

Approximation Scheme for the Capacitated Vehicle Routing Problem with Time Windows and Non-uniform Demand

Michael Khachay^{1,2,3}(⊠) ⓑ and Yuri Ogorodnikov^{1,2} ⓑ

¹ Krasovsky Institute of Mathematics and Mechanics, Ekaterinburg, Russia {mkhachay,yogorodnikov}@imm.uran.ru

² Ural Federal University, Ekaterinburg, Russia

³ Omsk State Technical University, Omsk, Russia

Abstract. The Capacitated Vehicle Routing Problem with Time Windows (CVRPTW) is the well-known combinatorial optimization problem having numerous valuable applications in operations research. Unlike the classic CVRP (without time windows constraints), approximation algorithms with theoretical guarantees for the CVRPTW are still developed much less, even for the Euclidean plane. In this paper, perhaps for the first time, we propose an approximation scheme for the planar CVRPTW with non-uniform splittable demand combining the well-known instance decomposition framework by A. Adamaszek et al. and Quasi-Polynomial Time Approximation Scheme (QPTAS) by L. Song et al. Actually, for any $\varepsilon \in (0, 1)$ the scheme proposed finds a $(1+\varepsilon)$ -approximate solution of the problem in polynomial time provided the capacity q and the number p of time windows does not exceed $2^{\log^{\delta} n}$ for some $\delta = O(\varepsilon)$. For any fixed p and q the scheme is Efficient Polynomial Time Approximation

Keywords: Capacitated vehicle routing problem \cdot Time windows \cdot Splittable demand \cdot Polynomial time approximation scheme

1 Introduction

The Capacitated Vehicle Routing Problem (CVRP) is the famous combinatorial optimization problem, which was introduced by Dantzig and Ramser in their seminal paper [9] and has a wide range of relevant applications in practice (see, e.g. [30]). In the simplest setting of the problem, we are given by a finite set of customers having the same unit demand and a fleet of identical capacitated vehicles located initially at a single depot. The goal is to construct a collection of vehicle routes minimizing the total transportation cost and servicing all the customers.

The Capacitated Vehicle Routing Problem with Time Windows (CVRPTW) [20,30] is an extension of the CVRP, where service of each customer should start

© Springer Nature Switzerland AG 2019

M. Khachay et al. (Eds.): MOTOR 2019, LNCS 11548, pp. 309–327, 2019. https://doi.org/10.1007/978-3-030-22629-9_22

at a specified time interval, called a time window. CVRP with hard windows is widely applicable in natural gas distribution [7], dial-ride company planning [11], continent-scale distribution of building materials [23], low-carbon economy [26], and other practical transportation problems [25].

The problem is well-investigated by specialists in the field of exact methods, heuristics, and meta-heuristics. Recently, a significant progress was achieved in solving practically important instances of the CVRPTW by local-search heuristics [13], Tabu-search [29], genetic [31], memetic [6,21], and colony algorithms [22], and their combinations (see, e.g. [8]).

Nevertheless, approximation results for this problem in the class of algorithms with theoretical guarantees are still extremely rare. To the best of our knowledge, they are exhausted by the Quasi-Polynomial Time Approximation Scheme (QPTAS) proposed in [28] and extended recently to the case of multiple depots [27] and our recent Efficient Polynomial-Time Approximation Schemes (EPTAS) for the CVRPTW with any fixed capacity and number of time windows. In addition, all known results relate to the special setting of the problem, where all customers have the same unit demand.

Our Contribution. In this paper, perhaps for the first time for the CVRPTW with non-uniform demand, we propose an approximation scheme with theoretically proved time complexity bounds. Our scheme extends the decomposition framework introduced by Adamaszek et al. in [1] for efficient approximation of the simplest unit-demand CVRP on the Euclidean plane to more general case of the problem to take into account additional time windows constraints and a non-uniform splittable customer demand.

The rest of this paper is structured as follows. In Sect. 2, we give a short overview of known approximation results for the CVRPTW in the class of algorithms with theoretical bounds. In Sect. 3, we recall the mathematical setting of the CVRPTW with non-uniform demand. Section 4 presents the mail idea of the proposed scheme. In subsequent sections, we discuss this scheme in detail. We start in Sect. 5 with basic known results needed for the subsequent constructions. Then, in Sect. 6 we present our approximation scheme with a proof of its accuracy bound. Time complexity bounds are proved in the Sect. 7. Finally, in Sect. 8, we summarize the results obtained and list some questions that still remain open.

2 Related Work

Being an extension of the well-known strongly NP-hard Traveling Salesman Problem (TSP) [30], the Capacitated Vehicle Routing Problem is also strongly NP-hard even in the Euclidean plane [24] provided the capacity q belongs to the input. The metric CVRP remains intractable and APX-hard even for any fixed $q \geq 3$ and for the two-valued $\{1, 2\}$ -metric.

For the Euclidean CVRP, the first approximation results date to the seminal paper by Haimovich and Rinnooy Kan [12], where the first PTAS for the CVRP on the plane and capacity $q = o(\log \log n)$ and first constant-factor algorithms for an arbitrary metric were introduced. Then, in [3] an improved scheme, whose running time retains polynomial for the wider range $q = O(\log n / \log \log n)$, was proposed.

The ideas proposed by Arora in his celebrated paper [2] were used by Das and Mathieu to design their Quasi-Polynomial Time Approximation Scheme (QPTAS) [10] for the general case of the planar Euclidean CVRP. Their QPTAS finds a $(1 + \varepsilon)$ -approximate solution of this problem (for the case, when q is a part of the instance) in time $n^{(\log n)^{O(1/\varepsilon)}}$. Using this QPTAS as a black-box, Adamaszek, Czumaj, and Lingas [1] showed that $(1 + \varepsilon)$ -approximate solution of the planar CVRP can be found in polynomial time, if $q \leq 2^{\log^{\delta} n}$ for some $\delta = \delta(\varepsilon)$. Some aforementioned results were extended to the case of Euclidean spaces of an arbitrary finite dimension [14, 18, 19] and several special graphs [4, 5].

