Emerging Soft Computation Tools for Skin Cancer Diagnostics

J. Bethanney Janney, Sindu Divakaran, T. Sudhakar, P. Grace Kanmani, R. J. Hemalatha, and Manas Nag

1 Introduction

Machine learning (ML) and artifcial intelligence (AI) are quickly developing felds, particularly adversely infuencing numerous conventional organizations and enterprises, and offer to rebuild numerous parts of day-to-day existence. Such rebuilding will be especially helpful in medicine, where life or death choices could be altogether further developed utilizing information and calculations. High-level clinical image examination is progressively fundamental in the visualization, treatment, and analytical assessment of illness. A perspective of machine-learning and deeplearning algorithms is extended to investigate and prefer a non-invasive technique for skin cancer diagnosis that accurately classifes the lesions as malignant or benign melanoma.

Earlier recognition of skin malignancy is critical. Skin cancer is now considered to be a major hazardous form of cancer observed in humans. One of the biggest causes of skin cancer is the sun's ultraviolet (UV) emission. Continuous exposure to sun can affect ageing and pave the way for cancer development. The sun's UV light may damage the elastin fbers present in the skin, and when these fbers break down they continue to sag and stretch and fnally lose the ability to get back to the original

R. J. Hemalatha

M. Nag Department of Radiology and Imaging Sciences, National Institute of Health, Bethesda, MD, USA

J. Bethanney Janney · S. Divakaran (\boxtimes) · T. Sudhakar · P. Grace Kanmani

Department of Biomedical Engineering, Sathyabama Institute of Science and technology, Chennai, India

Department of Biomedical Engineering, Vel's Institute of Science, Technology and Advanced Studies, Chennai, India

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place [\[1](#page-16-0)]. Skin malignancy develops when the melanocytes mutate and become cancerous. Skin malignancy is commonly categorized as malignant or benign melanoma. When a group of melanocytes gather together and form a lesion, owing to elevated concentration of melanin, a brown pigmented patch appears on the skin. These melanocytic lesions may consist of cells that are benign or malignant. It is possible to divide non-melanocytic lesions into benign and malignant neoplasms. Seborrheic keratoses, vascular lesions, and dermatofbroma are examples of the former. The malignant neoplasm is termed basal cell carcinoma (BCC). It is the prevalent type of fatal skin disease, but owing to its slow growth, it is regarded as less hazardous than melanoma [\[2](#page-16-1)].

Melanoma is an assortment of melanocytic injuries that is dangerous. This injury progresses more quickly than BCC, profoundly ft for attacking tissues and metastasizing to different organs. The deadliest type of skin malignant growth is one of these melanomas [[3\]](#page-17-0). Recuperating can be effective when melanoma malignant growth is recognized at the beginning phase. One of the strategies utilized by dermatologists to analyze melanomas is an imaging strategy called dermoscopy, where an amplifcation apparatus and a light source are utilized to review the skin injury. This enables the dermatologist to detect subcutaneous patterns that would require extensive preparation to be undetectable [[4\]](#page-17-1). Furthermore, the determination is abstract and often diffcult to imitate. Hence, programmed strategies should be created to help dermatologists give a more exact conclusion. Clinical image determination can be successfully performed utilizing Personal Computer vision. A computer-based demonstrative framework for the skin image has signifcant screening and disease-fnding potential. Improvement in the determination of the progress of melanoma is accomplished utilizing computer-based object recognition system. As a visual framework frequently causes fault, the requirement for better accuracy and second opinions is featured. On the other hand, it decreases a doctor's assignments and obligations. Many investigations in the programmed recognition of melanoma have been created. The imminent advantages of such examinations are signifcant and immense. In addition, the interdependence of diffculties is high, and the new contributions in the area are highly valued. Then again, it is generally perceived that better precision is expected by the more certain and profcient identifcation frameworks $[5]$ $[5]$.

