Chapter 1 Weil Algebra, 3-Lie Algebra and B.R.S. Algebra

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Abstract We consider a method that allows to construct the 3-Lie algebra if we have a Lie algebra equipped with an analogue of the notion of trace. At the same time, it is well known that, based on a Lie algebra, we can construct the Weil algebra, which is a universal model for connection and curvature. In this paper, we propose an answer to the question of how one could extend the construction of the Weil algebra from a Lie algebra to the induced 3-Lie algebra. To this end, in addition to universal connection and curvature, we introduce new elements and extend the action of the differential of Weil algebra to these new elements with the help of structure constants of 3-Lie algebra. Since one of the most important applications of Weil algebra in a field theory is the construction of B.R.S. algebra, we propose an analogue of B.R.S. algebra constructed by means of a 3-Lie algebra.

Keywords *ⁿ*-Lie algebra · 3-Lie algebra · Weil algebra · Connection · Curvature · Equivariant differential forms

MSC 2010 Classification Primary 17B60 · Secondary 17B56

1.1 Introduction

n-Lie algebra, where $n \geq 2$, is a generalization of the notion of Lie algebra, which is the particular case of *n*-Lie algebra, when $n = 2$. Here, an integer *n* is the number of elements of algebra, which is required to compose a product. Thus, a multiplication law of *n*-Lie algebra g is an *n*-ary multilinear mapping $g \times g \times ... \times g$ (*n* times) $\rightarrow g$, which is totally skew-symmetric and satisfies the Filippov–Jacobi identity, which is also called fundamental identity in applications of *n*-Lie algebras in Nambu's generalization of Hamiltonian mechanics and field theories.

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The notion of *n*-Lie algebra was introduced and studied by Filippov in [\[6](#page-11-0)]. Nambu in [\[9](#page-11-1)] proposed a generalization of Hamiltonian mechanics based on a triple (or, more generally, *n*-ary) bracket of functions determined on a phase space. This *n*-ary bracket can be considered as an analog of the Poisson bracket in Hamiltonian mechanics and later this *n*-ary bracket was called the Nambu–Poisson bracket. It should be noted that Nambu–Poisson bracket is totally skew-symmetric, has the derivation property with respect to point-wise product of two functions and it also satisfies the Filippov–Jacobi identity. Hence, the Nambu–Poisson bracket determines the structure of *n*-Lie algebra on the algebra of functions on a phase space. The dynamics of this generalization of Hamiltonian mechanics is described by the Nambu-Hamilton equation of motion that contains $n - 1$ Hamiltonians. It should be pointed out that Y. Nambu proposed and developed his generalization of Hamiltonian mechanics with the goal to apply this approach to quarks model, where baryons are combinations of three quarks. This direction of research has received further development in the paper [\[10\]](#page-11-2), where the author introduced a notion of Nambu–Poisson manifold, which can be considered as an analog of the notion of Poisson manifold in Hamiltonian mechanics.

The problem of quantization of Nambu–Poisson bracket was studied in a number of papers and the first step in this direction was taken already by Nambu, but so far this is the outstanding problem. In the paper [\[4](#page-11-3)] the authors propose the realization of quantum Nambu bracket, which is defined as follows

$$
[X, Y, Z] = (\text{Tr } X) [Y, Z] + (\text{Tr } Y) [Z, X] + (\text{Tr } Z) [X, Y], \tag{1.1}
$$

where *X*, *Y*, *Z* are either square matrices or cubic matrices and $[X, Y] = XY - YX$ is the commutator of two matrices. In $[4]$ it is proved that this quantum ternary Nambu bracket satisfies the Filippov–Jacobi identity. Hence, a matrix Lie algebra endowed with the quantum ternary Nambu bracket (1.1) becomes the 3-Lie algebra, which will be referred to as the 3-Lie algebra induced by a matrix Lie algebra with the help of the trace. The quantum ternary Nambu bracket can be generalized by means of vector fields and differential forms on a smooth manifold [\[1\]](#page-11-4) and by means of a cochain of the Eilenberg–Cartan complex of a Lie algebra [\[2](#page-11-5)].