Unlike CVRP, approximability of the Euclidean CVRPTW is much less investigated. To the best of our knowledge, the family of known approximation algorithms for this problem is exhausted by a Quasi-Polynomial Time Approximation Scheme (QPTAS) developed in [27,28] for the general case of the problem and approximation schemes for the case of $\max\{p,q\} = o(\log \log n)$ and $p^3q^4 = O(\log n)$, where p is the number of time windows, proposed in [16] and [15,17], respectively.

All aforementioned results for the CVRPTW relate to the simplest setting of the problem, when all customers have the same unit demand. In this paper, we try to bridge this gap and to propose an approximation scheme for the case of the CVRPTW with a non-uniform splittable demand.

3 Problem Statement

We consider the Euclidean Capacitated Vehicle Routing Problem with Time Windows and non-uniform Splittable customer Demand (CVRPTW-SD). For the sake of simplicity, we restrict ourselves to the case of the Euclidean plane, pairwise disjoint time windows, and a single depot. An instance of the CVRPTW-SD is defined by

- a set $X = \{x_1, \ldots, x_n\}$ of customer locations (*customers*) on the Euclidean plane and a dedicated location y also known as *depot*, such that, for any locations $v_1, v_2 \in X \cup \{y\}$, transportation cost associated with the direct move from v_1 to v_2 coincides with $||v_1 - v_2||_2$
- a natural-valued function d specifying demand d(x) of any customer $x \in X$ that should be serviced by one or more vehicle routes
- an unbounded fleet of *vehicles* having the same integer *capacity* q and located initially in the depot y
- a linearly ordered set $\mathcal{T} = \{T_1, \ldots, T_p\}$ of the consecutive time windows, such that the demand d(x) of any customer x should be fulfilled within the given time window $T(x) \in \mathcal{T}$; we assume that, for any $1 \leq j < p$, the time window T_j precedes T_{j+1} and use the notation $T_j \prec T_{j+1}$.

The goal is to satisfy the demand of each customer minimizing the total transportation cost with respect to the capacity and time windows constraints.

Mathematically, an instance of the CVRPTW-SD is given by a complete node- and edge-weighted graph $G = (X \cup y, E, d, w)$, natural number q, and a partition

$$X_1 \cup \ldots \cup X_p = X$$
, where $X_j = \{x_i \in X : T(x_i) \in \mathcal{T}\}, (j \in \{1, \ldots, p\})$. (1)

To any customer node $x_i \in X$, the weighting function d assigns¹ the positive integer demand $d_i = d(x_i)$, while the function w defines the transportation cost $w(v_1, v_2) = ||v_1 - v_2||_2$ for any edge $e = \{v_1, v_2\} \in E$.

A feasible route is an ordered pair $\mathcal{R}_j = (R_j, D_j)$, where $R_j = y, x_{i_1}, \ldots, x_{i_s}, y$ is a simple cycle in the graph G and the n-tuple $D_j = (d_{1j}, \ldots, d_{nj})$ satisfying time windows

$$T(x_{i_l}) \preceq T(x_{i_{l+1}}), \quad (1 \le l < s)$$

and capacity

$$1 \le d_{i_l j} \le d_{i_l}, \quad (1 \le l \le s)$$

$$d_{ij} = 0, \qquad i \notin \{i_1, \dots, i_s\}$$

$$\sum_{i=1}^n d_{ij} \le q$$

constraints, where d_{ij} is a part of the *i*-th customer demand covered by the route R_j . To any feasible route \mathcal{R} , we assign the transportation cost

$$w(\mathcal{R}) = w(y, x_{i_1}) + w(x_{i_1}, x_{i_2}) + \ldots + w(x_{i_s}, y).$$

The goal is to find, for some $m \geq 1$, a minimum cost multi-cover $\mathcal{U} = (\mathcal{R}_1, \ldots, \mathcal{R}_m)$ of the graph G, satisfying the total customer demand, i.e.

$$\sum_{j=1}^{m} d_{ij} = d_i, \quad (1 \le i \le n).$$

In the sequel, we propose a novel approximation scheme for this problem, which is an Efficient Sub-Quadratic Approximation Scheme for any fixed capacity q and the number p of time windows retaining the polynomial running time, when $\max\{p,q\} \leq 2^{\log^{\delta} n}$ for some $\delta = \delta(\varepsilon)$.

4 Main Idea

Our scheme extends the approach proposed by Adamaszek et al. in [1] to the more general case of the Capacitated Vehicle Routing Problem augmented by non-uniform splittable customer demand and time windows constraints. In this section, we give a short overview of the scheme, which consists of the following stages.

¹ Without loss of generality, we can can assume that d(y) = 0, for the depot y.

Preprocessing. To any customer x_i , we assign the distance $r_i = w(y, x_i)$ from the depot y and relabel the customers in non-increasing order of these distances, i.e., $r_1 \ge \ldots \ge r_n$. Then, given an $\varepsilon > 0$, we set a tolerance threshold

$$\rho = \frac{r_1 \varepsilon}{N}, \text{ where } N = \sum_{i=1}^n \left\lceil \frac{d_i}{q} \right\rceil,$$
(2)

and exclude all the customers x_i , for which $r_i \leq \rho$.