2 Analogous Performance

To improve the computational capability of standard ABCD assessment, a computerassisted diagnostic system is adopted. Melanin production and surface (photodynamic therapy [PDT]) qualities are characterized by features gained from local investigation of lesion intensity. The fndings demonstrate that PDT structures are hopeful qualities that, when combined with standard ABCD features, can increase the detection efficiency of pigmented skin lesions $[6]$ $[6]$.

A Boltzman Entropy novel technique is employed for categorizing carcinogenic and noncarcinogenic skin lesions. DullRazor performs hair removal, whereas lesion texture and color information are used to enhance lesion contrast. A hybrid method is introduced in lesion segmentation and outcomes are combined using the addition law of probability. Subsequently, the serial-based technique is implemented to extract and fuse attributes such as color, texture, and histogram of oriented gradients (shape). The merged attributes are then chosen using a novel Boltzmann entropy technique. Last, support vector machine (SVM) classifes the chosen features. Compared with current techniques, the suggested method detects and classifes melanoma relatively well [[7\]](#page-17-4).

A multi parameter artifcial neural networks on basis of manageable personal health info with elevated sensitivity and specificity for early identification of nonmelanoma skin cancer, even in the lack of known exposure to UV rays was generated [\[7](#page-17-4)].

A further approach had two phases: an initial step used a kernel- and regionbased convolutional strategy to consistently crop the particular object on dermatological imaging, and the next segment used the ResNet152 framework to discriminate potentially cancerous abnormalities. The effcacy of the categorization methodology has been enhanced [\[8](#page-17-5)].

A deep convolutional neural network (CNN) based on a deep-learning strategy is also employed for appropriate identifcation of normal and infected dermatitis. The deep CNN paradigm is tested with transfer learning approaches such as AlexNet, DenseNet, MobileNet, ResNet, and VGG-16 to determine overall effectiveness. The eventual fndings of the current deep CNN model are described as being much more effective than authorization learning techniques [[9\]](#page-17-6).

Furthermore, a CNN with a dynamic GoogLeNet topology is constructed. The eight performance indicators assessed were polygon region, kappa, categorization effciency, sensitivity, F-score measurement, specifcity, area under the curve, and time complexity. According to the observations, the generated CNN had the best calculation effciency with the least amount of time to accomplish the assignment [[10\]](#page-17-7).

3 Evaluation of Skin Malignancy Using Machine-Learning Methodologies

In the development of computer-based detection methods for melanoma diagnosis, different classifcation algorithms were used. Whether one technique outperforms the other, however, is not evident. As there are robust and fragile points in each category process, selecting only one method to carry out all comparisons of features and descriptors is not simple. Therefore, fve distinct algorithms were implemented in this work. An appropriate classifcation scheme for melanoma images is developed using methods of machine learning to characterize skin lesions as harmless or cancerous. Figure [1](#page-3-0) uses machine-learning methods to demonstrate the fow chart of the classifcation of skin lesions.

Fig. 1 Flow chart of skin lesion classifcation using machine-learning techniques

3.1 Anisotropic Diffusion Filtering

Dermoscopic images usually contain some artifacts. Powerful approaches to eliminate artifacts and enhance the appearance of the initial images are therefore required. The basic motive behind this pre-processing is to improve melanoma image quality by evacuating irrelevant portions and noise for further processing in the background of an image. Using 2D anisotropic diffusion flter, noise and artifacts were removed at the original point [[11\]](#page-17-8). ADF method was applied to minimize image noises, assuring essential elements of image detail, generally borders as well as outlines / equivalent points are not disturbed from image view. On three channels (red green blue [RGB]) the anisotropic flters were implemented individually. Unsharp masking was implemented on an entire image only after denoising. The image was sharpened using gray world normalization. After that, color constancy was implemented on the three channels together. Hairs behave as an ambiguity on dermoscopic images. Gray world normalization is used to identify the hair. An inpainting technique was used to separate the identifed hairs. Figure [2](#page-4-0) shows the results of the steps used for pre-processing.

