

# **Evaluation of Range of Motion of the Tibiofemoral Joint 46**

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# **46.1 Visual Estimation of Knee Range of Movement (KROM)**

The knee can be described as a hinge joint with the main movement of fexion and extension, but we know this to be an oversimplifcation. The tibia unlocks at the beginning of fexion with external rotation of the joint. This is followed by lateral femoral condylar rollback and medial femoral condylar rotation  $[1-3]$  $[1-3]$ . If the tibiofemoral surfaces of the knee joint were of the same length and radii, evaluating the geometry of its motion would be very straightforward. However, both articulating surfaces have differing radii and lengths [[4\]](#page-5-2). This results in both the sliding and rolling of the extended tibiofemoral joint culminating in external rotation of approximately 15 degrees at terminal extension [\[5](#page-5-3), [6](#page-5-4)].

The normal fexion-extension range of movement for the knee is 0–140°. Most clinical tests assess this movement alone, as knee abduction– adduction and axial rotation movements are small and not appreciable with visual estimation [\[7](#page-5-5)]. The normal range for extension is  $0^{\circ}$  to  $-5^{\circ}$ 

in the hypermobile female [\[8](#page-5-6)]. Hyperextension is difficult to appreciate in the supine position and is better measured when prone. Deep fexion is 130–140°. A typical examination of KROM consists of positioning the patient semi-recumbent on an examination table with the pelvis square and both legs extended. In a study by Peters et al. comparing visual estimation of knee range of motion to hand goniometry and radiographic measurements, the following clinical technique was used:

- To gauge full extension or hyperextension, the examiner places a hand above the knee. The contralateral hand cups the ipsilateral heel to lift it off the table until resistance is felt (Fig. [46.1a\)](#page-1-0).
- The patient actively flexes their knee.
- With one hand, the examiner stabilises the thigh. The contralateral hand is placed to the front of the ankle with gentle pressure until an end point is reached. This determines maximal fexion (Fig. [46.1b\)](#page-1-0).

This study noted that visual estimation had high intra-relater reliability (ICC 0.8), consistent with other literature on this method [[9,](#page-6-0) [10](#page-6-1)] (a satisfactory ICC is generally accepted as >0.70, and excellent >0.90). However, there were some notable differences between visual estimation and other measurement methods. On average, goniometric measurement was 6° less than radio-

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**Fig. 46.1** (**a**) Positioning of the lower limb for assessment of knee extension (Courtesy of Dublin Hospitals Football Club). (**b**) Positioning of the lower limb for assessment of knee fexion (Courtesy of Dublin Hospitals Football Club)

graphic measurement and 8° less than visual estimation. They proposed 'is supine fexion of the knee synonymous with true full fexion?' as a potential explainer for some of this variation and advocated for not mixing methods [\[11](#page-6-2)]. Questions such as these are important as measurement of KROM has ramifcations for gait and function. KROM is incorporated into orthopaedic knee scoring tools to assess disease severity and recovery after arthroplasty and other knee surgeries and is frequently used as a benchmark in physiotherapy to assess progress with rehabilitation. Surgeons will typically visually estimate KROM in clinic. However, patients generally see different doctors within most public healthcare settings, and this method is the least accurate between different observers [[10\]](#page-6-1).

## **46.2 Universal Goniometer (UG)**

Goniometry is the measurement of the range of movement of a joint through the use of instruments. There are many instruments and techniques, the most common of which is the universal goniometer (UG). In its most basic form, the industry standard long-arm (50 cm) goniometer or short-arm (30 cm) goniometer gives a quick, gross measurement of static angles [\[12](#page-6-3)]. For assessment of the knee, the goniometer is placed with the proximal arm pointing towards

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Fig. 46.2 Short-arm goniometer with proximal limb centred on the greater trochanter and distal limb towards the lateral malleolus (Courtesy of Dublin Hospitals Football Club)

the greater trochanter and the distal arm towards the lateral malleolus (Fig. [46.2\)](#page-1-1) [[13\]](#page-6-4). Measurement accuracy is contingent on the alignment of the device arms between bony landmarks [\[14](#page-6-5)]. In patients with a bigger soft-tissue envelope, fnding the bony landmarks may be difficult and their position can change when cycling through fexion and extension [[15\]](#page-6-6). While the UG does not provide information about dynamic movement, it is widely available, is simple to use and, in experienced hands, has good intraobserver reliability.

