

# A Chomsky-Schützenberger Theorem for Weighted Automata with Storage

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**Abstract.** We enrich the concept of automata with storage by weights taken from any unital valuation monoid. We prove a Chomsky-Schützenberger theorem for the class of weighted languages recognizable by such weighted automata with storage.

## 1 Introduction

The classical Chomsky-Schützenberger theorem [3, Prop. 2] (for short: CS theorem) states that each context-free language is the homomorphic image of the intersection of a Dyck-language and a regular language. In [28] it was shown under which conditions the homomorphism can be non-erasing. In [23] the CS theorem was employed to specify a parser for context-free languages. The CS theorem has been extended to string languages generated by tree-adjoining grammars [32], multiple context-free languages [33], indexed languages [17]<sup>1</sup>, and yield images of simple context-free tree languages [25].

Already in [3] the CS theorem for context-free languages was proved in a special weight setting: each word in the language is associated with the number of its derivations. In [29] the CS theorem was shown for algebraic (formal) power series over commutative semirings. In [9] this result was generalized to algebraic power series over unital valuation monoids, called quantitative context-free languages; (unital) valuation monoids allow to describe, e.g., average consumption of energy. Also in [9] quantitative context-free languages were characterized by weighted pushdown automata over unital valuation monoids. Recently, the CS theorem has been proved for weighted multiple context-free languages over complete commutative strong bimonoids [6].

In the classical CS theorem, the set  $Y$  of letters occurring in the Dyck-language depends on the given context-free grammar or pushdown automaton. An alternative is to code  $Y$  by a homomorphism  $g$  over a two-letter alphabet and to obtain the following CS theorem [22, Thm. 10.4.3]: each context-free language  $L$  can be represented in the form  $L = h(g^{-1}(D_2) \cap R)$  for some homomorphisms  $h$  and  $g$  and a regular language  $R$ ;  $D_2$  denotes the Dyck-language over a two letter alphabet. In the sequel we call this alternative the CS theorem.

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<sup>1</sup> We are grateful to one of the reviewers for pointing out this reference to us.

In this paper we prove a CS theorem for the class of weighted languages recognizable by weighted iterated pushdown automata over unital valuation monoids. A weighted language<sup>2</sup> is a mapping from  $\Sigma^*$  to some weight algebra. Intuitively, an iterated pushdown is a pushdown in which each square contains a pushdown in which each square contains a pushdown ... (and so on). The idea of iterated pushdowns goes back to [21,26,27]. It was proved in [11, Thm. 6] that the classes of languages accepted by iterated pushdown automata form a strict, infinite hierarchy with increasing nesting of pushdowns. In [5] it was proved that  $n$ -iterated pushdown automata characterize the  $n$ -th level of the OI-string language hierarchy [4,13,31] which starts at its first three levels with the regular, context-free, and indexed languages [1] (equivalently, OI-macro languages [16]).

We obtain the CS theorem for weighted iterated pushdown automata as application of the even more general, main result of our paper: the CS theorem for  $K$ -weighted automata with storage where  $K$  is an arbitrary unital valuation monoid. An automaton with storage  $S$  [30,19,12]<sup>3</sup> is a one-way nondeterministic finite-state automaton with an additional storage of type  $S$ ; a successful computation starts with the initial state and an initial configuration of  $S$ ; in each transition the automaton can test the current storage configuration and apply an instruction to it. For instance, pushdown automata,  $n$ -iterated pushdown automata, stack automata [20], and nested stack automata [2] can be formulated as automata with storage. For a number of examples of storages we refer to [12] where these automata were called REG( $S$ ) r-acceptors. The concept of automata with storage is quite flexible: for instance, we can also express  $M$ -automata [24] where  $M$  is a (multiplicative) monoid, in a straightforward way as such automata with storage (cf. Ex. 4).

We extend the concept of automata with storage to that of  $K$ -weighted automata with storage where  $K$  is a unital valuation monoid; this extension is done in the same way as pushdown automata have been extended in [9] to weighted pushdown automata over unital valuation monoids. Then our main result states the following (cf. Thm. 11). Let  $r: \Sigma^* \rightarrow K$  be recognizable by some  $K$ -weighted automaton over storage type  $S$ . Then there are a regular language  $R$ , a finite set  $\Omega$  of pairs (each consisting of a predicate and an instruction), a configuration  $c$  of  $S$ , a letter-to-letter morphism  $g$ , and a (weighted) alphabetic morphism  $h$  such that  $r = h(g^{-1}(B(\Omega, c)) \cap R)$  where  $B(\Omega, c)$  is the set of all  $\Omega$ -behaviours of  $c$ .

## 2 Preliminaries

*Notations and Notions.* The set of non-negative integers (including 0) is denoted by  $\mathbb{N}$ . Let  $n \in \mathbb{N}$ . Then  $[n]$  denotes the set  $\{i \in \mathbb{N} \mid 1 \leq i \leq n\}$ . Thus  $[0] = \emptyset$ . Let  $A$  and  $B$  be sets. The set of all subsets (finite subsets) of  $A$  is denoted by  $\mathcal{P}(A)$  ( $\mathcal{P}_{\text{fin}}(A)$ , resp.). We denote the identity mapping on  $A$  by  $\text{id}_A$ . Let  $f: A \rightarrow B$  be a mapping. We denote by  $\text{im}(f)$  the set  $\{b \in B \mid \exists a \in A : f(a) = b\}$ .

<sup>2</sup> or, equivalently, formal power series

<sup>3</sup> If we cite notions or definitions from [12], then we always refer to the version of 2014.

We fix a countably infinite set  $A$  and call its elements symbols. We call each finite subset  $\Sigma$  of  $A$  an *alphabet*. In the rest of this paper, we let  $\Sigma$  and  $\Delta$  denote alphabets unless specified otherwise.

*Unital Valuation Monoids.* The concept of valuation monoid was introduced in [7,8] and extended in [9] to unital valuation monoid. A *unital valuation monoid* is a tuple  $(K, +, \text{val}, 0, 1)$  such that  $(K, +, 0)$  is a commutative monoid and  $\text{val}: K^* \rightarrow K$  is a mapping such that (i)  $\text{val}(a) = a$  for each  $a \in K$ , (ii)  $\text{val}(a_1, \dots, a_n) = 0$  whenever  $a_i = 0$  for some  $i \in [n]$ , (iii)  $\text{val}(a_1, \dots, a_{i-1}, 1, a_{i+1}, \dots, a_n) = \text{val}(a_1, \dots, a_{i-1}, a_{i+1}, \dots, a_n)$  for any  $i \in [n]$ , and (iv)  $\text{val}(\varepsilon) = 1$ .

