Evaluation and Comparison of Simulated Electric Field Differences Using Three Image Segmentation Methods for TMS

Tayeb Zaidi and Kyoko Fujimoto

1 Introduction

Magnetic and electrical brain stimulation therapies are widely used to treat neurodegenerative disorders. One of the commonly used non-invasive techniques is transcranial magnetic stimulation (TMS) that employs magnetic induction to stimulate the brain to improve symptoms for diseases such as depression. Computational modeling has been used to assess the effectiveness and safety of TMS. A detailed brain model is available to allow for these assessments [[5\]](#page-11-0); however, the model is only based on one subject. In order to allow for careful planning of a given treatment regimen, modeling needs to be completed on a per-patient basis.

A patient-specifc brain model can be created using medical imaging data. Magnetic Resonance Imaging (MRI) structural data is often used for such purpose. There are a variety of semi-automatic segmentation methods available [[1,](#page-11-1) [2,](#page-11-2) [4,](#page-11-3) [22](#page-12-0)] that can generate a 3D head model using a set of T_1 - and T_2 -weighted images. Segmentation varies across different methods [[6,](#page-11-4) [18\]](#page-12-1). Therefore, it may affect electric feld distributions in electric-feld modeling. Some of the segmentation methods resulted in differences in electric feld distributions of up to 30% when evaluated with one computational modeling method [[11\]](#page-12-2). More investigations are needed to confrm the degree of differences among different image segmentation and computational modeling methods.

In this study, the T_1 - and T_2 -weighted images of 16 subjects were processed with three different segmentation methods. Computational modeling of TMS was performed based on each segmented data by targeting both the primary motor cortex and the dorsolateral left prefrontal cortex (DLPFC), then the simulated electric feld results were compared and evaluated.

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T. Zaidi \cdot K. Fujimoto (\boxtimes)

Center for Devices and Radiological Health, US Food and Drug Administration, Silver Spring, MD, USA

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2 Materials and Methods

2.1 MRI Data and Segmentation

MRI T_1 - and T_2 -weighted images were used from 16 Human Connectome Project healthy subjects [[19\]](#page-12-3) with an isotropic resolution of 0.7 mm per voxel. Two pipelines implemented in the SimNIBS software package v3.2 [[15\]](#page-12-4) were used for segmentation, *headreco* [[10\]](#page-12-5) and *mri2mesh* [[20\]](#page-12-6), as well as a highresolution FreeSurfer [\[2](#page-11-2)] pipeline (*fshires*) [[21\]](#page-12-7). Both the *headreco* and *mri2mesh* segmentation methods generate surface and volume segmentation of brain and head structures including gray matter (GM), white matter (WM), cerebrospinal fuid (CSF), skull, and skin. The *fshires* pipeline produces GM and WM segmentation based on the native submillimeter resolution.

The surface meshes were generated using the default options from SimNIBs for both *headreco* and *mri2mesh* and the high resolution option within Freesurfer (*fshires*) using the *-hires* fag. The default surface resolution yields surface meshes containing a combined total of roughly 800,000 to 1 million facets.

2.2 Electromagnetic Simulation

A boundary element fast multipole method (BEM-FMM) solver was used for electromagnetic modeling [\[7](#page-11-5)[–9](#page-11-6)]. The solver utilizes the generated surface meshes for feld estimation. A fgure-eight TMS coil was modeled with a diameter of 90 mm for each loop. The coil model was modeled based on a commercial coil (MRiB91 of MagVenture, Denmark). The coil was placed to target both the patient's left primary motor cortex (the hand knob) and the DLPFC via a projection approach and sulcusaligned mapping [[3,](#page-11-7) [12\]](#page-12-8). These regions were chosen because they are common targets for TMS therapy. An example positioning of the coil is shown in Fig. [1.](#page-2-0) Two target points were used for each subject, located within the primary motor cortex and the DLPFC, respectively. The coil position was determined using three steps. First, the coil was placed so that the centerline (shown as the black line in Fig. [1](#page-2-0)) passed through the given target point on the gray matter interface. Second, the coil centerline was made to be perpendicular to the skin surface. Lastly, the coil position was adjusted so that the dominant feld direction was roughly perpendicular to the nearest sulci [\[7](#page-11-5)].