As time moves on, the digitised goniometer looks set to replace the manual goniometer at least in research felds, and perhaps, in the nottoo-distant future, in clinical practice.

## **46.3 Electrical Digital Inclinometers (EDI)**

An electrical digital inclinometer is a device that is affxed to bony landmarks and interprets the movement of the knee using the same technology that determines the position in mobile phones, car airbags and aircraft [\[16](#page-6-7)]. An accelerometer in the device monitors the effect of gravity on a tiny mass held within an elastic support structure. When the EDI tilts, the suspended mass moves slightly, causing a change in capacitance. The tilt angle is calculated from the measured capacitances. Several EDIs are available, including the Cybex EDI 320 (New York, USA), HALO Digital inclinometer (New South Wales, Australia) (Fig. [46.3\)](#page-2-0) and the Limit Mini Digital Inclinometer (Alingsås, Sweden). When purchasing any equipment or adjunct to aid in clinical practice, the primary question is what does the device add and does it improve on the industry standard? The typical cost of a UG is several pounds (£) compared to several hundred for an EDI. Digital measurements have been reported as having similar validity and reliability as traditional goniometry measurements [[17\]](#page-6-8). Hancock et al. report that an EDI has the smallest minimum signifcant difference, concluding that it is the most accurate compared to other standard measurements [[10\]](#page-6-1). They did not compare to

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Fig. 46.3 HALO Digital inclinometer (New South Wales, Australia). (Reproduced with permission from [www.sportsphysio.ie](https://sportsphysio.ie/))

digital photographic goniometry, another modern modality of measurement in KROM.

## **46.4 Digital Photographic Goniometry (DPG)**

Digital photographic goniometry has appeared in the literature on knee kinematic measurement as a viable means of measuring KROM over the last 10 years [\[15](#page-6-6), [18](#page-6-9), [19](#page-6-10)].

Recording and measuring knee joint motion using digital imaging were frst described by Beverland et al. in 2009. High inter-observer  $(r > 0.948)$  and intra-observer repeatability  $(r > 0.906)$  was demonstrated in ten patients by two observers. The equipment needed was simply a digital camera and image analysis software (Rhinoceros, Seattle, USA).

The software available for interpreting KROM in DPG can account for variables such as camera lens quality and parallax errors [[19](#page-6-10)]. The main beneft of DPG is that the digital images taken allow for further measurements by a different investigator at a later date and they can be rechecked for reproducibility. Even when the bony landmarks are not overtly identifed in the image, the inter-rater reliability remains high [\[18](#page-6-9)]. The availability of such serial imaging may serve as a visual cue for the patient of their progress during rehabilitation and may even motivate them to engage in targeted improvements [[20\]](#page-6-11). Use of a designated digital camera and separate software is cumbersome in an age where we strive for technology to work seamlessly across platforms. Smartphone applications look to fll this void by offering the ability to image and interpret the KROM on the device that most people carry in their pockets. In one such application, a virtual goniometer is placed on the image taken of the desired joint, with superimposed markers indicating the joint position and relationship to the foor. Their use has been validated across different joints, albeit only in healthy participants [\[21–](#page-6-12)[23\]](#page-6-13). A variety of applications are available currently, including DrGoniometer (CDM S.r.L, Cagliari, Italy) (Fig. [46.4](#page-3-0)), Clinometer (Plaincode Software Solutions, Stephanskirchen, Germany) and ROM© goniometric application (Carci©, São

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**Fig. 46.4** DrGoniometer application interface. (Reproduced with permission from [www.drgoniometer.com\)](http://www.drgoniometer.com)

Paulo, Brazil), and it is likely that the market will become saturated with other iterations. In a systematic review by Milani et al., seven different applications were validated for use in lower limb measurements. DrGoniometer is an application that stood out over others for its ability to measure both static and dynamic angles, its potential to blind the rater to the measurement and its telemedicine integration [\[24\]](#page-6-14).

