## A Transparent Boundary Condition for an Elastic Bottom in Underwater Acoustics

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**Abstract.** This work deals with the derivation of a novel transparent boundary condition (TBC) for the coupling of the standard "parabolic" equation (SPE) in underwater acoustics (assuming cylindrical symmetry) with an elastic parabolic equation (EPE) for modelling the sea bottom extending hereby the existing TBCs for a fluid model of the seabed.

Keywords: Transparent boundary condition  $\cdot$  Elastic bottom  $\cdot$  One-way Helmholtz equation  $\cdot$  Standard "parabolic" equation  $\cdot$  Seabed interface

## 1 Introduction

"Parabolic" equation (PE) models appear in (underwater) acoustics as oneway approximations to the Helmholtz equation in cylindrical coordinates with azimuthal symmetry. These PE models have been widely used in the recent past for wave propagation problems in various application areas, e.g. seismology, optics and plasma physics but here we focus on their application to underwater acoustics, where PEs have been introduced by Tappert [17]. For more details we refer to [10].

In computational ocean acoustics one wants to determine the acoustic pressure p(z, r) emerging from a time-harmonic point source situated in the water at  $(z_s, 0)$ . The radial range variable is denoted by r > 0 and the depth variable is  $0 < z < z_b$ . The water surface is located at z = 0, and the (horizontal) sea bottom at  $z = z_b$ . We point out that irregular bottom surfaces and sub-bottom layers can be included by simply extending the range of z. For an alternative strategy based on transformation techniques, including proofs of well-posedness in the case of upsloping and downsloping wedge-type domains in 2D and 3D we refer to [2,6]. Further, the 3D treatment of a sloping sea bootom in a finite element context was presented in [16]. In the sequel we denote the local sound speed by c(z, r), the density by  $\rho(z, r)$ , and the attenuation by  $\alpha(z, r) \geq 0$ .  $n(z, r) = c_0/c(z, r)$  is the refractive index, with a reference sound speed  $c_0$ . The reference wave number is  $k_0 = 2\pi f/c_0$ , where f denotes the (usually low) frequency of the emitted sound.

#### 1.1 The Parabolic Approximations

The acoustic pressure p(z, r) satisfies the Helmholtz equation

$$\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial p}{\partial r}\right) + \rho\frac{\partial}{\partial z}\left(\rho^{-1}\frac{\partial p}{\partial z}\right) + k_0^2 N^2 p = 0, \qquad r > 0, \tag{1}$$

with the complex refractive index (where  $\alpha$  accounts for damping in the medium)

$$N(z,r) = n(z,r) + i\alpha(z,r)/k_0.$$
(2)

In the far field approximation  $(k_0 r \gg 1)$  the (complex valued) outgoing acoustic field

$$\psi(z,r) = \sqrt{k_0 r} \, p(z,r) \, e^{-ik_0 r} \tag{3}$$

satisfies the one-way Helmholtz equation:

$$\psi_r = ik_0 (\sqrt{1-L} - 1)\psi, \qquad r > 0.$$
 (4)

Here,  $\sqrt{1-L}$  is a pseudo-differential operator, and L the Schrödinger operator

$$L = -k_0^{-2}\rho \,\partial_z(\rho^{-1}\partial_z) + V(z,r) \tag{5}$$

with the complex valued "potential"

$$V(z,r) = 1 - N^{2}(z,r) = 1 - \left[n(z,r) + i\alpha(z,r)/k_{0}\right]^{2}.$$
 (6)