Given a Lie algebra g one can associate to it the Weil algebra *^W*(g). The Weil algebra of a Lie algebra is the tensor product of exterior algebra of dual space g[∗] and the symmetric algebra of the dual space g[∗]. The Weil algebra is closely related to equivariant differential forms on a principal fiber bundle and it can be regarded as an universal algebraic model for connections and their curvatures on a principal fiber bundle [\[8\]](#page-11-6). It is also worth to mention that the Weil algebra is closely related to B.R.S. algebra [\[5\]](#page-11-7).

The aim of this paper is to show how we can extend the construction of the Weil algebra $W(g)$ from a Lie algebra g to the 3-Lie algebra induced by g with the help of an analog of trace. The quantum ternary Nambu bracket of induced 3-Lie algebra is defined by

$$
[x, y, z] = \omega(x) [y, z] + \omega(y) [z, x] + \omega(z) [x, y],
$$

where $\omega \in \mathfrak{g}^*$ and $\omega([x, y]) = 0$. In order to do this we introduce in addition to two elements of degree 1 and 2 of the Weil algebra new elements constructed by means of element ω of the dual space \mathfrak{g}^* . We extend the differential of the Weil algebra to these new elements and show that the property $d^2 = 0$ of the differential holds for these new elements.

1.2 3-Lie Algebra Induced by a Lie Algebra

An *n-Lie algebra*, where integer *n* is greater or equal to 2, is a vector space equipped with an *n*-ary Lie bracket

$$
(x_1, x_2, \ldots, x_n) \in \mathfrak{g} \times \mathfrak{g} \times \ldots \times \mathfrak{g} \ (n \ \text{times}) \rightarrow [x_1, x_2, \ldots, x_n] \in \mathfrak{g},
$$

which is totally skew-symmetric (it changes a sign in the case of odd permutation of variables and it does not change under an even permutation of variables) and satisfies the Filippov–Jacobi identity

$$
[x_1, x_2, \dots, x_{n-1}, [y_1, y_2, \dots, y_n]] = \sum_{k=1}^n [y_1, y_2, \dots, y_{k-1}, [x_1, x_2, \dots, x_{n-1}, y_k], y_{k+1}, \dots, y_n].
$$
\n(1.2)

A notion of *n*-Lie algebra was independently introduced and studied by Filippov [\[6\]](#page-11-0) and Nambu [\[9](#page-11-1)]. In particular case $n = 3$ it follows from the definition of *n*-Lie algebra that a *3-Lie algebra* is a vector space g endowed with a *ternary Lie bracket* [, ,] : $\mathfrak{g} \times \mathfrak{g} \times \mathfrak{g} \to \mathfrak{g}$, which has the symmetries

$$
[a, b, c] = [b, c, a] = [c, a, b], \quad [a, b, c] = -[b, a, c] = -[a, c, b] = -[c, b, a],
$$
\n
$$
(1.3)
$$

and satisfies the *ternary Filippov–Jacobi identity*

$$
[a, b, [c, d, e]] = [[a, b, c], d, e] + [c, [a, b, d], e] + [c, d, [a, b, e]]. \tag{1.4}
$$

A *metric 3-Lie algebra* is a 3-Lie algebra equipped with a positive definite nondegenerate bilinear form \langle , \rangle , which satisfies

$$
\langle [a, b, c], d \rangle + \langle c, [a, b, d] \rangle = 0.
$$

The well known example of simple *n*-Lie algebra can be constructed by means of analog of cross product of vectors in $(n + 1)$ -dimensional vector space. It was proved in [\[7](#page-11-8)] that this *n*-Lie algebra is the only simple finite-dimensional metric *n*-Lie algebra.

