



Guarantees for Maximization of k -Submodular Functions with a Knapsack and a Matroid Constraint

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Abstract. A k -submodular function is a generalization of a submodular function, whose definition domain is the collection of k disjoint subsets. In our paper, we apply a greedy and local search technique to obtain a $\frac{1}{6}(1 - e^{-2})$ -approximate algorithm for the problem of maximizing a k -submodular function subject to the intersection of a knapsack constraint and a matroid constraint. Furthermore, we use a special analytical method to improve the approximation ratio to $\frac{1}{3}(1 - e^{-3})$, when the k -submodular function is monotone.

Keywords: k -submodularity · Knapsack constraint · Matroid constraint · Approximation algorithm

1 Introduction

Consider a ground set G composed of n elements and $k \in N_+$, we define $(k + 1)^G$ as the family of k disjoint subset (X_1, \dots, X_k) , where $X_i \subseteq G, \forall i \in [k]$ and $X_i \cap X_j = \emptyset, \forall i \neq j$. A function $f : (k + 1)^G \rightarrow R$ is said to be k -submodular [7], if

$$f(\mathbf{x}) + f(\mathbf{y}) \geq f(\mathbf{x} \sqcup \mathbf{y}) + f(\mathbf{x} \sqcap \mathbf{y}),$$

for any $\mathbf{x} = (X_1, \dots, X_k)$ and $\mathbf{y} = (Y_1, \dots, Y_k)$ in $(k + 1)^G$, where

$$\mathbf{x} \sqcup \mathbf{y} := (X_1 \cup Y_1 \setminus (\bigcup_{i \neq 1} X_i \cup Y_i), \dots, X_k \cup Y_k \setminus (\bigcup_{i \neq k} X_i \cup Y_i)),$$

$$\mathbf{x} \sqcap \mathbf{y} := (X_1 \cap Y_1, \dots, X_k \cap Y_k).$$

Obviously, it is a submodular function for $k = 1$.

As early as 1978, Nemhauser et al. [11] studied the monotone submodular maximization problem subject to cardinality constraints and obtained a greedy $(1 - 1/e)$ -approximation algorithm. Many scholars extended submodular maximization to different constraints and design approximate algorithms, see [1–6, 10, 17, 20]. Among them,

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knapsack constraint and matroid constraint are mainly concerned, and most of the algorithms can achieve the tight $1 - 1/e$ approximation ratio. However, under the intersection constraint of a knapsack and a matroid, we have not found that the algorithm can achieve $1 - 1/e$ -approximation, since the loss of rounding is difficult to avoid. Recently, by combining greedy and local search techniques, Sarpatwa et al. [16] contributed an algorithm for reaching $\frac{1-e^{-2}}{2}$ -approximation ratio.

In recent years, k -submodular maximization problem has been widely concerned and studied. There have been many research results. For k -submodular maximization without constraint, Ward and Zivny [19] gave a deterministic greedy algorithm, whose approximate ratio reached $1/3$, and a randomized greedy algorithm whose approximate ratio is $\frac{1}{1+a}$, where $a = \max\{1, \sqrt{\frac{k-1}{4}}\}$. Iwata et al. [8] improved the approximation ratio to $1/2$. Later, [14] contributed an algorithm with ratio $\frac{k^2+1}{2k^2+1}$. Under the monotonicity assumption, Ward and Zivny [19] gave a $1/2$ approximation algorithm and Iwata et al. [8] improved the approximation ratio to $k/(2k-1)$, which is asymptotically tight. There are also many results for nonnegative monotone k -submodular maximization with constraints. In 2015, Ohsaka and Yoshida [13] designed a $1/2$ -approximation algorithm for a total size constraint. Sakaue [15] presented a $1/2$ -approximation algorithm with a matroid constraint. And for monotone k -submodular maximization subject to a knapsack constraint, Tang et al. [18] proposed an algorithm of $\frac{1-1/e}{2}$ approximate ratio. Liu et al. [9] design a combinatorial approximation algorithm for monotone k -submodular maximization subject to a knapsack and a matroid constraint and obtained a $\frac{1}{4}(1 - e^{-2})$ approximate ratio.

In this paper, we consider the k -submodular maximization subject to a knapsack and a matroid constraint, and do some work on the basis of the algorithm given by Liu et al. [9]. The main contributions of this paper are as follows:

- We extend the algorithm for k -submodular maximization problem with a knapsack and a matroid constraint to nonmonotone case, and achieve a $\frac{1}{6}(1 - e^{-2})$ approximate ratio, based on the pairwise monotone property.
- We improve the approximate ratio from $\frac{1}{4}(1 - e^{-2})$ in [9] to $\frac{1}{3}(1 - e^{-3})$ under the monotonicity assumption. In the theoretical analysis of the algorithm, we no longer rely on the results of the greedy algorithm for the unconstrained k -submodular maximization problem, and use the properties of k -submodular function to get the new result.

We organize our paper as follows. In Sect. 2, we first introduce the k -submodular function and some corresponding results, then present the k -submodular maximization problem with a knapsack and a matroid constraint. We present our results for non-monotone case in Sect. 3. In Sect. 4, we show our theoretical analysis for monotone case.