2.3 Analysis

Average surface displacement between mesh surfaces generated based on the *headreco* and *mri2mesh* segmentation methods were compared across the 16 subjects for the gray matter, white matter and CSF surfaces. The displacement was calculated by

Fig. 1 An example placement of the TMS coil targeting the subject's left motor cortex is shown. The black line (the coil axis) was used to confrm the coil placement and runs perpendicular to the coil

TMS Coil with Grav Matter

taking the mean of the shortest distance from every triangle centroid of the relevant surface from one segmentation method to all triangle centroids of the surface from the other segmentation method. The electric feld values were compared by extracting the values in a 100 mm line perpendicular to the TMS coil axis, along the black line shown in Fig. [1.](#page-2-0) Comparisons were performed in pairs between *mri2mesh* and *headreco* and between *mri2mesh* and *fshires*. These values were extracted for both of the target points for each subject. The average electric feld difference, maximum absolute difference, and maximum percentage difference were compared for all 16 subjects. The average feld differences at the target point for both the motor cortex and DLPFC were tested for statistical signifcance using a paired t-test.

Finally, for additional visualization of the electric feld stimulation mapping, all subject electric feld results were mapped onto the infated surface from the FreeSurfer common space (*fsaverage*). The electric feld was exported and mapped onto this common surface to map average electric feld and its difference surface over the 16 subjects. These maps allow for the qualitative evaluation of focality variations between three different segmentation methods over the entire subject space.

3 Results

All extracerebral and cortical surfaces were successfully reconstructed using the three segmentation methods. The average surface displacement was only calculated for regions of the brain located in the superior cerebral cortex for all 16 subjects between *headreco* and *mri2mesh* and the results are summarized in Fig. [2.](#page-3-0) The displacement between *fshires* and *mri2mesh* were not compared as the surfaces use the same algorithm from FreeSurfer and the comparison was done by other study [[21\]](#page-12-7). The CSF surface displacement was three times more than the white matter surface displacement, with an average difference of 0.9 mm $(\pm 0.2 \text{ mm})$ for the CSF and 0.3 mm (± 0.06 mm) for the white matter. An example of all the surfaces overlaid on a subject T_1 -weighted image is shown in Fig. [3.](#page-4-0)

Fig. 2 Average displacement between *headreco* and *mri2mesh* surfaces in millimeters across all 16 subjects for CSF, GM, and WM

For the target point located in the motor cortex, the electric felds showed similar distributions for the *mri2mesh* and the *headreco* segmentation methods. There was an average difference in magnitude of 0.8 V/m and a maximum difference of 61 V/m. The average percentage difference was 2%. In the region of interest within 5 mm of the target point, the average percentage difference was approximately 5%. For the *mri2mesh* and *fshires* segmentation methods, the average percentage difference in the region of interest surrounding the target point was 0.7%. Extracted electric felds (along the dotted line) and the surface contour lines are shown on the subject's T_1 image in Fig. [3.](#page-4-0)

For the target point located in the DLFPC, there was an average difference of 0.8 V/m in magnitude and a maximum difference of 50 V/m between the *mri2mesh* and *headreco* segmentation methods. The average percentage difference was 2.8%.