S.No.	Input Image	Anisotropic Diffusion	Unsharp masking	Gray world Normalization	Inpainting
$\mathbf{1}.$					
$\overline{2}$.					
3.					
$\overline{4}$.					
5.					

Fig. 2 Results of the pre-processing steps

3.2 Melanoma Segmentation Analysis

Numerous segmentation forms of algorithms such as Otsu's threshold, *k*, fuzzy *c*, and adaptive *k*-means were used for the segmentation of melanoma. Maximizing interclass variability and minimizing intraclass variability is performed using Otsu's thresholding method. A threshold limit is fxed and the value above the limit is regarded in the forefront and the value under the limit is taken in the background [[12\]](#page-17-9).

The variance of the inside class is described in Eq. [1](#page-4-1) as:

$$
\sigma_{w}^{2} = weight_{background} * \sigma_{background}^{2} + weight_{foreground} * \sigma_{foreground}^{2}
$$
 (1)

Only the centroid defnes all cluster. The closest centroid classifes each pixel. In *k*-means clustering [[13\]](#page-17-10), there were two clusters (Eq. [2\)](#page-5-0):

$$
\arg_{\min} (c_i, x)^2, c_i \in c. \tag{2}
$$

The centroid needs an update under each iteration's end, wherein the succeeding equation is used to update the centroid. If the value does not change further, the iteration stops (Eq. [3](#page-5-1)):

$$
c_i = \frac{1}{|s_i|} \sum x_i \in s_i, x_i.
$$
\n⁽³⁾

Fuzzy *c* means algorithm functions through assigning each pixel to the segment. The comparison depends on the distance of particular pixel from multiple clusters. The Euclidean division between two points states that the correlated condition that can characterize *i* and *j* in Eq. [4](#page-5-2) is

$$
\mu\left\{i,j\right\} = \frac{1}{\sum_{k=1}^{2} d\left\{ij\right\} / d^{\frac{2}{m}-1} \left\{ik\right\}}.
$$
\n(4)

There are two clusters: one cluster denotes the foreground whereas the background is denoted by the other one, m indicates the fuzziness factor, $\mu(i, j)$ represent the membership variable, $d(i, j)$ is Euclidean distance within *i*th data and the center of *j*th form of the data set. The outcome produced showcases the ground truth provided. The Dice similarity index (DSI) facilitates determination of image segmentation accuracy (Eq. [5](#page-5-3)):

$$
DSI = \frac{2|\text{Grnd.Truth} \cap \text{Seg.Image}|}{|\text{Grnd.Truth}| + |\text{Seg.Image}|}.
$$
\n(5)

To quantitatively assess performance of the segmentation method, the work also utilizes the Dice similarity coeffcient. All targeted areas are effectively segmented using the above-mentioned segmentation techniques. The focus of this procedure is to evaluate the execution of segmentation with radiotherapy conveyance control of the distinct techniques for treating the targeted region. Abdel and Allan [\[14](#page-17-11)] provided analysis parameters on the basis of a unique class pertaining to region from the calculated DSI shown (Table [1](#page-6-0)).

In segmenting lesions, the *k*-means and Otsu's Dice coeffcients appeared lower than FCM and adaptive *k*-means coeffcients. Findings (Table [1\)](#page-6-0) indicated that the Dice coefficient of adaptive *k*-means appeared significantly high and much more appropriate for region separation of images. Figure [3](#page-6-1) represents the outcomes of the different segmentation processes.

S. No	Clustering algorithm	Computed DSI
	Adaptive k -means	0.809 ± 0.1693
	Fuzzy c-means	0.807 ± 0.2320
	k -means	0.748 ± 0.1794
	Otsu's threshold	0.712 ± 0.3070

Table 1 Computed Dice similarity index (DSI) with various clustering algorithms

S.No.	InputImage	GroundTruth	K-means	FCM	Otsu	Adaptive K-Means
1.		\blacksquare	\bullet	in an	\bullet	\bullet
$\overline{2}$		\bullet	β	$\boldsymbol{\beta}$	$\boldsymbol{\beta}$	\bullet
3.			t.		\bullet	
4.		D	€	۷	\bullet	U
5.			7	÷.		J

Fig. 3 Output images from various algorithms of segmentation

3.3 Feature Extraction

To categorize the images, feature extraction techniques are used to obtain features. Three elements of structure are obtained from binary differentiated images: irregularity, shape, and circularity signal.

