

Computing Digraph Width Measures on Directed Co-graphs (Extended Abstract)

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Abstract. In this paper we consider the digraph width measures directed feedback vertex set number, cycle rank, DAG-depth, DAG-width and Kelly-width. While the minimization problem for these width measures is generally NP-hard, we prove that it is computable in linear time for all these parameters, except for Kelly-width, when restricted to directed co-graphs. As an important combinatorial tool, we show how these measures can be computed for the disjoint union, series composition, and order composition of two directed graphs, which further leads to some similarities and a good comparison between the width measures. This generalizes and expands our former results for computing directed path-width and directed tree-width of directed co-graphs.

Keywords: DFVS-number \cdot Cycle rank \cdot DAG-depth \cdot DAG-width \cdot Kelly-width \cdot Directed co-graphs

1 Introduction

Undirected width parameters are well-known and frequently used in computations. Many NP-hard graph problems admit polynomial-time solutions when restricted to graphs of bounded width, like for example bounded tree-width or bounded path-width. Computing both parameters is hard even for bipartite graphs and complements of bipartite graphs [2], while for co-graphs it has been shown [7] that the path-width equals the tree-width and how to compute this value in linear time.

During the last years, width parameters for directed graphs have received a lot of attention [18]. Among these are directed tree-width and directed pathwidth. In our paper [21] we proved that for directed co-graphs both parameters are equal and computable in linear time. But directed tree-width and directed path-width are not the only attempts to generalize undirected tree-width and path-width for directed graphs. Furthermore, there are the parameters directed

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feedback vertex set number, cycle rank, DAG-depth, DAG-width and Kellywidth, which have also been considered in [17]. In this paper, we extend our results from [21] and give linear time solutions to compute these width parameters for the disjoint union, series composition and, except for Kelly-width, as well for the order composition of two directed graphs. This leads to a constructive linear-time-algorithm to get the width and the according decompositions of directed co-graphs. For most of the parameters, we could even expand this algorithm to extended directed co-graphs, which are an extension of the directed co-graphs defined in [12] by an additional operation considered in [24].

Our algorithms lead to some tightened bounds for directed path-width, directed tree-width, directed feedback vertex set number, cycle rank, DAGdepth, DAG-width and Kelly-width of extended directed co-graphs and for some of the parameters, they even lead to equalities.

2 Preliminaries

We use the notations of Bang-Jensen and Gutin [3] for graphs and digraphs. When talking about digraphs, we always mean directed graphs with neither multi-edges nor loops. A digraph is a tournament if for all vertices $u \neq v$, there is exactly one of the edges (u, v) and (v, u). It is completely bidirectional if both of these edges are in the edge set.

Orientations. An orientation of an undirected graph G is a digraph, where all edges $\{u, v\}$ of G are replaced by either (u, v) or (v, u). For a biorientation, every edge $\{u, v\}$ is replaced by either (u, v) or (v, u) or both. For a complete biorientation, every edge $\{u, v\}$ is replaced by (u, v) and (v, u). The complete biorientation of an undirected graph G is denoted by G.

Special Directed Graphs. We recall some special directed graphs. Let

$$\overleftarrow{K_n} = (\{v_1, \dots, v_n\}, \{(v_i, v_j) \mid 1 \le i \ne j \le n\})$$

be a bidirectional complete digraph on n vertices. For $n \ge 2$ we denote by

$$\overrightarrow{P_n} = (\{v_1, \dots, v_n\}, \{(v_1, v_2), \dots, (v_{n-1}, v_n)\})$$

a directed path on n vertices and for $n \ge 2$ we denote by

$$\overrightarrow{C_n} = (\{v_1, \dots, v_n\}, \{(v_1, v_2), \dots, (v_{n-1}, v_n), (v_n, v_1)\})$$

a directed cycle on n vertices. A directed acyclic digraph (DAG for short) is a digraph without any $\overrightarrow{C_n}$, $n \ge 2$ as subdigraph. By $\overrightarrow{T_n}$ we denote the transitive tournament on n vertices.

2.1 Recursively Defined Digraphs

Co-graphs have been introduced in the 1970s by a number of authors under different notations. We recall the definition of directed co-graphs from [12]. The following operations have already been considered by Bechet in [4].

- The disjoint union of G_1, \ldots, G_k , denoted by $G_1 \oplus \ldots \oplus G_k$, is the digraph with vertex set $V_1 \cup \ldots \cup V_k$ and arc set $E_1 \cup \ldots \cup E_k$.
- The series composition of G_1, \ldots, G_k , denoted by $G_1 \otimes \ldots \otimes G_k$, is defined by their disjoint union plus all possible arcs between vertices of G_i and G_j for all $1 \leq i, j \leq k, i \neq j$.
- The order composition of G_1, \ldots, G_k , denoted by $G_1 \oslash \ldots \oslash G_k$, is defined by their disjoint union plus all possible arcs from vertices of G_i to vertices of G_j for all $1 \le i < j \le k$.

