

Chapter 9

Intuitionistic Existential Instantiation and Epsilon Symbol

Grigori Mints

Abstract A natural deduction system for intuitionistic predicate logic with existential instantiation rule presented here uses Hilbert's ϵ -symbol. It is conservative over intuitionistic predicate logic. We provide a completeness proof for a suitable Kripke semantics, sketch an approach to a normalization proof, survey related work and state some open problems. Our system extends intuitionistic systems with ϵ -symbol due to Dragalin and Maehara.

Keywords Hilbert's ϵ -symbol · Intuitionistic predicate logic · Existential instantiation · Natural deduction · Sequent calculus

9.1 Introduction

In natural deduction formulations of classical and intuitionistic logic, the existence-elimination rule is usually taken in the form

$$\frac{\begin{array}{c} A(a) \\ \vdots \\ \exists x A(x) \quad C \\ C \end{array}}{C} \exists\text{-}$$

where a is a fresh variable. Existential instantiation is the rule

$$\frac{\exists x A(x)}{A(a)} \exists\text{i}$$

Prof. Mints passed away May 29, 2014

G. Mints (✉)

Department of Philosophy, Stanford University, Building 90, Stanford, CA 94305-2155, USA

where a is a fresh constant. It is sound and complete (with suitable restrictions) in the role of existence-elimination rule in classical predicate logic but is not sound intuitionistically, since it makes possible for example the following derivation:

$$\frac{\frac{\frac{C \rightarrow \exists x A(x), C \Rightarrow \exists x A(x)}{C \rightarrow \exists x A(x), C \Rightarrow A(a)} \exists i}{C \rightarrow \exists x A(x) \Rightarrow C \rightarrow A(a)}}{C \rightarrow \exists x A(x) \Rightarrow \exists x (C \rightarrow A(x))} \Rightarrow (C \rightarrow \exists x A(x)) \rightarrow \exists x (C \rightarrow A(x))$$

There are several approaches in the literature to introduction of restrictions making this rule conservative over intuitionistic predicate calculus.

We present an approach using intuitionistic version of Hilbert's epsilon-symbol and strengthening works by Dragalin Dragalin (1974) and Maehara (1970) where ϵ -terms are treated as partially defined. Then a survey of extensions and related approaches including the important paper by Shirai (1971) is given and some problems are stated. There is an obvious connection with the problem of Skolemization of quantifiers. The role of existence conditions in that connection is prominent in the work by Baaz and Iemhoff (2006).

We do not include equality since in this case adding of ϵ -symbol with natural axioms is not conservative over intuitionistic logic (Mints 1974; Osswald 1975). A simple counterexample due (in other terms) to Smorynski (1977) is

$$\forall x \exists y P(x, y) \rightarrow \forall x x' \exists y y' (Pxy \& Px'y' \& (x = x' \rightarrow y = y'))$$

In our natural deduction system $\text{NJ}\epsilon$ axioms and propositional inference rules are the same as in ordinary intuitionistic natural deduction, the same holds for \forall -introduction. The remaining rules are as follows:

$$\frac{\Gamma \Rightarrow \exists x F(x)}{\Gamma \Rightarrow F(\epsilon x F(x))} \exists i \tag{9.1}$$

existential instantiation,

$$\frac{\Gamma \Rightarrow t \downarrow \quad \Delta \Rightarrow \forall z F(z)}{\Gamma, \Delta \Rightarrow F(t)} \quad \frac{\Gamma \Rightarrow t \downarrow \quad \Delta \Rightarrow F(t)}{\Gamma, \Delta \Rightarrow \exists z F(z)} \tag{9.2}$$

where

$$\epsilon x A(x) \downarrow := \exists y (\exists x A(x) \rightarrow A(y)), \tag{9.3}$$

and $t \downarrow := \top$ (the constant "true") if t is a variable or constant.

Two semantics are given for $\text{NJ}\epsilon$, or more precisely to an equivalent Gentzen-style system $\text{IPC}\epsilon$ (Sect. 9.2). The first semantics, which is incomplete but convenient for a proof of conservative extension property over IPC is defined in Sect. 9.3.