Rounding. We reduce the given instance of the CVRPTW-SD to an appropriate instance of the special kind, which we call rounded. To proceed with such a reduction, we draw a number of circles centered at the depot y and separating them into equal sectors by rays spreading from this depot and introduce an accuracy dependent grid consisting of *locations*, which are the intersections between circles and rays. We divide each location to p slots by the number of given time windows and move any customer x_i to the corresponding slot of the closest location. Finally, we show that any $(1 + \varepsilon)$ -approximate solution of the rounded instance obtained can be efficiently transformed to a $(1 + O(\varepsilon))$ -approximate solution of the initial one. Therefore, in the sequel, we assume that the given instance is rounded.

Decomposition. At this stage, we decompose the given rounded CVRPTW-SD instance into a number of independent subinstances of two kind, we call them white and gray, which can be solved in parallel. We show that, to obtain an $(1+O(\varepsilon))$ -approximate solution of the initial instance, it is sufficient to construct $(1 + \varepsilon)$ -approximate solution of any white subinstance and approximate any gray subinstance by an appropriate adaptation of the well-known Iterative Tour Partition (ITP) heuristic [12]. Then, following [1], we show that any subinstance (white or gray) can be efficiently reduced to an equivalent one, whose total demand does not exceed a polynomial of the capacity q, the number of time windows p and $1/\varepsilon$.

Blackboxing. Finally, we complete our approximation scheme by employing the QPTAS proposed in [28] and our extension of the ITP heuristic [16] to find approximate solutions of all the reduced white and gray subinstances, respectively.

5 Preliminaries

We start with some necessary definitions and facts. All of them remain valid not only for the planar setting of the CVRPTW considered in this paper but also for the general metric CVRPTW defined by an arbitrary non-negative edgeweighting function w satisfying the triangle inequality. **Lemma 1.** For any instance of the CVRPTW-SD, such that $r_1 \ge \ldots \ge r_n$, $r_i = w(y, x_i)$, the following inequality

$$OPT \ge \max\left\{ TSP^*(X \cup \{y\}), 2r_1, \frac{2}{q} \sum_{i=1}^n d_i r_i \right\}$$
(3)

is valid, where $\text{TSP}^*(X \cup \{y\})$ is the optimum value of the TSP instance defined by the graph $G = G(X \cup \{y\}, E, w)$.

Proof. Since the inequalities $OPT \ge TSP^*(X \cup \{y\}) \ge 2r_1$ are a straightforward consequence of the triangle inequality, we prove the bound $OPT \ge \frac{2}{q} \sum_{i=1}^{n} d_i r_i$.

Let $\mathcal{U} = \{\mathcal{R}_1, \ldots, \mathcal{R}_m\}$ be an arbitrary optimum solution of the given CVRP-TW-SD instance. For each $j \in [m] = \{1, \ldots, m\}$, introduce the non-empty subset $X(\mathcal{R}_j) = \{x_i \in X : d_{ij} > 0\}$ of customers visited by the route \mathcal{R}_j . Since, for any $x_i \in X(\mathcal{R}_j), 2r_i = w(y, x_i) + w(x_i, y) \leq w(\mathcal{R}_j)$, by the triangle inequality, the following equation

$$\frac{d_{ij}}{\sum_{l=1}^{n} d_{lj}} w(\mathcal{R}_j) \ge \frac{2d_{ij}}{\sum_{l=1}^{n} d_{lj}} r_i$$

is valid for each customer $x_i \in X$. Therefore,

$$w(\mathcal{R}_j) = \frac{\sum_{i=1}^n d_{ij}}{\sum_{l=1}^n d_{lj}} w(\mathcal{R}_j) \ge \frac{2\sum_{i=1}^n d_{ij}r_i}{\sum_{l=1}^n d_{lj}} \ge \frac{2}{q} \sum_{i=1}^n d_{ij}.r_i,$$

since $q \ge \sum_{l=1}^{n} d_l j$, and

$$w(\mathcal{U}) = \sum_{j=1}^{m} w(\mathcal{R}_j) \ge \frac{2}{q} \sum_{j=1}^{m} \sum_{i=1}^{n} d_{ij} r_i = \frac{2}{q} \sum_{i=1}^{n} r_i \sum_{j=1}^{m} d_{ij} = \frac{2}{q} \sum_{i=1}^{n} d_i r_i.$$

Lemma is proved.

The well-known Iterative Tour Partition (ITP) heuristic introduced in [12] for the metric Capacitated Vehicle Routing Problem (CVRP) with unit demand can be defined as follows. Consider an instance of the metric CVRP defined by the complete edge-weighted graph $G = G(X \cup \{y\}, E, w)$ and capacity q. Suppose, we are given by an arbitrary Hamiltonian cycle H in the subgraph $G\langle X \rangle$ induced by the customer subset X. Starting at some customer x, cut the cycle H onto $l = \lceil n/q \rceil$ chains, where n = |X|, such that each chain, except maybe the last one, visits q customers exactly. For any chain obtained, connect its endpoints with the depot y directly constructing the set S(x) of l routes. Proceed with the similar procedure taking each other customer $x \in X$ as a staring point and output the route set

$$S_{\text{ITP}} = \arg\min\{w(S(x)) \colon x \in X\}$$

of the minimum cost. The following lemma [12] gives an upper bound for the cost of the obtained solution.

Lemma 2.

$$w(S_{\text{ITP}}) \le 2\left\lceil \frac{n}{q} \right\rceil \frac{\sum_{i=1}^{n} r_i}{n} + (1 - 1/q)w(H) \le \left(1 + \frac{q}{n}\right) \cdot \frac{2}{q} \sum_{i=1}^{n} r_i + (1 - 1/q)w(H).$$

In [17], we extend ITP heuristic to the case of the metric CVRPTW with uniform demand. For the sake of completeness, we present this technique in this paper in Algorithm 1, which can be easily adapted to the case of the metric CVRPTW with non-uniform splittable demand.