The class of *directed co-graphs* can be defined recursively. The one-vertexdigraph is a directed co-graph and every disjoint union, series composition and order composition of directed co-graphs is a directed co-graph.

The following transformation has been considered by Johnson et al. in [24] and generalizes the operations disjoint union and order composition.

- The directed union of G_1, \ldots, G_k , denoted by $G_1 \ominus \ldots \ominus G_k$, is a subdigraph of the order composition $G_1 \oslash \ldots \oslash G_k$ and contains the disjoint union $G_1 \oplus \ldots \oplus G_k$ as a subdigraph.

Including this operation to the definition of directed co-graphs, we obtain the class of *extended directed co-graphs*.

For every (extended) directed co-graph, we can define a tree structure, denoted as di-co-tree. The leaves of the di-co-tree represent the vertices of the digraph and the inner nodes of the di-co-tree correspond to the operations applied on the subexpressions defined by the subtrees. For every directed co-graph one can construct a di-co-tree in linear time, see [12].

3 Digraph Width Measures

In Table 1 we summarize some examples for the value of digraph width measures of special digraphs. Further examples can be found in [17, Table 1].

G	$\operatorname{d-tw}(G)$	d-pw(G)	dfn(G)	$\operatorname{cr}(G)$	$\mathrm{ddp}(G)$	$\operatorname{dagw}(G)$	$\operatorname{kw}(G)$
$\overrightarrow{P_n}$	0	0	0	0	$\lfloor \log(n) \rfloor + 1$	1	0
$\overrightarrow{C_n}$	1	1	1	1	$\lfloor \log(n-1) \rfloor + 2$	2	1
$\overrightarrow{T_n}$	0	0	0	0	n	1	0
$\overrightarrow{P_n}$	1	1	$\lfloor \frac{n}{2} \rfloor$	$\lfloor \log(n) \rfloor$	$\lfloor \log(n) \rfloor + 1$	2	1
$\overrightarrow{K_n}$	n-1	n-1	n-1	n-1	n	n	n-1

Table 1. The value of digraph width measures of special digraphs.

3.1 Directed Tree-Width

We will use the directed tree-width introduced by Johnson et al. [24].¹

An out-tree is a tree with a distinguished root such that all arcs are directed away from the root. For two vertices u, v of an out-tree T, the notation $u \leq v$ means that there is a directed path on ≥ 0 arcs from u to v and u < v means that there is a directed path on ≥ 1 arcs from u to v.

Let G = (V, E) be some digraph and $Z \subseteq V$. A vertex set $S \subseteq V - Z$ is *Z*-normal if there is no directed path in G - Z with first and last vertices in S that uses a vertex of $G - (Z \cup S)$.

Definition 1 (Directed tree-width, [24]). A (arboreal) tree-decomposition of a digraph $G = (V_G, E_G)$ is a triple $(T, \mathcal{X}, \mathcal{W})$. Here $T = (V_T, E_T)$ is an outtree, $\mathcal{X} = \{X_e \mid e \in E_T\}$ and $\mathcal{W} = \{W_r \mid r \in V_T\}$ are sets of subsets of V_G , such that the following two conditions hold true.

(dtw-1) $\mathcal{W} = \{W_r \mid r \in V_T\}$ is a partition of V_G into non-empty subsets.² (dtw-2) For every $(u, v) \in E_T$ the set $\bigcup \{W_r \mid r \in V_T, v \leq r\}$ is $X_{(u,v)}$ -normal.

The width of a (arboreal) tree-decomposition $(T, \mathcal{X}, \mathcal{W})$ is

$$\max_{r \in V_T} |W_r \cup \bigcup_{e \sim r} X_e| - 1.$$

Here, $e \sim r$ means that r is one of the two vertices of arc e. The directed treewidth of G, d-tw(G) for short, is the smallest integer k such that there is a (arboreal) tree-decomposition $(T, \mathcal{X}, \mathcal{W})$ for G of width k.

Determining whether the directed tree-width of some given digraph is at most some given value w is NP-complete. On the other hand, determining whether the directed tree-width of some given digraph is at most some given value w is polynomial for directed co-graphs [21].

The results of [24] lead to an XP-algorithm³ for directed tree-width w.r.t. the standard parameter which implies that for each constant w, it is decidable in polynomial time whether a given digraph has directed tree-width at most w.

Lemma 1 ([20,21]). Let $G = (V_G, E_G)$ and $H = (V_H, E_H)$ be two vertexdisjoint digraphs, then the following properties hold.