A monoid  $(K, +, 0)$  is *complete* if it has an infinitary sum operation  $\sum_I: K^I \rightarrow K$  for each enumerable set  $I$  (for the axioms cf. [10]). We call a unital valuation monoid  $(K, +, \text{val}, 0, 1)$  complete if  $(K, +, 0)$  has this property. We write  $\sum_{i \in I} a_i$  instead of  $\sum_I(a_i \mid i \in I)$ .

We refer the reader to [9, Ex. 1 and 2] for a number of examples of unital valuation monoids. For instance, each complete semiring (in particular, the *Boolean semiring*  $\mathbb{B} = (\{0, 1\}, \vee, \wedge, 0, 1)$ ) and each complete lattice is a complete unital valuation monoid. In the rest of this paper, we let  $K$  denote an arbitrary unital valuation monoid  $(K, +, \text{val}, 0, 1)$  unless specified otherwise.

*Weighted Languages.* A  $K$ -weighted language over  $\Sigma$  is a mapping of the form  $r: \Sigma^* \rightarrow K$ . We denote the set of all such mappings by  $K\langle\langle \Sigma^* \rangle\rangle$ . For every  $r \in K\langle\langle \Sigma^* \rangle\rangle$ , we denote the set  $\{w \in \Sigma^* \mid r(w) \neq 0\}$  by  $\text{supp}(r)$ .

A family  $(r_i \mid i \in I)$  of  $K$ -weighted languages  $r_i \in K\langle\langle \Sigma^* \rangle\rangle$  is *locally finite* if for each  $w \in \Sigma^*$  the set  $I_w = \{i \in I \mid r_i(w) \neq 0\}$  is finite. In this case or if  $K$  is complete, we define  $\sum_{i \in I} r_i \in K\langle\langle \Sigma^* \rangle\rangle$  by  $(\sum_{i \in I} r_i)(w) = \sum_{i \in I_w} r_i(w)$  for each  $w \in \Sigma^*$ .

Each  $L \in \mathbb{B}\langle\langle \Sigma^* \rangle\rangle$  determines the set  $\text{supp}(L) \subseteq \Sigma^*$ . Vice versa, each set  $L \subseteq \Sigma^*$  determines the  $\mathbb{B}$ -weighted language  $\chi_L \in \mathbb{B}\langle\langle \Sigma^* \rangle\rangle$  with  $\chi_L(w) = 1$  if and only if  $w \in L$ . Thus, for every  $L \subseteq \Sigma^*$ , we have  $\text{supp}(\chi_L) = L$ ; and for every  $L \in \mathbb{B}\langle\langle \Sigma^* \rangle\rangle$  we have  $\chi_{\text{supp}(L)} = L$ . In the sequel we will not distinguish between these two points of view.

### 3 Weighted Automata with Storage

We take up the concept of automata with storage [30] and present it in the style of [12] (cf. [14,15] for further investigations). Moreover, we add weights to the transitions of the automaton where the weights are taken from some unital valuation monoid.

*Storage Types:* We recall the definition of storage type from [12,30] with a slight modification. A *storage type*  $S$  is a tuple  $(C, P, F, C_0)$  where  $C$  is a set (*configurations*),  $P$  is a set of total functions each having the type  $p: C \rightarrow \{\text{true}, \text{false}\}$  (*predicates*),  $F$  is a set of partial functions each having the type  $f: C \rightarrow C$  (*instructions*), and  $C_0 \subseteq C$  (*initial configurations*).

**Example 1.** Let  $c$  be an arbitrary but fixed symbol. The *trivial storage type* is the storage type  $\text{TRIV} = (\{c\}, \{\text{p}_{\text{true}}\}, \{\text{f}_{\text{id}}\}, \{c\})$  where  $\text{p}_{\text{true}}(c) = \text{true}$  and  $\text{f}_{\text{id}}(c) = c$ .  $\square$

Next we recall the pushdown operator  $P$  from [12, Def. 5.1] and [14, Def. 3.28]: if  $S$  is a storage type, then  $P(S)$  is a storage type of which the configurations have the form of a pushdown; each cell contains a pushdown symbol and a configuration of  $S$ . Formally, let  $\Gamma$  be a fixed infinite set (*pushdown symbols*). Also, let  $S = (C, P, F, C_0)$  be a storage type. The *pushdown of  $S$*  is the storage type  $P(S) = (C', P', F', C'_0)$  where

- $C' = (\Gamma \times C)^+$  and  $C'_0 = \{(\gamma_0, c_0) \mid \gamma_0 \in \Gamma, c_0 \in C_0\}$ ,
- $P' = \{\text{bottom}\} \cup \{(\text{top} = \gamma) \mid \gamma \in \Gamma\} \cup \{\text{test}(p) \mid p \in P\}$  such that for every  $(\delta, c) \in \Gamma \times C$  and  $\alpha \in (\Gamma \times C)^*$  we have
 
$$\begin{aligned} \text{bottom}((\delta, c)\alpha) &= \text{true} \text{ if and only if } \alpha = \varepsilon \\ (\text{top} = \gamma)((\delta, c)\alpha) &= \text{true} \text{ if and only if } \gamma = \delta \\ \text{test}(p)((\delta, c)\alpha) &= p(c) \end{aligned}$$

- $F' = \{\text{pop}\} \cup \{\text{stay}(\gamma) \mid \gamma \in \Gamma\} \cup \{\text{push}(\gamma, f) \mid \gamma \in \Gamma, f \in F\}$  such that for every  $(\delta, c) \in \Gamma \times C$  and  $\alpha \in (\Gamma \times C)^*$  we have

$$\begin{aligned} \text{pop}((\delta, c)\alpha) &= \alpha \text{ if } \alpha \neq \varepsilon \\ \text{stay}(\gamma)((\delta, c)\alpha) &= (\gamma, c)\alpha \\ \text{push}(\gamma, f)((\delta, c)\alpha) &= (\gamma, f(c))(\delta, c)\alpha \text{ if } f(c) \text{ is defined} \end{aligned}$$

and undefined in all other situations.

For each  $n \geq 0$  we define  $P^n(S)$  inductively as follows:  $P^0(S) = S$  and  $P^n(S) = P(P^{n-1}(S))$  for each  $n \geq 1$ .