"Parabolic" approximations of (4) are formal approximations of the pseudodifferential operator  $\sqrt{1-L}$  by rational functions of L. This procedure yields a PDE that is easier to solve numerically than the pseudo-differential equation (4). For more details we refer to [17,18]. The linear approximation of  $\sqrt{1-\lambda}$  by  $1-\frac{\lambda}{2}$ gives the narrow angle or *standard "parabolic" equation* (SPE) of Tappert [17]

$$\psi_r = -\frac{ik_0}{2}L\psi, \qquad r > 0. \tag{7}$$

This Schrödinger equation (7) is a good description of waves with a propagation direction within about  $15^{\circ}$  of the horizontal. Rational approximations of the form

$$(1-\lambda)^{\frac{1}{2}} \approx f(\lambda) = \frac{p_0 - p_1 \lambda}{1 - q_1 \lambda}$$
(8)

with real  $p_0$ ,  $p_1$ ,  $q_1$  yield the wide angle "parabolic" equations (WAPE)

$$\psi_r = ik_0 \left(\frac{p_0 - p_1 L}{1 - q_1 L} - 1\right) \psi, \qquad r > 0.$$
(9)

improving the description of the wave propagation up to angles of about  $40^{\circ}$ .

Here we focus on a proper boundary condition (BC) at the sea bottom for the SPE (7) coupled to an elastic "parabolic" model for the sea bottom. At the water surface one usually employs a Dirichlet BC  $\psi(z = 0, r) = 0$  and at the sea bottom one has to couple the wave propagation in the water to the wave propagation in the bottom.

#### 1.2 The Coupling Condition

For the bottom  $z > z_b$  one usually use a fluid model (i.e. assuming that (7) or (9) with possibly different rational approximation (8) also hold for  $z > z_b$ ) with constant parameters  $c_b$ ,  $\rho_b$ ,  $\alpha_b$  or with a linear squared refractive index [7,11].

In [4] we analyzed this coupling of WAPEs with different parameters  $p_0$ ,  $p_1$ ,  $q_1$  and it turned out that the coupled model is well-defined (and the resulting evolution equation is conservative in  $L^2(\mathbb{R}^+; (\sigma \rho)^{-1} dz))$  if the coupling condition

$$p_1(z)/q_1(z) =: \mu = \text{const} \tag{10}$$

is satisfied. Hence, it is not advisable to couple the WAPE and the SPE (where  $p_1 = 1/2; q_1 = 0$ ) numerically; in this case the evolution is not conservative in the dissipation-free case ( $\alpha \equiv 0$ ) [4]. If the parameters  $p_0, p_1, q_1$  are fixed in one medium, condition (10) still leaves two free parameters to choose a different rational approximation model of  $(1 - \lambda)^{\frac{1}{2}}$  in (8) for the second medium (cf. [8]). Hence, one can in fact obtain a better approximation in the second medium than with the originally intended "parabolic approximation".

#### **1.3** Transparent Boundary Conditions

In practical simulations one is only interested in the acoustic field  $\psi(z, r)$  in the water, i.e. for  $0 < z < z_b$ . While the physical problem is posed on the unbounded z-interval  $(0, \infty)$ , one wishes to restrict the computational domain in the z-direction by introducing an artificial boundary at or below the sea bottom. This artificial BC should of course change the model as little as possible, or ideally not at all.

In [13,15] Papadakis derived impedance BCs or transparent boundary conditions (TBC) for the SPE and the WAPE, which completely solves the problem of restricting the z-domain without changing the physical model: complementing the WAPE (9) with a TBC at  $z_b$  allows to recover — on the finite computational domain  $(0, z_b)$  — the exact half-space solution on  $0 < z < \infty$ . As the SPE is a Schrödinger equation, similar strategies have been developed independently for quantum mechanical applications, cf. the review article [1]. Let us finally note, that Zhang and Tindle [20] proposed an alternative approach to the impedance BCs or TBCs of Papadakis. By minimizing the reflection coefficient at the water-bottom interface they derived in their *equivalent fluid approximation* an expression for a complex fluid density that can be used for modelling an elastic sea bottom in a classical fluid model. However, this approach yields only satisfactory results for low shear wave speeds [20].

This work is organized as follows: In Sect. 2 we review the TBC for the SPE coupled to an elastic bottom in the frequency domain and in Sect. 3 present in detail the analytic inverse Laplace transformation to obtain this TBC in the time domain. Finally, we draw a conclusion and summarize the basic inversion rules previously used.