¹ There are also further directed tree-width definitions such as allowing empty sets W_r in [23], using sets W_r of size one only for the leaves of T in [29] and using strong components within (dtw-2) in [13, Chap. 6]. Further in works of Courcelle et al. [9–11] the directed tree-width of a digraph G is defined by the tree-width of the underlying undirected graph. One reason for this could be the algorithmic advantages of the undirected tree-width.

² A remarkable difference to the undirected tree-width from [30] is that the sets W_r have to be disjoint and non-empty.

 $^{^{3}}$ XP is the class of all parameterized problems that can be solved in a certain time, see [14] for a definition.

1. $d-tw(G \oplus H) = \max\{d-tw(G), d-tw(H)\}$ 2. $d-tw(G \oslash H) = \max\{d-tw(G), d-tw(H)\}$ 3. $d-tw(G \ominus H) = \max\{d-tw(G), d-tw(H)\}$ 4. $d-tw(G \otimes H) = \min\{d-tw(G) + |V_H|, d-tw(H) + |V_G|\}$

3.2 Directed Path-Width

The notation of directed path-width was introduced by Reed, Seymour, and Thomas around 1995 and relates to directed tree-width introduced by Johnson, Robertson, Seymour, and Thomas in [24].

Definition 2 (Directed path-width). A directed path-decomposition of some digraph G = (V, E) is a sequence (X_1, \ldots, X_r) of subsets of V, called bags, such that the following three conditions hold true.

(dpw-1) $X_1 \cup \ldots \cup X_r = V$.

(dpw-2) For each $(u, v) \in E$ there is a pair $i \leq j$ such that $u \in X_i$ and $v \in X_j$. (dpw-3) If $u \in X_i$ and $u \in X_j$ for some $u \in V$ and two indices i, j with $i \leq j$, then $u \in X_\ell$ for all indices ℓ with $i \leq \ell \leq j$.

The width of a directed path-decomposition $\mathcal{X} = (X_1, \ldots, X_r)$ is

$$\max_{1 \le i \le r} |X_i| - 1$$

The directed path-width of G, d-pw(G) for short, is the smallest integer w such that there is a directed path-decomposition of G of width w.

Determining whether the directed path-width of some given digraph with maximum semi-degree $\Delta^0(G) = \max\{\Delta^-(D), \Delta^+(D)\} \leq 3$ is at most some given value w is NP-complete by a reduction from undirected path-width for planar graphs with maximum vertex degree 3 [26].

Lemma 2 ([20,21]). Let $G = (V_G, E_G)$ and $H = (V_H, E_H)$ be two vertexdisjoint digraphs, then the following properties hold.

1. $d - pw(G \oplus H) = \max\{d - pw(G), d - pw(H)\}$ 1. $d - pw(G \oslash H) = \max\{d - pw(G), d - pw(H)\}$ 1. $d - pw(G \ominus H) = \max\{d - pw(G), d - pw(H)\}$ 1. $d - pw(G \otimes H) = \min\{d - pw(G) + |V_H|, d - pw(H) + |V_G|\}$

3.3 Directed Feedback Vertex Set (DFVS) Number

Definition 3 (DFVS-number). The directed feedback vertex set number of a digraph G = (V, E), denoted by dfn(G), is the minimum cardinality of a set $S \subset V$ such that G - S is a DAG.

Theorem 1 (\bigstar^4). Let $G = (V_G, E_G)$ and $H = (V_H, E_H)$ be two vertex-disjoint digraphs, then the following properties hold.

 $^{^4}$ The proofs of the results marked with a \bigstar are omitted due to space restrictions.

1. $dfn(G \oplus H) = dfn(G) + dfn(H)$ 2. $dfn(G \oslash H) = dfn(G) + dfn(H)$ 3. $dfn(G \ominus H) = dfn(G) + dfn(H)$ 4. $dfn(G \otimes H) = \min\{dfn(G) + |V_H|, dfn(H) + |V_G|\}$

3.4 Cycle Rank

Cycle rank was introduced in [15] and also appeared in [8] and [25].

Definition 4 (Cycle rank). The cycle rank of a digraph G = (V, E), denoted by cr(G), is defined as follows.

- If G is acyclic, cr(G) = 0.
- If G is strongly connected, then $cr(G) = 1 + \min_{v \in V} cr(G \{v\})$.
- Otherwise the cycle rank of G is the maximum cycle rank of any strongly connected component of G.

Results on the cycle rank can be found in [19]. In this papers Gruber proved the hardness of computing cycle rank, even for sparse digraphs of maximum outdegree at most 2.

Proposition 1 ([19]). For every digraph G, we have d-pw(G) $\leq cr(G)$.

The cycle rank can be much larger than the directed path-width, which can be shown by a complete biorientation of a path graph $\overrightarrow{P_n}$ which has directed path-width 1 but arbitrary large cycle rank $\lfloor \log(n) \rfloor$, see [25].

Proposition 2 ([17]). For every digraph G, we have $cr(G) \leq dfn(G)$.