2 Preliminaries

2.1 k -Submodular Function

For any two k disjoint subsets $\mathbf{x} = (X_1, \dots, X_k)$ and $\mathbf{y} = (Y_1, \dots, Y_k)$ in $(k+1)^G$, we need to introduce a remove operation and a partial order, i.e.

$$\mathbf{x} \setminus \mathbf{y} := (X_1 \setminus Y_1, \dots, X_k \setminus Y_k),$$

$$\mathbf{x} \preceq \mathbf{y}, \text{ if } X_i \subseteq Y_i, \forall i \in [k].$$

Define $\emptyset := (\emptyset, \dots, \emptyset) \in (k+1)^G$ and $(v, i) \in (k+1)^G$ such that $X_i = \{v\}$ and $X_j = \emptyset$ for $\forall j \in [k]$ with $j \neq i$. Refer $U(\mathbf{x}) = \bigcup_{i=1}^k X_i$. For $v \notin U(\mathbf{x})$, we use $f_{\mathbf{x}}((v, i)) = f(\mathbf{x} \sqcup (v, i)) - f(\mathbf{x})$ to represent the marginal gain of f . A function f is said to be pairwise monotone if $f_{\mathbf{x}}((v, i)) + f_{\mathbf{x}}((v, j)) \geq 0$ for any $i \neq j \in [k]$ holds. In addition, we call that the function f is orthant submodular, if $f_{\mathbf{x}}((v, i)) \geq f_{\mathbf{y}}((v, i))$ holds, for any $\mathbf{x} \preceq \mathbf{y}$. According to the above definition, we have the equivalent definition and property of the k -submodular function as follows.

Definition 1 [19]. *A function $f : (k + 1)^G \rightarrow R$ is k -submodular iff it is pairwise monotone and orthant submodular.*

Lemma 1 [18]. *Given a k -submodular f , we have*

$$f(\mathbf{y}) - f(\mathbf{x}) \leq \sum_{(v,i) \preceq \mathbf{y} \setminus \mathbf{x}} f_{\mathbf{x}}((v, i)),$$

for any $\mathbf{x} \preceq \mathbf{y}$.

Check the definition of k -submodular, we have the lemma as follows.

Lemma 2. *Given a k -submodular f , we set $g(\mathbf{x}) = f(\mathbf{x} \sqcup (v, i)) : (k + 1)^{G \setminus v} \rightarrow R$, then $g(\mathbf{x})$ is k -submodular.*

2.2 k -Submodular Maximization with a Knapsack and a Matroid Constraint

We define $\mathcal{L} \subseteq 2^G$ as the family of subsets of G . A pair (G, \mathcal{L}) is called as an independence system if $(\mathcal{M}1)$ and $(\mathcal{M}2)$ holds. And if $(\mathcal{M}3)$ also holds, the independence system (G, \mathcal{L}) is a matroid.

Definition 2. *Given a pair $\mathcal{M} = (G, \mathcal{L})$, where $\mathcal{L} \subseteq 2^G$. We call \mathcal{M} is a matroid if the following holds:*

$(\mathcal{M}1)$: $\emptyset \in \mathcal{L}$.

$(\mathcal{M}2)$: for any subset $A \in \mathcal{L}$, $B \subseteq A$ indicates $B \in \mathcal{L}$.

$(\mathcal{M}3)$: for any two subset $A, B \in \mathcal{L}$, $|A| > |B|$ indicates that there exists a point $v \in A \setminus B$, such that $B \cup \{v\} \in \mathcal{L}$.

Given a subset $A \in \mathcal{L}$ and a pair of points (a, b) , where $a \in A \cup \{\emptyset\}$ and $b \in G \setminus A$, we refer the pair (a, b) as a swap (a, b) if $A \setminus \{a\} \cup \{b\} \in \mathcal{L}$. It means that only some special points pair called swap can guarantee that $A \setminus \{a\} \cup \{b\} \in \mathcal{L}$ is still an independent set.

We highlight that the next lemma ensures that a swap(a, b) must exist between the optimal solution \mathbf{x}^* and the current solution \mathbf{x}^t in the later analysis. Consider the support set of the current solution $U(\mathbf{x}^t)$ as $A \in \mathcal{L}$ and $U(\mathbf{x}^*)$ as $B \in \mathcal{L}$. We will consider finding a special kind of swap($y(b), b$) of $U(\mathbf{x}^t)$, where $b \in U(\mathbf{x}^*) \setminus U(\mathbf{x}^t)$ and $y(b) \in U(\mathbf{x}^t) \setminus U(\mathbf{x}^*) \cup \{\emptyset\}$.

Lemma 3 [16]. *Assume two sets $A, B \in \mathcal{L}$, then we can construct a mapping $y : B \setminus A \rightarrow (A \setminus B) \cup \{\emptyset\}$, where every point $b \in B \setminus A$ satisfies $(A \setminus \{y(b)\}) \cup \{b\} \in \mathcal{L}$, and $a \in A \setminus B$ satisfies $|y^{-1}(a)| \leq 1$.*

Consider every point v in G , we give it a weight $w_v \geq 0$ and a total upper bound B . In the following, we assume that w_v is an integer, because we can always change all w_v and B proportionally without losing generality. The two constraints reduce the domain of candidate solutions, so we can only find some solutions $\mathbf{x} \in (k+1)^G$ such that the sum of weight w_v of all points v in $U(\mathbf{x})$ is less than B and $U(\mathbf{x})$ is an independent set. Define $w_x = \sum_{v \in U(\mathbf{x})} w_v$. The problem can be written as

$$\max_{\mathbf{x} \in (k+1)^G} \{f(\mathbf{x}) \mid w_x \leq B \text{ and } U(\mathbf{x}) \in \mathcal{L}\}. \quad (1)$$

In addition, in the later proof, we need to use the following lemma.