## 2 The Transparent Boundary Condition for a Fluid Bottom

The basic idea of the derivation is to explicitly solve the equation in the sea bottom, which is the exterior of the computational domain  $(0, z_b)$ . The TBC for the SPE (or Schrödinger equation) was derived in [3,13,15] for various application fields:

$$\psi(z_b, r) = -(2\pi k_0)^{-\frac{1}{2}} e^{\frac{\pi}{4}i} \frac{\rho_b}{\rho_w} \int_0^r \psi_z(z_b, r-\tau) e^{i\omega_b\tau} \tau^{-\frac{1}{2}} d\tau, \qquad (11)$$

with  $\omega_b = k_0 (N_b^2 - 1)/2$ . This BC is nonlocal in the range variable r and involves a mildly singular convolution kernel. Equivalently, it can be written as

$$\psi_z(z_b, r) = -\left(\frac{2k_0}{\pi}\right)^{\frac{1}{2}} e^{-\frac{\pi}{4}i} e^{i\omega_b r} \frac{\rho_w}{\rho_b} \frac{d}{dr} \int_0^r \psi(z_b, \tau) e^{-i\omega_b \tau} (r-\tau)^{-\frac{1}{2}} d\tau.$$
(12)

The r.h.s. of (12) can be expressed formally as a Riemann-Liouville fractional derivative of order  $\frac{1}{2}$ , cf. [3]:

$$\psi_{z}(z_{b},r) = -\sqrt{2k_{0}}e^{-\frac{\pi}{4}i}e^{i\omega_{b}r}\frac{\rho_{w}}{\rho_{b}}\partial_{r}^{1/2}[\psi(z_{b},r)e^{-i\omega_{b}r}].$$
(13)

## 3 The Transparent Boundary Condition for an Elastic Bottom

The coupling of the SPE with an *elastic parabolic equation* (EPE) for the sea bottom was described in [5,9,19]. Papadakis et al. [14,15] derived a TBC for this coupling in the frequency regime. It reads for the Laplace transformed wave field:

$$\hat{\psi}(z_b, s) = -\frac{\rho_b}{\rho_w} \frac{1}{k_0 N_s^4} \frac{1}{\sqrt[4]{M_p(s)}} \\ \times \left[ \left( 2M_s(s) + N_s^2 \right)^2 - 4 \sqrt[4]{M_p(s)} \sqrt[4]{M_s(s)} \left( M_s(s) + N_s^2 \right) \right] \hat{\psi}_z(z_b, s), \quad (14)$$

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with the notation

$$M_p(s) = 1 - N_p^2 - i\frac{2}{k_0}s, \qquad M_s(s) = 1 - N_s^2 - i\frac{2}{k_0}s.$$
(15)

Here,  $N_p = n_p + i\alpha_p/k_0$  and  $N_s = n_s + i\alpha_s/k_0$  denote the complex refractive indices for the compressional and shear waves in the bottom (cf. (2)).

# 4 The Transparent Boundary Condition in the Time Domain

In a tedious calculation the transformed TBC (14) can indeed be inverse Laplace transformed and it reads:

$$\psi(z_b, r) = C\left[\int_0^r \psi_z(z_b, r-\tau) e^{i\omega_p \tau} g(\tau) d\tau - 2i\varphi \int_0^r \psi_{zr}(z_b, r-\tau) e^{i\omega_p \tau} \tau^{-\frac{1}{2}} d\tau\right], \quad (16)$$

with

$$C = -\frac{\rho_b}{\rho_w} \frac{2}{k_0^{5/2} N_s^4} \sqrt{\frac{2}{\pi}} e^{\frac{\pi}{4}i}, \quad \omega_p = \frac{k_0}{2} \left(N_p^2 - 1\right), \quad \varphi = -\frac{k_0}{2} \left(N_p^2 - N_s^2\right),$$