The DFVS-number can be much larger than the cycle rank, which can be shown by the disjoint union of $\frac{n}{3}$ directed cycles $\overrightarrow{C_3}$ which has cycle rank 1 but arbitrary large DFVS-number $\frac{n}{3}$.

Theorem 2 (\bigstar). Let $G = (V_G, E_G)$ and $H = (V_H, E_H)$ be two vertex-disjoint digraphs, then the following properties hold.

1. $cr(G \oplus H) = \max\{cr(G), cr(H)\}$ 2. $cr(G \oslash H) = \max\{cr(G), cr(H)\}$ 3. $cr(G \ominus H) = \max\{cr(G), cr(H)\}$ 4. $cr(G \otimes H) = \min\{cr(G) + |V_H|, cr(H) + |V_G|\}$

3.5 DAG-depth

The DAG-depth of a digraph was introduced in [16] motivated by tree-depth for undirected graphs, given in [27].

For a digraph G = (V, E) and $v \in V$, let G_v denote the subdigraph of G induced by the vertices which are reachable from v. The maximal elements in the partially ordered set $\{G_v \mid v \in V\}$ w.r.t. the graph inclusion order are the reachable fragments of G and will be denoted by R(G).⁵

 $^{^{5}}$ In the undirected case, reachable fragments coincide with connected components.

Definition 5 (DAG-depth). Let G = (V, E) be a digraph. The DAG-depth of G, denoted by ddp(G), is defined as follows.

- If |V| = 1, then ddp(G) = 1.
- If G has a single reachable fragment, then $ddp(G) = 1 + \min\{ddp(G-v) \mid v \in V\}$.
- Otherwise, ddp(G) equals the maximum over the DAG-depth of the reachable fragments of G.

Proposition 3 ([17]). For every complete bioriented directed G, we have ddp(G) = cr(G) + 1.

Theorem 3. Let $G = (V_G, E_G)$ and $H = (V_H, E_H)$ be two vertex-disjoint digraphs, then the following properties hold.

- 1. $ddp(G \oplus H) = \max\{ddp(G), ddp(H)\}$
- 2. $ddp(G \oslash H) = ddp(G) + ddp(H)$
- 3. $ddp(G \ominus H) \leq ddp(G) + ddp(H)$
- 4. $ddp(G \otimes H) = \min\{ddp(G) + |V_H|, ddp(H) + |V_G|\}$
- *Proof.* 1. Since there is no edge in $G \oplus H$ between a vertex from V_G and a vertex from V_H , every reachable fragment is a subset of V_G or a subset of V_H .
- 2. First, we observe that the set of reachable fragments for $G \oslash H$ can be obtained by $R(G \oslash H) = \{f \cup V_H \mid f \in R(G)\}.$ $ddp(G \oslash H) \leq ddp(G) + ddp(H)$

First, we remove the vertices of G from $G \oslash H$ in the same order as from G when verifying the depth of ddp(G) using Definition 5. Afterwards, we remove the vertices of H from $G \oslash H$ in the same order as from H when verifying the depth of ddp(H) using Definition 5. The observation above allows to use this ordering.

 $\mathrm{ddp}(G \oslash H) \ge \mathrm{ddp}(G) + \mathrm{ddp}(H)$

First suppose that it is optimal to begin removing vertices from V_G of $G \oslash H$. Then it is no drawback to remove all vertices from V_G of $G \oslash H$ first and all vertices from V_H afterwards, since every vertex of V_H is reachable from every vertex of V_G . Since none of the vertices of V_G is reachable from a vertex of V_H the vertices of V_H do not effect the number of fragments, reachable from V_G . Next, suppose that it is optimal to begin removing vertices from V_H of $G \oslash H$. Then it is no drawback to remove all vertices from V_H of $G \oslash H$ first and all vertices from V_G afterwards, since none of the vertices of V_G is reachable from a vertex of V_H and thus the vertices of V_G do not effect the number of fragments, reachable from V_H .

3. $ddp(G \ominus H) \leq ddp(G) + ddp(H)$ holds, since the equality of 2. does not hold true in this case, since for a small number of edges $ddp(G \ominus H)$ is much smaller than ddp(G) + ddp(H). Note that a lower bound is $ddp(G \ominus H) \geq \max\{ddp(G), ddp(H)\}$, since $G \ominus H$ is equal to the disjoint union if no edges emerge.

4. $\operatorname{ddp}(G \otimes H) \leq \min\{\operatorname{ddp}(G) + |V_H|, \operatorname{ddp}(H) + |V_G|\}$

Since $G \otimes H$ has only one reachable fragment as long as it contains vertices from V_G and vertices from V_H , we can apply the second case of Definition 5 to verify an upper bound of $ddp(G) + |V_H|$ by removing the vertices of Hone by one from $G \otimes H$ and to verify an upper bound of $ddp(H) + |V_G|$ by removing the vertices of G one by one from $G \otimes H$.