Algorithm 1. The ITP heuristic for the metric CVRPTW

Input: an instance of the metric CVRPTW defined by a complete graph $G(X \cup \{y\}, E, w)$, capacity q, and partition $X_1 \cup \ldots \cup X_p = X$

Parameter: β -approximation algorithm \mathcal{A}_{β} for the metric TSP

Output: an approximate solution S_{ITP} of the given CVRPTW instance

- 1: using \mathcal{A}_{ρ} obtain a ρ -approximate metric TSP solution H for the subgraph $G\langle X \rangle$
- 2: by shortcutting, split the cycle H into smaller cycles H_1, \ldots, H_p , s.t. H_j spans customers from X_j
- 3: for each cycle H_j do
- 4: for each $x \in X_j$ do
- 5: starting from the node x, split the cycle H_j into $l_j = \lceil |X_j|/q \rceil$ chains, s.t. each of them, except maybe one, spans q vertices
- 6: connecting endpoints of each chain with the depot y directly, construct a set S(x) of l_j routes
- 7: end for

8: put
$$S_j = \arg\min\{w(S(x)) \colon x \in X_j\}$$

9: end for

10: output the solution $S_{\text{ITP}} = S_1 \cup \ldots \cup S_p$.

Indeed, to obtain an ITP-based approximate solution in this case, we represent each customer x_i with demand d_i by the family of d_i its unit-demand copies and reduce the initial instance to the obtained instance of the metric CVRPTW with unit demand defined by the auxiliary graph on $D = 1 + \sum_{i=1}^{n} d_i$ nodes. For the weight $w(S_{\text{ITP}})$ of the resulting solution, we obtain the following bound.

Lemma 3.

$$w(S_{ITP}) \le 2 \cdot \left(\frac{2}{q} \sum_{i=1}^{n} d_i r_i\right) + pw(H) \le 2 \cdot \left(\frac{2}{q} \sum_{i=1}^{n} d_i r_i\right) + p\beta \cdot \mathrm{TSP}^*(X).$$

Proof. Indeed, applying Lemma 2 to each customer subset X_j , we obtain

$$w(S_j) \le \left(1 + \frac{q}{D_j}\right) \cdot \frac{2}{q} \sum_{x_i \in X_j} d_i r_i + (1 - 1/q) w(H_j) \le 2 \cdot \left(\frac{2}{q} \sum_{x_i \in X_j} d_i r_i\right) + w(H),$$

where $D_j = \sum_{x_i \in X_j} d_i$. Since $w(S_{\text{ITP}}) = \sum_{j=1}^p w(S_j)$ and $W(H) \leq \beta \text{TSP}^*(X)$, Lemma is proved.

Finally, we present the following fact taken from [1], which helps us to reduce the instance in question to the equivalent one with much less total demand and to prove a polynomial time complexity bound of the scheme proposed. Hereinafter, we call a feasible route \mathcal{R} non-trivial, if it visits at least two distinct customers, i.e. $|X(\mathcal{R})| > 1$. Otherwise, the route is called *trivial*.

Lemma 4. For any instance of the CVRPTW-SD, there exists an optimum solution $\mathcal{U} = \{\mathcal{R}_1, \ldots, \mathcal{R}_m\}$, such that, among its m routes, at most |X| are non-trivial.

Actually, Lemma 4 was proven in [1] for a more restricted case, i.e. the unitdemand CVRP free of the time windows constraints. But this result can be easily extended to the CVRPTW with splittable non-uniform demand. For the sake of brevity, we skip the proof this claim, postponing it to the forthcoming paper.

6 Approximation Scheme

It this section, we describe our approximation scheme following the overview presented in Sect. 4 and prove its correctness.

Suppose, we are given by $\varepsilon \in (0,1)$ and an instance of the Euclidean CVRPTW-SD on the plane defined by a complete node- and edge-weighted graph $G = (X \cup \{y\}), E, d, w)$, capacity $q \in \mathbb{N}$, and partition $X_1 \cup \ldots \cup X_p = X$ induced by an ordered set $\mathcal{T} = \{T_1, \ldots, T_p\}$ of consecutive disjoint time windows (see Sect. 3 for details). In this section, we show how to construct an $(1 + \varepsilon)$ -approximate solution of this instance.

6.1 Instance Preprocessing

Discuss the details of an approximation scheme proposed by us. Firstly, reordering the customers X by decreasing their distances r(x) to the depot y. Then, we can notify that some customers can be ignoring with respect to the fixed ε . We start with assigning to each customer x_i the distance $r_i = w(x_i, y)$ from the depot y and reordering them by descending the distances $r_1 \ge \ldots \ge r_n$. Then, we show that, during construction an $(1 + \varepsilon)$ -approximate solution we can ignore the customers, which are located sufficiently close to the depot in accordance to formula (2).

Lemma 5. Demand of all customers, for which $r_i \leq \rho$, can be serviced by routes of at most $\varepsilon \cdot \text{OPT}$ total cost.

Proof. Indeed, for any customer x_i , its demand d_i can be serviced by $\lceil d_i/q \rceil$ trivial routes, each of them has the cost $2r_i$. Therefore, for the total cost C_{ρ} , we have

$$C_{\rho} \leq \sum_{i=1}^{n} 2r_i \left\lceil \frac{d_i}{q} \right\rceil \leq 2\rho \cdot N \leq 2N \frac{\varepsilon r_1}{N} \leq 2\varepsilon r_1 \leq \varepsilon \cdot \text{OPT},$$

where the last inequality follows from Lemma 1. Lemma is proved.

In the sequel, without loss of generality we assume that the equation $\rho \leq r_i \leq r_1$ holds for any customer $x_i \in X$.

