# **An Approach for Developing Fourier Convolutions and Applications**

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**Abstract** Based on the papers published recently, this talk presents a concept of convolution so-called pair-convolution which is a generalization of known convolutions, and considers applications for solving integral equations.

**Keywords** Generalized convolution · Integral equation of convolution type · Banach algebra

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# **1 Introduction**

It is well-known that the transform

$$
(f *_{\mathcal{F}} g)(x) = \frac{1}{(2\pi)^{\frac{d}{2}}} \int_{\mathbb{R}^d} f(x - y)g(y)dy
$$
 (1.1)

is called the Fourier convolution of two functions *g* and *f* , and the following factorization identity holds

$$
\mathcal{F}(f *_{\mathcal{F}} g)(x) = (\mathcal{F}f)(x)(\mathcal{F}g)(x).
$$

The above-mentioned convolution was found most early, and nowadays it has been applying widely in both theoretical and practical problems.

We can say that many convolutions, generalized convolutions, and polyconvolutions of the well-known integral transforms as Fourier's, Hankel's, Mellin's,

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Laplace's and their applications have been published. Loosely speaking, the theory of convolutions has been strongly developing and vigorously discussing in many research groups (see  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$  $[1, 2, 4, 5, 7, 10, 11, 14, 15]$ , and references therein).

In fact, convolutions are considered as a powerful tool in many fields of mathematics such as numerical computing, digital, image and signal processing, partialdifferential equations, and other fields of mathematics (see [[3,](#page-6-9) [6–](#page-6-10)[16,](#page-6-11) [20\]](#page-6-12)). Other reason for which the theory of convolutions attracts attention of many mathematicians is that each of convolutions is a new integral transform, therefore it could be a new object of study.

#### *1.1 Present Studies of Convolution Operators*

It is easy to show a long list of authors and their works concerning convolution operators such as: A. Böttcher, L.E. Britvina, Yu. Brychkov, L. Castro, I. Feldman, H.J. Glaeske, I. Gohberg, N. Krupnik, O.I. Marichev, S. Saitoh, B. Silbermann, H.M. Srivastava, V.K. Tuan, S.B. Yakubovich. . . Among those listed, there are many mathematicians leading the potential and strong groups in the worldwide, they have been creating significant discoveries, namely: A. Böttcher (Germany), L.E. Britvina (Ukraina), Yu. Brychkov (Russia), L. Castro and S. Saitoh (Aveiro-Portugal and Gunma-Japan), I. Gohberg (Israel), B. Silbermann (Germany), H.M. Srivastava (Canada), V.K. Tuan (USA), S.B. Yakubovich (Porto, Portugal).

## <span id="page-1-0"></span>**2 An Approach to Developing Convolutions**

The nice idea of convolution focuses on the factorization identity. We now deal with the concept of convolutions. Let  $U_1$ ,  $U_2$ ,  $U_3$  be the linear spaces on the field of scalars K, and let V be a commutative algebra on K. Suppose that  $K_1 \in L(U_1, V)$ ,  $K_2 \in L(U_2, V)$ ,  $K_3 \in L(U_3, V)$  are linear operators from  $U_1, U_2, U_3$  to V respectively. Let *δ* denote an element in algebra *V* . We recall the definition of convolutions.

**Definition 2.1** (see also [[4\]](#page-6-2)) A bilinear map  $* : U_1 \times U_2 : \longrightarrow U_3$  is called a convolution associated with  $K_3$ ,  $K_1$ ,  $K_2$  (in that order) if the following identity holds

$$
K_3(\ast(f,g)) = \delta K_1(f) K_2(g),
$$

for any  $f \in U_1$ ,  $g \in U_2$ . Above identity is called the factorization identity of the convolution.

We now deal with several approaches to developing convolutions.

# <span id="page-2-0"></span>*2.1 Using Eigenfunctions*

Let  $\Phi_{\alpha}$  denote the Hermite function (see [\[14](#page-6-7)]).