The second semantics with a completeness proof for $\text{IPC}\epsilon$ is given in Sect. 9.4.

Section 9.4.1 presents a sketch of a possible proof of a normal form theorem. Section 9.5 surveys some of the previous work and Sect. 9.6 outlines some open problems.

9.2 Gentzen-Style System $\text{IPC}\epsilon$

Let us state our Gentzen-style rules for the intuitionistic predicate calculus $\text{IPC}\epsilon$ with ϵ -symbol. For simplicity we assume that the language does not have function symbols except constants. Formulas and terms are defined by familiar inductive definition plus one additional clause:

If $A(x)$ is a formula then $\epsilon x A(x)$ is a term.

Derivable objects of $\text{IPC}\epsilon$ are *sequents* $\Gamma \Rightarrow A$ where Γ is a finite set of formulas, A is a formula. This means in particular that structural rules are implicitly included below.

First, let's list the rules of the intuitionistic predicate calculus IPC without ϵ -symbol.

Axioms:

$$\Gamma, A \Rightarrow A, \quad \Gamma, \perp \Rightarrow A.$$

Inference rules:

$$\frac{\Gamma \Rightarrow A \quad \Gamma \Rightarrow B}{\Gamma \Rightarrow A \& B} \Rightarrow \& \quad \frac{A, B, \Gamma \Rightarrow \Delta}{A \& B, \Gamma \Rightarrow \Delta} \& \Rightarrow$$

$$\frac{A, \Gamma \Rightarrow \Delta \quad B, \Gamma \Rightarrow \Delta}{A \vee B, \Gamma \Rightarrow \Delta} \vee \Rightarrow \quad \frac{\Gamma \Rightarrow A}{\Gamma \Rightarrow A \vee B} \Rightarrow \vee \quad \frac{\Gamma \Rightarrow B}{\Gamma \Rightarrow A \vee B} \Rightarrow \vee$$

$$\frac{\Gamma \Rightarrow A \quad B, \Gamma \Rightarrow \Delta}{A \rightarrow B, \Gamma \Rightarrow \Delta} \rightarrow \Rightarrow \quad \frac{A, \Gamma \Rightarrow B}{\Gamma \Rightarrow A \rightarrow B} \Rightarrow \rightarrow$$

$$\frac{\Gamma \Rightarrow A(t)}{\Gamma \Rightarrow \exists x A(x)} \Rightarrow \exists \quad \frac{\Gamma \Rightarrow A(b)}{\Gamma \Rightarrow \forall x A(x)} \Rightarrow \forall$$

$$\frac{A(b), \Gamma \Rightarrow G}{\exists x A(x), \Gamma \Rightarrow G} \exists \Rightarrow \quad \frac{A(t), \Gamma \Rightarrow G}{\forall x A(x), \Gamma \Rightarrow G} \forall \Rightarrow$$

$$\frac{\Gamma \Rightarrow C \quad C, \Gamma \Rightarrow G}{\Gamma \Rightarrow G} \text{Cut}$$

For $\text{IPC}\epsilon$ quantifier-inferences $\Rightarrow \exists, \Rightarrow \forall$ are modified by requirement that the term t substituted in the rule should be “defined” (cf. (9.3)).

$$\frac{\Gamma \Rightarrow t \downarrow F(t), \Delta \Rightarrow \Delta}{\forall z F(z), \Gamma, \Delta \Rightarrow \Delta} \forall \Rightarrow \quad \frac{\Gamma \Rightarrow \Delta, t \downarrow \Gamma \Rightarrow \Delta, F(t)}{\Gamma \Rightarrow \Delta, \exists z F(z)} \Rightarrow \exists \quad (9.4)$$

$\exists \Rightarrow$ -rule is also changed for $\text{IPC}\epsilon$:

$$\frac{A(\epsilon x A(x)) \Gamma \Rightarrow G}{\Gamma, \exists x A(x) \Rightarrow G} \exists_\epsilon \Rightarrow \quad (9.5)$$