6.2 Rounding

In this section, we reduce the given instance to a special one, which we call *rounded*. To proceed with this reduction, we introduce the accuracy dependent grid induced by the circles centered at the depot y of radii

$$\rho_i = \rho \left(1 + \frac{\varepsilon}{q} \right)^i, \ 0 \le i \le \lceil \log_{1 + \frac{\varepsilon}{q}} N/\varepsilon \rceil$$
(4)

and rays spreading from y dividing each disk into $s = \lceil 2\pi q/\varepsilon \rceil$ equal circular sectors with central angle $2\pi/s$. We call *locations* the obtained intersection points between rays and circles. To any location, we assign p slots, by the number of different time windows. Then, we move each customer $x_i \in X_j$ to the j-th slot of the nearest location such that, each slot accumulates the total demand of all customers that are moved to it. Since the number of circles and rays are

$$\log_{1+\frac{\varepsilon}{q}} \frac{N}{\varepsilon} = \Theta\left(\frac{q}{\varepsilon}\log\frac{N}{\varepsilon}\right) \text{ and } \Theta\left(\frac{q}{\varepsilon}\right),$$

respectively, the total number of slots is $\Theta\left(p \cdot \left(\frac{q}{\varepsilon}\right)^2 \log \frac{N}{\varepsilon}\right)$.

Thus, we reduce the initial instance to the special instance of the Euclidean CVRPTW-SD (we call it *rounded*), whose customers are slots assigned to grid locations.

Lemma 6. The proposed reduction changes the cost of any solution by at most $\varepsilon \cdot \text{OPT}$.

Proof. Indeed, consider an arbitrary customer x with demand d(x) located at a distance r(x) from the depot y, between two neighboring circles of radii ρ_i and ρ_{i+1} (Fig. 1). It is easy to verify that the distance between x and the nearest location l has the following upper bound

$$||x - l||_2 \le p_1 + p_2 \le r(x)\alpha/2 + (\rho_{i+1} - \rho_i)/2.$$

Therefore,

$$||x - l||_2 \le r(x)\frac{\varepsilon}{q},$$

since $\alpha \leq \varepsilon/q$, $\rho_{i+1} = \rho_i(1 + \varepsilon/q)$, and $r(x) \geq r(x)$, by construction. Since an arbitrary feasible solution visits each customer x_i by at most d_i routes, the total change of its cost induced by moving all the customers to slots at the closest locations does not exceed

$$\varepsilon \cdot \frac{2}{q} \sum_{i=1}^{n} d_i r_i \le \varepsilon \cdot \text{OPT},$$

by Lemma 1. Lemma is proved.

Thanks to Lemma 6, in the rest of this paper, we can assume without loss of generality that each CVRPTW-SD instance considered is rounded.



Fig. 1. Moving the customer x to the slot at the nearest location l

6.3 Instance Decomposition

In this section, we show that any rounded instance of the CVRPTW-SD can be decomposed into an appropriate collection of subinstances, which can be solved in parallel, such that $(1 + \varepsilon)$ -approximate solution of the initial instance can be combined from the approximate solutions of the subinstances obtained.

We start this decomposition with partitioning the enclosing disk (of radius r_1) to rings, such that each ring (except maybe the most inner one) consists of $k = \lceil \log_{1+\frac{\varepsilon}{q}} \frac{5}{\varepsilon} \rceil$ consecutive circles. Then, each regular ring K has an inner radius $r_{in} = \rho(1 + \varepsilon/q)^i$ for some $0 \le i \le \lceil \log_{1+\frac{\varepsilon}{q}} N/\varepsilon \rceil$ and the outer one $r_{out} = r_{in}(1 + \varepsilon/q)^k$. By W(K) we denote a width of the ring K. Since

$$W(K) = r_{in} \left(\left(1 + \frac{\varepsilon}{q} \right)^{\lceil \log_{1+\frac{\varepsilon}{q}} \frac{5}{\varepsilon} \rceil} - 1 \right) \ge r_{in} \left(\left(1 + \frac{\varepsilon}{q} \right)^{\log_{1+\frac{\varepsilon}{q}} \frac{5}{\varepsilon}} - 1 \right)$$
$$= r_{in} \left(\frac{5}{\varepsilon} - 1 \right) \ge r_{in} \left(\frac{5}{\varepsilon} - \frac{1}{\varepsilon} \right) = 2r_{in} \frac{2}{\varepsilon},$$

we obtain the following upper bound

$$2r_{in} \le \frac{\varepsilon}{2} \cdot W(K) \tag{5}$$

for the length of the inner radius of any ring K in terms of its width W(K), which is important for the subsequent constructions.

At the second step, for a positive integer $a = \lceil (20p\beta + 4)/\varepsilon \rceil$ and some number $b \in \{0, \ldots, a-1\}$, whose choice will be explained later, we color all the rings obtained in white and gray, starting from the outer one, such that the ring K_i is painted gray, if $i \equiv b \pmod{a}$. Here β is an approximation factor of the algorithm used for solving the auxiliary TSP instances and the choice of b will be explained later, in Lemma 10.

In the sequel, we show that such a coloring leads to a successful decomposition of the initial rounded CVRPTW-SD instance. Let us discuss it in detail. First, we prove Lemma 7 that holds for much more general white-gray ring colorings. Indeed, by $\mathfrak{F}_1, \ldots, \mathfrak{F}_\alpha$ and $OPT(\mathfrak{F}_i)$ denote the maximal (by inclusion) families of consecutive white rings and the optimum value of the CVRPTW-SD subinstance induced by slots located in rings of the family \mathfrak{F}_i , respectively.

Lemma 7. For any white-gray coloring of rings obtained by the following rules: (i) any monochromatic pair of the adjacent rings is white; (ii) the outer ring is white as well, the following equation

$$\sum_{i=1}^{\alpha} \operatorname{OPT}(\mathfrak{F}_i) \le \left(1 + \frac{\varepsilon}{2}\right) \operatorname{OPT}$$

is valid.

