Chapter 8 Advanced 3D Imaging and Transcatheter Valve Repair/Implantation

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Abbreviations

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8.1 Introduction

Valvular heart disease is a major cause of morbidity and mortality in developing and industrialized countries. While rheumatic and infectious causes are more common in developing countries, degenerative valvular disease is the predominant etiology in the aging population of the industrialized world. For patients with advanced, symptomatic disease, surgical open-heart valve replacement or repair remains the standard treatment with excellent short- and long-term outcomes. However, there is a signifcant percentage of typically older patients that are not considered surgical candidates. For example, in Europe and the United States surveys, about 30% of patients with severe symptomatic aortic stenosis are not considered surgical candidates secondary to advanced age and comorbidities [\[1](#page-22-0)]. Because these patients have a poor outcome with medical management $[2-5]$ $[2-5]$, less-invasive transcatheter approaches for valve repair/implantation appear promising for subgroups of these high-risk patients.

Transcatheter aortic valve implantation (TAVI) for symptomatic patients with severe aortic stenosis utilizes stent systems, in which a bioprosthetic valve is mounted. The procedure can be performed using a transfemoral, transcaval, transcarotid, transaxillary, transaortic, or transapical approach $[6–11]$ $[6–11]$ $[6–11]$. The stent/valve systems are anchored at the annulus and extend into the root or proximal ascending aorta. Since the initial successful human implantation in 2002, different generations of balloon-expandable or self-expandable valve prostheses have been implanted in several thousand patients with severe symptomatic aortic stenosis. The results in experienced centers are good, with high implantation success rate, signifcant hemodynamic and clinical improvements, and improved survival rates [\[11](#page-22-4)[–13](#page-23-0)]. TAVI was associated with improved outcomes compared to medical therapy, and comparable outcomes to open-heart surgery [\[14](#page-23-1)]. See chapter on TAVI devices for more information.

There are several percutaneous approaches for the treatment of mitral regurgitation, including both transcatheter mitral valve repair (TMVr) and replacement (TMVR). The most common percutaneous mitral valve repair procedure is derived from the Alferi edge-to-edge repair, which consists of suturing the free edges of the anterior and posterior mitral leafets [[15,](#page-23-2) [16\]](#page-23-3). The transcatheter procedure deploys a clip to join the free edges of the opposing leafets, thus creating a double-orifce valve [\[17](#page-23-4)[–20](#page-23-5)]. Alternative percutaneous procedures include coronary sinus (CS) annuloplasty with placement of devices in the CS. The goal is to displace the posterior portion of mitral annulus (MA), in order to improve the coaptation of the leaflets [[21–](#page-23-6)[24\]](#page-23-7). One study [[24\]](#page-23-7) showed the feasibility of percutaneous reduction in functional mitral regurgitation with a CS-based mitral annuloplasty device in patients with heart failure and was associated with an improvement in quality of life and exercise tolerance. For prosthetic mitral valve paravalvular regurgitation, percutaneous device closure has been successful. Several TMVR devices are currently under clinical investigation, and mitral valve-in-valve implantation with an aortic transcatheter valve has been performed with much success. See chapter on transcatheter mitral valve repair and replacement devices for more information.

Transcatheter pulmonic valve replacement has also been established in patients with dysfunctional right ventricular outfow tract conduits and pulmonary regurgitation [[25,](#page-23-8) [26](#page-23-9)]. More information on transcatheter pulmonic valve replacement is in future chapters.

Recent studies also describe transcatheter tricuspid valve implantation [[27\]](#page-23-10) and valve-in-valve implantation [[28,](#page-23-11) [29](#page-23-12)]. Transcatheter tricuspid valve repair or replacement is a rapidly advancing feld. Several therapies are currently under investigation, including suture or ring annuloplasty devices, coaptation devices (edge-to-edge repair), direct valve replacement, and caval (superior or inferior vena cava) implantation devices. Tricuspid valve edge-to-edge repair is currently the most commonly used method and heavily relies on two-dimensional (2D) and three-dimensional (3D) transesophageal echocardiography for technical success.

As described in more detail in other chapters of the book, transcatheter valvular procedures are becoming an alternative to open surgical approaches in selected patient populations. Low frequency of procedural-related complications and good long-term outcomes depend on careful selection of potential candidates, with an important role for imaging [\[30](#page-23-13)].

8.2 Imaging in the Context of Transcatheter Valve Procedures

Due to the lack of direct visualization of the operative feld during transcatheter procedures, imaging for preoperative planning and intraoperative guidance is an integral component of transcatheter procedures [[31,](#page-24-0) [32\]](#page-24-1).