**Theorem 2.2** ([\[18](#page-6-13), [19](#page-6-14)]) *The following transform defines a convolution*

$$
(f\stackrel{\Phi_{\alpha}}{\underset{\mathcal{F}}{\ast}}g)(x)=\frac{i^{|\alpha|}}{(2\pi)^d}\int_{\mathbb{R}^d}\int_{\mathbb{R}^d}f(u)g(v)\Phi_{\alpha}(x-u-v)dudv.
$$

Let  $r_0 \in \{0, 1, 2, 3\}$  be given, and let

<span id="page-2-2"></span>
$$
\Psi(x) = \sum_{|\alpha| = r_0 \pmod{4}} a_{\alpha} \Phi_{\alpha}(x) \quad (a_{\alpha} \in \mathbb{C})
$$
\n(2.1)

be a finite linear combination of the Hermite functions ( $|\alpha| \leq N$  for some  $N \in \mathbb{N}$ ). The following theorem is an immediate consequence of Theorem [2.2.](#page-2-0)

**Theorem 2.3** *The following transform defines a convolution*

<span id="page-2-3"></span>
$$
(f \frac{\psi}{\mathcal{F}} g)(x) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} f(u)g(v)\Psi(x-u-v)dudv.
$$

## *2.2 Trigonometric Weight Functions*

Let  $T_c$ ,  $T_s$  denote the Fourier-cosine and Fourier-sine integral transforms. Let  $h \in \mathbb{R}^d$  be fixed. Put  $\theta_1(x) = \cos x h := \cos(\langle x, h \rangle), \ \theta_2(x) = \sin x h := \sin(\langle x, h \rangle)$ as there is no danger of confusion.

**Theorem 2.4** (see [\[9](#page-6-15), [18,](#page-6-13) [19\]](#page-6-14)) *Each of the integral transforms* ([2.2](#page-2-1))*–*([2.5](#page-3-0)) *below defines a convolution*:

<span id="page-2-1"></span>
$$
(f \, \frac{\theta_1}{T_c} g)(x) = \frac{1}{4(2\pi)^{\frac{d}{2}}} \int_{\mathbb{R}^d} \left[ f(x - u + h) + f(x - u - h) + f(x + u + h) + f(x + u - h) \right] g(u) du, \tag{2.2}
$$

$$
(f \underset{T_c, T_s, T_s}{\overset{\theta_1}{*}} g)(x) = \frac{1}{4(2\pi)^{\frac{d}{2}}} \int_{\mathbb{R}^d} \left[ -f(x - u + h) - f(x - u - h) \right. \\ \left. + f(x + u + h) + f(x + u - h) \right] g(u) du, \tag{2.3}
$$

$$
(f \underset{T_c, T_s, T_c}{\overset{\theta_2}{*}} g)(x) = \frac{1}{4(2\pi)^{\frac{d}{2}}} \int_{\mathbb{R}^d} \left[ f(x - u + h) - f(x - u - h) + f(x + u + h) - f(x + u - h) \right] g(u) du, \tag{2.4}
$$

<span id="page-3-0"></span>
$$
(f \underset{T_c, T_c, T_s}{\overset{\theta_2}{*}} g)(x) = \frac{1}{4(2\pi)^{\frac{d}{2}}} \int_{\mathbb{R}^d} \left[ f(x - u + h) - f(x - u - h) - f(x + u + h) + f(x + u - h) \right] g(u) du.
$$
 (2.5)

<span id="page-3-1"></span>**Comparison 2.5** Different from the convolutions presented by other authors, what above does not require the invertibility of associated transforms. Indeed, according to our point of view as showed in Definition [2.1](#page-1-0) the condition about the invertibility of transforms is not needed for constructing convolutions; namely, three operators  $K_1, K_2, K_3$  may be un-injective. As we know that the Fourier-cosine and Fouriersine transforms  $T_c$  and  $T_s$  are not injective, but there are still many infinitely many convolutions associated with them as presented in [[9,](#page-6-15) [17–](#page-6-16)[19\]](#page-6-14). In our point of view, that is a main reason why no convolution for un-invertible transforms appears until this moment. Most of convolution multiplications published are not commutative and not associative.