Equation 6 shows how to calculate the irregularity:

Irregularity =
$$
\frac{\text{Standard Deviation (BI)}}{\text{Mean (BI)}},
$$
 (6)

where BI is the binary image. The fast Fourier transformed the shape signal and split it into ten rays. Each ray was considered an element. There were 13 shape elements in all. Binary object circularity is calculated in Eq. [7](#page-7-0):

$$
Circularity = \frac{4 * pi * area}{Perimeter^2}
$$
 (7)

Texture-derived attributes were obtained through three distinct channels (R, G, and B) from segmented images. Using mean and standard deviation the frst-order statistics of an image may be acquired. These are associated with separate pixel characteristics. Second-order image statistics obtained via the gray-level co-occurrence matrix (GLCM) accounting for spatial interdependence of two pixels at particular relative places. Contrast, correlation, power, homogeneity and entropy were fve Haralick attributes acquired from the GLCM. The following formula is used to mea-sure average (Eq. [8\)](#page-7-1) and standard deviation (SD) (Eq. [9\)](#page-7-2):

Mean =
$$
\sum_{k=0}^{L-1} r_k P(r_k);
$$
 (8)

$$
SD = \sum_{k=0}^{L-1} (r_k - \text{mean}) P(r_k).
$$
\n(9)

Ten local binary pattern features were also calculated [[15\]](#page-17-12).

3.4 Benign and Malignant Classifcation

Classifers have been trained via obtained attributes. Five distinctive classifers have been learned and their precision has been compared: k-nearest neighbor (k-NN), support vector machine (SVM), decision tree (DT), multi-layer perceptron (MLP), and random forest (RF) [[16\]](#page-17-13). The condition of all classifers has been enhanced by ten-fold cross-validation. Of the total images, 60% were used as training samples and the testing set utilized the remaining 40%.

3.5 K-Nearest Neighbor

This computation depends on a pseudo-parametric identifcation methodology. The output is determined as the category with the maximum malignancy from the k-most comparative events at the stage where k-NN is used for interpretation. The value of k has been maintained as fve. The melanoma that is categorized as harmless or cancerous will be identifed as the primary vote it gets from its nearest neighbor.

3.6 Support Vector Machine

It is selective. With labeled learning information being supplied, a hyperplane is drawn that chooses the boundaries of selection. To categorize images using SVM, the hyperplane separates item sets with completely unpredicted forms of memebership. The analysis of the hyperplane classifes the images as cancerous and non-cancerous.

3.7 Decision Tree

This classifer supports the algorithmic principle of supervised learning. The goal of using DT is to produce a training model that is used by learning data to predict category or estimate target variables by learning choice rules. By using tree delineation, the DT resolves the problem. The internal node of each tree is comparable with a quality. Each leaf node is associated with a category tag. In decision tree, it is typical to start at the base of the tree, predict a class label, and examine the root features with actual data. During examination, the algorithm compares the branch to successive nodes and moves forward. Once it reaches the leaf node of the expected class, the algorithm classifes as harmless (benign)/cancerous (malignant).