Standard 2D imaging is performed with conventional X-ray angiography and echocardiography before and during the procedure. Since angiography and echocardiography create 2D projections or acquire 2D planes, understanding of 3D relationships requires viewing and mentally reconstructing the object from multiple different projections or planes. In contrast, 3D imaging provides 3D visualization and is increasingly used for pre- and intraoperative visualization [[33–](#page-24-2)[37\]](#page-24-3). Threedimensional imaging modalities include 3D echocardiography, computed tomography (CT), C-arm CT, and magnetic resonance imaging (MRI).

Three-dimensional echocardiography [\[38](#page-24-4), [39](#page-24-5)] is used for real-time procedural image guidance during catheter-based therapies. Three-dimensional transthoracic and transesophageal echocardiography (TEE) is performed with rectangular (or matrix) array transducers, which acquire a 3D pyramidal data volume [\[39](#page-24-5)[–42](#page-24-6)]. With a full-volume acquisition, commonly acquired over several cardiac cycles, a full 3D data set with high temporal and spatial resolution can be obtained. Similar to CT,

offine reconstruction generates multiple 2D cut planes that can be applied to display structures of interest from different perspectives. This approach allows reconstruction of images orthogonal to the vessel's centerline for measurement, e.g., of the aortic annulus. Alternatively, 3D data acquisition can be real time, with a slightly lower temporal resolution compared to full 3D data sets obtained over several cardiac cycles. Real-time 3D echocardiography is especially useful in the guidance of mitral valve procedures, as it provides the unique enface viewing perspective of the mitral valve from the left atrium (often termed the "surgeon's view"). Further, the 3D matrix probe also allows the simultaneous real-time display of two adjustable image planes at high temporal and spatial quality, in both 2D and color Doppler modes. This is especially important for color Doppler imaging where low temporal resolution often signifcantly limits the use of true 3D techniques such as real-time and full-volume acquisitions. Biplane imaging is particularly useful in assessing mitral, aortic, and tricuspid valve pathologies where high spatial and temporal resolutions similar to 2D echocardiography are often needed, but simultaneous imaging of two planes helps to assess the 3D structure. Initial experience with 3D TEE demonstrates its value in the clinical evaluation of structural heart disease, intraoperative assessment, and guidance of interventional procedures [\[43](#page-24-7)[–49](#page-24-8)].

C-arm CT describes the use of CT-like acquisition and reconstruction techniques to obtain 3D data with C-arm-based X-ray angiography systems. The C-arm is rotated over a wide arc (>180°) around the patient typically during continuous contrast injection, acquiring multiple views of the cardiovascular structure in order to reconstruct a 3D image [[50,](#page-24-9) [51](#page-25-0)]. For electrocardiogram (ECG)-referenced cardiac imaging, alternating forward and backward rotations are triggered by the ECG signal to acquire projections covering the entire acquisition range at a similar cardiac phase. C-arm CT has shown potential for use during various cardiovascular interventional procedures including coronary angiography and percutaneous coronary interventions [[52,](#page-25-1) [53\]](#page-25-2), pulmonary vein isolation [[54\]](#page-25-3), and endovascular stent repair of aortic disease [[55\]](#page-25-4).

The use of CT for cardiovascular indications has become possible due to improvements of spatial and temporal resolution and an increased number of detector systems [[56–](#page-25-5)[58\]](#page-25-6). Using dual-tube technology, temporal resolution of 75 ms can be achieved with a spatial resolution of about 0.5 mm and slice thickness of about 0.5–0.75 mm. With 320-slice systems, 16 cm can be covered in one rotation. These isotropic data sets allow oblique reconstruction without degradation of spatial resolution. Most imaging experience in the context of transcatheter valve procedures is based on retrospectively ECG-gated helical acquisitions (typically with use of tube current modulation, but a wide dose modulation window). The ECG-synchronized image acquisition throughout the cardiac cycle allows reconstruction at any point throughout the R-R interval, and cine display of multiple phases throughout the cardiac cycle permits dynamic display of cardiac and valvular motion, as well as reconstruction at specifc positions in the R-R interval. For example, visualization of a plane at the tip of the leafets at different times during the cardiac cycle allows determination of the maximal opening of the aortic valve during the cardiac cycle by planimetry (typically mid-late systole). However, the temporal resolution of CT is lower than that of echocardiography and MRI.

These CT protocols are usually associated with increased radiation exposure [\[59](#page-25-7)[–61](#page-25-8)]. Careful individual planning of the imaging protocol and consideration of potential alternative imaging modalities are important to control radiation exposure [\[62](#page-25-9)]. Strategies associated with lower doses for cardiovascular CT imaging include tube current modulation with retrospective ECG-gated helical imaging, prospectively ECG-triggered imaging techniques, and use of low X-ray tube voltage (e.g., 100 kVp) [[63–](#page-25-10)[67\]](#page-25-11). If four-dimensional (4D) imaging is not necessary, prospective ECG-triggered axial acquisitions focused on a specifc phase in the cardiac cycle should be preferred in patients with stable heart rate, because of the signifcantly lower radiation exposure. Most protocols are performed after intravenous contrast administration. If contrast administration is not feasible, non-contrast images can be useful to visualize calcifcation of the valve and/or aortic root and remaining segments of the vasculature, although precise measurements may be difficult.