and the kernel  $g(\tau)$  given by

$$g(\tau) = -3(1 - e^{i\varphi\tau})\tau^{-\frac{5}{2}} + i\frac{k_0}{2}(3N_p^2 - N_s^2 - 2N_s^2 e^{i\varphi\tau})\tau^{-\frac{3}{2}} + \frac{k_0^2}{2}(N_p^4 - N_p^2N_s^2 + \frac{1}{2}N_s^4 + N_p^2 - N_s^2)\tau^{-\frac{1}{2}} = O(\tau^{-\frac{1}{2}}), \text{ for } \tau \to \infty.$$

While this inverse transformation was carried out numerically in [14,15], our novel analytical TBC in the time regime may simplify both the analysis and the numerical solution of this coupled model. Let us remark that an asymptotic analysis of the elastic seabed was made by Makrakis [12].

#### 4.1 Derivation of (16)

With the abbreviation  $\hat{\psi}(s) := \hat{\psi}(z_b, s)$  and the notation

$$m_p(s) = \frac{k_0}{2} M_p(s) = -i \left[ s - i \frac{k_0}{2} (N_p^2 - 1) \right], \tag{17}$$

$$m_s(s) = \frac{k_0}{2} M_s(s) = -i \left[ s - i \frac{k_0}{2} (N_s^2 - 1) \right], \tag{18}$$

the transformed TBC (14) reads

$$\begin{split} \hat{\psi}(s) \\ &= -\frac{\rho_b}{\rho_w} \frac{1}{k_0 N_s^4} \left[ \frac{k_0}{2} \frac{\left(\frac{4}{k_0} m_s(s) + N_s^2\right)^2}{\sqrt[4]{m_p(s)}} - 4\sqrt{\frac{2}{k_0}} \sqrt[4]{m_s(s)} \left(\frac{2}{k_0} m_s(s) + N_s^2\right) \right] \hat{\psi}_z(s) \\ &= -\frac{\rho_b}{\rho_w} \frac{8\sqrt{2}}{k_0^{5/2} N_s^4} \left[ \frac{\left(m_s(s) + \frac{k_0}{4} N_s^2\right)^2}{\sqrt[4]{m_p(s)}} - 4\sqrt[4]{m_s(s)} \left(m_s(s) + \frac{k_0}{2} N_s^2\right) \right] \hat{\psi}_z(s), \quad (19) \end{split}$$

where we denote the content of the square brackets by  $f(s - \sigma)$  with

$$\sigma = i \frac{k_0}{2} \left( N_p^2 - 1 \right).$$
 (20)

We observe that we can write

$$m_p(s) = -i [s - \sigma], \qquad m_s(s) = -i \left[ s - \sigma + i \frac{k_0}{2} (N_p^2 - N_s^2) \right].$$

The next step is a shift in the argument of  $\hat{\psi}_z(s)$  in (19) by  $\sigma$ :

$$\hat{\psi}(s+\sigma) = -\frac{\rho_b}{\rho_w} \frac{8\sqrt{2}}{k_0^{5/2} N_s^4} f(s) \,\hat{\psi}_z(z_b, s+\sigma),\tag{21}$$

Taking the branch with positive real part  $\sqrt[+]{-i} = e^{-\frac{\pi}{4}i}$  we get the kernel f(s)

$$f(s) = \frac{\left[-is + \frac{k_0}{2}(N_p^2 - N_s^2) + \frac{k_0}{4}N_s^2\right]^2}{e^{-\frac{\pi}{4}i}\sqrt[4]{s}} - e^{-\frac{\pi}{4}i}\sqrt[4]{s} + i\frac{k_0}{2}(N_p^2 - N_s^2)(-i)\sqrt[4]{s} + i\frac{k_0}{2}(N_p^2 - N_s^2)}\left[s + i\frac{k_0}{2}N_p^2\right],$$