Given the matrix Lie algebra $\mathfrak{gl}(n)$ of *n*th order matrices one can introduce the ternary Lie bracket of *n*th order matrices as follows

$$
[A, B, C] = (\text{Tr } A) [B, C] + (\text{Tr } B) [C, A] + (\text{Tr } C) [A, B]. \tag{1.5}
$$

Evidently this ternary Lie bracket obeys the symmetries (1.3) . It is proved in [\[4\]](#page-11-3) that this ternary Lie bracket satisfies the ternary Filippov–Jacobi identity and the authors propose to call this ternary Lie bracket *quantum Nambu bracket*. Hence the vector space of *n*th order matrices equipped with the quantum Nambu bracket [\(1.5\)](#page-3-0) becomes the matrix 3-Lie algebra. The matrix 3-Lie algebra of *n*th order matrices with the quantum Nambu bracket (1.5) is the metric 3-Lie algebra if we endow it with the bilinear form

$$
\langle A, B \rangle = \text{Tr}\,(AB).
$$

Now our aim is to extend this approach to a case more general than the trace of a matrix. Let g be a finite-dimensional Lie algebra and g[∗] be its dual space. Fix an element of the dual space $\omega \in \mathfrak{g}^*$ and, by analogy with [\(1.5\)](#page-3-0), define the triple product as follows

$$
[x, y, z] = \omega(x) [y, z] + \omega(y) [z, x] + \omega(z) [x, y], \quad x, y, z \in \mathfrak{g}.
$$
 (1.6)

Obviously, this triple product is symmetric with respect to cyclic permutations of *x*, *y*,*z* and skew-symmetric with respect to non-cyclic permutations, i.e. it obeys the symmetries [\(1.3\)](#page-2-0). Straightforward computation of the left hand side and the right hand side of the ternary Filippov–Jacobi identity

$$
[x, y, [u, v, t]] = [[x, y, u], v, t] + [u, [x, y, v], t] + [u, v, [x, y, t]], \quad (1.7)
$$

shows that one can split all the terms into three groups, where two of them vanish because of binary Jacobi identity and skew-symmetry of binary Lie bracket. The third group can be split into subgroups of terms, where each subgroup has the same structure and it is determined by one of the commutators $[x, y]$, $[u, v]$, $[u, t]$, $[v, t]$. For instance, if we collect all the terms containing the commutator $[x, y]$ then we get the expression

$$
(\omega(u)\,\omega([v,t]) + \omega(v)\,\omega([t,u]) + \omega(t)\,\omega([u,v]))\,[x,y].\tag{1.8}
$$

Hence the triple product (1.6) will satisfy the ternary Filippov–Jacobi identity if for any elements $u, v, t \in \mathfrak{g}$ we require

$$
\omega(u)\,\omega([v,t]) + \omega(v)\,\omega([t,u]) + \omega(t)\,\omega([u,v]) = 0.
$$

Now we consider ω as a $\mathbb C$ -valued cochain of degree one of the Chevalley–Eilenberg complex of a Lie algebra g. Making use of the coboundary operator $\delta : \wedge^k \mathfrak{g}^* \to$ $∧^{k+1}$ g[∗], we obtain the degree two cochain δω, where δω(*x*, *y*) = ω([*x*, *y*]). Finally

we can form the wedge product of two cochains $\omega \wedge \delta \omega$, which is the cochain of degree three, and

$$
\omega \wedge \delta \omega(u, v, t) = \omega(u) \omega([v, t]) + \omega(v) \omega([t, u]) + \omega(t) \omega([u, v]).
$$

Hence the third group of terms [\(1.8\)](#page-3-2) of the Filippov–Jacobi identity vanishes if $\omega \in \mathfrak{g}^*$ satisfies

$$
\omega \wedge \delta \omega = 0. \tag{1.9}
$$

Thus, if a 1-cochain ω satisfies the Eq. [\(1.9\)](#page-4-0), then the ternary bracket [\(1.6\)](#page-3-1) is the ternary Lie bracket and, by analogy with [\(1.5\)](#page-3-0), we will call this ternary Lie bracket *the quantum Nambu bracket induced by a 1-cochain*.