#### **3 New Concept: Pair-Convolution**

In this section we propose a new concept so-called *pair-convolution* which is a considerable generalization of convolution and generalized convolutions.

For any given multi-index  $\alpha \in \mathbb{N}^d$ , consider the transform

$$
D_1(f,g)(x) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \Phi_\alpha(x+u+v) f(u)g(v) du dv.
$$

Using the convolutions in  $[18]$  $[18]$  we get

• *The case*  $|\alpha| = 0 \pmod{4}$ :

$$
T_c(D_1(f,g))(x) = \Phi_{\alpha}(x) ((T_c f)(x) (T_c g)(x) - (T_s f)(x) (T_s g)(x)),
$$
  
\n
$$
T_s(D_1(f,g))(x) = -\Phi_{\alpha}(x) ((T_c f)(x) (T_s g)(x) + (T_s f)(x) (T_c g)(x)).
$$

• *The case*  $|\alpha| = 1 \pmod{4}$ :

$$
T_c(D_1(f,g))(x) = \Phi_{\alpha}(x) ((T_c f)(x) (T_s g)(x) + (T_s f)(x) (T_c g)(x)),
$$
  
\n
$$
T_s(D_1(f,g))(x) = \Phi_{\alpha}(x) ((T_c f)(x) (T_c g)(x) - (T_s f)(x) (T_s g)(x)).
$$

• *The case*  $|\alpha| = 2 \pmod{4}$ :

$$
T_c(D_1(f,g)(x)) = \Phi_{\alpha}(x) ((T_s f)(x) (T_s g)(x) - (T_c f)(x) (T_c g)(x)),
$$
  
\n
$$
T_s(D_1(f,g))(x) = \Phi_{\alpha}(x) ((T_c f)(x) (T_s g)(x) + (T_s f)(x) (T_c g)(x)).
$$

• *The case*  $|\alpha| = 3 \pmod{4}$ :

$$
T_c(D_1(f,g))(x) = -\Phi_{\alpha}(x) ((T_c f)(x) (T_s g)(x) + (T_s f)(x) (T_c g)(x)),
$$
  
\n
$$
T_s(D_1(f,g))(x) = \Phi_{\alpha}(x) ((T_s f)(x) (T_s g)(x) - (T_c f)(x) (T_c g)(x)).
$$

Motivated by the operational identities above, we introduce the following concept. Let  $U$  be a linear space, and let  $V$  be a commutative algebra on the complex field  $\mathbb{C}$ . Let  $T_1, T_2 \in L(U, V)$  be the linear operators from *U* to *V*.

**Definition 3.1** A bilinear map  $* : U \times U : \longrightarrow U$  is called a *pair-convolution* associated with  $T_1, T_2$ , if there exist eight elements  $\delta_k \in V, k = 1, \ldots, 8$  so that the following identities hold for any  $f, g \in U$ :

$$
T_1(* (f, g)) = \delta_1 T_1 f T_1 g + \delta_2 T_1 f T_2 g + \delta_3 T_2 f T_1 g + \delta_4 T_2 f T_2 g,
$$
  

$$
T_2(* (f, g)) = \delta_5 T_1 f T_1 g + \delta_6 T_1 f T_2 g + \delta_7 T_2 f T_1 g + \delta_8 T_2 f T_2 g.
$$

*Example 3.2* The above-mentioned bilinear transform  $D_1$ (, ) is the pair-convolution for  $T_c$ ,  $T_s$ . Note that this transform is not the generalized convolution associated with  $T_c, T_s$ .