Lemma 4 [11]. *Given two fixed $P, D \in N_+$ and a sequence of numbers $\gamma_i \in R_+$, where $i \in [P]$, then we have*

$$\begin{aligned} & \frac{\sum_{i=1}^P \gamma_i}{\min_{t \in [P]} (\sum_{i=1}^{t-1} \gamma_i + D\gamma_t)} \\ & \geq 1 - \left(1 - \frac{1}{D}\right)^P \geq 1 - e^{-P/D}. \end{aligned} \quad (2)$$

2.3 Algorithm

Before giving the algorithm to solve problem (1), we firstly introduce a greedy algorithm for unconstrained k -submodular by [19]. We know that a k -submodular function f is pairwise monotone due to Definition 1, that is, $f_x((v, i)) + f_x((v, j)) \geq 0$ for any $i \neq j \in [k]$. It means that for a fixed $\mathbf{x} \in (k+1)^G$ and $v \in G \setminus U(\mathbf{x})$, there are no two positions $i \neq j \in [k]$ such that $f_x((v, i)) < 0$ and $f_x((v, j)) < 0$ both hold. So we can always find a position $i \in [k]$ such that $f_x((v, i)) \geq 0$ for any $v \in G \setminus U(\mathbf{x})$. Therefore, for every current solution \mathbf{x}^t in the Algorithm 1, we add $v \in G \setminus U(\mathbf{x}^t)$ with a greedy position i_j until all points $v \in G$ are added to $U(\mathbf{x}^t)$.

Then we give an algorithm inspired by [16] and [18] for problems (1) called MK-KM abbreviated as maximizing k -submodular function with a knapsack constraint and a matroid constraint. Let's highlight some important nodes. Firstly, we select three elements with the largest marginal return from the optimal solution \mathbf{x}^* by enumerating. Second, for every current solution $\mathbf{x}^t \in \mathcal{L}$ and the optimal solution $\mathbf{x}^* \in \mathcal{L}$, we can always find a swap($y(b), b$) satisfying $y(b) \in \mathbf{x}^t \setminus \mathbf{x}^*$ and $b \in \mathbf{x}^* \setminus \mathbf{x}^t$ by Lemma 3. But we always choose a swap(a, b) with the highest marginal profit density $\rho(a, b)$. In the

Algorithm 1. Greedy Algorithm (f, G)**Require:** A function $f : (k+1)^G \rightarrow R_+$ and a set $G = [n]$ **Ensure:** A k -disjoint set $x \in (k+1)^G$

- 1: $x \leftarrow (\emptyset, \dots, \emptyset)$
- 2: **for** $j = 1$ to n **do**
- 3: $i_j \leftarrow \arg \max_{i \in [k]} f_x((v, i))$
- 4: $x \leftarrow x \sqcup (v, i_j)$
- 5: **end for**
- 6: **return** x

line 9 of MK-KM, we reorder the $U(x^t)$ after the operation of $\text{swap}(a, b)$ and ensure $x^0 \preceq x^t$. Considering the order of each element in $(U(x^{t-1} \setminus x^0) \setminus \{a\}) \cup \{b\}$ as it is added to current solution in MK-KM, we add them to Greedy Algorithm in the same order. Last but not least, only when x^t is updated, S will be regenerated in line 5. Otherwise, MK-KM will continue to pick and remove the next swap in the loop from 6 to 13. So MK-KM will break the loop when $S = \emptyset$ in line 6.

Algorithm 2. MK-KM (G, B, M)**Require:** A function $f : (k+1)^G \rightarrow R_+$, a budget $B \in R_+$ and a matroid (G, \mathcal{L}) **Ensure:** A k -disjoint set $x \in (k+1)^G$ satisfying $w_x \leq B$ and $U(x) \in \mathcal{L}$

- 1: Let $x^\alpha \in \arg \max_{|U(x)|=1, x \preceq x^*} f(x)$, $x^\beta \in \arg \max_{|U(x)|=2, x^\alpha \preceq x \preceq x^*} f(x)$
 $x^\gamma \in \arg \max_{|U(x)|=3, x^\beta \preceq x \preceq x^*} f(x)$ and $t = 0$
- 2: $x^t \leftarrow x^\gamma$ and $\text{switch} = \text{false}$
- 3: **while** $\text{switch} = \text{false}$ **do**
- 4: $\text{switch} = \text{true}$
- 5: Generate a collection of all swaps $S = S(U(x^t \setminus x^0))$
- 6: **while** $\text{switch} = \text{true}$ and $S \neq \emptyset$ **do**
- 7: Pick a swap (a, b) from S with a maximum value of $\rho(a, b) = \max_{j \in [k]} \frac{f((x^t \setminus (a, i)) \sqcup (b, j)) - f(x^t)}{w_b}$
- 8: **if** $\rho(a, b) > 0$ and $w_x - w_a + c_b \leq B$ **then**
- 9: $\tilde{x}^t \leftarrow \text{Greedy Algorithm for } f(\tilde{x}^t \sqcup x^0) \text{ over } (U(x^t \setminus x^0) \setminus \{a\}) \cup \{b\}$
- 10: $x^{t+1} = \tilde{x}^t \sqcup x^0$
- 11: $w_{x^{t+1}} = w_{x^t} - w_a + w_b$
- 12: $\text{switch} = \text{false}$
- 13: **end if**
- 14: $S = S \setminus \{(a, b)\}$
- 15: **end while**
- 16: **end while**
- 17: **return** x

We modify MK-KM and give MK-KM' algorithm for problem (1) with monotonicity. MK-KM' selects two elements with the largest marginal return from the optimal solution \mathbf{x}^* by enumerating. This modification reduces the running time.