It is not however available on Android devices for which a viable alternative is the ROM© application. This was used by Dos Santos et al. in healthy female population  $(n = 34)$  and demonstrated a high degree of correlation ( $r \geq 0.90$ ;  $p < 0.0001$ ) with the universal goniometer and importantly no signifcant difference in variation between the two methods in any analysis (*p* > 0.05) (Fig. [46.5](#page-3-1)) [[25\]](#page-6-15).

The following techniques in measuring KROM are mostly if not exclusively confned to use in research studies and include fuoroscopy and cross-sectional imaging, radiostereometric analysis and motion capture analysis. These methods lend themselves to an assessment of the nuance of knee movement beyond fexion and extension in the sagittal plane.

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Fig. 46.5 Determination of knee angle with smartphone application; (**a**) initial position (0°); (**b**) fnal position;  $\alpha$  = final joint angle of knee flexion. (Reprinted from the Journal of Bodywork and Movement Therapies, 21:3, Dos

Santos et al., Evaluation of knee range of motion: Correlation between measurements using a universal goniometer and a smartphone goniometric application, p 699– 703, Copyright (2017), with permission from Elsevier)

# **46.5 Fluoroscopy and Cross-Sectional Imaging**

Single or biplane fuoroscopy measures in vivo joint kinematics using image intensifer(s) and provides in real time anatomic assessment during dynamic activities [[26\]](#page-6-16). Fluoroscopy can be used to match 3-dimensional models from CT or computer-aided design (CAD) imaging of implants to 2-dimensionally acquired fuoroscopic images [\[27](#page-6-17)]. The set-up of the C-arm limits the ability of the imaging to only capture a small portion of the gait cycle, and some laboratories have made their systems mobile [[28\]](#page-6-18). Biplane fuoroscopy has been traditionally used in combination with implanting markers into the bone; however, a number of studies have reported non-invasive model-based tracking techniques that provide submillimetre accuracy [[29,](#page-6-19) [30\]](#page-6-20).

Cross-sectional imaging techniques such as ultra-fast cine computed tomography or kinematic MRI studies can be used to measure KROM. Both modalities when frst described in the late 1980s were focused on the evaluation of patellofemoral movement, mainly patellar tracking and subluxation [[31,](#page-6-21) [32\]](#page-6-22).

The frst iterations of ultra-fast cine CT consisted of sequential static slices at different angles, and the frst truly dynamic kinematic CT protocol was described by Elias et al. (2014) using a 256-multi-detector CT (MDCT) [[33\]](#page-6-23). Compared to 64-MDCT, 256-MDCT is far superior in the acquisition of dynamic images [[34\]](#page-6-24). Protocols are designed to minimise radiation exposure but again are focused on patellar tracking analysis rather than KROM. Kinematic MRI avoids exposure to ionising radiation and details the anatomy of bone and soft tissue in both static and dynamic positions. Dynamic MRI evolved from its initial cardiac applications of blood fow and valvular motion [\[35](#page-6-25)] to the measurement of joint movement. Conventional MR imaging is both non-weight bearing and static. Dynamic MRI can be divided into cine PC-MRI and realtime MRI. Cine PC-MRI has been used to measure tibiofemoral kinematics and to visualise cartilage contact during movement by Kaiser et al. In their study, external tibial rotation and

anterior tibial translation of the knee were evident from extension to approximately 40° of fexion [[36\]](#page-6-26). A signifcant rate-limiting step is that cine PC-MRI requires repeated repetitions of the movement cycle. Real-time MRI needs only one motion cycle and is preferable for patients who would be unable to participate in repeated movements due to pain or fatigue [\[37](#page-6-27)]. A lack of standardisation in musculoskeletal protocols including optimal acquisition time, feld strength parameters, and patient and radiofrequency coil position limits the utility of this modality in standard clinical practice [[38\]](#page-6-28).