Interventional cardiovascular MR techniques have been developed to guide transcatheter procedures [\[68](#page-25-12)[–72](#page-26-0)]. The advantage of these approaches is that they provide good soft tissue visualization and functional assessment, including blood flow without radiation exposure. However, they add significant complexity to the procedure and require special compatible instruments and considerable capital investment [[73\]](#page-26-1). An important concept is the development of MR road maps, which are combined with live X-ray fuoroscopy using a conventional clinical environment and conventional catheter equipment (Fig. [8.1](#page-4-0)). Such data provide additional anatomic landmarks and functional information to guide procedures [\[74](#page-26-2), [75\]](#page-26-3). Magnetic resonance might aid in positioning nonsurgical replacement of heart valves, relative to vital structures such as coronary artery ostia [\[69](#page-25-13)]. A limitation of MRI in the context of TAVI is the signal void caused by calcium and metal, which precludes precise assessment of densely calcifed valves and after stent-valve placement.

Fig. 8.1 Interventional MRI and angiographic fusion. Interventional applications of MRI allow real-time fusion of angiographic and MRI images in hybrid MRI/angiosuites for direct procedural guidance. (Image courtesy of Dr. Lederman; adapted with permission from Ratnayaka et al. [\[74\]](#page-26-2))

8.2.1 Transcatheter Aortic Valve Implantation

8.2.1.1 Anatomy

Aortic root anatomy, including the aortic valve and coronary artery ostia, is complex [\[76](#page-26-4)[–78](#page-26-5)]. The geometry and relationship of the aortic root structures change throughout the cardiac cycle [\[79](#page-26-6)[–82](#page-26-7)]. Implantation of a stent/valve is incompletely understood, including the consequences of these structures and their relationships.

The aortic annulus describes the interface between the left ventricular outflow tract and the aortic root at the commissures of the aortic valve leafets (Fig. [8.2](#page-5-0)). The three commissures extend upward into the aortic root similar to the shape of a crown or the struts of a bioprosthetic valve. The "annular" level at the lowest point of the valve hinge point ("inferior virtual basal ring") defnes the level where valve prostheses are sutured or secured. During valve surgery, the annulus is ftted to the valve. On the other hand, when the transcatheter valve is deployed, the stent/valve must adjust to the "aortic root." Therefore, in addition to size and shape, the composition and material properties of the surrounding structures have important implications for the interaction between device and root. Approximately two-third are in contact

Fig. 8.2 Relationship between aortic valve, left ventricular outfow tract (LVOT), and anterior mitral leafet. The upper panels show (*left* to *right*) cross sections through aortic valve, LVOT, and anterior mitral leafet. The close relationship between these structures is demonstrated

with ventricular myocardium, and the remaining one-third are composed of the aortic leafet of the mitral valve [\[31](#page-24-0)].

The three individual cusps of the aortic valve are attached to the aortic wall along the commissures in a crescentic fashion (Fig. [8.3](#page-6-0)). Behind the cusps are the outward bulging sinuses of Valsalva, with the origins of the coronary arteries at the superior aspect of the left and right aortic sinuses. There is a wide variation in distance between the leafet tips and the coronary ostia, and in about 50% of patients, the length of the left coronary leafet exceeds the distance between the annulus and the ostium of the left coronary artery. This has important implications during preprocedural planning for TAVI, especially when evaluating risk of coronary obstruction with valve implantation.

The sinotubular junction describes the margin between the aortic root and tubular ascending aorta and has an important role in maintaining valve competence (Fig. [8.4](#page-7-0)) [\[83](#page-26-8)]. During the TAVI procedures, the sinotubular junction provides support for the deployment balloon; depending on valve design (short vs. long), the sinotubular junction and proximal ascending aorta are important for proper implantation (distal anchor zone). Please see Chap. [2](https://doi.org/10.1007/978-3-031-25541-0_2) for more information on the anatomy of the semilunar valves.