 $\mathrm{ddp}(G \otimes H) \ge \min\{\mathrm{ddp}(G) + |V_H|, \mathrm{ddp}(H) + |V_G|\}$

Since in $G \otimes H$ every vertex of V_G has an edge to and from every vertex of V_H , $G \otimes H$ has only one reachable fragment as long as it contains vertices from V_G and V_H . Thus, we have to apply the second case of Definition 5 as long we have vertices from V_G and vertices from V_H . This either leads to a subdigraph induced by $V_G - V'_G$ for some $V'_G \subset V_G$ or to a subdigraph induced by $V_H - V'_H$ for some $V'_H \subset V_H$. Thus, we have

$$ddp(G \otimes H) \ge \min\{|V_H| + |V'_G| + ddp(G - V'_G), \\ |V_G| + |V'_H| + ddp(H - V'_H)\} \\ \ge \min\{|V_H| + ddp(G), |V_G| + ddp(H)\}.$$

This completes the proof.

Note that $ddp(G \ominus H)$ cannot be computed from ddp(G) and ddp(H) by a simple formula, since the disjoint union and the order operation behave differently.

3.6 DAG-width

The DAG-width is a graph parameter which describes how close a digraph is to a directed acyclic graph (DAG). It has been defined in [5, 6, 28].

Let $G = (V_G, E_G)$ be a acyclic digraph. The partial order \preccurlyeq_G on G is the reflexive, transitive closure of E_G . A source or root of a set $X \subseteq V_G$ is a \preccurlyeq_G -minimal element of X, that is, $r \in X$ is a root of X, if there is no $y \in X$, such that $y \preccurlyeq_G r$ and $y \neq x$. Analogously, a sink or leaf of a set $X \subseteq V_G$ is a \preccurlyeq_G -maximal element.

Let $V' \subseteq V_G$, then a set $W \subseteq V_G$ guards V' if for all $(u, v) \in E_G$ it holds that if $u \in V'$ then $v \in V' \cup W$.

Definition 6 (DAG-width). A DAG-decomposition of some digraph $G = (V_G, E_G)$ is a pair (D, \mathcal{X}) where $D = (V_D, E_D)$ is a DAG and $\mathcal{X} = \{X_u \mid X_u \subseteq V_G, u \in V_D\}$ is a family of subsets of V_G such that:

- (dagw-1) $\bigcup_{u \in V_D} X_u = V_G$.
- (dagw-2) For all vertices $u, v, w \in V_D$ with $u \succeq_D v \succeq_D w$, it holds that $X_u \cap X_w \subseteq X_v$.
- (dagw-3) For all edges $(u, v) \in E_D$ it holds that $X_u \cap X_v$ guards $X_{\succeq v} \setminus X_u$, where $X_{\succeq v} = \bigcup_{v \geq D} W X_w$. For any source $u, X_{\succeq u}$ is guarded by \emptyset .

The width of a DAG-decomposition (D, \mathcal{X}) is the number

$$\max_{u \in V_D} |X_u|.$$

The DAG-width of a digraph G, dagw(G) for short, is the smallest width of all possible DAG-decompositions for G.

We use the restriction to nice DAG-decompositions from [6, Theorem 24].

Proposition 4 ([6]). For every graph G, we have $dagw(\overleftarrow{G}) = tw(G) + 1$.

Proposition 4 implies that the NP-hardness of tree-width carries over to DAG-width.

There are even digraphs on n vertices whose optimal DAG-decompositions have super-polynomial many bags w.r.t n [1]. Furthermore, it has been shown that deciding whether the DAG-width of a given digraph is at most a given value is PSPACE-complete [1].

Proposition 5 ([17]). For every digraph G, we have $dagw(G) \leq d pw(G) + 1$.

Proposition 6 ([6]). For every digraph G, we have $d\text{-}tw(G) \leq 3 \cdot dagw(G) + 1$.

Lemma 3 (\bigstar). Let G = (V, E) be a digraph of DAG-width at most k, such that $V_1 \cup V_2 = V$, $V_1 \cap V_2 = \emptyset$, and $\{(u, v), (v, u) \mid u \in V_1, v \in V_2\} \subseteq E$. Then there is a DAG-decomposition (D, \mathcal{X}) , $D = (V_D, E_D)$, of width at most k for G such that for every $v \in V_D$ holds $V_1 \subseteq X_v$ or for every $v \in V_D$ holds $V_2 \subseteq X_v$.

Obviously, this lemma also holds for a nice DAG-decomposition.

Theorem 4. Let $G = (V_G, E_G)$ and $H = (V_H, E_H)$ be two vertex-disjoint digraphs, then the following properties hold.