A routine proof shows that $\text{IPC}\epsilon$ is equivalent to a Hilbert-style system obtained by weakening familiar axioms for quantifiers to

$$(\epsilon Q1) \ t \downarrow \& \forall x A(x) \rightarrow A(t)$$

$$(\epsilon Q2) \ t \downarrow \& A(t) \rightarrow \exists x A(x)$$

and adding the axiom

$$\exists x A(x) \rightarrow A(\epsilon x A(x))$$

9.2.1 Equivalence of $\text{IPC}\epsilon$ and $\text{NJ}\epsilon$

Let us recall that in natural deduction a sequent

$$A_1, \dots, A_n \Rightarrow A$$

is used to indicate that A is deducible from assumptions A_1, \dots, A_n .

Theorem 9.1 *A sequent is provable in $\text{NJ}\epsilon$ iff it is provable in $\text{IPC}\epsilon$.*

Proof The proof is routine: every rule of one of these systems is directly derivable in the other system. Let's show derivations of the rules $\exists i$ and $\exists \Rightarrow$ from each other using abbreviation $e := \epsilon x F(x)$.

$$\frac{\Gamma \Rightarrow \exists x F(x) \quad \frac{F(e) \Rightarrow F(e)}{\exists x F(x) \Rightarrow F(e)}}{\Gamma \Rightarrow F(e)} \exists \Rightarrow \quad \frac{\exists x F(x) \Rightarrow \exists x F(x) \quad \frac{F(e), \Gamma \Rightarrow G}{\Gamma \Rightarrow F(e) \rightarrow G}}{\exists x F(x), \Gamma \Rightarrow G} \exists i$$

9.3 A Kripke Semantics for Intuitionistic ϵ -symbol

To prove that $\text{IPC}\epsilon$ is conservative over IPC we present an incomplete semantics modifying a semantics from Dragalin (1974). The main modification is in the definition of $t \downarrow$ and treatment of atomic formulas containing ϵ -terms $\epsilon x A$.

Definition 9.1 Let w be a world in a Kripke model. Denote

$$\epsilon x A(x) \downarrow w \equiv w \models \epsilon x A(x) \downarrow .$$

We say that a term $\epsilon x A$ is *defined* in w iff $\epsilon x A(x) \downarrow w$.

The symbol \perp in the next definition indicates the condition (9.6) below.

Definition 9.2 An intuitionistic Kripke $\epsilon \perp$ -model (or simply model in this section)

$$\mathcal{M} = (W, <, D, \models, V)$$

has to satisfy the following conditions:

$(W, <)$ is a Kripke frame with a strict partial ordering $<$,

D is a domain function assigning to every $w \in W$ a non-empty set $D(w)$ monotone with respect to $<$,

$w \models A$ is a relation between worlds $w \in W$ and atomic formulas A with constants from

$$D := \cup_{w \in W} D(w)$$

monotonic with respect to \leq and such that

$$w \not\models A \text{ if } A \text{ contains at least one constant in } D - D(w). \quad (9.6)$$

V is a valuation function assigning a constant $V(e, w) \in D$ to any ϵ -term e (possibly containing constants from D) and $w \in W$.

The relation \models is extended to composite formulas in the familiar way. The components of an ϵ -model have to satisfy the following conditions.

$$V(\epsilon x B(x, \epsilon y C), w) = V(\epsilon x B(x, V(\epsilon y C, w)), w), \quad (9.7)$$

$$w \models A(\epsilon y C) \leftrightarrow w \models A(x, V(\epsilon y C)), \quad (9.8)$$

where substitution of $\epsilon y C$ is safe, that is no free variable of $\epsilon y C$ becomes bound. Also, if $e \downarrow w$ for a term $e := \epsilon x A(x)$, then

$$V(e, w) \in D(w) \text{ and } V(e, w') = V(e, w) \text{ for every } w' \geq w.$$

Note. The requirement (9.6) is sound as we prove at the rest of this section, but it leads to incompleteness. For example the formula

$$P(\epsilon x P(x)) \rightarrow \exists x P(x)$$

is valid: if $\epsilon x P(x)$ is undefined in a world w then the premise is false in w , otherwise the conclusion is true. However this formula is not derivable, since its instance

$$(C \rightarrow P(e)) \rightarrow \exists x(C \rightarrow P(x)) \quad (9.9)$$

where C is a propositional variable and $e = \epsilon x(C \rightarrow P(x))$, implies

$$(C \rightarrow \exists x P(x)) \rightarrow \exists x(C \rightarrow P(x)). \quad (9.10)$$