Proof. Indeed, let $\mathcal{U} = \{\mathcal{R}_1, \ldots, \mathcal{R}_m\}$ be an arbitrary optimum solution of the initial rounded instance of the CVRPTW-SD. By the following recurrent procedure, transform any route $\mathcal{R} \in \mathcal{U}$ to an appropriate collection of routes, such that each new route visits the slots located in a single family of white rings exclusively. For the given route \mathcal{R} , consider the outermost white ring family visited by this route, say \mathfrak{F}_1 , and the adjacent gray ring K (Fig. 2). Including $2 \cdot l$ inner radii r_{in} and l chords of the ring K, split the route \mathcal{R} into subroutes $\mathcal{R}_g(1), \ldots, \mathcal{R}_g(l)$, each of them visits no slots outside \mathfrak{F}_1 and a single subroute \mathcal{R}_b located in the interior of the ring K. Thanks to Eq. (5) and the triangle inequality, such a transformation results in the increase of the transportation cost by at most

$$4 \cdot r_{in} \cdot l \le 2l \cdot \varepsilon/2 \cdot W(K) \le \varepsilon/2 \cdot w(\mathcal{R} \cap K),$$

where $w(\mathcal{R} \cap K)$ denotes the partial cost of the route \mathcal{R} related to its intersection with the ring K. Continuing this transformation procedure recursively



Fig. 2. Splitting of the route \mathcal{R} into $\mathcal{R}_g(1), \ldots, \mathcal{R}_g(l)$ and \mathcal{R}_b subroutes

(proceeding with the subroute \mathcal{R}_b and so on), we obtain that the total cost increasing caused by such a transformation for the route \mathcal{R} does not exceed

$$\frac{\varepsilon}{2} \cdot \sum_{j=1}^{\alpha} w(\mathcal{R} \cap K_j),$$

where the summation is performed over all gray rings $K_1 \ldots, K_{\alpha}$. Therefore, the total cost of the obtained routes is at most

$$w(\mathcal{U}) + \frac{\varepsilon}{2} \sum_{i=1}^{m} \sum_{j=1}^{\alpha} w(\mathcal{R}_i \cap K_j) \le (1 + \varepsilon/2) w(\mathcal{U}).$$

Lemma follows from the obvious observation that, for any family \mathfrak{F}_i , the optimum value $OPT(\mathfrak{F}_i)$ does not exceed the total cost of the subroutes produced by the above recursive procedure that visit this family.

For any gray ring K, by $\text{TSP}^*(K)$ we denote the optimum value of the Euclidean TSP for the slots located in this ring. Evidently, each $\text{TSP}^*(K)$ does not exceeds the optimum value of the TSP instance induced by all slots and the depot, we denote this value by TSP^* . The following lemma gives much more accurate bound.

Lemma 8. Let K_1, \ldots, K_{α} be gray rings. Then,

$$\sum_{i=1}^{\alpha} \mathrm{TSP}^*(K_i) \le (1 + \pi\varepsilon) \,\mathrm{TSP}^*.$$

Proof. Let H be an arbitrary minimum cost Hamiltonian cycle passing through all the slots and the depot, such that $w(H) = \text{TSP}^*$ (Fig. 3a). To obtain the desired bound, we employ the following recursive tour splitting procedure similar to the procedure provided in the proof of Lemma 7. We start with the outermost gray ring K and cut out segments of the cycle H that belong to this ring and its exterior (Fig. 3b). By $W_{ext}(K)$ denote their total cost. Further, without loss of generality, we can assume that each such a segment touches the inner circle of the ring K in two points. Therefore, the number of such points is even.

Connecting the adjacent points by chords and including the perfect matching as it is done in Fig. 4a, we construct the auxiliary 4-regular multi-graph having the Eulerian cycle E(K), which admits shortcutting to the Hamiltonian cycle H(K) containing all the aforementioned outer segments of the cycle H (Fig. 4b).

Again, taking into account Eq. (5) and the triangle inequality, obtain the upper bound for the cost w(H(K)) of the constructed cycle H(K)

$$w(H(K)) \le w(E(K)) \le W_{ext}(K) + 4\pi \cdot r_{in}$$

$$\le W_{ext}(K) + \pi\varepsilon \cdot W(K) \le W_{ext}(K) + \pi\varepsilon \cdot w(H \cap K),$$



Fig. 3. (a) the initial cycle (b) cutting out the outer segments



Fig. 4. (a) constructing the Eulerian cycle (b) shortcutting to the Hamiltonian cycle

where $w(H \cap K)$ denotes the cost of the segment of the cycle H that belongs to the ring K. Proceeding with this procedure recursively and summing over all the gray rings, we obtain the final bound

$$\sum_{i=1}^{\alpha} \operatorname{TSP}^{*}(K_{i}) \leq \sum_{i=1}^{\alpha} w(H(K_{i})) \leq (1 + \pi\varepsilon) w(H) = (1 + \pi\varepsilon) \operatorname{TSP}^{*}.$$

Lemma is proved.

Further, applying Lemma 8 twice to the alternating coloring, where each family \mathfrak{F}_i consists of a single ring, we estimate the total cost of the optimum Hamiltonan cycles for all rings obtained at the first step of instance decomposition.

