



Correction to: Stiffness Control of Soft Robotic Manipulator for Minimally Invasive Surgery (MIS) Using Scale Jamming

S.M.Hadi Sadati, Yohan Noh, S. Elnaz Naghibi, Kaspar Althoefer,
and Thrishantha Nanayakkara

Correction to:
Chapter “Stiffness Control of Soft Robotic Manipulator for Minimally Invasive Surgery (MIS) Using Scale Jamming”
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The book was inadvertently published with an incorrect version of an author’s name in Chapter 13 as “Althoefer Kaspar” whereas it has been updated as “Kaspar Althoefer”.

The updated version of this chapter can be found at
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