Indeed, the following figure (where $e_0 = \epsilon x P(x)$) is a derivation, and one application of (9.9) yields (9.10).

$$\frac{\frac{\frac{C \Rightarrow C}{C \rightarrow \exists x P(x)}, \frac{P(e_0) \Rightarrow C \rightarrow P(e_0)}{\exists x P(x) \Rightarrow e_0 \downarrow}}{\exists x P(x) \Rightarrow \exists x(C \rightarrow P(x))}, \frac{C, C \rightarrow P(e) \Rightarrow P(e)}{C, \exists x(C \rightarrow P(x)) \Rightarrow P(e)}}{C, \exists x P(x) \Rightarrow P(e)} \quad (9.11)$$

We continue the proof of soundness. The proofs of the next lemmata are routine.

Lemma 9.1 *Let t be a closed term, A a closed formula with constants from D . Then*

$$w \leq w' \rightarrow (t \downarrow w \rightarrow t \downarrow w' \ \& \ (w \models A \rightarrow w' \models A))$$

Proof Simultaneous induction on t, A .

Lemma 9.2 *If Γ is a set of formulas, G a formula then $\Gamma \vdash G$ in $\text{IPC}\epsilon$ implies $\Gamma \models G$.*

Proof Induction on derivations. Checking the rule $\exists \Rightarrow$ uses the fact that $\exists x A(x)$ implies $\epsilon x A(x) \downarrow$. It may be interesting to check whether any other properties of the formula $t \downarrow$ are used. \square

Theorem 9.2 *If A, B are formulas without ϵ -symbol then $A \vdash B$ in $\text{IPC}\epsilon$ implies $A \vdash B$ in intuitionistic predicate logic IPC .*

Proof We need to prove that for every Kripke model

$$\mathcal{M}_0 = (W, <, D, \models_0)$$

for intuitionistic predicate logic refuting $A \rightarrow B$ there is an $\text{IPC}\epsilon$ -model refuting $A \rightarrow B$. Before applying the construction from Dragalin (1974), let us recall a refinement of a completeness theorem for intuitionistic predicate logic IPC .

Lemma 9.3 *The following additional requirements to the definition of a Kripke frame $(W, <, D)$ for IPC are still complete:*

1. W is a countable tree with a root $\mathbf{0}$ such that each $w \in W$ except $\mathbf{0}$ has unique immediate $<$ -predecessor and the number of predecessors of w is finite.

2. domains $D(w)$ are strictly increasing: if $w < w'$ then $D(w)$ is a proper subset of $D(w')$.

Proof The requirement 1 is satisfied by the canonical proof search tree for a given sequent, see for example Mints (2000). To satisfy the second requirement, note that an infinite branch of the canonical proof search tree does not have “leaf worlds”: for every $w \in W$ there exists a $w' > w$. Now take a fixed element $e \in D(w_0)$ and duplicate it by a fresh element, say e_w in every world w . More precisely for the new domain function D' define

$$e_w \in D'(w) - D'(w^-),$$

where w^- is the immediate predecessor of w . Let's extend the relation \models by identifying e_w and e , more precisely define for atomic formulas $P(c_1, \dots, c_n)$ with constants $c_i \in D'(w)$

$$w \models P(c_1, \dots, c_n) := w \models P(c_1^-, \dots, c_n^-)$$

where $c_i^- = e$, if $c_i = e_w$ and $c_i^- = c_i$ otherwise. It is easily proved by induction on formulas that this property extends to all formulas:

$$w \models A(c_1, \dots, c_n) \text{ implies } w \models A(c_1^-, \dots, c_n^-)$$

so that the new model verifies (and refutes) the same formulas. \dashv

Proof of the Theorem 9.2. We extend the model for IPC satisfying the previous Lemma by the definition of values for ϵ -terms without changing domains $D(w)$, which is done by induction on construction of the term. Assume that the elements of D are well-ordered by a relation $<$ in some arbitrary way. In view of the condition (9.7) it enough to define $V(\epsilon x A, w)$ when $\epsilon x A$ does not have proper non-closed ϵ -subterms. In that case,

if $\epsilon x A(x) \downarrow w$, take the $<$ -minimal element $v \leq w$ such that $\epsilon x A \downarrow v$, then define

$$V(\epsilon x A(x), w) := \text{the } < \text{-first } d \in D(v) (v \models (\exists x A(x) \rightarrow A(d)))$$