Algorithm 3. MK-KM' (G, B, M)

Require: A function $f : (k + 1)^G \rightarrow R_+$, a budget $B \in R_+$ and a matroid (G, \mathcal{L})

Ensure: A k -disjoint set $\mathbf{x} \in (k + 1)^G$ satisfying $w_{\mathbf{x}} \leq B$ and $U(\mathbf{x}) \in \mathcal{L}$

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1: Let  $\mathbf{x}^\alpha \in \arg \max_{|U(\mathbf{x})|=1, \mathbf{x} \preceq \mathbf{x}^*} f(\mathbf{x})$ ,  $\mathbf{x}^\beta \in \arg \max_{|U(\mathbf{x})|=2, \mathbf{x}^\alpha \preceq \mathbf{x} \preceq \mathbf{x}^*} f(\mathbf{x})$ , and  $t = 0$ 
2:  $\mathbf{x}^t \leftarrow \mathbf{x}^\beta$  and  $switch = false$ 
3: while  $switch = false$  do
4:    $switch = true$ 
5:   Generate a collection of all swaps  $S = S(U(\mathbf{x}^t \setminus \mathbf{x}^0))$ 
6:   while  $switch = true$  and  $S \neq \emptyset$  do
7:     Pick a swap  $(a, b)$  from  $S$  with a maximum value of  $\rho(a, b) = \max_{j \in [k]} \frac{f((\mathbf{x}^t \setminus (a, i)) \sqcup (b, j)) - f(\mathbf{x}^t)}{w_b}$ 
8:     if  $\rho(a, b) > 0$  and  $w_{\mathbf{x}^t} - w_a + w_b \leq B$  then
9:        $\tilde{\mathbf{x}}^t \leftarrow$  Greedy Algorithm for  $f(\tilde{\mathbf{x}}^t \sqcup \mathbf{x}^0)$  over  $(U(\mathbf{x}^t \setminus \mathbf{x}^0) \setminus \{a\}) \cup \{b\}$ 
10:       $\mathbf{x}^{t+1} = \tilde{\mathbf{x}}^t \sqcup \mathbf{x}^0$ 
11:       $w_{\mathbf{x}^{t+1}} = w_{\mathbf{x}^t} - w_a + w_b$ 
12:       $switch = false$ 
13:    end if
14:     $S = S \setminus \{(a, b)\}$ 
15:  end while
16: end while
17: return  $\mathbf{x}$ 
    