Fig. 3 (continued) feld results and the thin contours show the *headreco* feld results (*fshires* contours are not shown because they are almost identical to the *mri2mesh* results). Color indications for surfaces are red for skin, orange for skull, yellow for CSF, cyan for gray matter, and purple for white matter. The dotted white line on the axial cross section is a projection onto the XY plane of the 100 mm line running along the axis perpendicular from the coil. The electric feld result along the dotted white line was extracted as shown at the bottom of the fgure. The dotted black line indicates the location of the target point of stimulation. The feld peaks were observed at the anatomical structure transition points (represented by arrows): (1) Skin-Skull, (2) Skull-CSF, (3) CSF-GM, (4) GM-WM

Axial Cross Section

122317 Electric Field Extract (motor)

Fig. 3 Example of electric feld targeted on motor cortex is shown along with an axial cross section of a subject (target stimulation point in magenta). The thick contours show the *mri2mesh* feld

In the region of interest within 5 mm of the target point, the average percentage difference was approximately 1.8%. For the *mri2mesh* and *fshires* segmentation comparison, the average percentage difference in the region of interest surrounding the target point was 0.1%. Extracted electric felds (along the dotted line) and the surface contour lines are shown on the subject's T_1 image in Fig. [4.](#page-6-0)

The electric feld difference across all 16 subjects at the target point between *headreco* and *mri2mesh* was statistically significant ($p = 0.005$) for the motor cortex and not significant between $mri2mesh$ and *fshires* ($p = 0.83$). The electric field difference at the target point for the DLFPC was not signifcant for either the comparison between *mri2mesh* and *headreco* (*p* = 0.19) or between *mri2mesh* and the *fshires* ($p = 0.23$). The average percentage differences in the electric field over the 100 mm line for all subjects and target points are shown in Tables [1](#page-7-0) and [2](#page-8-0).

The average surface mappings for both the frontal and motor cortices are shown in Figs. [5](#page-9-0) and [6.](#page-9-1) The average difference between the *headreco* and *mri2mesh* electric feld results for the motor cortex are shown in Fig. [7](#page-10-0). The electric felds and corresponding differences are mapped onto the *fsaverage* infated surface along with cortical parcellation contours.

4 Discussion and Conclusion

This study focused on an evaluation of the electric feld differences between The surface displacement between *mri2mesh* and *headreco* were seen at the CSF boundary, where the CSF surface was estimated closer to the gray matter for the *headreco* segmentation. Such surface displacement aligns with results shown in previous studies (cf., [\[11](#page-12-2), [13](#page-12-9)]). In particular, Seiger et al. 2018 demonstrated that Freesurfer was more accurate in its calculation of cortical thickness; however, CAT12 based methods (such as *headreco*) were faster and yielded reliable results [[16\]](#page-12-10).

Differences between the *mri2mesh* and *fshires* were subtle as the underlying algorithm within FreeSurfer to segment the T_1 image is same for both methods. The lack of signifcant differences seen in the electric.

feld between the two methods indicates that additional proceces to use a native submillimeter resolution is not necessary for BEM-FMM based computational modeling. Nevertheless, this may not be the case when highly detailed submillimeter surfaces are needed such as a very small structure.

In both the motor cortex and the DLPFC, the low average percent difference in the electric feld suggests that the effect of the segmentation method differences was

Fig. 4 (continued) because they are almost identical to the *mri2mesh* results). Color indications for surfaces are red for skin, orange for skull, yellow for CSF, cyan for gray matter, and purple for white matter. The dotted white line on the axial cross section is a projection onto the XY plane of the 100 mm line running along the axis perpendicular from the coil. The electric feld result along the dotted white line was extracted as shown at the bottom of the fgure. The dotted black line indicates the location of the target point of stimulation. The feld peaks were observed at the anatomical structure transition points (represented by arrows): (1) Skin-Skull, (2) Skull-CSF, (3) CSF-GM, (4) GM-WM

Fig. 4 Example of electric feld targeted on DLPFC cortex is shown along with an axial cross section of a subject (target stimulation point in magenta). The thick contours show the *mri2mesh* feld results and the thin contours show the *headreco* feld results (*fshires* contours are not shown

Axial Cross Section

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DLPFC (target) 0.99 1.00 1.05 0.99 1.03 0.98 0.98 1.00 1.02 1.01 0.99 1.00 0.96 0.97 0.98 0.95