where

$$\begin{bmatrix} \cdots \end{bmatrix}^2 = -\left[s + i\frac{k_0}{2}N_p^2 - i\frac{k_0}{4}N_s^2\right]^2 \\ = -\left[s + i\frac{k_0}{2}(N_p^2 - N_s^2)\right]\left[s + i\frac{k_0}{2}N_p^2\right] + \frac{k_0^2}{16}N_s^4,$$

i.e. we have

$$\begin{split} f(s) &= e^{\frac{\pi}{4}i} \left\{ \frac{1}{\sqrt[4]{5}} \left[ \frac{k_0^2}{16} N_s^4 - \left[ s + i\frac{k_0}{2} (N_p^2 - N_s^2) \right] \left[ s + i\frac{k_0}{2} N_p^2 \right] \right\} \\ &+ \sqrt[4]{5} + i\frac{k_0}{2} (N_p^2 - N_s^2) \left[ s + i\frac{k_0}{2} N_p^2 \right] \right\} \\ &= e^{\frac{\pi}{4}i} \left\{ \left[ \sqrt[4]{5} + i\frac{k_0}{2} (N_p^2 - N_s^2) - \sqrt[4]{5} - i\frac{k_0}{2} (N_p^2 - N_s^2) \frac{1}{\sqrt[4]{5}} \right] \cdot \\ &\cdot \left[ s + i\frac{k_0}{2} N_p^2 \right] + \frac{k_0^2}{16} N_s^4 \frac{1}{\sqrt[4]{5}} \right\} \\ &= e^{\frac{\pi}{4}i} \left\{ \left[ \sqrt[4]{5} - \gamma - \sqrt[4]{5} + \gamma \frac{1}{\sqrt[4]{5}} \right] \left[ s + i\frac{k_0}{2} N_p^2 \right] + \frac{k_0^2}{16} N_s^4 \frac{1}{\sqrt[4]{5}} \right\}, \end{split}$$

with

$$\gamma = -i\frac{k_0}{2}(N_p^2 - N_s^2).$$

Hence, inserting in (21) we obtain

$$\hat{\psi}(s+\sigma) = \tilde{C} \left\{ i \frac{k_0}{2} N_p^2 \left[ \frac{1}{\sqrt{s-\gamma}} - \frac{1}{\sqrt{s}} + \gamma \frac{1}{\frac{1}{\sqrt{s}}} \right] + \frac{k_0^2}{16} N_s^4 \frac{1}{\frac{1}{\sqrt{s}}} \right\} \hat{\psi}_z(s+\sigma) \\ + \tilde{C} \left[ \frac{1}{\sqrt{s-\gamma}} - \frac{1}{\sqrt{s}} + \gamma \frac{1}{\frac{1}{\sqrt{s}}} \right] \left\{ s \hat{\psi}_z(s+\sigma) \right\},$$
(22)

where

$$\tilde{C} = -\frac{\rho_b}{\rho_w} \frac{8\sqrt{2}}{k_0^{5/2} N_s^4} e^{\frac{\pi}{4}i}.$$
(23)

Next, an inverse Laplace transformation of (22) yields the convolution integral

$$\psi(r) e^{-\sigma r} = \tilde{C} \int_0^r \psi_z(r-\tau) e^{-\sigma(r-\tau)} g_1(\tau) d\tau + \tilde{C} \int_0^r -\frac{\partial}{\partial \tau} \left[ \psi_z(r-\tau) e^{-\sigma(r-\tau)} \right] g_2(\tau) d\tau, \qquad (24)$$