```

In order to pave the way for analysis of Sect. 4, we consider the process of the current solution \mathbf{x}^t generated by $\mathbf{x}^0 \sqcup \tilde{\mathbf{x}}^t$. We carefully define $\tilde{\mathbf{x}}_j^t$ as the current solution of each iteration of the greedy algorithm of the 9th line, where $j \in \{1, \dots, |U(\mathbf{x}^t) - 2|\}$ for every fixed t . Define $(v_j, i_j) = \tilde{\mathbf{x}}_j^t \setminus \tilde{\mathbf{x}}_{j-1}^t$ in Greedy Algorithm.

For the convenience of writing, we define $\mathbf{x}_j^t = \tilde{\mathbf{x}}_j^t \sqcup \mathbf{x}^0$. Then immediately $(v_j, i_j) = (\mathbf{x}_j^t \setminus \mathbf{x}_{j-1}^t) = ((\tilde{\mathbf{x}}_j^t \sqcup \mathbf{x}^0) \setminus (\tilde{\mathbf{x}}_{j-1}^t \sqcup \mathbf{x}^0))$ holds. For each fixed iteration step t , there are a string of iteration steps $j \in \{1, \dots, |U(\mathbf{x}^t) - 2|\}$ for the nested greedy algorithm.

3 Analysis for Non-monotone k -submodular Maximization with a Knapsack Constraint and a Matroid Constraint

In this section, we will draw support from the nested greedy algorithm to solve problem (1). For nonnegative, non-monotone and unconstrained k -submodular, we need the following conclusions. Lemma 5 comes from Proposition 2.1 in [8]. If there exists a solution achieving the optimal value, we can construct an optimal solution containing all points of ground set. Therefore, for unconstrained k -submodular maximization, we

only analyze the optimal solution which is the partition of ground set of Algorithm 1. And Lemma 6 ensures that we can obtain a $1/3$ -approximate greedy solution in the nested greedy Algorithm 1 by using $(U(\mathbf{x}^t \setminus \mathbf{x}^0) \setminus \{a\}) \cup \{b\}$ as ground set G , where $\text{OPT}_f(G)$ is the optimal value of unconstrained k -submodular f maximization over G .

Lemma 5 [8]. *For maximizing a non-monotone k -submodular f over a set G , there exists a partition of G achieving the optimal value.*

Lemma 6 [19]. *For maximizing a non-monotone k -submodular f over a set G , by greedy algorithm, we can get a solution \mathbf{x} such that $U(\mathbf{x}) = G$ and $3f(\mathbf{x}) \geq \text{OPT}_f(G)$.*

Drawing support from the nested greedy algorithm, we reorder each iterative solution of MK-KM and analyze the approximate ratio in two cases.

Theorem 1. *Applying MK-KM algorithm to problem (1), we can obtain a $\frac{1}{6}(1 - e^{-2})$ -approximate ratio.*

Proof. Using Lemma 3 between the iterative solution \mathbf{x}^t of MK-KM and the optimal solution \mathbf{x}^* , there exists swap $(y(b), b)$ satisfying $y(b) \in (U(\mathbf{x}^t) \setminus U(\mathbf{x}^*)) \cup \{\emptyset\}$ and $b \in U(\mathbf{x}^*) \setminus U(\mathbf{x}^t)$.

For any iteration step t , we construct a solution $\hat{\mathbf{x}}^t$. Considering all $(b, i) \preceq \mathbf{x}^* \setminus \mathbf{x}^t$, we add them to \mathbf{x}^t and get $\hat{\mathbf{x}}^t$. Note that $\mathbf{x}^0 \preceq \mathbf{x}^t \preceq \hat{\mathbf{x}}^t$ and $U(\hat{\mathbf{x}}^t) = U(\mathbf{x}^*) \cup U(\mathbf{x}^t)$.

Due to Lemma 5, there exists an optimal solution containing all points in ground set G . And by Lemma 2, we know that $f(\mathbf{x} \sqcup \mathbf{x}^0)$ is a k -submodular over $U(\hat{\mathbf{x}}^t) \setminus U(\mathbf{x}^0)$. So we define that $\text{OPT}_{f(\mathbf{x} \sqcup \mathbf{x}^0)}(U(\hat{\mathbf{x}}^t) \setminus U(\mathbf{x}^0))$ is the optimal value of $f(\mathbf{x} \sqcup \mathbf{x}^0)$ over $U(\hat{\mathbf{x}}^t \setminus \mathbf{x}^0)$. Using Lemma 6 for each \mathbf{x}^t in MK-KM, we always have

$$\begin{aligned}
& \text{OPT}_{f(\mathbf{x} \sqcup \mathbf{x}^0)}(U(\hat{\mathbf{x}}^t) \setminus U(\mathbf{x}^0)) \\
& \leq 3f(\hat{\mathbf{x}}^t) \\
& \leq 3f(\mathbf{x}^t) + 3 \sum_{(b,i) \preceq \hat{\mathbf{x}}^t \setminus \mathbf{x}^t} [f(\mathbf{x}^t \sqcup (b, i)) - f(\mathbf{x}^t)] \\
& \leq 3f(\mathbf{x}^t) + 3 \sum_{(b,i) \preceq \hat{\mathbf{x}}^t \setminus \mathbf{x}^t} [f((\mathbf{x}^t \setminus (y(b), j)) \sqcup (b, i)) - f((\mathbf{x}^t \setminus (y(b), j)))] .
\end{aligned} \tag{3}$$