We can generalize the quantum Nambu bracket (1.6) constructed by means of a 1-cochain ω if we consider a C-valued cochain of degree $n - 2$, i.e. $\omega \in \wedge^{(n-2)} \mathfrak{g}^*$, and define the *n*-ary bracket as follows and define the *n*-ary bracket as follows

$$
[x_1, x_2, \dots, x_n] = \sum_{i < j} (-1)^{i+j+1} \omega(x_1, x_2, \dots, \hat{x}_i, \dots, \hat{x}_j, \dots, x_n) \ [x_i, x_j]. \tag{1.10}
$$

Theorem 1.2.1 *Let* g *be a finite-dimensional Lie algebra,* g^* *be its dual and* ω *be a cochain of degree n* − 2*, i.e.* $\omega \in \wedge^{n-2}$ g^{*}. The vector space of Lie algebra g *equipped with the n-ary bracket* [\(1.10\)](#page-4-1) *is the n-Lie algebra, i.e. the n-ary bracket* [\(1.10\)](#page-4-1) *satisfies the Filippov–Jacobi identity* [\(1.2\)](#page-2-1)*, if and only if a* (*n* − 2)*-cochain* ω *satisfies the equation*

$$
\omega \wedge \delta \omega = 0. \tag{1.11}
$$

Particularly the vector space of a Lie algebra g *endowed with the n-ary Lie bracket* [\(1.10\)](#page-4-1) *is the n-Lie algebra if* ω *is an* (*n* − 2)*-cocycle, i.e.* $\delta \omega = 0$ *.*

Particularly from this theorem it immediately follows that the quantum Nambu bracket for matrices [\(1.5\)](#page-3-0) satisfies the ternary Filippov–Jacobi identity. Indeed in this case $\omega = \text{Tr}$ and this is 1-cocycle because for any two matrices A, B we have

$$
(\delta \operatorname{Tr})(A, B) = \operatorname{Tr}([A, B]) = 0.
$$

In [\[3\]](#page-11-9) it is proposed to call the 3-Lie algebra constructed by means of an analog of trace the 3-Lie algebra induced by a Lie algebra. In our approach we will use the similar terminology and call the *n*-Lie algebra constructed by means of a $(n - 2)$ cochain ^ω [\(1.10\)](#page-4-1) the *n-Lie algebra induced by a Lie algebra* g *and an (n-2)-cochain* ω. The *n*-ary Lie bracket will be referred to as the *n-ary quantum Nambu bracket induced by a (n-2)-cochain*.

1.3 Weil Algebra of Induced 3-Lie Algebra

Given a finite-dimensional Lie algebra, one can construct the Weil algebra, which can be considered as a universal algebraic model for connection and curvature. In this section we propose a construction, which allows to construct an analog of Weil algebra of 3-Lie algebra in the case, when 3-Lie algebra is induced by a Lie algebra. This analog of Weil algebra of 3-Lie algebra can be considered as an extension of Weil algebra of Lie algebra to 3-Lie algebra.

Let g be a finite-dimensional Lie algebra and \mathfrak{g}^* be its dual. Let us denote by $\wedge(\mathfrak{g}^*)$ the exterior algebra of g^* and by $S(g^*)$ the symmetric algebra of g^* . We remind that the *Weil algebra* of a Lie algebra g [\[8\]](#page-11-6) is the tensor product $S(\mathfrak{g}^*) \otimes \wedge (\mathfrak{g}^*)$, which will be denoted by $W(\mathfrak{g})$.

Let dim $g = n$ and T_a be a basis for g, where a runs from 1 to *n*. Then

$$
[T_b, T_c] = f_{bc}^a T_a,
$$

where f_{bc}^a are the structure constants of a Lie algebra g. The structure constants of a Lie algebra satisfies the Jacobi identity Lie algebra satisfies the Jacobi identity

$$
f_{bc}^d \t f_{ad}^k + f_{ca}^d \t f_{bd}^k + f_{ab}^d \t f_{cd}^k = 0.
$$
 (1.12)

Let T^a be the dual basis for \mathfrak{g}^* , i.e. $T^a(T_b) = \delta^a_\beta$. We denote the image of T^a in the exterior algebra $\Delta(\mathfrak{g}^*)$ by A^a and the image of T^a in the symmetric algebra $S(\mathfrak{g}^*)$ exterior algebra \wedge (\mathfrak{g}^*) by A^a and the image of T^a in the symmetric algebra $S(\mathfrak{g}^*)$ by F^a . Hence A^a are the generators of the exterior algebra \wedge (\mathfrak{g}^*) and we will assign degree 1 to each of these generators. Analogously F^a are the generators of symmetric algebra $S(\mathfrak{g}^*)$ and we will assign degree 2 to each of these generators. The degree of a generator A^a will be denoted by $|A^a|$ and the degree of F^a will be denoted by $|F^a|$. Then