### **46.6 Radiostereometric Analysis (RSA)**

Radiostereometric analysis (RSA) is a technique used to predict long-term prosthesis stability by studying its early behaviour. Traditionally, RSA involves the invasive implantation of tantalum beads into a joint at the time of arthroplasty, and subsequently the position of these beads can be evaluated by X-ray images. So how can this technique be applied to measure the ROM of the tibiofemoral joint? There are two obvious problems here: the invasiveness of implanting a foreign body, particularly in the setting where one wants to measure native rather than prosthetic knee joint, and the use of static imaging. Invasive insertion of any device to measure KROM, from tantalum beads to cortical pins, carries with them the inherent risk of infection [\[39](#page-7-0)]. In order to address this, a model-based RSA method was introduced in the early 2000s [\[40](#page-7-1), [41](#page-7-2)]. This allows prosthesis or native knee tracking without the use of markers. This method has been validated by Stentz-Olesen et al., who measured the mean difference between the model method and the marker method for knee movement recorded by static and dynamic radiographs in a cadaveric study. They found that submillimetres of precision are lost compared to standard RSA; however (notwithstanding the added radiation of the CT image), the bone model has the potential to be developed as a clinical tool for measuring KROM [[42\]](#page-7-3).

#### **46.7 Motion Capture Analysis**

Modern non-invasive motion capture systems (MoCap) employ skin markers or virtual markers and video or optical sensors to capture trial data from an individual as they move during gait [\[43](#page-7-4)] or specific tasks such as squatting [\[44](#page-7-5)] or climbing stairs [\[45](#page-7-6)]. Indirect measures are taken from these systems to interpret the kinetics and kinematics of the upper or lower limbs. The main purpose of this approach is to determine the six degrees of freedom of different joint kinematics during activities of daily living and yield a more in-depth understanding of KROM than simple fexion and extension. Such systems use anatomical landmarks and functional models to resolve joint centres and axes, from which the range of motion of the joint can be ascertained  $[46]$ . The positions of the markers in space are determined using stereophotogrammetry, which requires a minimum of two cameras. In marker-based MoCap, there are issues with soft-tissue artefact, as the markers do not rigidly stay in place over bony landmarks but are mobile due to muscle and skin movement [\[47](#page-7-8)]. It is this artefact which renders MoCap less accurate than methods such as biplane fuoroscopy. The coordinate data from the markers is sent to either a commercial programme such as Vicon Plug In Gait (Oxford Metrics Limited, UK) or a bespoke programme to interpret the variables produced by standard coding software, e.g. MATLAB (MathWorks, USA). MoCap studies can determine fexion-extension angles, abduction-adduction angles and internal and external rotation angles. These studies have yielded some useful information, such as continued external rotation of the tibia during stair ascension [[48](#page-7-9), [49\]](#page-7-10). In other activities, e.g. squatting, there is no agreement in the literature with respect to abduction or adduction of the femur relative to the tibia [\[44,](#page-7-5) [50,](#page-7-11) [51\]](#page-7-12). Looking at these studies, the conditions under which MoCap is performed are variable, including some early post-operative patients [[44](#page-7-5)] and stairs of different slopes and heights. A greater number of higher powered studies using standardised conditions and patient cohorts are necessary to make the fndings generalisable to a normal population in the future.

#### **46.8 Conclusion**

At its simplest, tibiofemoral motion is measured in day-to-day clinical practice in the sagittal plane. There are devices and applications available, which improve on the universal goniometer and allow record-keeping for posterity and future treatment. Tibiofbular joint motion as well as other tibiofemoral movements (medial and lateral translational and knee abduction-adduction) are not routinely factored into consideration. Six degrees of freedom models consider knee movement in the sagittal, coronal and transverse planes. We have shown that this requires sophisticated and potentially costly equipment, such as fuoroscopy, cross-sectional imaging or motion capture analysis. These technologies are not routinely available and necessarily merited for everyday evaluation, but certainly have their place in a specialist gait laboratory for complex knee pathology.

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