The first inequality is due to Lemma 6. And the second is due to Lemma 1. By orthant submodularity, we get the third inequality. Recall that MK-KM breaks all loops when $S = \emptyset$ in line 6. It implies that we cannot find a qualified swap (a, b) to update the output solution \mathbf{x} . We only consider swaps $(y(b), b)$ in $S(U(\mathbf{x} \setminus \mathbf{x}^0))$ related to $b \in U(\mathbf{x}^*) \setminus U(\mathbf{x})$ instead of all candidate swaps (a, b) . Now we use this construction method to analyze the algorithm in two cases.

Case 1: Consider a very special case that every swap $(y(b), b)$ was rejected just due to $\rho(y(b), b) \leq 0$ instead of knapsack constraint.

Applying formula (3) for the output solution \mathbf{x} and constructed solution $\hat{\mathbf{x}}$, we get

$$\begin{aligned}
 & f(\mathbf{x}^*) \\
 & \leq OPT_{f(\mathbf{x} \sqcup \mathbf{x}^0)}(U(\hat{\mathbf{x}}) \setminus U(\mathbf{x}^0)) \\
 & \leq 3f(\mathbf{x}) + 3 \sum_{(b,i) \preceq \hat{\mathbf{x}} \setminus \mathbf{x}} [f((\mathbf{x} \setminus (y(b), j)) \sqcup (b, i)) - f((\mathbf{x} \setminus (y(b), j)))].
 \end{aligned} \tag{4}$$

Since $\rho(y(b), b) \leq 0$, we have

$$f((\mathbf{x} \setminus (y(b), j)) \sqcup (b, i)) \leq f(\mathbf{x}) \tag{5}$$

for all $(b, i) \preceq \hat{\mathbf{x}} \setminus \mathbf{x}$. We define $\{(y(b), j)\}_{b \in U(\hat{\mathbf{x}}^t \setminus \mathbf{x}^t) \setminus \{\emptyset\}} = \{(y_1, j_1), \dots, (y_K, j_K)\}$, then we get

$$\begin{aligned}
 & \sum_{(b,i) \preceq \hat{\mathbf{x}} \setminus \mathbf{x}} [f(\mathbf{x}) - f((\mathbf{x} \setminus (y(b), j)))] \\
 & \leq \sum_{l=1}^K [f((\mathbf{x} \setminus ((y_1, j_1) \sqcup \dots \sqcup (y_K, j_K))) \sqcup ((y_1, j_1) \sqcup \dots \sqcup (y_l, j_l))) \\
 & \quad - f((\mathbf{x} \setminus ((y_1, j_1) \sqcup \dots \sqcup (y_K, j_K))) \sqcup ((y_1, j_1) \sqcup \dots \sqcup (y_{l-1}, j_{l-1})))] \\
 & = f(\mathbf{x}) - f(\mathbf{x} \setminus ((y_1, j_1) \sqcup \dots \sqcup (y_K, j_K))) \\
 & \leq f(\mathbf{x}).
 \end{aligned} \tag{6}$$

The first inequality is due to orthant submodularity. Because f is nonnegative, the second inequality holds. So we can get

$$f(\mathbf{x}^*) \leq 6f(\mathbf{x}). \tag{7}$$

Therefore, we find a $1/6$ -approximate solution in Case 1.

Case 2: Consider the opposite of Case 1 that there exists at least one swap $(y(b), b)$ satisfying $w_{\mathbf{x}} - w_{y(b)} + w_b > B$.

Assume a special iteration step t^* . For the first time, there appears a swap $(y(b_*), b_*)$ in $S(U(\mathbf{x}^{t^*} \setminus \mathbf{x}^0))$ such that $w_{\mathbf{x}^{t^*}} - w_{y(b_*)} + w_{b_*} > B$, where $b_* \in U(\mathbf{x}^*) \setminus U(\mathbf{x}^{t^*})$ and $y(b_*) \in (U(\mathbf{x}^{t^*}) \setminus U(\mathbf{x}^*)) \cup \{\emptyset\}$.

Although this swap $(y(b_*), b_*)$ violates the knapsack constraint, we use it to construct a solution $(\mathbf{x}^{t^*} \setminus (y(b_*), j_{y(b_*)})) \sqcup (b_*, i_{b_*})$. By orthant submodularity, pairwise monotonicity and the greedy choice of \mathbf{x}^α , \mathbf{x}^β and \mathbf{x}^γ , we have

$$f((\mathbf{x}^{t^*} \setminus (y(b_*), j_{y(b_*)})) \sqcup (b_*, i_{b_*})) - f(\mathbf{x}^{t^*}) \leq \frac{2}{3}f(\mathbf{x}^0). \tag{8}$$

The detailed process of proof is shown in the Appendix. By Lemma 2, we know that $g(\mathbf{x}) = f(\mathbf{x}) - f(\mathbf{x}^0)$ is a k -submodular function. Then applying formula (3) for the current solution \mathbf{x}^t and constructed solution $\hat{\mathbf{x}}^t$, we can get

$$g(\mathbf{x}^*) \leq 6[g(\mathbf{x}^t) + \frac{(B - w_{\mathbf{x}^0})}{2} \rho_{t+1}]. \tag{9}$$

for all $t \in \{1, \dots, t^*\}$. The detailed process of proof is shown in the Appendix. We introduce a construction method inspired by K. K. Sarpatwar [16]. Its details are still in the Appendix. Due to the construction method, we can get

$$\frac{g((\mathbf{x}^{t^*} \setminus (y(b_*), j_{y(b_*)})) \sqcup (b_*, i_{b_*}))}{g(\mathbf{x}^*)} \geq \frac{1}{6}(1 - e^{-2}). \quad (10)$$

Then, combining (8) and (10), we have