**Example 2.** Intuitively,  $P(\text{TRIV})$  corresponds to the usual pushdown storage except that there is no empty pushdown. For  $n \geq 0$ , we abbreviate  $P^n(\text{TRIV})$  by  $P^n$  and call it the  *$n$ -iterated pushdown storage*.  $\square$

*Throughout this paper we let  $S$  denote an arbitrary storage type  $(C, P, F, C_0)$  unless specified otherwise.*

*Automata with Storage:* An  $(S, \Sigma)$ -automaton is a tuple  $\mathcal{A} = (Q, \Sigma, c_0, q_0, Q_f, T)$  where  $Q$  is a finite set (*states*),  $\Sigma$  is an alphabet (*terminal symbols*),  $c_0 \in C_0$  (*initial configuration*),  $q_0 \in Q$  (*initial state*),  $Q_f \subseteq Q$  (*final states*), and  $T \subseteq Q \times (\Sigma \cup \{\varepsilon\}) \times P \times Q \times F$  is a finite set (*transitions*). If  $T \subseteq Q \times \Sigma \times P \times Q \times F$ , then we call  $\mathcal{A}$   $\varepsilon$ -free.

The computation relation of  $\mathcal{A}$  is the binary relation on the set  $Q \times \Sigma^* \times C$  of  $\mathcal{A}$ -configurations defined as follows. For every transition  $\tau = (q, x, p, q', f)$  in  $T$  we define the binary relation  $\vdash^\tau$  on the set of  $\mathcal{A}$ -configurations: for every  $w \in \Sigma^*$  and  $c \in C$ , we let  $(q, xw, c) \vdash^\tau (q', w, f(c))$  if  $p(c)$  is true and  $f(c)$  is defined. The *computation relation of  $\mathcal{A}$*  is the binary relation  $\vdash = \bigcup_{\tau \in T} \vdash^\tau$ . The *language recognized by  $\mathcal{A}$*  is the set  $L(\mathcal{A}) = \{w \in \Sigma^* \mid (q_0, w, c_0) \vdash^* (q_f, \varepsilon, c) \text{ for some } q_f \in Q_f, c \in C\}$ .

A *computation* is a sequence  $\theta = \tau_1 \dots \tau_n$  of transitions  $\tau_i$  ( $i \in [n]$ ) such that there are  $\mathcal{A}$ -configurations  $c_0, \dots, c_n$  with  $c_{i-1} \vdash^{\tau_i} c_i$ . We abbreviate this

computation by  $c_0 \vdash^\theta c_n$ . Let  $q \in Q$ ,  $w \in \Sigma^*$ , and  $c \in C$ . A  $q$ -computation on  $w$  and  $c$  is a computation  $\theta$  such that  $(q, w, c) \vdash^\theta (q_f, \varepsilon, c')$  for some  $q_f \in Q_f$ ,  $c' \in C$ . We denote the set of all  $q$ -computations on  $w$  and  $c$  by  $\Theta_{\mathcal{A}}(q, w, c)$ . Furthermore, we denote the set of all  $q_0$ -computations on  $w$  and  $c_0$  by  $\Theta_{\mathcal{A}}(w)$ . Thus we have  $L(\mathcal{A}) = \{w \in \Sigma^* \mid \Theta_{\mathcal{A}}(w) \neq \emptyset\}$ .

We say that  $\mathcal{A}$  is *ambiguous* if there is a  $w \in \Sigma^*$  such that  $|\Theta_{\mathcal{A}}(w)| \geq 2$ . Otherwise  $\mathcal{A}$  is *unambiguous*. A language  $L \subseteq \Sigma^*$  is  $(S, \Sigma)$ -recognizable if there is an  $(S, \Sigma)$ -automaton  $\mathcal{A}$  with  $L(\mathcal{A}) = L$ .

**Example 3.** (1) The TRIV-automata are (usual) finite-state automata, and  $P^1$ -automata are essentially pushdown automata. (2) For each  $n \geq 1$ ,  $P^n$ -automata correspond to  $n$ -iterated pushdown automata of [26,27,11,5]. (3) Nested stack automata [2] correspond to NS(TRIV)-automata where NS is an operator on storage types (cf. [14, Def. 7.1]). In [14, Thm. 7.4] it was proved that, for every  $S$ , the storage types  $P^2(S)$  and NS( $S$ ) are equivalent (cf. [14, Def. 4.6] for the definition of equivalence), which implies that the acceptance power of automata using these storage types is the same (cf. [14, Thm. 4.18] for this implication).  $\square$

**Example 4.** We indicate how to embed the concept of  $M$ -automata [24] where  $(M, \cdot, 1)$  is a multiplicative monoid, into the setting of automata with storage. For this we define the storage type *monoid*  $M$ , denoted by  $\text{MON}(M)$ , by  $(C, P, F, C_0)$  where  $C = M$  and  $C_0 = \{1\}$ ,  $P = \{\text{true?}\} \cup \{1?\}$  with  $\text{true?}(m) = \text{true}$ , and  $1?(m) = \text{true}$  if and only if  $m = 1$ ,  $F = \{[m] \mid m \in M\}$  and  $[m]: M \rightarrow M$  is defined by  $[m](m') = m' \cdot m$ .

For a given  $M$ -automaton  $\mathcal{A}$ , we construct an equivalent  $\text{MON}(M)$ -automaton  $\mathcal{B}$  as follows. If  $(q, x, q', m)$  is a transition of  $\mathcal{A}$  (with states  $q, q'$ , input symbol  $x$ , and  $m \in M$ ), then  $(q, x, \text{true?}, q', [m])$  is a transition of  $\mathcal{B}$ . Moreover, for each final state  $q$  of  $\mathcal{A}$ , the transition  $(q, \varepsilon, 1?, q_f, [1])$  is in  $\mathcal{B}$  where  $q_f$  is the only final state of  $\mathcal{B}$ .  $\square$

*Weighted Automata with Storage:* Next we define the weighted version of  $(S, \Sigma)$ -automata. The line of our definitions follows the definition of weighted pushdown automata in [9].

An  $(S, \Sigma)$ -automaton with weights in  $K$  is a tuple  $\mathcal{A} = (Q, \Sigma, c_0, q_0, Q_f, T, \text{wt})$  where  $(Q, \Sigma, c_0, q_0, Q_f, T)$  is an  $(S, \Sigma)$ -automaton (*underlying*  $(S, \Sigma)$ -automaton) and  $\text{wt}: T \rightarrow K$  (*weight assignment*). If the underlying  $(S, \Sigma)$ -automaton is  $\varepsilon$ -free, then we call  $\mathcal{A}$   $\varepsilon$ -free. Let  $\theta = \tau_1 \dots \tau_n$  be a computation of  $\mathcal{A}$ . The *weight* of  $\theta$  is the element in  $K$  defined by  $\text{wt}(\theta) = \text{val}(\text{wt}(\tau_1), \dots, \text{wt}(\tau_n))$ .