$$
A^{a} A^{b} = (-1)^{|A^{a}||A^{b}|} A^{b} A^{a},
$$

\n
$$
A^{a} F^{b} = (-1)^{|A^{a}||F^{b}|} F^{b} A^{a},
$$

\n
$$
F^{a} F^{b} = (-1)^{|F^{a}||F^{b}|} F^{b} F^{a}.
$$

Now the Weil algebra $W(\mathfrak{g})$ is the graded algebra $W(\mathfrak{g}) = \bigoplus_i W^i(\mathfrak{g})$. The differential $d \cdot W^i(\mathfrak{g}) \to W^{i+1}(\mathfrak{g})$ is defined by $d: W^i(\mathfrak{g}) \to W^{i+1}(\mathfrak{g})$ is defined by

$$
dA^{a} = F^{a} - \frac{1}{2} f_{bc}^{a} A^{b} A^{c}, \quad dF^{a} = f_{bc}^{a} F^{b} A^{c}.
$$
 (1.13)

The differential *d* has the properties:

1. *d* satisfies the graded Leibniz rule which means that when we differentiate the product of two elements of the Weil algebra and interchange the differential *d* with the first factor of this product then there appears the coefficient (−1)*^k* in the second term of Leibniz formula, where *k* is the degree of the first factor,

1 Weil Algebra, 3-Lie Algebra and B.R.S. Algebra 7

2. $d^2 = 0$.

It is worth to mention that the Weil algebra is very closely related to the formalism of equivariant differential forms on a principle fiber bundle. Bearing this relation to equivariant forms in mind we can interpret the degree 1 generators *A^a* of exterior algebra [∧](g[∗]) as components of a Lie algebra valued connection 1-form on a principal fiber bundle, the degree 2 generators of the symmetric algebra $S(\mathfrak{g}^*)$ as components of a Lie algebra valued curvature 2-form of connection *A^a* and *d* as the exterior differential for differential forms.

Now our aim is to extend the Weil algebra of a Lie algebra g to the 3-Lie algebra \mathfrak{g}_t induced by a Lie algebra g with the help of an analog of trace. Let $\omega \in \mathfrak{g}^*$ be an element of the dual space, which for any two elements $x, y \in \mathfrak{g}$ satisfies $\omega([x, y]) = 0$. Making use of the dual basis for \mathfrak{g}^* we can write $\omega = \omega_a T^a$, where the coefficients ω_a are numbers. Then the condition $\omega([x, y]) = 0$ is equivalent to the relations

$$
f_{bc}^a \omega_a = 0. \tag{1.14}
$$

The ternary quantum Nambu bracket of the induced 3-Lie algebra g_t , constructed with the help of 1-cochain, is defined by

$$
[x, y, z] = \omega(x) [y, z] + \omega(y) [z, x] + \omega(z) [x, y].
$$
 (1.15)

It is shown in the previous section that the ternary quantum Nambu bracket [\(1.15\)](#page-6-0) satisfies the Filippov–Jacobi identity. Let us denote the structure constants of the induced 3-Lie algebra \mathfrak{g}_t in a basis T_a by K^a_{bcd} , that is

$$
[T_b, T_c, T_d] = K_{bcd}^a T_a.
$$

Since the 3-Lie algebra g_t is induced by a Lie algebra g the structure constants of the 3-Lie algebra \mathfrak{g}_f can be expressed in terms of the structure constants of a Lie algebra g as follows

$$
K_{abc}^d = \omega_a f_{bc}^d + \omega_b f_{ca}^d + \omega_c f_{ab}^d.
$$

It can be proved that the Filippov–Jacobi identity

$$
K_{bcd}^{a} K_{kma}^{l} = K_{kmb}^{a} K_{acd}^{l} + K_{kmc}^{a} K_{bad}^{l} + K_{kmd}^{a} K_{bca}^{l},
$$