Fig. 5 Mean electric feld values are mapped on the infated surface for the motor cortex stimulation across all 16 subjects for *mri2mesh* (**a**), *fshires* (**b**), and *headreco* (**c**) along with the cortical parcellation contours. All three methods showed high electric feld values in the target (precentral gyrus) along with the postcentral and caudal middle frontal gyri. No notable differences were observed between *fshires* and mri2mesh, and higher electric feld values were observed in all three regions for the *headreco* method

Fig. 6 Mean electric feld values are mapped on the infated surface for the DLPFC stimulation across all 16 subjects for *mri2mesh* (**a**), *fshires* (**b**), and *headreco* (**c**) along with the cortical parcellation contours. All three methods showed high electric feld values in the target (superior frontal gyrus). No notable differences were observed between *fshires* and *mri2mesh*, and slightly lower electric felds were observed in all three regions for the *headreco* method

minimal. Although the overall difference was low $(j 5\%)$, the localized field difference near the target point across all 16 subjects was statistically signifcant for the motor cortex and could affect the intended stimulation there. The feld difference for the DLPFC was not signifcant and the felds were more similar between *headreco* and *mri2mesh* as shown in Fig. [4.](#page-6-0)

Motor Cortex Difference Mapping

Fig. 7 Mean electric feld differences between *mri2mesh* and *headreco* on the infated surface are shown for the motor cortex stimulation. The area where the *headreco* electric feld was lower than the *mri2mesh* electric feld is shown in blue, and the area where the *headreco* electric feld was higher than the *mri2mesh* electric feld is shown in red

The percent difference in the electric feld for the DLPFC was similar to that of the motor cortex along the entire 100 mm line for all 16 subjects. However, the region directly surrounding the target point showed lower variability for the DLPFC target compared to the motor cortex (Fig. [4](#page-6-0)). This trend is consistent in the average percent difference in the 5 mm region surrounding the target point. Therefore, there may be more segmentation variability in the motor cortex.

Analysis of the extracted electric feld in Figs. [3](#page-4-0) and [4](#page-6-0) showed sudden changes in the feld that resulted from the anatomical structure transitions. Some peaks are not aligned at the distance from the coil. For example, the Skull-CSF transitions in both fgures were approximately 23 mm for the *headreco* segmentation whereas it was approximately 22.5 mm from the coil for the simulation with the *mri2mesh* and *fshires* methods. These sudden electric feld changes resulting from segmentation differences can affect TMS therapy because the resulting neuronal excitation is a function of the electric feld gradient rather than the electric feld magnitude. Additional work that directly evaluates the gradient of the electric feld will provide more insight into the effect of the segmentation on the TMS therapy.

The average electric feld mapped on the *fsaverage* surface showed minimal differences between the *fshires* and *mri2mesh* segmentation methods as the differences were within 2 V/m. The electric feld difference mapped on the *fsaverage* surface revealed that there were clusters that exceed 10 V/m of the electric feld differences between *headreco* and *mri2mesh* (Fig. [7\)](#page-10-0). The differences were also largely onesided, with the felds from the *headreco* segmentation consistently higher than those from *mri2mesh*.

Coil positioning was critical to the electric feld estimation. In this study, coil positioning was determined automatically based on the topology of the input meshes used. The pre-processing steps to select the proper coil position may differ signifcantly between segmentation methods.

The resulting feld differences for each coil position were small but measurable. Though average percent differences observed along the 100 mm observation line were less than 5%, signifcant differences in the electric felds between segmentation methods were observed for the motor cortex simulation. Moreover, the feld differences shown by subtle segmentation differences indicate an importance of patientspecifc modeling as various previous studies have shown morphometric differences across age [[14\]](#page-12-11) and sex [\[17](#page-12-12)]. Future studies with different types of TMS coils and different segmentation and computational modeling methods may further improve a modeling approach for robust treatment for TMS and other neuromodulation devices.

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