An  $(S, \Sigma, K)$ -automaton is an  $(S, \Sigma)$ -automaton  $\mathcal{A}$  with weights in  $K$  such that (i)  $\Theta_{\mathcal{A}}(w)$  is finite for every  $w \in \Sigma^*$  or (ii)  $K$  is complete. In this case the *weighted language recognized by*  $\mathcal{A}$  is the  $K$ -weighted language  $\|\mathcal{A}\|: \Sigma^* \rightarrow K$  defined for every  $w \in \Sigma^*$  by  $\|\mathcal{A}\|(w) = \sum_{\theta \in \Theta_{\mathcal{A}}(w)} \text{wt}(\theta)$ .

A weighted language  $r: \Sigma^* \rightarrow K$  is  $(S, \Sigma, K)$ -recognizable if there is an  $(S, \Sigma, K)$ -automaton  $\mathcal{A}$  such that  $r = \|\mathcal{A}\|$ .

**Example 5.** (1) Each  $(S, \Sigma, \mathbb{B})$ -automaton  $\mathcal{A}$  can be considered as an  $(S, \Sigma)$ -automaton which recognizes  $\text{supp}(\|\mathcal{A}\|)$ . (2) Apart from  $\varepsilon$ -moves,  $(\text{TRIV}, \Sigma, K)$ -automata are the same as weighted finite automata over  $\Sigma$  and the valuation monoid  $K$  [9]. (3) The  $(P^1, \Sigma, K)$ -automata are essentially the same as weighted pushdown automata over  $\Sigma$  and  $K$  [9] where acceptance with empty pushdown can be simulated in the usual way. Thus, for every  $r: \Sigma^* \rightarrow K$  we have:  $r$  is the quantitative behaviour of a WPDA as defined in [9] if and only if  $r$  is  $(P^1, \Sigma, K)$ -recognizable.  $\square$

For  $n \geq 0$ , a *weighted  $n$ -iterated pushdown language over  $\Sigma$  and  $K$*  is a  $(P^n, \Sigma, K)$ -recognizable weighted language.

## 4 Separating the Weights from an $(S, \Sigma, K)$ -Automaton

In this section we will represent an  $(S, \Sigma, K)$ -recognizable weighted language as the homomorphic image of an  $(S, \Delta)$ -recognizable language.

We recall from [9] the concept of (weighted) alphabetic morphism. First, we introduce monomes and alphabetic morphisms. A mapping  $r: \Sigma^* \rightarrow K$  is called a *monome* if  $\text{supp}(r)$  is empty or a singleton. If  $\text{supp}(r) = \{w\}$ , then we also write  $r(w).w$  instead of  $r$ . We let  $K[\Sigma \cup \{\varepsilon\}]$  denote the set of all monomes with support in  $\Sigma \cup \{\varepsilon\}$ .

Let  $\Delta$  be an alphabet and  $h: \Delta \rightarrow K[\Sigma \cup \{\varepsilon\}]$  be a mapping. The *alphabetic morphism induced by  $h$*  is the mapping  $h': \Delta^* \rightarrow K\langle\langle \Sigma^* \rangle\rangle$  such that for every  $n \geq 0$ ,  $\delta_1, \dots, \delta_n \in \Delta$  with  $h(\delta_i) = a_i.y_i$  we have  $h'(\delta_1 \dots \delta_n) = \text{val}(a_1, \dots, a_n).y_1 \dots y_n$ . Note that  $h'(v)$  is a monome for every  $v \in \Delta^*$ , and  $h'(\varepsilon) = 1.\varepsilon$ . If  $L \subseteq \Delta^*$  such that the family  $(h'(v) \mid v \in L)$  is locally finite or if  $K$  is complete, we let  $h'(L) = \sum_{v \in L} h'(v)$ . In the sequel we will use the following convention. If we write “alphabetic morphism  $h: \Delta \rightarrow K[\Sigma \cup \{\varepsilon\}]$ ”, then we mean the alphabetic morphism induced by  $h$ .

We define a special case of alphabetic morphisms in which  $K = \mathbb{B}$ . If for every  $\delta \in \Delta$  the support of  $h(\delta)$  is  $\{\sigma\}$  for some  $\sigma \in \Sigma$ , then we call  $h'$  a *letter-to-letter morphism*. Note that in this case the alphabetic morphism induced by  $h$  has the property that for every  $v \in \Delta^*$ ,  $\text{supp}(h'(v))$  contains at most one element and if  $\text{supp}(h'(v)) = \{w\}$  for some  $w \in \Sigma^*$ , then the lengths of  $w$  and  $v$  are equal.

**Theorem 6.** *For every  $r \in K\langle\langle \Sigma^* \rangle\rangle$  the following two statements are equivalent:*

- (1)  *$r$  is  $(S, \Sigma, K)$ -recognizable.*
- (2) *There are an alphabet  $\Delta$ , an unambiguous  $\varepsilon$ -free  $(S, \Delta)$ -automaton  $\mathcal{A}$ , and an alphabetic morphism  $h: \Delta \rightarrow K[\Sigma \cup \{\varepsilon\}]$  such that  $r = h(L(\mathcal{A}))$ .*

*Proof.* (1)  $\Rightarrow$  (2): This generalizes [9, Lm. 3] in a straightforward way. Let  $\mathcal{B} = (Q, \Sigma, c_0, q_0, Q_f, T, \text{wt})$  be an  $(S, \Sigma, K)$ -automaton. We construct the  $(S, T)$ -automaton  $\mathcal{A} = (Q, T, c_0, q_0, Q_f, T')$  and the mapping  $h: T \rightarrow K[\Sigma \cup \{\varepsilon\}]$  such that, if  $\tau = (q, x, p, q', f)$  is in  $T$ , then  $(q, \tau, p, q', f)$  is in  $T'$  and we define  $h(\tau) = \text{wt}(\tau).x$ . Obviously,  $\mathcal{A}$  is unambiguous and  $\varepsilon$ -free.