holds in this particular case of induced 3-Lie algebra [\[1\]](#page-11-4). Now we introduce two elements of the Weil algebra $W(\mathfrak{q})$ as follows

$$
\chi = \omega_a A^a, \ \varphi = \omega_a F^a.
$$

Evidently the element χ has the degree 1 and the element φ has the degree 2. If we apply the differential (1.13) to the element χ then we get

$$
d\chi = \omega_a d(A^a) = \omega_a (F^a - \frac{1}{2} f_{bc}^a A^b A^c)
$$

= $\omega_a F^a - \frac{1}{2} \omega_a f_{bc}^a A^b A^c = \omega_a F^a = \varphi,$ (1.16)

where we used the relation [\(1.14\)](#page-6-1). Similarly we find that the differential of φ is

$$
d\varphi = \omega_a dF^a = \omega_a f_{bc}^a F^b A^c = 0,
$$

where we again used the relation [\(1.14\)](#page-6-1). Hence the element φ is closed with respect to the differential *d* and we can write

$$
d\chi = \varphi, \, d\varphi = 0. \tag{1.17}
$$

Let us introduce the following products of elements A^a , F^a and χ , φ

$$
\chi^a = \chi A^a, \ \varphi^a = \varphi A^a, \psi^a = \chi F^a, \ \Omega^a = \varphi F^a.
$$

These products have the following degrees $|\chi^a| = 2$, $|\varphi^a| = |\psi^a| = 3$, $|\Omega^a| = 4$. Straightforward computation of the differential of these products gives

$$
d\chi^{a} = \varphi^{a} - \psi^{a} + \frac{1}{3!} K_{bcd}^{a} A^{b} A^{c} A^{d},
$$

\n
$$
d\varphi^{a} = \Omega^{a} - \frac{1}{2} f_{bc}^{a} \varphi^{a} A^{c},
$$

\n
$$
d\psi^{a} = \Omega^{a} - f_{bc}^{a} \psi^{a} A^{c},
$$

\n
$$
d\Omega^{a} = f_{bc}^{a} \Omega^{b} A^{c}.
$$

In order to show more clearly the relation with the structure of the induced 3-Lie algebra g_t , we will do the transformation in the space of elements of degree 3 by introducing new elements \mathcal{Z}_{ω}^a , Φ_{ω}^a as follows

$$
\mathcal{E}^a = \varphi^a + \psi^a, \quad \Phi^a = \varphi^a - \psi^a. \tag{1.18}
$$

Then

$$
d\Phi^{a} = \frac{1}{2} f_{bc}^{a} A^{b} \Phi^{c} - \frac{3}{2} K_{bcd}^{a} F^{b} A^{c} A^{d},
$$

\n
$$
d\Xi^{a} = 2 \Omega^{a} - \frac{1}{2} f_{bc}^{a} A^{b} \Xi^{c} - \frac{1}{2} f_{bc}^{a} A^{b} \Phi^{c} + \frac{1}{2} K_{bcd}^{a} F^{b} A^{c} A^{d},
$$

\n
$$
d\Omega^{a} = K_{bcd}^{a} F^{b} F^{c} F^{d}.
$$

Thus, in order to construct the extension of Weil algebra $W(\mathfrak{g}) = S(\mathfrak{g}_F^*) \otimes \wedge (\mathfrak{g}_A^*)$
of a Lie algebra of a to the Weil algebra $W(\mathfrak{g})$ of the induced 3-Lie algebra \mathfrak{g}_c , we of a Lie algebra of g to the Weil algebra $W(\mathfrak{g}_t)$ of the induced 3-Lie algebra \mathfrak{g}_t , we introduce in addition to elements A^a , F^a the element χ of degree 2, two elements Φ^a , Ξ^a of degree 3 and the element Ω^a of degree 4, i.e. we take

$$
W(\mathfrak{g}_{\mathfrak{t}})=S(\mathfrak{g}_F^*)\otimes S(\mathfrak{g}_\chi^*)\otimes S(\mathfrak{g}_\Omega^*\otimes \wedge (\mathfrak{g}_A^*)\otimes \wedge (\mathfrak{g}_\mathfrak{S}^*\otimes \wedge (\mathfrak{g}_\Phi^*),
$$

