also has to hold under time reversal (S7) [10, 11, 14].

2.2 Near-Wall Scaling Requirements

Using numerical simulations, Chapman and Kuhn [2] have revealed the near-wall scaling behavior of the time-averaged turbulent stresses. We will require that the modeled stresses show the same asymptotic behavior, but then instantaneously (P1). Denoting the wall-normal distance by x_2 , we can express this property as

This ensures that, for instance, dissipative effects fall off quickly enough near walls.

2.3 Requirements Relating to the Production of Subgrid-Scale Kinetic Energy

We now focus on the production of subgrid-scale kinetic energy, also referred to as subgrid dissipation. Given the rate-of-strain tensor, see (12), it can be expressed as

$$D_{\tau} = -\mathrm{tr}(\tau \,\bar{S}) \,. \tag{7}$$

Vreman's Model Requirements Vreman [20] requires that the modeled production of subgrid-scale kinetic energy vanishes for flows for which the actual production is known to be zero. Preferably, also the converse is true. In summary, P2a,b:

$$D_{\tau^{\text{mod}}} = 0 \text{ when } D_{\tau} = 0 , \qquad (8)$$

$$D_{\tau^{\mathrm{mod}}} \neq 0 \text{ when } D_{\tau} \neq 0 .$$
 (9)

These conditions are aimed at making sure that subgrid-scale models are neither overly (P2a), nor underly dissipative (P2b).

Nicoud et al. Model Requirements On the basis of physical grounds, Nicoud et al. [8] argue that certain flows cannot be maintained if energy is transported to subgrid scales. They therefore require that the modeled subgrid dissipation vanishes for all two-component flows (P3a) and for the pure axisymmetric strain (P3b). Note

that these requirements are not compatible with the mathematical properties of the turbulent stresses as found by Vreman [20] and thus not with requirements P2a,b.

Consistency with the Second Law of Thermodynamics In turbulent flows, energy can be transported from large to small scales (forward scatter) and vice versa (backscatter). The second law of thermodynamics requires that the net transport of energy is of the former type, P4 [14]:

$$D_{\tau^{\text{mod}}} \ge -2\nu \operatorname{tr}(\bar{S}^2) . \tag{10}$$

3 Analysis of Existing Subgrid-Scale Models

Before aiming to create subgrid-scale models that satisfy the constraints discussed in the previous section, we present a summary of the properties of several existing models in Table 1. A detailed discussion of results is omitted, but observe that the models do not necessarily satisfy all the desired properties. Because we assume the use of an isotropic filter, results relating to properties P2a,b differ slightly from those of Vreman [20].

4 Examples of Physically Consistent Subgrid-Scale Models

The subgrid-scale models of Sect. 3 are all based on the local filtered velocity gradient. Looking for models of a similar form to satisfy the constraints of Sect. 2, we take [4, 6, 12]

$$\tau^{\text{mod}} = \alpha_0 I + \alpha_1 \bar{S} + \alpha_2 \bar{S}^2 + \alpha_3 \bar{\Omega}^2 + \alpha_4 (\bar{S}\bar{\Omega} - \bar{\Omega}\bar{S}) + \dots , \qquad (11)$$

where the filtered rate-of-strain and rate-of-rotation tensors are given by

$$\bar{S}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{u}_i}{\partial x_j} + \frac{\partial \bar{u}_j}{\partial x_i} \right) , \qquad \bar{\Omega}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{u}_i}{\partial x_j} - \frac{\partial \bar{u}_j}{\partial x_i} \right) , \tag{12}$$

and, by isotropy (S4), the coefficients can depend only on the tensor invariants

$$I_1 = \operatorname{tr}(\bar{S}^2), \ I_2 = \operatorname{tr}(\bar{\Omega}^2), \ I_3 = \operatorname{tr}(\bar{S}^3), \ I_4 = \operatorname{tr}(\bar{S}\bar{\Omega}^2), \ I_5 = \operatorname{tr}(\bar{S}^2\bar{\Omega}^2).$$
 (13)

We now aim to set this dependence in such a way that more constraints of Sect. 2 are fulfilled. Here it is important to keep in mind that the requirements of Nicoud et al. (P3a,b) are incompatible with those of Vreman (P2a,b). Furthermore, no two-dimensional material frame-indifferent quantities (S6) were found that satisfy both of Vreman's requirements. This may point to a limitation of the model ansatz (11).