Fig. 8.3 Relationship between aortic valve cusps and coronary ostia. The central panels show a cross section through the aortic root with the three aortic valve cusps. The three surrounding panels show oblique sagittal images of each cusp. *LCC,* left coronary cusp; *RCC,* right coronary cusp; *NCC,* non-coronary cusp

Fig. 8.4 Aortic root, aortic valve, and coronary ostia. The upper panels show (*left* to *right*) cross sections at the "aortic annulus," aortic valve, sinuses of Valsalva, and sinotubular junction. There is moderate thickening and calcifcation of the aortic valve leafets

8.2.1.2 Imaging

The position of the aortic root relative to the body axis and corresponding alignment of the X-ray plane are critically important for precise placement of the valve. With angiography, overlap-free visualization of the three coronary cusps, which are oriented along the aortic valve plane, typically requires caudal angulation in the RAO projection and cranial angulation in the LAO projection. The current standard approach is based on the identifcation of X-ray root angiograms (using a pigtail catheter in either the non-coronary cusp or right coronary cusp depending on the type of valve being used) in one or preferably two orthogonal planes prior to the procedure after repeated root injections. Pre-procedural multi-detector CT data of the aortic root allow prediction of the optimal angulation of the root angiogram, which facilitates the angiographic procedure and reduces the number of root injections (Fig. [8.5\)](#page-8-0) [[84,](#page-26-9) [85](#page-26-10)]. In cases of TAVI within a prior surgical or transcatheter bioprosthetic aortic valve (i.e., "valve-in-valve"), X-ray fuoroscopy alone can be used to identify the bottom aortic annulus (coplanar view), obviating the need for aortic root angiograms during positioning and deployment of the transcatheter heart valve [[86\]](#page-26-11).

As described above, using imaging modalities, the annulus plane is defned as the plane created by the lowest hinge point of the three leafets of the aortic valve ("inferior virtual basal ring") (Figs. [8.2](#page-5-0) and [8.4\)](#page-7-0). Detailed 3D analysis demonstrates

Fig. 8.5 Prediction of angiographic planes for transcatheter aortic valve implantation. In a doubleoblique reconstructed image, the crosshair of the cut planes is centered on the aortic valve (*left upper panel*) and rotated to obtain images of the aortic root, described in angiographic coordinates/ planes (*right upper panel*)

that this clinically defned annulus is typically elliptical [[87–](#page-26-12)[97\]](#page-27-0), and therefore, maximal and minimal annular diameters are reported with CT. Mean annular diameter by CT correlates best but is typically slightly larger than that obtained with TEE. Despite this, CT is now the most commonly used method for valve sizing/ selection (based on the aortic annulus area or perimeter) given its superiority in clinical outcomes compared to echocardiography [[98\]](#page-27-1). Measurement of the distance between the coronary arteries, artery ostia, and distal tip of the aortic valve leafets is important and can be derived from angiography, CT, and TEE (Fig. [8.4](#page-7-0)). In the case of a low ostium or a long leafet, there is increased risk of coronary (particular

left main) occlusion [[87,](#page-26-12) [89,](#page-26-13) [90,](#page-26-14) [94\]](#page-27-2). This information is vital intra-procedurally such that operators can prepare for coronary protection in advanced. Coronary reaccess can be challenging due to a multitude of reasons, including native leafet obstruction, stent frame position, and mal-aligned commissures [\[99](#page-27-3)]. Studies have shown this to be particularly more challenging in self-expanding valves compared to balloon-expandable valves [\[100](#page-27-4)]. Due to this, special device advancement techniques have been utilized and validated to signifcantly reduce the occurrence of commissural overlap with the coronary ostium and thereby theoretically increase success of coronary re-access if needed [[101\]](#page-27-5). A special leafet laceration technique called BASILICA (Bioprosthetic or native Aortic Scallop Intentional Laceration to prevent Iatrogenic Coronary Artery obstruction during TAVR) has been shown to be feasible and safe to prevent coronary artery obstruction from TAVR in high-risk patient subsets [\[102](#page-27-6)].

Imaging allows detailed description of the presence and distribution of valve and root calcifcation (Fig. [8.6](#page-9-0)) [[103–](#page-27-7)[109\]](#page-28-0). For example, calcifcation frequently extends from the aortic valve commissures to the base of the anterior mitral leafets and sinotubular junction. The amount and distribution of calcifcation in the proximal device landing zone at the annulus can affect sealing of the prosthesis, leading to paravalvular regurgitation post-valve deployment. Aortic calcifcation of the sinotubular junction can infuence precise placement of the valve during TAVI by restricting balloon expansion and potentially leading to the ventricular displacement of

Fig. 8.6 Dense calcification of aortic valve. In this image of a non-contrast-enhanced scan, dense calcifcation is seen along all three aortic valve cusps. This pattern suggests a tricuspid valve. Using calcium scoring software, the extent of calcifcation can be quantifed

device at the time of deployment. Presence of eccentric or calcifed nodules can also increase the risk of rare, but catastrophic peri-procedural complications such as aortic annular rupture or ventricular septal defects. Lastly, the extent and quantifcation of aortic calcifcation using calcium scoring software (and using sex-specifc thresholds of the Agatston score) can assist clinically with the diagnosis of severe aortic stenosis in diffcult or ambiguous cases.