and define the differential by

$$
dA^{a} = F^{a} - \frac{1}{2} f_{bc}^{a} A^{b} A^{c}, \qquad (1.19)
$$

$$
dF^a = f^a_{bc} F^b A^c,\tag{1.20}
$$

$$
d\chi^{a} = \Phi^{a} + \frac{1}{3!} K_{bcd}^{a} A^{b} A^{c} A^{d},
$$
\n(1.21)

$$
d\Phi^{a} = \frac{1}{2} f_{bc}^{a} A^{b} \Phi^{c} - \frac{3}{2} K_{bcd}^{a} F^{b} A^{c} A^{d}, \qquad (1.22)
$$

$$
dE^{a} = 2\Omega^{a} - \frac{1}{2}f_{bc}^{a} A^{b} E - \frac{1}{2}f_{bc}^{a} A^{b} \Phi^{c} + \frac{1}{2}K_{bcd}^{a} F^{b} A^{c} A^{d}, \quad (1.23)
$$

$$
d\Omega^a = K^a_{bcd} F^b F^c F^d. \tag{1.24}
$$

It can be proved that the differential *d* defined by the above formulae satisfies $d^2 = 0$. Hence the formulae [\(1.21\)](#page-8-0)–[\(1.24\)](#page-8-0) can be regarded as the extension of differential *d* defined on the Weil algebra $W(g)$ to differential on the Weil algebra $W(g_t)$ of the induced 3-Lie algebra.

The formulae can be written by means of brackets (binary and ternary) if we consider the tensor product $\mathfrak{g} \otimes W(\mathfrak{g}_t)$. Given three elements of this product $X_1 \otimes$ $\Lambda_1, X_2 \otimes \Lambda_2, X_3 \otimes \Lambda_3$, where $X_1, X_2, X_3 \in \mathfrak{g}$ and $\Lambda_1, \Lambda_2, \Lambda_3 \in W(\mathfrak{g}_t)$ we can compose two products as follows

$$
[X_1 \otimes A_1, X_2 \otimes A_2] = [X_1, X_2] \otimes A_1 \cdot A_2, [X_1 \otimes A_1, X_2 \otimes A_2, X_3 \otimes A_3] = [X_1, X_2, X_3] \otimes A_1 \cdot A_2 \cdot A_3.
$$

Let us denote

$$
A = T_a \otimes A^a, \ F = T_a \otimes F^a, \ \chi = T_a \otimes \chi^a,
$$

$$
\Phi = T_a \otimes \Phi^a, \ \Xi = T_a \otimes \Xi^a, \ \Theta = T_a \otimes \Theta^a.
$$

Then the formulae (1.19) – (1.24) can be written in the form

$$
dA = F - \frac{1}{2} [A, A],
$$

\n
$$
dF = [F, A],
$$

\n
$$
d\chi = \Phi + \frac{1}{3!} [A, A, A],
$$

\n
$$
d\Phi = \frac{1}{2} [A, \Phi] - \frac{3}{2} [F, A, A],
$$

$$
d\mathcal{E} = 2 \Omega - \frac{1}{2} [A, \mathcal{E}] - \frac{1}{2} [A, \Phi] + \frac{1}{2} [F, A, A],
$$

$$
d\Omega = [F, F, F].
$$

1.4 B.R.S. Algebra and 3-Lie Algebra

Our aim in this section is to show how one can use the 3-Lie algebra \mathfrak{g}_t to construct the universal B.R.S. algebra [\[5](#page-11-7)]. The advantage of approach based on the 3-Lie algebra q_t is that ghost field, auxiliary field and their transformations naturally arise from the structure of 3-Lie algebra.