- 1. $dagw(G \oplus H) = \max\{dagw(G), dagw(H)\}$
- 2. $dagw(G \oslash H) = \max\{dagw(G), dagw(H)\}$
- 3. $dagw(G \ominus H) = \max\{dagw(G), dagw(H)\}$
- 4. $dagw(G \otimes H) = \min\{dagw(G) + |V_H|, dagw(H) + |V_G|\}$

Proof. Let G and H be two vertex-disjoint digraphs and let further (D_G, \mathcal{X}_G) and (D_H, \mathcal{X}_H) be their nice DAG-decompositions with minimum DAG-width. Let r_H be the root of D_H and let l_G be a leaf of D_G .

1. For $J = G \oplus H$, we first define a legit DAG-decomposition (D_J, \mathcal{X}_J) for J and show that it is of minimum width afterwards. Let D_J be the disjoint union of D_G and D_H with an additional arc (l_G, r_H) . Further, $\mathcal{X}_J = \mathcal{X}_G \cup \mathcal{X}_H$. (D_J, \mathcal{X}_J) is a valid DAG-decomposition because it satisfies the conditions as follows. It holds that (dagw-1) is satisfied by (D_G, \mathcal{X}_G) and (D_H, \mathcal{X}_H) it is also satisfied by (D_J, \mathcal{X}_J) because all vertices of J are included. As we do not add any vertices to the X-sets and G and H are vertex-disjoint, (dagw-2) is satisfied for (D_J, \mathcal{X}_J) . Further, (dagw-3) is satisfied for all arcs in D_G and D_H . In D_J there is only one additional arc, (l_G, r_H) . Since it holds that for r_H , $X_{\geq r_H}$ is guarded by \emptyset and we do not add any outgoing vertices to H and $X_{l_G} \cap X_{r_H} = \emptyset$, (dagw-3) is satisfied for (D_J, \mathcal{X}_J) . Thus, the DAG-width of the decomposition is limited by the larger width of G and H, such that $\operatorname{dagw}(G \oplus H) \leq \max\{\operatorname{dagw}(G), \operatorname{dagw}(H)\}$.

The lower bound holds as G and H are both induced subdigraphs of J and a graph cannot have lower DAG-width than its induced subdigraphs. Hence $\operatorname{dagw}(J) \geq \max\{\operatorname{dagw}(G), \operatorname{dagw}(H)\}$ applies, which leads to $\operatorname{dagw}(J) = \max\{\operatorname{dagw}(G), \operatorname{dagw}(H)\}$.

- 2. Holds by the same arguments as given in (1.).
- 3. Holds by the same arguments as given in (1.).
- 4. For $J = G \otimes H$, set $D_J = D_G$ and $\mathcal{X}_J = \{X_u \cup V_H \mid X_u \in \mathcal{X}_G\}$. Then (D_J, \mathcal{X}_J) is a DAG-decomposition for J: Obviously, (dagw-1) is satisfied. (dagw-2) and (dagw-3) are satisfied since they are satisfied for \mathcal{X}_G and we add V_H to every vertex set in \mathcal{X}_G . Further, it holds that the width of (D_J, \mathcal{X}_J) is dagw $(G) + |V_H|$. In the same way, we get a DAG-decomposition of width dagw $(H) + |V_G|$, so we have dagw $(G \otimes H) \leq \min\{\text{dagw}(G) + |V_H|, \text{dagw}(H) + |V_G|\}$.

For the lower bound, we use Lemma 3. Assume that $\operatorname{dagw}(G \otimes H) < \min\{\operatorname{dagw}(G) + |V_H|, \operatorname{dagw}(H) + |V_G|\}$. Let (D_J, \mathcal{X}_J) be a minimal DAGdecomposition of J of size $k < \min\{\operatorname{dagw}(G) + |V_H|, \operatorname{dagw}(H) + |V_G|\}$. By Lemma 3 we have $V_H \subseteq X_v$ for all $X_v \in \mathcal{X}_J$ or $V_G \subseteq X_v$ for all $X_v \in \mathcal{X}_J$. Without loss of generality assume $V_H \subseteq X_v$ for all $X_v \in \mathcal{X}_J$ (because $V_G \subseteq X_v$ for all $X_v \in \mathcal{X}_J$, respectively). Then (D'_G, \mathcal{X}'_G) with $D'_G = D_J$, $\mathcal{X}'_G = \{X_u \setminus V_H \mid X_u \in \mathcal{X}_J\}$ is a DAG-decomposition of size $k - |V_H|$ of G: – (dagw-1) is satisfied since

$$\bigcup_{u \in V_{D'_G}} X_u = \bigcup_{u \in V_{D_J}} (X_u \setminus V_H) = \left(\bigcup_{u \in V_{D_J}} X_u\right) \setminus V_H$$
$$= V_J \setminus V_H$$
$$= (V_G \cup V_H) \setminus V_H$$
$$= V_G.$$