Direct observation of the aortic valve opening area allows for correlation of the pattern of valve opening with leafet anatomy and leafet calcifcation. Direct planimetry of the aortic valve opening area with CT has been shown to provide reproducible results in comparison with TEE and MRI (Fig. [8.7](#page-10-0)) [\[110](#page-28-1)[–117](#page-28-2)].

Fig. 8.7 Image reconstruction in systolic and diastolic phase of the cardiac cycle. Image reconstruction in systolic (*left*) and diastolic (*right*) phase of the cardiac cycle demonstrates restricted systolic opening and incomplete diastolic coaptation, consistent with moderate aortic stenosis and mild insufficiency, respectively

During periprocedural 3D TEE, the biplane imaging mode is valuable in simultaneously imaging the aortic valve in both the short- and long-axis views, both in 2D and in color Doppler (Fig. [8.8\)](#page-12-0). This allows the accurate positioning of the prosthetic device in the center of the stenotic valve in both orientations, as well as rapidly localizing post-implantation paravalvular regurgitation. However, the trend has been moving away from general anesthesia, and more toward conscious sedation, hence decreasing the usage of intra-procedural TEE. Transthoracic echocardiogram, aortic root angiography, and/or hemodynamics are now the most commonly used assessments for post-implantation paravalvular regurgitation.

8.2.2 Transcatheter Mitral Valve Procedures

8.2.2.1 Anatomy

The annulus of the mitral valve is an oval, saddle-shaped structure which is formed by continuity of the left atrial tissue with the left ventricular tissue, as well as the base of the mitral valve leafets (Figs. [8.9](#page-13-0) and [8.10](#page-14-0)) [\[118](#page-28-3), [119](#page-28-4)]. The mitral valve apparatus consists of the annulus, leafet, chordae, and the papillary muscles (the anteromedial and posterolateral papillary muscles). The annulus is divided into anterior and posterior parts by the commissures.

The anterior leafet is larger in length but covers only about one-third of the circumference of the annulus. The posterior leafet is shorter in length but covers approximately two-third of the annulus. The chordae arise from the papillary muscle tips and then span to the leafets in a fan-shaped manner (Fig. [8.11\)](#page-15-0). There are two main chordae arising from each head of the papillary muscle, reaching each of the leafets. However, there is a considerable variation in the origin and distribution of the chordae.

The coronary sinus (CS) extends along the left atrioventricular groove close to the mitral annulus and drains into the right atrium. In the context of sinus annuloplasty procedures, a major concern is the close proximity of the CS to the left circumfex artery (LCX) and the potential risk of CS-based devices potentially impinging on the LCX [\[120](#page-28-5)]. See Chap. [1](https://doi.org/10.1007/978-3-031-25541-0_1) for more information on the anatomy of the atrioventricular valves.

8.2.2.2 Imaging

Three-dimensional imaging allows a detailed understanding of the mitral valve apparatus including the mitral annulus and leafets and has been extensively described with echocardiography [[121–](#page-28-6)[126\]](#page-29-0). Description of mitral valvular anatomy is critical for procedures involving the mitral leafets, including mitral valve repair/replacement procedures and percutaneous closure of paravalvular regurgitation. Real-time 3D and full-volume acquisition with TEE allows imaging of the

Fig. 8.8 Biplane real-time three-dimensional (3D) echocardiography. Biplane real-time imaging of a patient with severe aortic stenosis undergoing transcatheter aortic valve implantation (TAVI), in both short and long axis, before (*top panel*), during (*middle panel*), and after (*bottom panel*) device deployment. Simultaneous imaging of the aortic valve in two planes in high spatial and temporal resolution is crucial for the precise positioning of the prosthetic device in TAVI

Fig. 8.9 Relationship between LVOT, anterior mitral leafet, and mitral annulus. The upper panels show (*left* to *right*) cross sections of the LVOT/anterior mitral leafet and mitral annulus. The close relationship of the structures is demonstrated

entire mitral valve and annulus over full cardiac cycles [\[47](#page-24-10), [127–](#page-29-1)[130\]](#page-29-2). Therefore, 3D echocardiography is a critical part of the pre-procedural assessment of patients with mitral regurgitation and allows clarifcation of etiology (i.e., degenerative versus functional mitral regurgitation), determination of severity, and assessment of amenability of the mitral valve to percutaneous procedures and pre-procedural planning (Fig. [8.12\)](#page-16-0). For periprocedural guidance, full-volume 3D echocardiography data acquisition is less useful because of the need for offine analysis. However, real-time 3D echocardiography with its enface mitral valve view from the left atrium similar to the surgeon's view, as well as simultaneous biplane imaging with its high temporal and spatial resolutions both in 2D and in color Doppler modes, is invaluable for procedures such as mitral valve clip (Fig. [8.13](#page-17-0)) and percutaneous closure of paravalvular regurgitation (Fig. [8.14\)](#page-18-0). Specifcally, the 3D enface mitral valve view is particularly useful for orientation of the mitral valve clip device. Biplane imaging in the 2D echocardiography mode is particularly useful for medial/lateral and anterior/posterior orientation and is the key view for leafet grasping. In addition, 2D