Lemma 9. Let $\text{TSP}^*(K_i)$ be the optimum value for the Euclidean TSP instance enclosed in the ring K_i . Then, the following equation holds:

$$\sum_{i=1}^{k} \mathrm{TSP}^{*}(K_{i}) \leq 10 \cdot \mathrm{TSP}^{*}.$$

Proof. Indeed. Consider two alternative colorings. In the first one, we color gray each even ring, whilst, in the second one, each odd. Employing Lemma 8, and taking into account the additional assumption that the outermost ring K_1 cannot be gray, we obtain the following equation

$$\sum_{i=1}^{k} \operatorname{TSP}^{*}(K_{i}) = \sum_{i \equiv 0 \pmod{2}} \operatorname{TSP}^{*}(K_{i}) + \sum_{i \equiv 1 \pmod{2}} \operatorname{TSP}^{*}(K_{i})$$
$$\leq 2 (1 + \pi\varepsilon) \operatorname{TSP}^{*} + \operatorname{TSP}^{*}(K_{1}) \leq 2 (1 + \pi\varepsilon) \operatorname{TSP}^{*} + \operatorname{TSP}^{*} \leq 10 \cdot \operatorname{TSP}^{*},$$

since $\varepsilon < 1$. Lemma is proved.

In the sequel, for any gray ring, we will solve the associated subinstance by the ITP heuristic. The following lemma gives an upper bound for the total cost of these solutions.

Lemma 10. There exists a number $b \in \{1, ..., a\}$, such that the total cost of all *ITP* solutions for the subinstances enclosed in the gray rings is at most $\frac{\varepsilon}{2} \cdot \text{OPT}$.

Proof. Indeed, for any ring K, by $X_{slots}(K)$ and $S_{ITP}(K)$ denote the subset of slots enclosed in the ring K and the ITP-solution of the corresponding subinstance, respectively. Then,

$$w(S_{\text{ITP}}(K)) \le 2 \cdot \frac{2}{q} \sum_{x \in X_{slots}(K)} d(x)r(x) + p\beta \cdot \text{TSP}^*(K)$$

Therefore, by Lemmas 3, 9, and 1,

$$\sum_{b=0}^{a-1} \sum_{i\equiv b \pmod{a}} w(S_{\text{ITP}}(K_i)) \le 2 \cdot \frac{2}{q} \sum_{x \in X_{slots}} d(x)r(x) + p\beta \cdot \sum_{i=1}^k \text{TSP}^*(K_i)$$
$$\le 2 \cdot \text{OPT} + 10p\beta \cdot \text{TSP}^* \le (2 + 10p\beta)\text{OPT}.$$

Hence, there exists b, such that

$$\sum_{i\equiv b \pmod{a}} w(S_{\text{ITP}}(K_i)) \le \frac{2+10p\beta}{a} \text{OPT} \le \frac{\varepsilon}{2} \text{OPT},$$

by construction. Lemma is proved.

To complete the decomposition of the given instance, we perform white-gray coloring of the rings driven by the parameters a and b and obtain subinstances

defined by white families \mathfrak{F}_i and gray rings K_j . Hereinafter, we call them *white* and *gray*, respectively. Then, by Lemma 4, we reduce each subinstance with σ slots and an arbitrarily large demand to the equivalent one, whose total demand does not exceed $\sigma^2 q$. Finally, we find a $(1 + \varepsilon/2)$ -approximate solution and an ITP-solution of any reduced white and gray subinstance, respectively. Our first result follows straightforwardly from Lemmas 7 and 10.

Theorem 1. For any $\varepsilon \in (0,1)$, the proposed decomposition provides $(1 + \varepsilon)$ -approximate solution for the initial rounded CVRPTW-SD instance.

6.4 Approximate Algorithms for Subinstances

As we mentioned in Sect. 4, to find an approximate solution for an arbitrary white subinstance we apply as a black box the quasi-polynomial approximation scheme (QPTAS) proposed by Song et al. in [28], whilst, each gray subinstance we approximate with our recent modification [16,17] of the well-known ITP heuristic.

7 Time Complexity Bounds

As shown in Sect. 6, the proposed scheme consists of the following stages: preprocessing, rounding, instance decomposition and the main stage dealing with the approximation of white and gray subinstances.

It can be easily verified that the first three stages can be carried out in time $O(n \log n)$, where n is the number of distinct customers. To estimate time complexity of the final stage, recall that the Song's QPTAS and our modification of the ITP are developed for the case of CVRPTW with unit demand. Therefore, in our case, their complexity bounds should be represented in terms of the total customer demand D defining the instance in question, i.e. $O\left(D^{\log^{O(1/\varepsilon)}D}\right)$ and $O(D^3)$, respectively (see [16,28]).

Thanks to Lemma 4, for any subinstance (white or gray) obtained during the decomposition of the given rounded instance, its total demand $D = \sigma^2 q$, where σ is the number of slots engaged, which in turn is determined by the number of circles included into an appropriate family of white rings or to the gray ring. By construction, each ring contains

$$O\left(\log_{1+\frac{\varepsilon}{q}}\frac{1}{\varepsilon}\right) = O\left(\frac{q}{\varepsilon} \cdot \log\frac{1}{\varepsilon}\right)$$

circles, each of them consists of $O(pq/\varepsilon)$ slots. Therefore, for any gray subinstance,

$$\sigma = \sigma_g = O\left(\frac{pq^2}{\varepsilon^2} \cdot \log\frac{1}{\varepsilon}\right),\,$$

while any white instance is determined by

$$\sigma = \sigma_w = a \cdot \sigma_g = O\left(\frac{(pq)^2}{\varepsilon^3} \cdot \log \frac{1}{\varepsilon}\right)$$

slots. Further, the number I of white (or gray) subinstances is

$$I = O\left(\frac{\log \frac{N}{\varepsilon}}{a \log \frac{1}{\varepsilon}}\right) = O\left(\frac{\varepsilon}{p} \frac{\log \frac{N}{\varepsilon}}{\log \frac{1}{\varepsilon}}\right),$$

where N is defined by Eq. (2). Thus, we proved our second result.