$$g_{1}(\tau) = \mathcal{L}^{-1} \left\{ i \frac{k_{0}}{2} N_{p}^{2} \left[ \sqrt{s - \gamma} - \sqrt{s} + \gamma \frac{1}{\sqrt{s}} \right] + \frac{k_{0}^{2}}{16} N_{s}^{4} \frac{1}{\sqrt{s}} \right\}$$
$$= i \frac{k_{0}}{2} N_{p}^{2} \mathcal{L}^{-1} \left\{ \sqrt{s - \gamma} - \sqrt{s} \right\} + \frac{k_{0}^{2}}{4} (N_{p}^{2} - \frac{1}{2} N_{s}^{2})^{2} \mathcal{L}^{-1} \left\{ \frac{1}{\sqrt{s}} \right\}$$
$$= i \frac{k_{0}}{4\sqrt{\pi}} N_{p}^{2} (1 - e^{\gamma \tau}) \tau^{-\frac{3}{2}} + \frac{k_{0}^{2}}{4\sqrt{\pi}} (N_{p}^{2} - \frac{1}{2} N_{s}^{2})^{2} \tau^{-\frac{1}{2}}, \qquad (25)$$

$$g_{2}(\tau) = \mathcal{L}^{-1} \left\{ \sqrt{s - \gamma} - \sqrt{s} + \gamma \frac{1}{\sqrt{s}} \right\} = \frac{1}{2\sqrt{\pi}} (1 - e^{\gamma\tau}) \tau^{-\frac{3}{2}} + \frac{\gamma}{\sqrt{\pi}} \tau^{-\frac{1}{2}} \\ = \underbrace{\frac{1}{2\sqrt{\pi}} \left[ (1 - e^{\gamma\tau}) \tau^{-\frac{3}{2}} + \gamma \tau^{-\frac{1}{2}} \right]}_{=g_{3}(\tau)} + \underbrace{\frac{\gamma}{2\sqrt{\pi}} \tau^{-\frac{1}{2}}}_{=g_{4}(\tau)},$$
(26)

$$I_{3} = \int_{0}^{r} -\frac{\partial}{\partial \tau} \left[ \psi_{z}(r-\tau) e^{-\sigma(r-\tau)} \right] g_{3}(\tau) d\tau$$
  
= 
$$\int_{0}^{r} \psi_{z}(r-\tau) e^{-\sigma(r-\tau)} g_{3}'(\tau) d\tau - \underbrace{\psi_{z}(r-\tau) e^{-\sigma(r-\tau)} g_{3}(\tau) \Big|_{\tau=0}^{\tau=r}}_{=0 \quad (\text{with } \psi_{z}(0)=0)}, \quad (27)$$

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$$\psi(r) e^{-\sigma r} = \tilde{C} \int_0^r \psi_z(r-\tau) e^{-\sigma(r-\tau)} \left[ g_1(\tau) + g'_3(\tau) \right] d\tau$$
  
+  $\tilde{C} \int_0^r - \frac{\partial}{\partial r} \left[ \psi_z(r-\tau) e^{-\sigma(r-\tau)} \right] g_4(\tau) d\tau$   
=  $\tilde{C} \int_0^r \psi_z(r-\tau) e^{-\sigma(r-\tau)} \left[ g_1(\tau) + g'_3(\tau) \right] d\tau$   
+  $\tilde{C} \int_0^r \left[ \psi_{zr}(r-\tau) e^{-\sigma(r-\tau)} - \sigma \psi_z(r-\tau) e^{-\sigma(r-\tau)} \right] g_4(\tau) d\tau,$  (28)

i.e.

$$\psi(r) = \tilde{C} \left[ \int_0^r \psi_z(r-\tau) \, e^{\sigma\tau} \tilde{g}(\tau) \, d\tau + \int_0^r \psi_{zr}(r-\tau) \, e^{\sigma\tau} g_4(\tau) \, d\tau \right], \qquad (29)$$

where

$$\tilde{g}(\tau) := \left[g_1(\tau) + g'_3(\tau) - \sigma g_4(\tau)\right].$$
(30)