If not $\epsilon x A(x) \downarrow w$, define $V(\epsilon x A(x), w)$ as the $<$ -first $d \in D - D(w)$. \square

9.4 Completeness Proof for IPC ϵ

We prove that removing condition (9.6) but preserving familiar monotonicity requirement

$$w \leq w' \rightarrow (w \models A \rightarrow w' \models A) \tag{9.12}$$

leads to a complete semantics for IPC ϵ .

For simplicity consider term models where individual domain $D(w)$ for every world w consists of terms, and the evaluation function for terms is identity: value of a term t is t . In particular the value of $\epsilon x A$ is $\epsilon x A$.

Definition 9.3 An intuitionistic Kripke (term) ϵ -model (or simply ϵ -model)

$$\mathcal{M} = (W, <, D, \models, V)$$

has to satisfy the following conditions.

$(W, <)$ is a Kripke frame with a strict partial ordering $<$,

D is a domain function assigning to every $w \in W$ a non-empty set $D(w)$ (of terms) monotone with respect to $<$,

$w \models A$ is a relation between worlds w and atomic formulas A with constants from

$$D := \cup_{w \in W} D(w)$$

monotonic with respect to \leq .

V is a valuation function assigning a constant $V(e, w) \in D$ to any ϵ -term e (possibly containing constants from D) and $w \in W$. (In a term model $V(e, w) = e$.)

The relation \models is extended to composite formulas in the familiar way. The components of an ϵ -model have to satisfy the following conditions.

$$V(\epsilon x B(x, \epsilon y C), w) = V(\epsilon x B(x, V(\epsilon y C, w)), w) \quad (9.13)$$

$$w \models A(\epsilon y C) \leftrightarrow w \models A(x, V(\epsilon y C)) \quad (9.14)$$

where substitution of $\epsilon y C$ is safe, that is no free variable of $\epsilon y C$ becomes bound. Also if $e \downarrow w$ for a term $e := \epsilon x A(x)$, then

$$V(e, w) \in D(w) \text{ and } V(e, w') = V(e, w) \text{ for every } w' \geq w.$$

Let's present a completeness proof along familiar lines.

Definition 9.4 An infinite sequent is a pair of sets Γ, Δ of formulas such that there is an infinite number of variables not in $\Gamma \cup \Delta$. An infinite sequent w is written as $\Gamma \Rightarrow \Delta$ and notation

$$w_a := \Gamma, w_s := \Delta$$

is used for its antecedent and succedent.

L_w denotes the set of all terms and formulas with free variables and constants occurring in formulas of w .

$D(w)$ is the set of all terms $t \in L_w$ such that $(t \downarrow) \in w_a$. In other words $D(w)$ consists of all free variables and constants in w plus all ϵ -terms $\epsilon x A(x)$ such that $\exists y (\exists x A(x) \rightarrow A(y)) \in w_a$.

An infinite sequent w is *consistent*, if it is underivable, that is if no finite sequent $\Gamma \Rightarrow \Delta$ with $\Gamma \subset w_a$, $\Delta \subset w_s$ is derivable in IPC ϵ .

A consistent infinite sequent w is *maximal consistent* if $w_a \cup w_s$ is the whole set of formulas in L_w .

Lemma 9.4 *Every consistent infinite sequent w_0 can be extended to a maximal consistent sequent.*

Proof Enumerate all formulas containing only free variables and constants in L_{w_0} , then add them one by one to w_a or w_s preserving consistency. At the n -th stage of this process a sequent w_n , an extension of w_0 by a finite number of formulas is generated.