3.8 Multilayer Perceptron

This classifer relies on a neural mechanism (feed forward) made up of three layers. Each layer is entirely connected to the layers above in the system. The primary is the layer of input, the hidden level represents the second, and the tertiary is the yield layer. The input data are represented by nodes within the primary layer. All distinct node points of input layer are processed by using linear input mixture with node w weights linked to bias b and using activation function. It could be formed with $K + 1$ layers (Eq. [10\)](#page-8-0) in a network frame for the MLP classifer as needed. The sigmoid operator is used by nodes in hidden layers (Eq. [11\)](#page-8-1).

$$
x = \left(\dots f_2 \left(w^T f_1 \left(w^T x + b_1 \right) + b_2 \right) \dots + b_k \right)
$$
\n
$$
(10)
$$

$$
(z_i) = \frac{1}{1 + e^{-z_i}}.
$$
\n(11)

Nodes in the yield layer use the softmax function (Eq. [12](#page-8-2)):

$$
(z_i) = \frac{e^{z_i}}{\sum_{N} k = 1 e^{k}}.
$$
\n(12)

To train MLP, the back propagation method is utilized. The number of neural network nodes equivalent to number of categories in the yield layer.

3.9 Random Forest

This creates a DT group from an arbitrarily selected sub-set of the training set. It then summarizes the votes from various trees of selection to settle on the test object's ultimate category. It is made up of the number of DTs. There were 100 trees in this analysis. The principal distinction between DT and RF is that the single tree is represented by DT, whereas RF consists of multiple trees [\[17](#page-17-14)].

Receiver-operating characteristics (ROC) curve indicates sensitivity/specifcity for testing to evaluate the consistency of fve classifers. The ROC curve is nothing but the true-positive (TP) rate and the false-positive (FP) rate relation. TP, FP, false negative (FN), and true negative (TN) are the four parameters that are utilized to fgure out the accuracy, sensitivity, and specifcity of the classifers. The positive qualities effectively estimated by the model defne the true-positive rate, and the false-positive rate is positively misidentifed by negative attributes. The corresponding condition measured the accuracy of the different computational models (Eq. [13\)](#page-9-0), their sensitivity (Eq. 14), and their specificity (Eq. [15\)](#page-9-2):

$$
Accuracy = \frac{TP + TN}{TP + TN + FP + FN} * 100;
$$
\n(13)

Sensitivity =
$$
\frac{TP}{TP + FN} * 100;
$$
 (14)

$$
Specificity = \frac{TN}{TN + FP} * 100\tag{15}
$$

Figure [4](#page-10-0) revealed the effects of classifcation using the ROC curve of fve distinct classifers.

The accuracy of different classifers is mentioned in Table [2.](#page-10-1) The general accuracy of RF can be obviously noted to be the highest. The confusion matrix of fve classifers is depicted in Table [3,](#page-11-0) for DT, out of 900 (458 benign and 269 malignant) 727 are properly classifed and 173 misclassifed (benign), 99 are categorized as malignant and 74 as benign. For k-NN, out of 900, 727 are properly categorized (420 benign and 307 malignant) and 173 are found to be misclassifed, 71 as malignant and 102 as benign. For MLP, 727 out of 900 are correctly classifed (393 benign and 334 malignant) and 173 are misidentifed, 54 as malignant and 118 as benign. For SVM, 727 out of 900 are properly classifed (411 benign and 316 malignant) and 173 misclassifed, 47 as malignant and 126 as benign. For RF, 727 are properly categorized (613 benign and 114 malignant) and 173 misclassifed, 121 as malignant and 52 as benign.

Fig. 4 Receiver-operating characteristic curve of the classifers

Computational models	Training accuracy	Testing accuracy	Total accuracy
K-nearest neighbor	0.8405	0.57	0.7141
Support vector machine	0.7766	0.5865	0.6816
Decision tree		0.7287	0.8683
Multi-layer perceptron	0.9218	0.5587	0.7402
Random forest		0.8593	0.9337

Table 2 Classification accuracy by different computational models

The average calculation time for pre-processing to classifcation was found to be 2.043 ± 0.122 min. Overall computation interval in 20 images is graphically denoted in Fig. [5](#page-12-0).

Table [4](#page-12-1) demonstrates that the highest level of learning and test efficiency is generated by RF. A cross-validity score of 93.47% was estimated for RF.