Fig. 8.10 Mitral annulus and mitral valve leafets. The upper panels show a cross section through the mitral annulus (*left*) and mitral leafets close to the tips

biplane imaging is crucial for the trans-septal puncture (crossing from the right atrium into the left atrium), which is a crucial procedural step to the mitral valve clip device and other transcatheter mitral valve replacement (TMVR) procedures.

Similar to TAVI, CT is essential for annular sizing in TMVR. The typical measurements obtained from CT include the annular: projected area, perimeter, intercommissural, septal-lateral, and trigone-trigone distances [\[131](#page-29-3)]. Depending on the

Fig. 8.11 Mitral leafets, mild mitral annular calcifcation, and papillary muscles. In this image, mild mitral annular calcifcation is seen in the infero-lateral aspect of the annulus. The images also show the posterior papillary muscles and chordae tendineae. The images are reconstructed with standard "fltered back projection" (*upper panels*) and "iterative reconstruction" (*lower panels*). Iterative reconstruction is associated with signifcantly decreased image noise

device selected for use, different variables/parameters are used for sizing. Threedimensional TEE sizing of the mitral annulus can also be used as well, with the added beneft of the high temporal resolution providing information on the dynamics and function of the mitral annulus. CT and echocardiography are also helpful in evaluating the transapical access point, ideal intercostal access site, annular landing zone, presence of calcifcation (i.e., mitral annular calcifcation), fuoroscopic coplanar angles, and prediction of left ventricular outfow tract (LVOT) obstruction post-procedure [\[132](#page-29-4)]. This is helpful in cases of transcatheter valve-in-valve, valvein-ring, valve-in-mitral annular calcifcation, or TMVR. For any type of implantation in the mitral position, post-procedural LVOT obstruction is a concern and CT simulations (along with aortomitral angulation, left ventricular cavity size,

Fig. 8.12 Three-dimensional echocardiography assessment of a patient with severe mitral regurgitation. With the full-volume 3D acquisition, offine analysis of the data set accurately identifes the posterior mitral leafet medial fail segment (*left panel*). Real-time 3D acquisitions also visualize the posterior medial fail segment with an enface view of the mitral valve from the left atrium, similar to the surgeon's view of the mitral valve (*top right panel*). Simultaneous biplane imaging of the mitral valve allows the assessment of the fail segment in high temporal and spatial resolution, both in two-dimensional (2D) and in color Doppler modes (*bottom right panel*). The medial location of the fail segment near the commissure makes it challenging for percutaneous treatment

interventricular septal size) can be used to predict the risk in patients being evaluated for TMVR. A technique similar to BASILICA for prevention of coronary obstruction in TAVR has been developed for TMVR called LAMPOON (Laceration of the Anterior Mitral leafet to Prevent Outfow Obstruction) technique and has been shown to be effective in preventing and treating LVOT obstruction [[133\]](#page-29-5). Twodimensional and three-dimensional echocardiography are vital intra-procedurally to assist with trans-septal puncture, trans-apical cannulation, guidewire and device positioning/functioning, assessment of paravalvular leak, device seating and stability, and LVOT obstruction [\[132](#page-29-4)]. Figure [8.15](#page-18-1) depicts fuoroscopic images of mitral valve-in-valve, valve-in-ring- and valve-in-mitral annular calcifcation, respectively.

For CS-related procedures, fuoroscopy, CT, and TEE are helpful for proper positioning of the device and evaluating the effectiveness of the intervention. Several studies have used angiography and CT to describe the in vivo anatomical relationships between mitral annulus and CS as well as CS and LCX [\[134](#page-29-6)[–137](#page-29-7)]. These studies observed signifcant variance of CS to mitral annulus separation. The LCX crossed between the CS and mitral annulus in 74–97% of patients at a variable distance from the ostium of CS, depending on coronary dominance. In addition, obtuse marginal branches and posterolateral branches were also in a position to potentially be compressed by a device placed within the CS. Therefore, evaluation of the relationship between the CS/great cardiac vein and the LCX is an important factor in determining the safety of CS-based devices.