It cannot happen that at some stage n of this process a formula A fits none of w_a^n , w_s^n , i.e., both of

$$w_a^n \Rightarrow w_s^n, A_n \quad A_n, w_a^n \Rightarrow w_s^n$$

are inconsistent, since in that case $w_a^n \Rightarrow w_s^n$ is inconsistent by a cut rule. \square

Important example. If w is $\forall x P(x) \Rightarrow P(\epsilon x Q(x))$ with $P \neq Q$, and the first “undecided” formula is $\exists y(\exists x Q(x) \rightarrow Q(y))$ then this formula is added to the succedent, since adding it to the antecedent results in an inconsistent sequent.

Lemma 9.5 *Every maximal consistent infinite sequent w is closed under invertible rules of multiple-succedent version of IPC ϵ , that is under all rules except $\Rightarrow \forall$, $\Rightarrow \rightarrow$. More precisely*

$$(A \& B) \in w_a \text{ implies } A \in w_a \text{ and } B \in w_a,$$

$$(A \rightarrow B) \in w_a \text{ implies } A \in w_s \text{ or } B \in w_a,$$

$$(A \vee B) \in w_a \text{ implies } A \in w_a \text{ or } B \in w_a,$$

$$(\forall x A(x)) \in w_a \text{ implies } (\forall t \in D(w))(A(t) \in w_a)$$

$$(\exists x A(x)) \in w_a \text{ implies } A(\epsilon x A(x)) \in w_a$$

$$(A \vee B) \in w_s \text{ implies } A \in w_a \text{ and } B \in w_a,$$

$$(A \& B) \in w_s \text{ implies } A \in w_a \text{ or } B \in w_a,$$

$$(\exists x A(x)) \in w_s \text{ implies } (\forall t \in D(w))(A(t) \in w_s)$$

Proof Suppose $(A \& B) \in w_a$. If $A \notin w_a$ then by maximality $A \in w_s$. Therefore w is inconsistent.

Suppose $\forall x A \in w_a$. If $A(t) \notin w_a$ for some $t \in D(w)$ then by maximality $A(t) \in w_s$. Therefore $\forall x A \Rightarrow A(t)$ is derived by one application of the $\forall \Rightarrow$ -rule,

and hence w is inconsistent. Note that additional premise $t \downarrow$ of this rule is available by $t \in D(w)$.

Other cases are similar. \square

Definition 9.5 For infinite sequents w, w' define

$$w < w' \text{ iff } w_a \subseteq w'_a \text{ and } D(w) \subseteq D(w')$$

Lemma 9.6 *The set of maximal consistent sequents is closed under non-invertible rules $\Rightarrow \rightarrow, \Rightarrow \forall$. More precisely,*

For every maximal consistent sequent w , if $(A \rightarrow B) \in w_s$ then there exists a maximal consistent sequent $w' > w$ with $A \in w'_a, B \in w'_s$.

For every maximal consistent sequent w , if $\forall x A(x) \in w_s$ then there exists a maximal consistent sequent $w' > w$ with $A(a) \in w'_s$ for some variable $a, a \in D(w')$.

Proof If $(A \rightarrow B) \in w_s$ then the sequent $A, w_a \Rightarrow B$ is consistent, since otherwise one application of the rule $\Rightarrow \rightarrow$ leads to inconsistency of w . Now extend $A, w_a \Rightarrow B$ to a complete consistent sequent.

If $\forall x A(x) \in w_s$ then the sequent $w_a \Rightarrow A(a)$ for a fresh variable a is consistent, since otherwise one application of the rule $\Rightarrow \forall$ leads to inconsistency of w . Now extend $A, w_a \Rightarrow B$ to a complete consistent sequent. \square

Definition 9.6 (Canonical model) Consider the following model

$$M = (W, <, V, \models).$$

W is the set of all maximal complete sequents, $<, V$ are as above,

$w \models A$ iff $A \in w_a$ for atomic formulas A .

This definition implies that $w \not\models A$ for atomic $A \in w_s$, since otherwise w is inconsistent.