3.10 Summary of Melanoma Classifcation Using Machine Learning

An effective melanoma image classifcation scheme has been developed to classify a noncancerous (benign) form and a similarly cancerous (malignant) type of lesion. Different segmentation algorithms employed over 900 dataset images. The DSI was used to validate the segmentation technique, and adaptive *k*-means clustering

becision tree		K-nearest neighbor			Multi-layer perceptron		Support vector machine	Random forest	
Benign	Malignant	Benign	Malignant	Benign Malignant		Benign	Malignant	Benign	Malignant
458	269	420	307	393	334	411	316	613	14
99	74	ŕ	102	54	118	47	126	$\overline{121}$	52

Table 3 Error (confusion) matrix for classified images **Table 3** Error (confusion) matrix for classifed images

Fig. 5 Time taken for the computation of 20 images

Parameters	Specificity $%$	Sensitivity %	Accuracy $%$
Ebtihal Almansour	85.84	93.97	90.32
Mohd Anas			83.33
Esteva et al. [20]		96	72.10
Gautam [27]	79.81	86.21	77.26
Li and Shen $[23]$			91.20
Random forest			93.47

Table 4 Comparative representation of present work with that of random forest classifcation

outperformed the other clustering algorithms in terms of precision. The estimation of the effciency of the fve classifers is determined. The best of fve classifers is assessed on the basis of precision, specifcity, and sensitivity. The ROC plot is used for further analysis. From the observational outcome, the precision of the classifer is 93%, 86.9%, 75%, 71.5%, and 69% respectively for RF, DT, MLP, k-NN, and SVM. From this it could be surmised that the classifer with the greatest accuracy is RF. Thus, it served as an effective classifer for the detection of benign/malignant forms of skin lesions.

4 Deep-Learning Approaches to Skin Cancer Diagnosis

Deep-learning strategies are now employed to categorize harmless and cancerous lesions [[18\]](#page-17-17). Using a similar sample, transfer learning techniques such as AlexNet are being used to assess effectiveness. The layout of the intended work is presented in Fig. [6](#page-13-0) as a schematic drawing.

Fig. 6 Schematic layout: diagnosis of skin cancer

4.1 Image Enhancement

Many strategies exist for downsizing, hiding, fltering, hair elimination, and converting RGB shading to gray resolution images. They are implemented to greatly reduce noise and refective aberrations. The median window is used to de-clutter the image, disguise the undesirable traits, and eradicate them. It is frequently employed to remove the error without diminishing the image quality, thereby improving the image clarity [\[19](#page-17-18)].

4.2 Augmentation of Images

Augmentation is a technique for increasing the volume of data without generating new data by introducing slightly altered imagery into old training samples. The training sample number could be considerably increased, or the system could be protected against overftting, through oversampling. To minimize overftting, augmentation parameters such as rotation, shear, zoom, channel shift, height shift, and width shift are applied [\[20](#page-17-15)].

4.3 AlexNet Topology

Krizhevsky designed AlexNet, which uses the ReLu function. AlexNet provides multi-general processing unit (GPU) learning, in which half of a net neuron is handled on one GPU whereas the remaining neurons are processed on the other. AlexNet is composed of eight layers: fve convolutional layers with a combination of maxpooling layers, and three fully linked layers [\[21](#page-17-19)]. This primarily enables larger-scale training, thereby also reducing the training process [[22\]](#page-17-20).

4.4 Experimental Findings

The effectiveness of skin cancer screening is improved by employing deep neural networks. Melanoma malignancy is diagnosed through images from the International Skin Imaging Collaboration (ISIC) repository dataset. Initially, the image is loaded and normalized. It is processed via image augmentation, and the architecture and layers of the network are constructed. The CNN uses AlexNet [[23,](#page-17-16) [24\]](#page-18-1). The system is then trained using supervised learning after the loss function of the dataset is created. During testing and training, the data are equally divided. Finally, the validation is performed by computing accuracy $(Eq. 16)$ $(Eq. 16)$ $(Eq. 16)$, F-measure $(Eq. 17)$ $(Eq. 17)$ and recall (Eq. [18](#page-14-2)):

$$
Accuracy = \frac{TN + TP}{TN + TP + FN + FP};
$$
\n(16)

$$
F-\text{Measure} = \frac{2TP}{2TP+FN+FP};
$$
\n(17)

$$
Recall = \frac{TP}{FN + TP}.
$$
\n(18)