First we remind the notion of universal B.R.S. algebra associated to a Lie algebra g. Let T_a be a basis for g and T^a be the dual basis for g^* . Take four copies of the dual space $\mathfrak{g}^*_{A}, \mathfrak{g}^*_{F}, \mathfrak{g}^*_{X}, \mathfrak{g}^*_{\phi}$ with dual basis A^a, F^a, χ^a, ϕ^a respectively. Let $\mathcal{A}(\mathfrak{g})$ be the free bigraded commutative algebra generated by A^a in the bidegree (1, 0) χ^a the free bigraded commutative algebra generated by A^a in the bidegree (1, 0), χ^a in the bidegree $(0, 1)$, F^a in the bidegree $(2, 0)$, ϕ^a in the bidegree $(1, 1)$, i.e.

$$
\mathscr{A}(\mathfrak{g}) = \wedge (\mathfrak{g}^*_{A}) \otimes S(\mathfrak{g}^*_{F}) \otimes \wedge (\mathfrak{g}^*_{\chi}) \otimes S(\mathfrak{g}^*_{\phi}).
$$

In analogy with the previous section we introduce the tensor product $\mathfrak{g} \otimes \mathcal{A}(\mathfrak{g})$ and the products of elements $A = T_a \otimes A^a$, $F = T_a \otimes F^a$, $\chi = T_a \otimes \chi^a$, $\phi = T_a \otimes \phi^a$. Define two differentials d , δ , of bidegrees (1, 0) and (0, 1) respectively as follows

$$
dA = F - \frac{1}{2} [A, A], \ dF = [F, A], \ d\chi = \phi, \ d\phi = 0,
$$

and

$$
\delta A = -\phi - [A, \chi], \ \delta F = [F, \chi], \ \delta \chi = -\frac{1}{2} [\chi, \chi], \ \delta \phi = [\phi, \chi].
$$

These differentials satisfy the equations

$$
d^2 = \delta^2 = (d + \delta)^2 = 0.
$$

The algebra $\mathscr{A}(\mathfrak{g})$ is referred to as the universal B.R.S. algebra of a Lie algebra g.

Now our aim is to use the structure of the 3-Lie algebra \mathfrak{g}_t to construct the universal B.R.S. algebra. For this purpose we consider an analog of gauge transformation [\[4\]](#page-11-3) constructed by means of ternary quantum Nambu bracket

$$
[X, Y, Z] = (\text{Tr } X) [Y, Z] + (\text{Tr } Y) [Z, X] + (\text{Tr } Z) [X, Y]. \tag{1.25}
$$

Indeed, one can consider the following analog of gauge transformation

$$
D A = i [X, Y, A].
$$

This analog of gauge transformation suggests to introduce two elements ξ , η of the bidegrees $(0, 1)$, $(0, 0)$ respectively and define the differential δ of A as follows

$$
\delta A = -[A, \xi, \eta]. \tag{1.26}
$$

Applying the formula for the ternary quantum Nambu bracket we find

$$
\delta A = -[\text{Tr}(\xi)\,\eta - \text{Tr}(\eta)\,\xi, A] - \text{Tr}(A)\,[\xi, \eta].\tag{1.27}
$$

Now it is natural to define the ghost field χ and the auxiliary field ϕ by

$$
\chi = \text{Tr}(\xi) \, \eta - \text{Tr}(\eta) \, \xi, A, \, \phi = \text{Tr}(A) \, [\xi, \eta] \tag{1.28}
$$

Substituting these definitions into [\(1.27\)](#page-10-0) we obtain the differential for *A*, i.e.

$$
\delta A = -\phi - [A, \chi].
$$

Now we define the differential δ for the elements ξ , η by

$$
\delta \xi = -\frac{1}{2} \operatorname{Tr}(\eta) [\xi, \xi] + \operatorname{Tr}(\xi) [\eta, \xi], \tag{1.29}
$$

$$
\delta \eta = -\text{Tr}(\eta) [\eta, \xi]. \tag{1.30}
$$

Differentiating by δ the both sides of [\(1.28\)](#page-10-1) and making use of [\(1.29\)](#page-10-2), [\(1.30\)](#page-10-2) we get the formulae for the differential δ of χ and ϕ , i.e.

$$
\delta \chi = -\frac{1}{2} [\chi, \chi], \ \delta \phi = [\phi, \chi].
$$

We conclude this section by pointing out that proposed here approach clearly demonstrates that the formulae for the differential δ (or BRS-operator) are consequences of two-parameter gauge transformation [\(1.26\)](#page-10-3) constructed with the help of ternary quantum Nambu bracket [\(1.25\)](#page-9-0).

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