Lemma 9.7 *The relation \models for atomic formulas and the function D is monotonic.*

Proof Consider only $D(w)$. Let $w < w'$. All variables and constants in $D(w)$ are in $D(w')$ by the definition of $<$. Assume $\epsilon x A(x) \in D(w)$, that is $\epsilon x A(x) \downarrow \in w_a$. Then $\epsilon x A(x) \downarrow \in w'_a$ by $w < w'$, and hence $\epsilon x A(x) \in D(w')$. \square

Lemma 9.8 *For every formula $A \in L_w$*

1. $A \in w_a$ implies $w \models A$,
2. $A \in w_s$ implies $w \not\models A$,

Proof Induction on formulas using Lemmata 9.5 and 9.6. For example, if $A \& B \in w_a$ then $A, B \in w_a$, therefore $w \models A, w \models B$ by induction hypothesis, and hence $w \models A \& B$.

If $\forall x A \in w_s$ then there exists $w' > w$ such that $A(a) \in w'_s$ for some variable $a \in D(w')$. Therefore $w' \not\models A(a)$ and hence $w \not\models \forall x A(x)$. \square

Theorem 9.3 *The system $IPC\epsilon$ is sound and complete.*

Proof Soundness is checked as before. For completeness take an arbitrary underivable formula A , then extend sequent $\Rightarrow A$ to a maximal consistent set w . By the previous Lemma $w \not\models A$. \square

9.4.1 About a Cut-Free Formulation

It is plausible that the completeness proof for the rules with cut given above can be modified to provide completeness of a cut-free formulation. As our example (9.11) shows, complete cut-elimination is impossible. One may need to admit cuts for formulas of the form $\epsilon x A(x) \downarrow$ where $\epsilon x A(x)$ occurs in the conclusion, and subformulas of such formulas. The following proof where $e := \epsilon x P(x)$ is another example.

$$\frac{\frac{\frac{\exists x P(x) \Rightarrow e \downarrow \quad \neg P(e), P(e), \exists x P(x) \Rightarrow P(0)}{\forall x \neg P(x), P(e), \exists x P(x) \Rightarrow P(0)}}{\forall x \neg P(x), P(e) \Rightarrow \exists x P(x) \rightarrow P(0)}}{\forall x \neg P(x), P(e) \Rightarrow \exists y (\exists x P(x) \rightarrow P(y))} \quad \frac{e \downarrow \Rightarrow e \downarrow \quad \neg P(e), P(e) \Rightarrow}{e \downarrow, \forall x \neg P(x), P(e) \Rightarrow}}{\forall x \neg P(x), P(e) \Rightarrow}$$

9.5 Comparison with Previous Work

9.5.1 System $IPC\Omega\epsilon$

Let $\exists \epsilon x A(x) := \exists x A(x)$.

A. Dragalin's system $IPC\Omega\epsilon$ from Dragalin (1974) for a given language $\Omega\epsilon$ is obtained by weakening familiar axioms for quantifiers

$$(\epsilon Q1) \exists t \& \forall x A(x) \rightarrow A(t)$$

$$(\epsilon Q2) \exists t \& A(t) \rightarrow \exists x A(x)$$

and adding the axiom

$$\exists x A(x) \rightarrow A(\epsilon x A(x))$$

A. Dragalin (Dragalin 1974) tried to avoid as much as possible dealing with a value of an ϵ -term in a world w where the term is not defined. Values (in a given world w) are assigned only to ϵ -terms defined in w , and many intermediate results are proved

only for the case when all relevant ϵ -terms are defined. Nevertheless soundness is established for all formulas, without any restrictions. As pointed out earlier, this system is not complete.

In Sect. 9.3 we changed the definition of a model from Dragalin (1974) to a more uniform version: ϵ -term e which is not defined at the world w is assigned a value at w , but this value does not belong to the individual domain $D(w)$. To make this possible, the Kripke frame underlying the model and the domain function should satisfy additional conditions that still guarantee completeness.

Let us consider other systems in the literature.