Let  $w \in \Sigma^*$  and  $\theta = \tau_1 \dots \tau_n \in \Theta_{\mathcal{B}}(w)$ . By definition of  $h$ , we have that  $h(\theta) = \text{val}(\text{wt}(\tau_1), \dots, \text{wt}(\tau_n)).w$ . Hence  $\text{wt}(\theta) = (h(\theta))(w)$ . Also, by definition of  $(S, \Sigma, K)$ -automata, the set  $\Theta_{\mathcal{B}}(w)$  is finite if  $K$  is not complete. Thus the family  $(h(\theta) \mid \theta \in L(\mathcal{A}))$  is locally finite if  $K$  is not complete. Then, for every  $w \in \Sigma^*$ , we have  $\|\mathcal{B}\|(w) = \sum_{\theta \in \Theta_{\mathcal{B}}(w)} \text{wt}(\theta) = \sum_{\theta \in \Theta_{\mathcal{B}}(w)} (h(\theta))(w) \stackrel{(*)}{=} \sum_{\theta \in L(\mathcal{A})} (h(\theta))(w) = (\sum_{\theta \in L(\mathcal{A})} h(\theta))(w) = (h(L(\mathcal{A})))(w)$  where  $(*)$  holds because for every  $\theta \in L(\mathcal{A})$  with  $\theta \notin \Theta_{\mathcal{B}}(w)$ , we have  $(h(\theta))(w) = 0$  and due to the fact that  $\sum_{\theta \in L(\mathcal{A}), \theta \notin \Theta_{\mathcal{B}}(w)} 0 = 0$ . Thus  $\|\mathcal{B}\| = h(L(\mathcal{A}))$ .

(2)  $\Rightarrow$  (1): Let  $\mathcal{A} = (Q, \Delta, c_0, q_0, Q_f, T)$  be an unambiguous  $\varepsilon$ -free  $(S, \Delta)$ -automaton and  $h: \Delta \rightarrow K[\Sigma \cup \{\varepsilon\}]$  an alphabetic morphism. Moreover, we assume that the family  $(h(v) \mid v \in L(\mathcal{A}))$  is locally finite if  $K$  is not complete. We will construct an  $(S, \Sigma, K)$ -automaton  $\mathcal{B}$  such that  $\|\mathcal{B}\| = h(L(\mathcal{A}))$ .

Our construction employs a similar technique of coding the preimage of  $h$  into the set of states as in [9, Lm. 4] in order to handle non-injectivity of  $h$  appropriately. However, we have to modify the construction slightly, because the straightforward generalization would require that  $S$  has an identity instruction (needed in the first step of the computation), which in general we do not assume. In our constructed automaton, the target state (and not, as in [9, Lm. 4], the source state) of each transition encodes a preimage of the symbol which is read by this transition.

Formally, we construct the  $(S, \Sigma, K)$ -automaton  $\mathcal{B} = (Q', \Sigma, c_0, q'_0, Q'_f, T', \text{wt})$  where  $Q' = \{q'_0\} \cup \Delta \times Q$  with some element  $q'_0$  with  $q'_0 \notin \Delta \times Q$ ,  $Q'_f = \Delta \times Q_f$ , and  $T'$  and  $\text{wt}$  are defined as follows. Let  $\delta \in \Delta$  and  $h(\delta) = a.y$ .

- If  $(q_0, \delta, p, q, f)$  is in  $T$ , then  $(q'_0, y, p, (\delta, q), f)$  is in  $T'$ , and its weight is  $a$ .
- If  $(q, \delta, p, q', f)$  is in  $T$ , then  $((\delta', q), y, p, (\delta, q'), f)$  is in  $T'$  for each  $\delta' \in \Delta$ , and its weight is  $a$ .

Let  $w \in \Sigma^*$ . First, let  $v \in \Delta^*$  with  $h(v) = z.w$  for some  $z \in K$ . We write  $v = \delta_1 \dots \delta_n \in \Delta^*$  with  $n \geq 0$  and  $\delta_i \in \Delta$ . Let  $h(\delta_i) = a_i.y_i$  for every  $1 \leq i \leq n$ . Thus  $h(v) = \text{val}(a_1, \dots, a_n).y_1 \dots y_n$  and  $w = y_1 \dots y_n$  and  $z = \text{val}(a_1, \dots, a_n)$ .

Let  $\theta = \tau_1 \dots \tau_n$  be a  $q_0$ -computation in  $\Theta_{\mathcal{A}}(v)$ . Clearly, for each  $i \in [n]$ , the second component of  $\tau_i$  is  $\delta_i$ . Then we construct the  $q'_0$ -computation  $\theta' = \tau'_1 \dots \tau'_n$  in  $\Theta_{\mathcal{B}}(y_1 \dots y_n)$  inductively as follows:

- If  $\tau_1 = (q_0, \delta_1, p_1, q_1, f_1)$ , then we let  $\tau'_1 = (q'_0, y_1, p_1, (\delta_1, q_1), f_1)$ .
- If  $1 < i \leq n$  and  $\tau_i = (q_{i-1}, \delta_i, p_i, q_i, f_i)$ , then we let  $\tau'_i = ((\delta_{i-1}, q_{i-1}), y_i, p_i, (\delta_i, q_i), f_i)$ .

Note that  $(h(v))(w) = \text{val}(a_1, \dots, a_n) = \text{val}(\text{wt}(\tau'_1), \dots, \text{wt}(\tau'_n)) = \text{wt}(\theta')$ .

Conversely, for every  $q'_0$ -computation  $\theta' = \tau'_1 \dots \tau'_n$  in  $\Theta_{\mathcal{B}}(w)$  by definition of  $T'$  there are a uniquely determined  $v \in \Delta^*$  and a uniquely determined  $q_0$ -computation  $\theta = \tau_1 \dots \tau_n$  in  $\Theta_{\mathcal{A}}(v)$  such that  $\theta'$  is the computation constructed above. Hence, for every  $v \in \Delta^*$  and  $w \in \Sigma^*$ , if  $h(v) = z.w$  for some  $z \in K$ , then  $\Theta_{\mathcal{A}}(v)$  and  $\Theta_{\mathcal{B}}(w)$  are in a one-to-one correspondence.

Thus, for every  $w \in \Sigma^*$ , we obtain  $(h(L(\mathcal{A})))(w) = \sum_{v \in L(\mathcal{A})} (h(v))(w) = \sum_{\substack{v \in L(\mathcal{A}): \\ (h(v))(w) \neq 0}} (h(v))(w)$ . Since  $\mathcal{A}$  is unambiguous this is equal to

$\sum_{\substack{v \in L(\mathcal{A}), \theta \in \Theta_{\mathcal{A}}(v): \\ (h(v))(w) \neq \emptyset}} \text{wt}(\theta')$ . Since there is a one-to-one correspondence between  $\Theta_{\mathcal{A}}(v)$  and  $\Theta_{\mathcal{B}}(w)$ , this is equal to  $\sum_{\theta' \in \Theta_{\mathcal{B}}(w)} \text{wt}(\theta') = \|\mathcal{B}\|(w)$ . Thus  $h(L(\mathcal{A})) = \|\mathcal{B}\|$ .  $\square$

We could strengthen Theorem 6 by proving  $(2') \Rightarrow (1)$  where  $(2')$  is obtained from  $(2)$  by dropping the  $\varepsilon$ -freeness of  $\mathcal{A}$ .