$$\begin{aligned} & f(\mathbf{x}^{t^*}) \\ &= f(\mathbf{x}^0) + g(\mathbf{x}^{t^*}) \\ &= f(\mathbf{x}^0) + g((\mathbf{x}^{t^*} \setminus (y(b_*), j_{y(b_*)})) \sqcup (b_*, i_{b_*})) \\ &\quad - [g((\mathbf{x}^{t^*} \setminus (y(b_*), j_{y(b_*)})) \sqcup (b_*, i_{b_*})) - g(\mathbf{x}^{t^*})] \\ &= f(\mathbf{x}^0) + g((\mathbf{x}^{t^*} \setminus (y(b_*), j_{y(b_*)})) \sqcup (b_*, i_{b_*})) \\ &\quad - [f((\mathbf{x}^{t^*} \setminus (y(b_*), j_{y(b_*)})) \sqcup (b_*, i_{b_*})) - f(\mathbf{x}^{t^*})] \\ &\geq f(\mathbf{x}^0) + \frac{1}{6}(1 - e^{-2})g(\mathbf{x}^*) - \frac{2}{3}f(\mathbf{x}^0) \\ &\geq \frac{1}{6}(1 - e^{-2})f(\mathbf{x}^*). \end{aligned} \quad (11)$$

Therefore, we have a $\frac{1}{6}(1 - e^{-2})$ -approximate solution \mathbf{x}^{t^*} for MK-KM.

4 Analysis for Monotone k -Submodular Maximization with a Knapsack and a Matroid Constraint

A function f is said to be monotone, if $f(\mathbf{x}) \leq f(\mathbf{y})$ for any $\mathbf{x} \preceq \mathbf{y}$. It is easy to see that f must be pairwise monotone if f is monotone. Therefore, a monotone function $f : (k+1)^G \rightarrow R$ is k -submodular if and only if it is orthant submodular. In this section, we introduce a special construction method inspired by Lan N. Nguyen [12], and obtain a better approximate ratio by MK-KM' algorithm.

For a fixed iteration t , recall that $(v_j, i_j) = \mathbf{x}_j^t \setminus \mathbf{x}_{j-1}^t$. Define $(v_j, i_*) \preceq \mathbf{x}^*$. We construct two sequences $\{\mathbf{o}_{j-1/2}\}$ and $\{\mathbf{o}_j\}$ such that $\mathbf{o}_{j-1/2} = (\mathbf{x}^* \sqcup \mathbf{x}_j^t) \sqcup \mathbf{x}_{j-1}^t$ and $\mathbf{o}_j = (\mathbf{x}^* \sqcup \mathbf{x}_j^t) \sqcup \mathbf{x}_j^t$, where $j \in \{1, \dots, |U(\mathbf{x}^t)| - 2\}$ and $\mathbf{o}_{j=0} = \mathbf{x}^*$.

Note that $\mathbf{x}_{j-1}^t \preceq \mathbf{x}_j^t \preceq \mathbf{o}_j$ and $\mathbf{o}_{j-1/2} \preceq \mathbf{o}_j$. By Lemma 2, we know that $g(\mathbf{x}) = f(\mathbf{x}) - f(\mathbf{x}^0)$ is a monotone k -submodular function. Then for any $j \in \{1, \dots, |U(\mathbf{x}^t)| - 2\}$, we have

$$g(\mathbf{o}_{j-1}) - g(\mathbf{o}_j) \leq g(\mathbf{o}_{j-1}) - g(\mathbf{o}_{j-1/2}) \leq g(\mathbf{x}_j^t) - g(\mathbf{x}_{j-1}^t). \quad (12)$$

The first inequality is due to monotonicity and $\mathbf{o}_{j-1/2} \preceq \mathbf{o}_j$. When $v_j \notin U(\mathbf{x}^*)$ or $v_j \in U(\mathbf{x}^*)$ with $i_j = i_*$, we have $g(\mathbf{o}_{j-1}) - g(\mathbf{o}_{j-1/2}) \leq 0$ by monotonicity. When $v_j \in U(\mathbf{x}^*)$ and $i_j \neq i_*$, we have $g(\mathbf{o}_{j-1}) - g(\mathbf{o}_{j-1/2}) \geq 0$. Using orthant submodularity, we get the following inequality.

$$g(\mathbf{o}_{j-1}) - g(\mathbf{o}_{j-1/2}) \leq g(\mathbf{x}_{j-1}^t \sqcup (v_j, i_*)) - g(\mathbf{x}_{j-1}^t) \quad (13)$$

Then by greedy choice, the inequality (12) holds.

Theorem 2. According to MK-KM' algorithm, a $\frac{1}{3}(1 - e^{-3})$ -approximate solution of problem (1) can be obtained, if f is monotone.

Proof. Similarly to Theorem 1, we analyze the algorithm in two cases. When we get the output solution \mathbf{x} , there is not any qualified swap (a, b) to update \mathbf{x} . We only consider swaps $(y(b), b)$ in $S(U(\mathbf{x} \setminus \mathbf{x}^0))$ related to $b \in U(\mathbf{x}^*) \setminus U(\mathbf{x})$ instead of all candidate swaps (a, b) .

Case 1: Consider a very special case that every swap $(y(b), b)$ was rejected just due to $\rho(y(b), b) \leq 0$ instead of knapsack constraint.

For the optimal solution \mathbf{x}^* and the output solution \mathbf{x} , we construct two sequences $\{\mathbf{o}_{j-1/2}\}$ and $\{\mathbf{o}_j\}$, where $j \in \{1, \dots, |U(\mathbf{x})| - 2\}$. Sum (12) for j from 1 to $(|U(\mathbf{x})| - 2)$, we have

$$\begin{aligned} g(\mathbf{x}^*) - g(\mathbf{o}_{|U(\mathbf{x})|-2}) &= \sum_{j=1}^{|U(\mathbf{x})|-2} [g(\mathbf{o}_{j-1}) - g(\mathbf{o}_j)] \\ &\leq \sum_{j=1}^{|U(\mathbf{x})|-2} [g(\mathbf{x}_j) - g(\mathbf{x}_{j-1})] \\ &= g(\mathbf{x}). \end{aligned} \tag{14}$$

Using Lemma 1, orthant submodularity and $\rho(y(b), b) \leq 0$, we get