Combining compatible constraints, we obtain a class of what we will call physically consistent subgrid-scale models. The simplest models in this class with the

| reflection invi behavior: P2a | triance; S5: sci zero subgrid | aling invarianc dissipation for | ce; S6: two-dim r laminar flow t | iensional mate vpes: P2b: no | rrial frame-ind nzero subgrid | ifference; S7: t dissipation for | ime reversal i nonlaminar fl | nvariance; P1: ow types; P3a: | the proper nea | rr-wall scaling dissipation for |
|----------------------------------|----------------------------------|------------------------------------|-------------------------------------|---------------------------------|----------------------------------|-------------------------------------|---------------------------------|----------------------------------|----------------|------------------------------------|
| two-compone | nt flows; P3b: : | zero subgrid d | issipation for th | ie pure axisyn | nmetric strain; | P4: consistency | / with the seco | nd law of ther | modynamics | - |
| | Smag. [16] | WALE [9] | Vreman [20] | σ [8] | QR [19] | S3PQR [18] | Clark [3] | EASSM [7] | Ex. 1 (14) | Ex. 2 (15) |
| S1-4 | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| S5 ^a | No | No | No | No | No | No | No | No | No | No |
| S6 | Yes | No | No | Yes | Yes | Yes ^b | No | No | Yes | Yes |
| S7 ^a | No | No | No | No | No | Yes ^b | Yes | No | Yes | No |
| P1 | No | Yes | No | Yes | No | Yes | No | No | Yes | Yes |
| P2a | No | No | No | Yes | Yes | Yes ^b | Yes | No | Yes | Yes |
| P2b | Yes | Yes | Yes | No | No | No | No | Yes | No | No |
| P3a | No | No | No | Yes | Yes | Yes ^b | Yes | No | Yes | Yes |
| P3b | No | No | No | Yes | No | No | No | No | No | Yes |
| P4 | Yes | Yes | Yes | Yes | Yes | Yes ^b | No | Yes | No | Yes |
| a The dynami | c procedure [5 |] may restore t | hese symmetrie | cs [1, 10, 14] | | | | | | |

 b Depending on the value of the model parameter

Constructing Physically Consistent Subgrid-Scale Models

Table 1 Summary of the properties of several subgrid-scale models. The properties considered are S1-4: time, pressure, generalized Galilean, and rotation and

proper near-wall scaling behavior (P1) have coefficients that depend only on the invariants of the rate-of-strain tensor, I_1 and I_3 . For example (Ex. 1),

$$\tau^{\text{mod}} = c_0 \bar{\delta}^2 \frac{I_3^4}{I_1^5} I + c_1 \bar{\delta}^2 \frac{I_3^3}{I_1^4} \bar{S} + c_4 \bar{\delta}^2 \frac{I_3^4}{I_1^6} (\bar{S}\bar{\varOmega} - \bar{\varOmega}\bar{S}) .$$
(14)

Here, $\overline{\delta}$ denotes the filter length. Without additional procedures, the above model satisfies all the symmetries of the Navier-Stokes equations, apart from scale invariance (S5). Being orthogonal to each other, the three terms all have a different role. The first term on the right-hand side models the generalized subgrid-scale kinetic energy, the second describes dissipative processes, whereas the last term represents energy transport among large scales.

In view of the requirements of Nicoud et al. (P3a,b), a possibly attractive model of eddy viscosity type is based on the nonnegative quantity $I_5 - \frac{1}{2}I_1I_2$, Ex. 2:

$$\tau_{\rm e}^{\rm mod} - \frac{1}{3} {\rm tr}(\tau_{\rm e}^{\rm mod}) I = -2(C\bar{\delta})^2 \sqrt{I_1} (\frac{1}{2} - \frac{I_5}{I_1 I_2})^{3/2} \bar{S} .$$
(15)

It has the desired near-wall scaling behavior (P1) and it vanishes only in twocomponent flows, and in states of pure shear and pure rotation.

For comparison, the properties of these example models are summarized in Table 1.

5 Summary

We studied the construction of subgrid-scale models for large-eddy simulation of incompressible turbulent flows, aiming to preserve important mathematical and physical properties of the Navier-Stokes equations and the turbulent stresses. To this end, we first outlined model requirements coming from the symmetries of the Navier-Stokes equations, and from the near-wall scaling and dissipation behavior of the turbulent stresses. An analysis of existing subgrid-scale models showed that they do not all satisfy these requirements. We then considered a general class of subgrid-scale models based on the local filtered velocity gradient and provided examples of 'physically consistent models' that satisfy different combinations of model requirements. Although no models were obtained that exhibit all the desired properties, we believe the current reasoning has led to an interesting class of models, particularly because it allows for the description of nondissipative processes in turbulent flows.

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