## 5 Separating the Storage from an $(S, \Delta)$ -Automaton

In this section we will characterize the language recognized by an  $\varepsilon$ -free  $(S, \Delta)$ -automaton  $\mathcal{A}$  as the image of the set of behaviours of the initial configuration of  $\mathcal{A}$  under a simple transducer mapping. Note that  $\mathcal{A}$  need not be unambiguous. Our proof follows closely the technique in the proof of [14, Thm. 3.26].

Let  $c_0$  be the initial configuration of  $\mathcal{A}$  and  $\theta$  a computation of  $\mathcal{A}$ , i.e.,  $\theta \in \Theta_{\mathcal{A}}(q_0, w, c_0)$  for some  $w$ . By dropping from  $\theta$  all references to states and to the input, a sequence of pairs remains where each pair consists of a predicate and an instruction. This sequence might be called a behaviour of  $c_0$ . Formally, let  $\Omega$  be a finite subset of  $P \times F$ ,<sup>4</sup>  $c \in C$ , and  $v = (p_1, f_1) \dots (p_n, f_n) \in \Omega^*$ . We say that  $v$  is an  $\Omega$ -behaviour of  $c$  if for every  $i$  with  $i \in [n]$  we have (i)  $p_i(c') = \text{true}$  and (ii)  $f_i(c')$  is defined where  $c' = f_{i-1}(\dots f_1(c) \dots)$  (note that  $c' = c$  for  $i = 1$ ). We denote the set of all  $\Omega$ -behaviours of  $c$  by  $B(\Omega, c)$ . Note that each behaviour of  $c$  is a path in the approximation of  $c$  according to [14, Def. 3.23].

An  $a$ -transducer [19] is a machine  $\mathcal{M} = (Q, \Omega, \Delta, \delta, q_0, Q_f)$  where  $Q$ ,  $\Omega$ , and  $\Delta$  are alphabets (*states*, *input/output symbols*, resp.),  $q_0 \in Q$  (*initial state*),  $Q_f \subseteq Q$  (*final states*), and  $\delta$  is a finite subset of  $Q \times \Omega^* \times Q \times \Delta^*$ . We say that  $\mathcal{M}$  is a *simple transducer (from  $\Omega$  to  $\Delta$ )* if  $\delta \subseteq Q \times \Omega \times Q \times \Delta$ . The binary relation  $\vdash_{\mathcal{M}}$  on  $Q \times \Omega^* \times \Delta^*$  is defined as follows: let  $(q, ww', v) \vdash_{\mathcal{M}} (q', w', vv')$  if  $(q, w, q', v') \in \delta$ . The *mapping induced by  $\mathcal{M}$* , also denoted by  $\mathcal{M}$ , is the mapping  $\mathcal{M}: \Omega^* \rightarrow \mathcal{P}(\Delta^*)$  defined by  $\mathcal{M}(w) = \{v \in \Delta^* \mid (q_0, w, \varepsilon) \vdash_{\mathcal{M}}^* (q, \varepsilon, v), q \in Q_f\}$ . If  $\mathcal{M}$  is a simple transducer, then  $\mathcal{M}(w)$  is finite for every  $w$ . For every  $L \subseteq \Omega^*$  we define  $\mathcal{M}(L) = \bigcup_{v \in L} \mathcal{M}(v)$ .

Our goal is to prove the following theorem.

**Theorem 7.** *Let  $S = (C, P, F, C_0)$  be a storage type. Moreover, let  $L \subseteq \Delta^*$ . Then the following are equivalent:*

- (1)  *$L$  is recognizable by some  $\varepsilon$ -free  $(S, \Delta)$ -automaton.*
- (2) *There are  $c \in C$ , a finite set  $\Omega \subseteq P \times F$ , and a simple transducer  $\mathcal{M}$  from  $\Omega$  to  $\Delta$  such that  $L = \mathcal{M}(B(\Omega, c))$ .*

We note that  $(1) \Rightarrow (2)$  of Theorem 7 is similar to [19, Lm. 2.3] (after decomposing the simple transducer  $\mathcal{M}$  from  $\Omega$  to  $\Delta$  according to Theorem 9).

For the proof of this theorem, we define the concept of relatedness between an  $\varepsilon$ -free  $(S, \Delta)$ -automaton  $\mathcal{A}$  and a simple transducer  $\mathcal{M}$  with the following intention:

<sup>4</sup> We recall that  $S = (C, P, F, C_0)$  is an arbitrary storage type.



$\mathcal{A}$  allows a computation

$$(q_0, x_1, p_1, q_1, f_1)(q_1, x_2, p_2, q_2, f_2) \dots (q_{n-1}, x_n, p_n, q_n, f_n) ,$$

for some states  $q_1, \dots, q_{n-1}$  if and only if

$$(q_0, (p_1, f_1) \dots (p_n, f_n), \varepsilon) \vdash_{\mathcal{M}}^* (q_n, \varepsilon, x_1 \dots x_n) .$$

That is, while reading a behaviour of the initial configuration of  $\mathcal{A}$ , the simple transducer  $\mathcal{M}$  produces a string which is recognized by  $\mathcal{A}$ . Formally, let  $\mathcal{A} = (Q, \Delta, c, q_0, Q_f, T)$  be an  $\varepsilon$ -free  $(S, \Delta)$ -automaton and  $\mathcal{M} = (Q', \Omega, \Delta', \delta, q'_0, Q'_f)$  be a simple transducer. Then  $\mathcal{A}$  is related to  $\mathcal{M}$  if

- $Q = Q'$ ,  $q_0 = q'_0$ ,  $Q_f = Q'_f$ ,
- $\Delta = \Delta'$  and  $\Omega$  is the set of all pairs  $(p, f)$  such that  $T$  contains a transition of the form  $(q, x, p, q', f)$  for some  $q, q'$ , and  $x$ , and
- for every  $q, q' \in Q$ ,  $x \in \Delta$ ,  $p \in P$ , and  $f \in F$  we have:  $(q, x, p, q', f) \in T$  if and only if  $(q, (p, f), q', x) \in \delta$ .