Fig. 8.13 Three-dimensional echocardiography and mitral valve clip. In the mitral valve clip procedure, real-time 3D echocardiography identifes the position of the clip with respective to the mitral valve, in the enface perspective (*top panel*). The accurate positioning of the mitral clip often relies on simultaneous biplane imaging that more precisely defnes the relationship between the arms of the clip with the valve leafets (*bottom panel*)

Fig. 8.14 Three-dimensional echocardiography and percutaneous closure of paravalvular leaks. The enface view of the mitral valve obtained by real-time 3D echocardiography is especially important in the percutaneous closure of prosthetic paravalvular mitral regurgitation, as it provides the interventionist an anatomical orientation of the paravalvular regurgitation and the valve leafets and surrounding structure. In this example, the defect is identifed in the posterior aspect of the mitral prosthesis (*left panel*). In combination with other 2D and color Doppler views, a guidewire is successfully passed through the defect with subsequent successful deployment of the closure device (*right panel*)

Fig. 8.15 Fluoroscopic Images of mitral: (**a**) valve-in-valve, (**b**) valve-in-ring, and (**c**) valve-inmitral annular calcifcation

For all transcatheter valvular procedures, assessment of vascular access is important and relies on different imaging modality (Fig. [8.16\)](#page-19-0). Absolute size, amount, and extent of calcifcation, as well as tortuosity of iliac and femoral artery determine suitability for the procedure [[138,](#page-29-8) [139](#page-29-9)]. Vascular complications are the major cause of morbidity and mortality in patients undergoing TAVI, and this should therefore be considered as transcatheter valve procedures increase in number with an expansion toward lower-risk, younger patients.

Fig. 8.16 Assessment of vascular access. Computed tomography allows assessment of the iliac anatomy including vessel diameter, calcifcation, and tortuosity

8.2.3 Transcatheter Tricuspid Valve Procedures

8.2.3.1 Anatomy

The tricuspid valve (TV) is the most anterior and apical of the four cardiac valves, and its apparatus is composed of leafets, chordae and papillary muscles, annulus, and surrounding structures [\[140](#page-30-0)[–142](#page-30-1)]. The valve leafet orifce area is typically large at 7–9 cm² and with a low diastolic pressure gradient across the valve between the right atrium (RA) and right ventricle (RV) (mean gradient < 2 mmHg). The number of tricuspid leafets is variable, but most commonly consists of an anterior, posterior, and septal leafet; usually of unequal size, with anatomical variations of > 3 leafets being present not being uncommon. The anterior leafet is usually the largest, longest, and the most mobile of the three leafets while the septal leafet is the shortest in the radial direction and the least mobile. The posterior leafet may have multiple scallops depending on anatomic variations. Overall, the leafets are very thin and translucent which may be less ideal for anchoring interventional devices.

There are typically two papillary muscles with an occasional variant third. The anterior papillary muscle is the largest, located along the anterolateral RV wall, and provides chordae support to the anterior and posterior leafets. The posterior papillary muscle provides chordae to the posterior and septal leafets. The third variable septal papillary muscle may be present, absent, or even multiple. Chordae may even arise directly from the interventricular septum attaching to the anterior and septal leafets, as well as other locations such as the RV free wall or moderator band.

The tricuspid annulus lacks a robust fbrous structure, is D-shaped (fat along the septum), and nonplanar. Due to this, annular dilation typically occurs laterally and posteriorly where there is lack of fbrous tissue. Coaptation of the TV leafets occurs at the level or just below the annulus. The tricuspid annulus is dynamic, with signifcant changes in area size depending on phase in the cardiac cycle and volume loading conditions.

Surrounding structures to the TV include the non-coronary sinus of Valsalva near the anteroseptal commissure, atrioventricular (AV) node and Bundle of His near the septal leafet attachment, right coronary artery (RCA) which courses in the AV groove, and the superior vena cava (SVC) and inferior vena cava (IVC) which are potential therapeutic targets. Awareness of these structures is important as they can be inadvertently damaged during transcatheter tricuspid valve interventions leading to signifcant complications, morbidity, and mortality.

8.2.3.2 Imaging

Pre-procedural and intra-procedural imaging are vital to transcatheter TV interventions. Two-dimensional and three-dimensional imaging is useful in pre-procedural planning using various modalities (i.e., echocardiography, computed tomography, and cardiac magnetic resonance imaging) [\[143](#page-30-2)]. Imaging is imperative to evaluate severity of pathology, tricuspid annulus size, leafet coaptation/tethering, and etiology. Pre-procedural echocardiography is essential to assess amenability and feasibility. Sometimes the tricuspid valve may be diffcult to image from an echocardiographic standpoint due to the anterior location of the valve; hence, feasibility is partially based on image quality suitable for intra-procedural guidance. Important measurements include RA & RV dimensions/areas and function, tricuspid annulus dimensions (i.e., antero-posterior/septal-lateral diameter, perimeter, area, RV apex-annulus distance), calcifcation, relationship and distance of the RCA to the tricuspid annulus, leafet tethering height, coaptation gap, distance, tenting area and volume, subvalvular apparatus, and IVC/SVC dimensions [[144,](#page-30-3) [145\]](#page-30-4). Similar to TAVI and TMVR, pre-procedural CT is essential in obtaining measurements to choose the optimal tricuspid intervention device.