*Example 3.3* Consider the transform

$$
D_2(f, g)(x) := \frac{1}{4(2\pi)^d} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \left[ a \Phi_{\alpha}(x + u + v) + b \Phi_{\beta}(x + u - v) + c \Phi_{\gamma}(x - u + v) + d \Phi_{\delta}(x - u - v) \right] f(u)g(v) du dv,
$$

where  $a, b, c, d \in \mathbb{C}$ , and  $\alpha, \beta, \gamma, \delta$  are the multi-indexes. As ([2.2\)](#page-2-1),  $D_2($ , is a pairconvolution associated with  $\mathcal{F}, \mathcal{F}^{-1}.$ 

*Example 3.4* Let  $\Psi$  be the Hermite-type function as defined by [\(2.1\)](#page-2-2). Write

$$
\Psi(x) := \sum_{|\alpha|=0 \pmod{4}} a_{\alpha} \Phi_{\alpha}(x) + \sum_{|\alpha|=1 \pmod{4}} a_{\alpha} \Phi_{\alpha}(x)
$$
  
+ 
$$
\sum_{|\alpha|=2 \pmod{4}} a_{\alpha} \Phi_{\alpha}(x) + \sum_{|\alpha|=3 \pmod{4}} a_{\alpha} \Phi_{\alpha}(x).
$$
(3.1)

Using the operational identities of  $D_1($ ,  $)$ , we can prove that the transform

$$
D_3(f, g)(x) := \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \Psi(x \pm u \pm v) f(u) g(v) du dv \tag{3.2}
$$

is a pair-convolution associated with  $T_c, T_s$ .

*Example 3.5* Suppose that  $a_1, a_2, a_3, a_4$  are any complex numbers. By Theorem [2.4](#page-2-3) we can prove that the transform

$$
D_4(f, g)(x) := \frac{1}{4(2\pi)^{\frac{d}{2}}} \int_{\mathbb{R}^d} [a_1 f(x - u + h) + a_2 f(x - u - h) + a_3 f(x + u + h) + a_4 f(x + u - h)]g(u)du
$$

defines a pair-convolution associated with the transforms  $T_c$ ,  $T_s$ .

We now consider the general integral equation

<span id="page-5-0"></span>
$$
\lambda \varphi(x) + \int_{E} K(x, y)\varphi(y)dy = f(x). \tag{3.3}
$$

We suppose that, by way of decomposing the kernel as

$$
K(x, y) = \sum_{n=1}^{N} k_n(x, y)
$$
 (3.4)

such that each one of the transforms

$$
(K_n \varphi)(x) = \int_E k_n(x, y)\varphi(y)dy
$$
\n(3.5)

is a pair-convolution for specific operators  $T_1$ ,  $T_2$ , then ([3.3](#page-5-0)) may be solved by convolution approach. The main key of this approach is that we can reduce integral equations to a linear algebraic system of functional equations, and then apply an inverse transform of the transform  $aT_1 + bT_2$  for some  $a, b \in \mathbb{C}$ . Thanks to pairconvolutions this approach could be more flexible, and realizable for a larger class of equations.

## **4 Final Remarks**

To summary Sect. [3](#page-3-1), we can interpret in other words as: the generalized convolution transforms, and the pair-convolution transforms might be called the *factorisable integrals, and pair-factorisable integrals* respectively by means of two specific transforms.

**Problems for Further Studying** Construct more pair-convolutions for the wellknown integral transforms such as Hilbert, Mellin, Laplace, . . . , and look for their applications.

Finally, since the set of all Hermite functions is a normally orthogonal basic of  $L^2(\mathbb{R}^d)$ , and thanks to the infinitely many pair-convolutions concerning the Hermite functions as presented, we propose the following conjecture.

**Conjecture 4.1** *For any function*  $k \in L^2(\mathbb{R}^d)$ , *there exists a function*  $f \in L^2(\mathbb{R}^d)$ *sufficiently closed to k such that each one of the transforms*

$$
\int_{E} \int_{E} k(x \pm u \pm v) f(u)g(v) du dv
$$

*is either convolution or pair-convolution for specific operators*  $K_1, K_2$ .

If this fact would be proved, we would have an approximately solvable manner called convolution one which could be different from that of the Galerkin method for Fredholm integral equations.

<span id="page-6-9"></span><span id="page-6-1"></span><span id="page-6-0"></span>**Acknowledgements** This talk is based on the works joint with P.K. Anh, L.P. Castro, B.T. Giang, N.T.T. Huyen, S. Saitoh, P.T. Thao, and P.D. Tuan. This work was supported partially by the Viet Nam National Foundation for Science and Technology Development.

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