**Lemma 8.** Let  $\mathcal{A}$  be an  $\varepsilon$ -free  $(S, \Delta)$ -automaton with initial configuration  $c$  and let  $\mathcal{M}$  be a simple transducer from  $\Omega$  to  $\Delta$ . If  $\mathcal{A}$  is related to  $\mathcal{M}$ , then  $L(\mathcal{A}) = \mathcal{M}(B(\Omega, c))$ .

*Proof.* Let  $\mathcal{A} = (Q, \Delta, c, q_0, Q_f, T)$  and  $\mathcal{M} = (Q, \Omega, \Delta, \delta, q_0, Q_f)$ . First we prove that  $L(\mathcal{A}) \subseteq \mathcal{M}(B(\Omega, c))$ . Let  $v \in L(\mathcal{A})$ . Then  $v = x_1 \dots x_n$  for some  $n \geq 0$  and  $x_i \in \Delta$  for every  $1 \leq i \leq n$ . Moreover, there is a  $q_0$ -computation  $\theta$  in  $\Theta_{\mathcal{A}}(v)$  with  $\theta = \tau_1 \dots \tau_n$ , such that  $\tau_i \in T$  where  $\tau_1 = (q_0, x_1, p_1, q_1, f_1)$ , for every  $2 \leq i \leq n$  we have  $\tau_i = (q_{i-1}, x_i, p_i, q_i, f_i)$ , and  $q_n \in Q_f$ . Since  $\mathcal{A}$  is related to  $\mathcal{M}$ , we have  $(q_{i-1}, (p_i, f_i), q_i, x_i) \in \delta$  for every  $1 \leq i \leq n$ . Hence  $(q_0, w, \varepsilon) \vdash_{\mathcal{M}}^* (q_n, \varepsilon, x_1 \dots x_n)$  with  $w = (p_1, f_1) \dots (p_n, f_n)$ . Since  $w \in B(\Omega, c)$  is a behaviour of  $c$ ,  $v = x_1 \dots x_n$ , and  $q_n \in Q_f$ , we obtain that  $v \in \mathcal{M}(B(\Omega, c))$ .

Next we prove that  $\mathcal{M}(B(\Omega, c)) \subseteq L(\mathcal{A})$ . Let  $v \in \mathcal{M}(B(\Omega, c))$  with  $v = x_1 \dots x_n$  for some  $n \geq 0$  and  $x_i \in \Delta$  for every  $1 \leq i \leq n$ . Then there is a behaviour  $w \in B(\Omega, c)$  of  $c$  such that  $v \in \mathcal{M}(w)$ . Then there are  $(p_i, f_i) \in \Omega$  with  $1 \leq i \leq n$  such that  $w = (p_1, f_1) \dots (p_n, f_n)$ . Moreover, there are  $q_0, \dots, q_n \in Q$  such that  $(q_0, (p_1, f_1), q_1, x_1) \in \delta$ , for every  $2 \leq i \leq n$ :  $(q_{i-1}, (p_i, f_i), q_i, x_i) \in \delta$ , and  $q_n \in Q_f$ . Since  $\mathcal{A}$  is related to  $\mathcal{M}$ , we have  $\tau_i = (q_{i-1}, x_i, p_i, q_i, f_i) \in T$ . Since  $w \in B(\Omega, c)$ ,  $q_0$  is the initial state of  $\mathcal{A}$ , and  $q_n \in Q_f$ , we have that  $\tau_1 \dots \tau_n \in \Theta_{\mathcal{A}}(v)$  and thus  $v \in L(\mathcal{A})$ .  $\square$

*Proof (of Theorem 7).* (1)  $\Rightarrow$  (2): Let  $L$  be recognizable by some  $\varepsilon$ -free  $(S, \Delta)$ -automaton  $\mathcal{A} = (Q, \Delta, c, q_0, Q_f, T)$ . Let  $\Omega$  be the set of all pairs  $(p, f)$  such that  $T$  contains a transition of the form  $(q, x, p, q', f)$  for some  $q, q'$ , and  $x$ . We construct the simple transducer  $\mathcal{M} = (Q, \Omega, \Delta, \delta, q_0, Q_f)$  by defining  $(q, (p, f), q', x) \in \delta$  if and only if  $(q, x, p, q', f) \in T$  for every  $q, q' \in Q$ ,  $x \in \Delta$ , and  $(p, f) \in \Omega$ . Clearly,  $\mathcal{A}$  is related to  $\mathcal{M}$  and thus, by Lemma 8, we have that  $L(\mathcal{A}) = \mathcal{M}(B(\Omega, c))$ .

(2)  $\Rightarrow$  (1): Let  $c \in C$ ,  $\Omega$  a finite subset of  $P \times F$ , and  $\mathcal{M} = (Q, \Omega, \Delta, \delta, q_0, Q_f)$  a simple transducer. First we reduce  $\mathcal{M}$  to the simple transducer  $\mathcal{M}' = (Q, \Omega', \Delta, \delta, q_0, Q_f)$  where  $\Omega'$  is the set of all pairs  $(p, f)$  such that  $(q, (p, f), q', x) \in \delta$  for some  $q, q' \in Q$  and  $x \in \Delta$ . Obviously,  $\delta \subseteq Q \times \Omega' \times Q \times \Delta$  and  $\mathcal{M}(B(\Omega, c)) = \mathcal{M}'(B(\Omega', c))$ .

Next we construct the  $\varepsilon$ -free  $(S, \Delta)$ -automaton  $\mathcal{A} = (Q, \Delta, c, q_0, Q_f, T)$  by defining  $T = \{(q, x, p, q', f) \mid (q, (p, f), q', x) \in \delta\}$ . Since  $\mathcal{A}$  is related to  $\mathcal{M}'$ , we have that  $L(\mathcal{A}) = \mathcal{M}'(\mathbb{B}(\Omega', c)) = \mathcal{M}(\mathbb{B}(\Omega, c))$  by Lemma 8.  $\square$

## 6 The Main Result and Its Applications

For the proof of our CS theorem for weighted automata with storage, we first recall a result for simple transducers [18, proof of Thm. 2.1].