$$\begin{aligned} g(\mathbf{x}^*) &\leq g(\mathbf{o}_{|U(\mathbf{x})|-2}) + g(\mathbf{x}) \\ &\leq g(\mathbf{x}) + \sum_{(b,i) \preceq (\mathbf{o}_{|U(\mathbf{x})|-2} \setminus \mathbf{x})} [g(\mathbf{x} \sqcup (b, i)) - g(\mathbf{x})] + g(\mathbf{x}) \\ &\leq 2g(\mathbf{x}) + \sum_{(b,i) \preceq (\mathbf{o}_{|U(\mathbf{x})|-2} \setminus \mathbf{x})} [g((\mathbf{x} \setminus (y(b), j)) \sqcup (b, i)) - g(\mathbf{x} \setminus (y(b), j))] \tag{15} \\ &\leq 2g(\mathbf{x}) + \sum_{(b,i) \preceq (\mathbf{o}_{|U(\mathbf{x})|-2} \setminus \mathbf{x})} [g(\mathbf{x}) - g(\mathbf{x} \setminus (y(b), j))]. \end{aligned}$$

Let $\{(y(b), j)\}_{b \in U(\mathbf{o}_{|U(\mathbf{x})|-2} \setminus \mathbf{x})} \setminus \{\emptyset\} = \{(y_1, j_1), \dots, (y_K, j_K)\}$, then we have

$$\begin{aligned} g(\mathbf{x}^*) &\leq 2g(\mathbf{x}) + \sum_{l=1}^K [g((y_1, j_1) \sqcup \dots \sqcup (y_l, j_l)) - g((y_1, j_1) \sqcup \dots \sqcup (y_{l-1}, j_{l-1}))] \\ &\leq 2g(\mathbf{x}) + \sum_{l=1}^K g((y_1, j_1) \sqcup \dots \sqcup (y_K, j_K)) \\ &\leq 3g(\mathbf{x}). \end{aligned} \tag{16}$$

Therefore,

$$f(\mathbf{x}^*) \leq 3f(\mathbf{x}) - 2f(\mathbf{x}^0) \leq 3f(\mathbf{x}). \tag{17}$$

We obtain 1/3-approximate ratio in case 1.

Case 2: Consider the opposite of case 1 that there exists at least one swap $(y(b), b)$ satisfying $w_x - w_{y(b)} + w_b > B$.

For the first time, there appears a swap $(y(b_*), b_*)$ in $S(U(\mathbf{x}^{t^*} \setminus \mathbf{x}^0))$ such that $w_{\mathbf{x}^{t^*}} - w_{y(b_*)} + w_{b_*} > B$, where $b_* \in U(\mathbf{x}^*) \setminus U(\mathbf{x}^{t^*})$ and $y(b_*) \in (U(\mathbf{x}^{t^*}) \setminus U(\mathbf{x}^*)) \cup \{\emptyset\}$. For each $t \in \{1, \dots, t^*\}$, we construct two sequences $\{\mathbf{o}_{j-1/2}\}$ and $\{\mathbf{o}_j\}$ between \mathbf{x}^t and \mathbf{x}^* , where $j \in \{1, \dots, |U(\mathbf{x}^t)| - 2\}$. Summing (13) for j from 1 to $|U(\mathbf{x}^t)| - 2$ and using Lemma 1, we have

$$\begin{aligned} g(\mathbf{x}^*) &\leq g(\mathbf{o}_{|U(\mathbf{x}^t)|-2}) + g(\mathbf{x}^t) \\ &\leq g(\mathbf{x}^t) + \sum_{(b,i) \preceq (\mathbf{o}_{|U(\mathbf{x}^t)|-2} \setminus \mathbf{x}^t)} [g(\mathbf{x}^t \sqcup (b, i)) - g(\mathbf{x}^t)] + g(\mathbf{x}^t). \end{aligned} \quad (18)$$

Then applying (18) and the similar technique of (3) and (6), we can get

$$g(\mathbf{x}^*) \leq 3g(\mathbf{x}^t) + (B - w_{\mathbf{x}^0})\rho_{t+1}, \quad (19)$$

for all $t \in \{1, \dots, t^*\}$. The detailed process of proof is shown in the Appendix. Similar to the proof of (10), using (19), we can get

$$\frac{g((\mathbf{x}^{t^*} \setminus (y(b_*), j_{y(b_*)})) \sqcup (b_*, i_{b_*}))}{g(\mathbf{x}^*)} \geq \frac{1}{3}(1 - e^{-3}). \quad (20)$$

We modify inequality (8) as follows. By orthant submodularity, monotonicity and the greedy choice of \mathbf{x}^α , \mathbf{x}^β , we have

$$f((\mathbf{x}^{t^*} \setminus (y(b_*), j_{y(b_*)})) \sqcup (b_*, i_{b_*})) - f(\mathbf{x}^{t^*}) \leq \frac{f(\mathbf{x}^0)}{2}. \quad (21)$$

The detailed process of proof is shown in the Appendix. Combing (20) and (21), we have

$$\begin{aligned} &f(\mathbf{x}^{t^*}) \\ &= f(\mathbf{x}^0) + g((\mathbf{x}^{t^*} \setminus (y(b_*), j_{y(b_*)})) \sqcup (b_*, i_{b_*})) \\ &\quad - [f((\mathbf{x}^{t^*} \setminus (y(b_*), j_{y(b_*)})) \sqcup (b_*, i_{b_*})) - f(\mathbf{x}^{t^*})] \\ &\geq f(\mathbf{x}^0) + \frac{1}{3}(1 - e^{-3})g(\mathbf{x}^*) - \frac{f(\mathbf{x}^0)}{2} \\ &\geq \frac{1}{3}(1 - e^{-3})f(\mathbf{x}^*). \end{aligned} \quad (22)$$

Hence, MK-KM' has an approximation ratio of at least $\frac{1}{3}(1 - e^{-3})$.

5 Discussion

To summarize this paper, inspired by [16] and [18], we propose a nested algorithm applicable to monotone and non-monotone k -submodular maximization with the intersection of a knapsack and a matroid constraint. For problem (1), we have a $\frac{1}{6}(1 - e^{-2})$ -approximate ratio. Inspired by [12], we use a new construction method between optimal solution and current solution. For monotone k -submodular maximization with a knapsack and a matroid constraint, we achieve at least $\frac{1}{3}(1 - e^{-3})$ approximation ratio.

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