We calculate

$$g'_{3}(\tau) = \frac{1}{2\sqrt{\pi}} \left[ -\frac{3}{2} (1 - e^{\gamma\tau}) \tau^{-\frac{5}{2}} - \gamma e^{\gamma\tau} \tau^{-\frac{3}{2}} - \frac{\gamma}{2} \tau^{-\frac{3}{2}} \right]$$
$$= \frac{1}{4\sqrt{\pi}} \left[ -3(1 - e^{\gamma\tau}) \tau^{-\frac{5}{2}} - 2\gamma(\frac{1}{2} + e^{\gamma\tau}) \tau^{-\frac{3}{2}} \right],$$
(31)

and

$$\sigma g_4(\tau) = \frac{\sigma \gamma}{2\sqrt{\pi}} \tau^{-\frac{1}{2}} = \frac{1}{4\sqrt{\pi}} \frac{k_0^2}{2} (N_p^2 - 1) (N_p^2 - N_s^2) \tau^{-\frac{1}{2}},$$
(32)

i.e. (30) gives finally

$$\tilde{g}(\tau) = \frac{1}{4\sqrt{\pi}} \left[ ik_0 N_p^2 \left( 1 - e^{\gamma\tau} \right) \tau^{-\frac{3}{2}} + k_0^2 \left( N_p^2 - \frac{1}{2} N_s^2 \right)^2 \tau^{-\frac{1}{2}} - 3 \left( 1 - e^{\gamma\tau} \right) \tau^{-\frac{5}{2}} \right. \\ \left. + ik_0 \left( N_p^2 - N_s^2 \right) \left( \frac{1}{2} + e^{\gamma\tau} \right) \tau^{-\frac{3}{2}} - \frac{k_0^2}{2} \left( N_p^2 - 1 \right) \left( N_p^2 - N_s^2 \right) \tau^{-\frac{1}{2}} \right] \right] \\ = \frac{1}{4\sqrt{\pi}} \left[ \frac{k_0^2}{2} \left( N_p^4 - N_p^2 N_s^2 + \frac{1}{2} N_s^4 + N_p^2 - N_s^2 \right) \tau^{-\frac{1}{2}} \right. \\ \left. + i \frac{k_0}{2} \left( 3N_p^2 - N_s^2 - 2N_s^2 e^{\gamma\tau} \right) \tau^{-\frac{3}{2}} - 3 \left( 1 - e^{\gamma\tau} \right) \tau^{-\frac{5}{2}} \right] \\ = O(\tau^{-\frac{1}{2}}), \quad \tau \to \infty.$$

$$(33)$$

Finally, we define  $\varphi$ ,  $\omega$ , by setting  $\gamma =: i\varphi$ ,  $\sigma =: i\omega$  and

$$g(\tau) = 4\sqrt{\pi}\tilde{g}(\tau), \qquad C = \frac{\tilde{C}}{4\sqrt{\pi}}.$$
 (34)

This completes the calculation of (16).

## 5 Conclusion and Outlook

First, we will make first numerical investigations for these new TBCs and investigate their superiority compared to using their formulation in transformed space. Next, instead of using an ad-hoc discretization of the analytic transparent BC we will construct discrete TBCs of the fully discretized half-space problem in the spirit of [4].

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## **Appendix: Laplace–Transformations**

$$\mathcal{L}^{-1}\left\{\sqrt{s-\gamma} - \sqrt{s}\right\} = \frac{1}{2\sqrt{\pi}} (1 - e^{\gamma t}) t^{-\frac{3}{2}}, \qquad (L.1)$$

$$\mathcal{L}^{-1}\left\{\frac{1}{\sqrt{s}}\right\} = \frac{1}{\sqrt{\pi}} t^{-\frac{1}{2}},$$
 (L.2)

$$\mathcal{L}^{-1}\left\{\hat{\psi}(s+\sigma)\right\} = \psi(t) e^{-\sigma t},\tag{L.3}$$

$$\mathcal{L}^{-1}\left\{s\,\hat{\psi}(s+\sigma)\right\} = \frac{d}{dt}\,\left\{\psi(t)\,e^{-\sigma t}\right\} \quad \text{if }\psi(0) = 0. \tag{L.4}$$

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