**Theorem 9.** *Let  $\Omega$  be an alphabet and  $L \subseteq \Omega^*$  and let  $\mathcal{M}: \Omega^* \rightarrow \mathcal{P}_{\text{fin}}(\Delta^*)$  be induced by a simple transducer  $\mathcal{M}$ . Then there are an alphabet  $\Phi$ , two letter-to-letter morphisms  $h_1: \Phi \rightarrow \mathbb{B}[\Omega]$  and  $h_2: \Phi \rightarrow \mathbb{B}[\Delta]$ , and a regular language  $R \subseteq \Phi^*$  such that  $\mathcal{M}(L) = h_2(h_1^{-1}(L) \cap R)$ .*

Next we show that a letter-to-letter morphism  $h_2: \Phi \rightarrow \mathbb{B}[\Delta]$  and an alphabetic morphism  $h: \Delta \rightarrow K[\Sigma \cup \{\varepsilon\}]$  can be combined smoothly. We define the alphabetic morphism  $(h \circ h_2): \Phi \rightarrow K[\Sigma \cup \{\varepsilon\}]$  for every  $x \in \Phi$  by  $(h \circ h_2)(x) = h(\delta)$  if  $h_2(x) = 1.\delta$  for some  $\delta \in \Delta$  (recall that  $|\text{supp}(h_2(x))| = 1$ ).

**Lemma 10.** *Let  $h_2: \Phi \rightarrow \mathbb{B}[\Delta]$  be a letter-to-letter morphism and  $h: \Delta \rightarrow K[\Sigma \cup \{\varepsilon\}]$  an alphabetic morphism. Moreover, let  $H \subseteq \Phi^*$  be a language. If  $(h(v) \mid v \in h_2(H))$  is locally finite, then  $((h \circ h_2)(w) \mid w \in H)$  is locally finite.*

*Proof.* Let  $u \in \Sigma^*$ . By assumption, we have that  $\{v \in h_2(H) \mid u \in \text{supp}(h(v))\}$  is finite; let us denote this set by  $C_u$ . Since  $h_2$  is letter-to-letter, we have that  $\{y \in H \mid v \in h_2(y)\}$  is finite for each  $v \in h_2(H)$ . Then we have:  $|\{w \in H \mid u \in \text{supp}((h \circ h_2)(w))\}| = \sum_{v \in C_u} |\{y \in H \mid v \in h_2(y)\}|$ . Hence,  $\{w \in H \mid u \in \text{supp}((h \circ h_2)(w))\}$  is finite.  $\square$

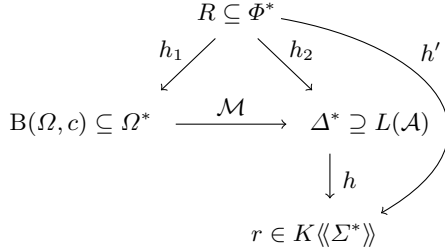
Now we can prove the CS theorem for  $(S, \Sigma, K)$ -automata (cf. Fig.1).

**Theorem 11.** *Let  $S = (C, P, F, C_0)$  be a storage type,  $\Sigma$  an alphabet, and  $K$  a unital valuation monoid. If  $r \in K\langle\langle\Sigma^*\rangle\rangle$  is  $(S, \Sigma, K)$ -recognizable, then there are*

- an alphabet  $\Phi$  and a regular language  $R \subseteq \Phi^*$ ,
- a finite set  $\Omega \subseteq P \times F$  and a configuration  $c \in C$ ,
- a letter-to-letter morphism  $h_1: \Phi \rightarrow \mathbb{B}[\Omega]$ , and
- an alphabetic morphism  $h': \Phi \rightarrow K[\Sigma \cup \{\varepsilon\}]$

such that  $r = h'(h_1^{-1}(\mathbb{B}(\Omega, c)) \cap R)$ .

*Proof.* By Theorem 6 there are an alphabet  $\Delta$ , an  $\varepsilon$ -free  $(S, \Delta)$ -automaton  $\mathcal{A}$ , and an alphabetic morphism  $h: \Delta \rightarrow K[\Sigma \cup \{\varepsilon\}]$  such that  $r = h(L(\mathcal{A}))$ . Hence, if  $K$  is not complete, then  $\Theta_{\mathcal{A}}(w)$  is finite for every  $w \in \Sigma^*$ , and  $(h(v) \mid v \in L(\mathcal{A}))$  is locally finite. According to Theorem 7, there are  $c \in C$ , a finite set  $\Omega \subseteq P \times F$ , and a simple transducer  $\mathcal{M}$  from  $\Omega$  to  $\Delta$  such that  $L(\mathcal{A}) = \mathcal{M}(\mathbb{B}(\Omega, c))$ . Due to Theorem 9, there are an alphabet  $\Phi$ , two letter-to-letter morphisms  $h_1: \Phi \rightarrow \mathbb{B}[\Omega]$  and  $h_2: \Phi \rightarrow \mathbb{B}[\Delta]$ , and a regular language  $R \subseteq \Phi^*$  such that



**Fig. 1.** An illustration of the proof of Theorem 11

$\mathcal{M}(B(\Omega, c)) = h_2(h_1^{-1}(B(\Omega, c)) \cap R)$ . Let us denote the language  $h_1^{-1}(B(\Omega, c)) \cap R$  by  $H$ . Thus  $L(\mathcal{A}) = h_2(H)$ .

Since  $(h(v) \mid v \in L(\mathcal{A}))$  is locally finite if  $K$  is not complete, we have by Lemma 10 that also  $((h \circ h_2)(w) \mid w \in H)$  is locally finite if  $K$  is not complete. Thus  $r = (h \circ h_2)(h_1^{-1}(B(\Omega, c)) \cap R)$  and we can take  $h' = (h \circ h_2)$ .  $\square$

Finally we instantiate the storage type  $S$  in Theorem 11 in several ways and obtain the CS theorem for the corresponding class of  $(S, \Sigma, K)$ -recognizable weighted languages: (1)  $S = P^n$ :  $K$ -weighted  $n$ -iterated pushdown languages. (2)  $S = \text{NS}(\text{TRIV})$  where NS is the nested stack operator defined in [14, Def. 7.1]:  $K$ -weighted nested stack automata (cf. Ex. 3). (3)  $S = \text{SC}(\text{TRIV})$  where SC is obtained from NS by forbidding instructions for creating and destructing nested stacks:  $K$ -weighted stack automata (weighted version of stack automata [20]). (4)  $S = \text{MON}(M)$  for some monoid  $M$  (cf. Ex. 4):  $K$ -weighted  $M$ -automata (weighted version of  $M$ -automata [24]).

In future investigations we will compare formally the CS theorem for quantitative context-free languages over  $\Sigma$  and  $K$  [9, Thm. 2(1)  $\Leftrightarrow$  (2)] with our Theorem 11 for  $(P^1, \Sigma, K)$ -recognizable weighted languages.

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