The deep neural module in MATLAB R2020b is employed to construct and validate the network. The dataset aggregation is categorized into two major groups: 80% data trained and 20% data utilized for testing. The learning rate is set at 0.0001 and the number of epochs is limited to six. In elements of accuracy, F-measure, precision, and recall, the relevant formulas are utilized to analyze and evaluate the results of the network procedure.

The ISIC dataset (<http://www.isic-archive.com>) has been used to collect 900 pictures (600 benign and 300 malignant) for this proposed assessment [\[25](#page-18-2)]. Eighty percent of the lesions in each category were selected at random and utilized as training examples, whereas the leftover data have been used as a testing set. Both malignant and benign presentations are displayed in Fig. [7.](#page-15-0) The use of AlexNet to characterize benign and diseased lesions is a high priority of our conceptual framework.

The confusion matrix of AlexNet is given in Table [5.](#page-15-1) Table [6](#page-15-2) depicts its performance when examining quantitative metrics such as accuracy, F-measure, precision, and recall evaluation outcomes. The efficiency of the AlexNet framework training and testing processes is depicted in Fig. [8.](#page-16-2)

To validate the effcacy of the AlexNet architecture, F-measure, precision, accuracy, and recall parameters are estimated. Specifc factors such as TN, FP, TP, and FN were employed to compute the performance of the AlexNet system [[26](#page-18-3)]. The TP factor refers to the percentage of positive traits correctly identifed by the system, whereas the FP score refers to the percentage of negative traits misappropriated as positive.

Fig. 7 Sample images of cancerous (M) and noncancerous (B) lesions

Table 6 Correlation of quantitative performance measures

Table [5](#page-15-1) indicates that AlexNet correctly categorized 855 images out of 900 datasets, whereas 45 were inaccurately categorized (295 malignant and 560 benign). Table [5](#page-15-1) shows the quantifable parameters used by AlexNet. AlexNet is shown to have a 95% accuracy level. As an outcome, AlexNet may be used by specialists to categorize dermoscopy images and generate appropriate predictions.

As a result, larger sample sources are set to increase the signifcance of the fndings. The approach can be implemented in a clinician's computer-assisted sensing devices to aid in the identifcation of skin malignancy. It can also be applied to images of lesions taken from patients and delivered on handheld devices. It therefore allows a quick cancer diagnosis, which dramatically streamlines therapy and improves chances of recovery.

Fig 8 Progress of the training of AlexNet

5 Conclusion

The signifcant impacts of work in this feld are summed up concerning portions of the framework, potential strategies, intercessions, and insightful results. A viewpoint on machine learning and deep learning is described in the above review to propel a skin injury acknowledgment technique for characterization on dermatoscopic images of threatening and harmless lesions. A thorough examination data set is produced by gathering dermoscopic images from different chroniclers such as the International Society for Digital Imaging of the Skin and ISIC. To empower similar examinations on dermoscopic image division and characterization calculation for research and benchmarking purposes, the PH2 dataset has been made. The main attribute of the examination work is that around 900 dermoscopic image tests are chosen for the exploratory work. Thus, the handling speed is essentially expanded. A systematic evaluation was successfully carried out between different machinelearning techniques, such as DT, MLP, SVM, k-NN, RF, and deep-learning techniques such as AlexNet. The experimental results illustrate the importance and main achievements of this work, which has an estimated classifcation accuracy of 93% for the RF model and 95% for the AlexNet model. Therefore, the deep-learning system shows an automated diagnostic technique for constant and accurate determination of skin malignancy with an extraordinary ability to carry out treatment strategies using non-invasive methods.

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