TV edge-to-edge repair is currently the most commonly used and shown to be an effective method for transcatheter-based treatment of severe tricuspid regurgitation [\[140](#page-30-0), [146](#page-30-5), [147\]](#page-30-6). TV edge-to-edge repair cannot be possible without TEE guidance intra-procedurally. Both 2D (with biplane imaging) and 3D echocardiography are essential intra-procedurally to guide the clip device to the TV (making sure to avoid puncture of the inter-atrial septum), clip positioning and grasping of leafets, evaluate for device stability and effcacy after clip deployment, and assess for any adverse complications during and post-procedure (i.e., pericardial effusion). Specifcally, 3D TEE enface view in the deep transgastric position is used for clip orientation, and 2D TEE biplane imaging in the mid or deep esophageal position is often used for leafet grasping. Other views are used to verify or confrm adequate tissue grasp before full deployment of the clips. Typically, approximation of the edges of the anterior and septal leafets together has been associated with the best outcomes; however, each case is tailored based on the etiology of pathology.

There are several other transcatheter tricuspid interventional devices (annular reduction devices, heterotopic caval valve implantation, valve-in-valve

transcatheter valve replacement, and total tricuspid valve replacement) that are still under clinical investigation. Similar to the edge-to-edge repair device, intraprocedural 2D $\&$ 3D TEE guidance is imperative to device implantation and success. Given the rapid advancement of these technologies and current clinical investigation, the optimal techniques and intra-procedural imaging protocols are yet to be determined.

8.3 From Bench to Bedside: Imaging and Device Design/ Development

Beyond its value for clinical decision-making in the individual patient, 3D data are increasingly used for device design [\[148](#page-30-7), [149\]](#page-30-8). Advances in medical imaging and computational modeling allow simulation of physiological conditions in patientspecifc 3D vascular models. Such models can account for the unique features of the human circulation with appropriate 3D anatomical and physiological input data. This approach will allow prospective design of devices. Computed tomography is particularly attractive, because it acquires high-resolution volumetric data sets with sufficient temporal resolution for multiphasic analysis $[150]$ $[150]$. Along with high spatial resolution, newer state-of-the-art multi-detector CT systems have improved temporal resolutions and allow for quantifcation of the anatomy at multiple points in the cardiac cycle and subsequent mathematical modeling [[151\]](#page-30-10).

Finite element analysis is widely used in clinical research and device development. Finite element models quantitate the effects of changes in one or more of the parameters characterizing the system, including geometrical dimensions, mechanical properties, and fuid dynamics. The reliability of the results obtained through fnite element modeling depends on the degree of realism achieved in modeling the physical characteristics that affect valvular biomechanics, including geometry, tissue mechanical properties, and boundary conditions due to the interaction with the surrounding tissues.

Models derived from in vivo 3D imaging provide realistic data. For example, fnite element analysis using real-time 3D echocardiography examined regional mitral annular geometry and demonstrated that the nonplanar shape of the mitral annulus diminishes mitral leafet stress [\[152](#page-30-11)]. Three-dimensional fnite element models were also developed based on MRI of normal human aortic valve and root [[153\]](#page-30-12).

Computational methodology simulating valve systems is an integral part of valve design. The Food and Drug Administration in the United States and similar regulatory bodies in the European Community have established detailed guidelines for in vitro and in vivo preclinical testing of heart valve prostheses, with standardized methods and equipment in assessing fatigue, fow dynamics, and hydrodynamics of valve implants [[154–](#page-30-13)[156\]](#page-30-14).

Direct clinical application has been described in the context of implantation of a new percutaneous pulmonary valve into a dilated pulmonary trunk, using patientspecifc data to infuence the design of the device and ensure patient safety [\[157](#page-31-0)[–160](#page-31-1)].

8.4 Conclusion

Transcatheter procedures for valvular and structural heart disease require multimodality imaging both for preoperative planning and direct guidance. Imaging modalities include 2D modalities, such as fuoroscopy and 2D echocardiography, as well as 3D imaging modalities, including CT, MRI, C-arm CT, and 3D echocardiography, which acquire volumetric data sets and allow subsequent 3D display and visualization in unlimited planes. The data described above suggest an emerging role of 3D imaging for novel surgical and transcatheter approaches including device design.

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