9.5.2 Systems with $\exists y(\exists x A(x) \rightarrow A(y))$ as Existence Condition

In systems due to Maehara (1970) and Shirai (1971), instead of using $\exists x A(x)$ as a discriminating criterion, a weaker formula $\exists y(\exists x A(x) \rightarrow A(y))$ is employed. This still allows to anticipate a correct future value of the term $\epsilon x A(x)$ in a world w even if $\exists x A(x)$ fails in w .

Sh. Maehara treats a weaker language than ours: $\epsilon x A(x)$ is a syntactically correct term only if it is closed. He proves (using partial cut-elimination and other syntactic transformations) conservativity over IPC of the rules

$$\frac{\Gamma, \exists x A(x) \quad A(\epsilon x A(x)), \Delta \Rightarrow G}{\Gamma, \Delta \Rightarrow G} \exists_{\epsilon}$$

$$\frac{\Gamma \Rightarrow t \downarrow \quad F(t), \Delta \Rightarrow G}{\forall z F(z), \Gamma, \Delta \Rightarrow G} \quad \frac{\Gamma \Rightarrow t \downarrow \quad \Delta \rightarrow F(t)}{\Gamma, \Delta \Rightarrow \exists z F(z)} \quad (9.15)$$

where

$$\epsilon x A(x) \downarrow := \exists y(\exists x A(x) \rightarrow A(y)); \quad a \downarrow := \top \quad (9.16)$$

Here \top is the constant true, a is an arbitrary variable.

Note that the first of these rules contains a hidden cut. This conservativity result is used to establish a kind of completeness theorem for IPC over a modification of Kripke semantics, although this modification is not stated explicitly. More precisely, Sh. Maehara proves Kripke-style soundness and completeness results for the relation $A \in \alpha$ between formulas A and complete consistent (in his sense) subsets α of the set of formulas. Only his condition for \forall is not standard:

$$\forall x A(x) \in \alpha \leftrightarrow (\exists B)(B \in \alpha \& \forall \beta \forall t [B \in \beta \rightarrow (t \in D_{\beta} \rightarrow A(t) \in \beta)])$$

To establish this condition he uses admissibility of the following rule in his system:

$$\frac{\exists y(\exists x \neg A(x) \rightarrow \neg A(y)) \rightarrow A(\underline{x} \neg A(x))}{\forall x A(x)}$$

This rule approximates equivalence

$$\forall x A(x) \leftrightarrow A(\epsilon x \neg A(x))$$

which is valid only classically.

Shirai (1971) removes the restriction to closed ϵ -terms. He considers a language with the existence predicate denoted by D . Instead of the rules used by Maehara he considers the following axioms:

$$D(t), \exists y(\exists x A(x, t) \rightarrow A(y, t)) \Rightarrow D(\epsilon x A(x)) \quad (9.17)$$

$$D(t), \exists x A(x, t) \Rightarrow A(\epsilon x A(x, t), t)$$

plus standard modifications of quantifier rules for the system with existence predicate D .

He proves conservativity of his system over IPC by a combination of a partial cut-elimination and Maehara's argument.

Leivant (1973) and Smirnov (1979) define logical systems with ϵ -symbol conservative over IPC by requiring that assumptions discharged in natural deduction rules contain no ϵ -symbol. These systems are probably much weaker than $\text{IPC}\epsilon$. The system introduced by the author (Mints 1974) is certainly weaker than $\text{IPC}\epsilon$: a sequent containing subterm $\epsilon x A(x, y)$ with a bound variable y is syntactically correct only provided $\forall y \exists x A(x, y)$ is a member of the antecedent.

9.6 Further Work

Complete the proof of cut-elimination for $\text{IPC}\epsilon$ and of the normal form theorem for $\text{NJ}\epsilon$.

Give a syntactic proof of cut-elimination for $\text{IPC}\epsilon$ and of normalization for $\text{NJ}\epsilon$.

Provide a semantics for the systems by Maehara (1970) and Shirai (1971) and find out whether these systems admit cut-elimination. It seems that the system by Shirai provides the most general formulation of the idea that ϵ -terms are partially defined in some arbitrary way. The restriction $D(t)$ allowing to quantify over value of t can be an arbitrary predicate with the only condition (9.17).

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