- (dagw-2) is satisfied since for all $u, v, w \in V_{D'_G}$ with $u \succcurlyeq_{D'_G} v \succcurlyeq_{D'_G} w$ and X_u^J, X_v^J and X_w^J the corresponding sets in (D_J, \mathcal{X}_J) it holds that $X_u \cap X_w = (X_u^J \setminus V_H) \cap (X_w^J \setminus V_H) = (X_u^J \cap X_w^J) \setminus V_H \subseteq X_v^J \setminus V_H = X_v$ as $u \succcurlyeq_{D_J} v \succcurlyeq_{D_J} w$.
- (dagw-3) is satisfied since for all edges $(u, v) \in E_{D'_G}$, we have $(u, v) \in E_{D_J}$ and as $X_u \cap X_v = (X_u^J \cap X_v^J) \setminus V_H$ which guards $X_{\succeq D'_G v} \setminus X_u = X_{\succeq D_J v} \setminus X_u^J$. For the root, the condition is trivially satisfied.

But it holds that $k - |V_H| < \min\{\operatorname{dagw}(G) + |V_H|, \operatorname{dagw}(H) + |V_G|\} - |V_H| \le \operatorname{dagw}(G) + |V_H| - |V_H| = \operatorname{dagw}(G)$. This is a contradiction, as it is not possible to create a DAG-decomposition of size smaller than $\operatorname{dagw}(G)$.

It follows that $\operatorname{dagw}(G \otimes H) \ge \min\{\operatorname{dagw}(G) + |V_H|, \operatorname{dagw}(H) + |V_G|\}$ and thus that $\operatorname{dagw}(G \otimes H) = \min\{\operatorname{dagw}(G) + |V_H|, \operatorname{dagw}(H) + |V_G|\}.$

This completes the proof.

3.7 Kelly-Width

The Kelly-width is also led from directed acyclic graphs, which leads to the idea that it is very similar to the DAG-width. It has been defined in [22].

Definition 7. (Kelly-width). A Kelly decomposition of a digraph $G = (V_G, E_G)$ is a triple $(\mathcal{W}, \mathcal{X}, D)$ where D is a directed acyclic graph, $\mathcal{X} = \{X_u \mid X_u \subseteq V_G, u \in V_D\}$ and $\mathcal{W} = \{W_u \mid W_u \subseteq V_G, u \in V_D\}$ are families of subsets of V_G such that:

- 1. W is a partition for V_G .
- 2. For all vertices $v \in V_G$, X_v guards W_{\succeq_v} .
- 3. For all vertices $v \in V_G$, there is a linear order u_1, \ldots, u_s on the children of v such that for every u_i it holds that $X_{u_i} \subseteq W_i \cup X_i \cup \bigcup_{j < i} W_{\succcurlyeq u_j}$. Similarly, there is a linear order r_1, r_2, \ldots on the roots of D such that for each root r_i it holds that $W_{r_i} \subseteq \bigcup_{j < i} W_{\succcurlyeq r_j}$.

The width of a Kelly decomposition $(\mathcal{W}, \mathcal{X}, D)$ is the number

$$\max_{u \in V_D} |X_u| + |W_u|.$$

The Kelly-width of a digraph G, denoted with kw(G), is the smallest width of all possible Kelly decompositions for G.

Definition 8. (Directed elimination ordering). Let G = (V, E) be a digraph. A directed elimination ordering \triangleleft on G is a linear ordering on V. For $\triangleleft = (v_0, v_1, \dots, v_{n-1})$ we define

 $\begin{array}{l} - \ G_0^{\lhd} = G \\ - \ G_{i+1}^{\lhd} = (V_{i+1}^{\lhd}, E_{i+1}^{\lhd}) \ \text{with} \ V_{i+1}^{\lhd} = V_i^{\lhd} \setminus \{v_i\} \ \text{and} \\ E_{i+1}^{\lhd} = \{(u, v) \mid (u, v) \in E_i^{\lhd} \ \text{and} \ u, v \neq v_i \ \text{or} \ (u, v_i), (v_i, v) \in E_i^{\lhd}, u \neq v \} \end{array}$

 G_i^{\triangleleft} is the directed elimination graph at step *i* according to \triangleleft . The width of \triangleleft is the maximum out-degree of v_i in G_i^{\triangleleft} over all *i*.

Lemma 4 ([22]). Let G be a digraph. The following are equivalent:

1. G has Kelly-width at most k + 1

2. G has a directed elimination ordering of width $\leq k$

Proposition 7 ([22]). For every digraph G, we have d-tw(G) $\leq 6 \cdot kw(G) - 2$.

Proposition 8 ([17]). For every digraph G, we have $kw(G) \leq d pw(G) + 1$.

Theorem 5. Let $G = (V_G, E_G)$ and $H = (V_H, E_H)$ be two vertex-disjoint digraphs, then the following properties hold.

- 1. $kw(G \oplus H) = \max\{kw(G), kw(H)\}$
- 2. $kw(G \oslash H) = \max\{kw(G), kw(H)\}$
- 3. $kw(G \ominus H) = \max\{kw(G), kw(H)\}$

4.
$$kw(G \otimes H) \leq \min\{kw(G) + |V_H|, kw(H) + |V_G|\}$$

Proof. We use the fact that by Lemma 4, a digraph has Kelly-width k + 1 if and only if it has a directed elimination ordering of width k. Let $G = (V_G, E_G)$ and $H = (V_H, E_H)$ be two vertex-disjoint digraphs with $\text{kw}(G) = k_G$ and $\text{kw}(H) = k_H$. Then, there exists a directed elimination ordering \triangleleft_G of G of width $k_G - 1$ and a directed elimination ordering \triangleleft_H of H of width $k_H - 1$.

- 1. For $J = G \oplus H$, we obtain a linear ordering \triangleleft_J of J by adding first all vertices from \triangleleft_H and from \triangleleft_G to \triangleleft_J afterwards. As no edges from H to G are inserted to J, this is a directed elimination ordering of width max{ $k_H - 1, k_G - 1$ }. As G and H are both induced subdigraphs of J, there cannot exist a directed elimination ordering of smaller width. By Lemma 4 it follows that kw(J) = max{ k_H, k_G }, such that kw($G \oplus H$) = max{kw(G), kw(H)}.
- 2. Holds by the same arguments as in (1.).
- 3. Holds by the same arguments as in (1.).
- 4. For $J = G \otimes H$, we obtain a linear ordering \triangleleft_J of J by adding first all vertices from \triangleleft_H and afterwards from \triangleleft_G to \triangleleft_J (first \triangleleft_G , then \triangleleft_H respectively). As there are exactly V_G (V_H) more outgoing edges for every vertex in V_H (V_G), this is a directed elimination ordering of J of width $k_H - 1 + |V_G|$ ($k_G - 1 + |V_H|$, respectively).

This completes the proof.

Remark 1 (\bigstar). The value min{kw(G)+|V_H|, kw(H)+|V_G|} is not a lower bound for kw(G \otimes H), even not if G and H are directed co-graphs.

3.8 Comparison

Theorem 6. For every extended directed co-graph G, we have

 $kw(G) \le d - pw(G) = d - tw(G) = cr(G) = dagw(G) - 1 \le ddp(G) - 1 \le dfn(G).$

For DFVS-Number, DAG-depth and Kelly-width equality is not possible by the following examples. For the disjoint union of two $\overrightarrow{K_n}$, it holds that $d\text{-pw}(2\overrightarrow{K_n}) = n - 1 < 2n - 2 = dfn(2\overrightarrow{K_n})$. For transitive tournaments $\overrightarrow{T_n}$, it holds that $d\text{-pw}(\overrightarrow{T_n}) = 0 < n = ddp(\overrightarrow{T_n})$. Further, let K'_n be the 2n vertex graph which is obtained by a complete graph K_n on n vertices and adding a pendant vertex for every of the n vertices of K_n , then for the complete biorientation $\overleftarrow{K'_n}$ it holds that $kw(\overrightarrow{K'_n} \otimes \overrightarrow{K'_n}) = 2n - 1 < 3n - 1 = d\text{-pw}(\overrightarrow{K'_n} \otimes \overrightarrow{K'_n})$. But by Theorem 5 Kelly-width is always smaller or equal to path-width and

But by Theorem 5 Kelly-width is always smaller or equal to path-width and its equal parameters and by Theorem 3 DAG-depth is always greater or equal to path-width and its equal parameters.

Theorem 7. For every extended directed co-graph G = (V, E) which is given by a binary di-co-tree the directed path-width, directed tree-width, directed feedback vertex set number, cycle rank, and DAG-width can be computed in time O(|V|).

4 Conclusion and Outlook

In this paper, we are able to give linear time algorithms for the directed feedback set number, cycle rank and DAG-width of extended directed co-graphs and a linear-time algorithm for the DAG-depth of directed co-graphs. Further, we provided a comparison of all considered parameters for extended directed co-graphs and obtained equality for directed path-width, directed tree-width, cycle rank and DAG width. Further, we showed for bounds for the class of directed co-graphs for the directed vertex set number, DAG-depth and Kellywidth. This widely extends our results for directed path-width and directed tree-width from [21].

A further issue could be to find a linear or polynomial time algorithm to compute Kelly-width on directed co-graphs. Furthermore, it would be interesting for which superclasses of directed co-graphs it is still possible to find polynomial algorithms to get the considered parameters and for which superclasses these problems become NP-hard.

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