Theorem 2. Time complexity of the proposed scheme is

$$O\left(I \cdot \mathcal{K}(p, q, \varepsilon) + n \log n\right),\tag{6}$$

where

$$\mathcal{K}(p,q,\varepsilon) = \left(\sigma_w^2 q\right)^{(\log(\sigma_w^2 q))^{O(1/\varepsilon)}} + (\sigma_g^2 q)^3.$$
(7)

Notice that the proposed scheme admits near to linear parallel speedup, since all the subinstances obtained at the stage of instance decomposition can be solved independently.

Corollary 1. For any fixed $\varepsilon \in (0,1)$, the running time of the proposed scheme does not exceed $O(n \log N)$, if $p = \Omega(1)$, $q = \Omega(1)$, and

$$\max\{p,q\} \le 2^{\log^{\delta} n} \tag{8}$$

for some $\delta = O(\varepsilon)$.

Proof. Fix an arbitrary $\varepsilon \in (0, 1)$ and obtain an upper bound for (6). Indeed, $I = O(\log N), \ \sigma_w^2 q = C p^4 q^5$ for some constant C > 0, and the first term in (7) dominates the second one. Then, Eq. (8) implies that, for $n \gg 1$

$$\log \sigma_w^2 q = \log C + 4\log p + 5\log q \le 10\log^{\delta} n \le \log^{2\delta} n.$$

Therefore,

$$\begin{aligned} \mathcal{K}(p,q,\varepsilon) &= 2^{(\log(Cp^4q^5))^{O(1/\varepsilon)}} \le 2^{(\log^{2\delta}n)^{O(1/\varepsilon)}} \\ &= 2^{(\log n)^{C_1\delta/\varepsilon}} = \left(2^{\log n}\right)^{\frac{\log^{C_1\delta/\varepsilon}n}{\log n}} \le 2^{\log n} = n \end{aligned}$$

any time, when $C_1\delta/\varepsilon \leq 1$, where C_1 is some positive constant, and n > 1. Hence, for the fixed ε ,

$$I \cdot \mathcal{K}(p, q, \varepsilon) + n \log n = O(n \log N).$$

Corollary is proved.

Corollary 2. For any fixed p and q the proposed scheme is EPTAS with time complexity $O\left(\left(\frac{1}{\varepsilon^8}\right)^{\left(\log \frac{1}{\varepsilon}\right)^{O(1/\varepsilon)}} \cdot \log N + n \log n\right).$

8 Conclusion

In this paper, perhaps for the first time for the Euclidean Capacitated Vehicle Routing Problem with Time Windows and non-uniform splittable demand, a polynomial time approximation scheme is proposed. The scheme is based on the instance decomposition framework developed in [1] and uses the QPTAS from [28] and our modification [16] of the Iterative Tour Partition as a black box. For any fixed $\varepsilon \in (0, 1)$ and the total customer demand D, the scheme finds a $(1+\varepsilon)$ approximate solution of the problem in time $O(n \log D)$ any time provided that $\max\{p,q\} \leq 2^{\log^{\delta} n}$ for some $\delta = O(\varepsilon)$. Furthermore, for any fixed capacity qand the number p of time windows, the proposed scheme is an EPTAS, which significantly outperforms by the time complexity bound the previous best result [17] for the CVRPTW on the Euclidean plane.

For future work we left the open questions related to a possible extension of the proposed scheme to an arbitrary finite dimension Euclidean space and to the case of non-splittable demand.

References

- Adamaszek, A., Czumaj, A., Lingas, A.: PTAS for k-tour cover problem on the plane rof moderately large values of k. Int. J. Found. Comput. Sci. 21(06), 893–904 (2010). https://doi.org/10.1142/S0129054110007623
- Arora, S.: Polynomial Time Approximation Schemes for Euclidean Traveling Salesman and other geometric problems. J. ACM 45, 753–782 (1998)
- Asano, T., Katoh, N., Tamaki, H., Tokuyama, T.: Covering points in the plane by k-tours: towards a polynomial time approximation scheme for general k. In: Proceedings of the Twenty-Ninth Annual ACM Symposium on Theory of Computing, STOC 1997, pp. 275–283. ACM, New York (1997). https://doi.org/10. 1145/258533.258602
- Becker, A., Klein, P.N., Saulpic, D.: A quasi-polynomial-time approximation scheme for vehicle routing on planar and bounded-genus graphs. In: Pruhs, K., Sohler, C. (eds.) 25th Annual European Symposium on Algorithms, ESA 2017, Vienna, Austria, 4–6 September 2017. LIPIcs, vol. 87, pp. 12:1–12:15. Schloss Dagstuhl - Leibniz-Zentrum fuer Informatik (2017). https://doi.org/10. 4230/LIPIcs.ESA.2017.12. http://www.dagstuhl.de/dagpub/978-3-95977-049-1
- Becker, A., Klein, P.N., Saulpic, D.: Polynomial-time approximation schemes for k-center, k-median, and capacitated vehicle routing in bounded highway dimension. In: Azar, Y., Bast, H., Herman, G. (eds.) 26th Annual European Symposium on Algorithms, ESA 2018, Helsinki, Finland, 20–22 August 2018. LIPIcs, vol. 112, pp. 8:1–8:15. Schloss Dagstuhl - Leibniz-Zentrum fuer Informatik (2018). https://doi.org/10.4230/LIPIcs.ESA.2018.8. http://www.dagstuhl. de/dagpub/978-3-95977-081-1
- Blocho, M., Czech, Z.: A parallel memetic algorithm for the vehicle routing problem with time windows. In: 2013 Eighth International Conference on P2P, Parallel, Grid, Cloud and Internet Computing, pp. 144–151 (2013). https://doi.org/10. 1109/3PGCIC.2013.28

- Cassettari, L., Demartini, M., Mosca, R., Revetria, R., Tonelli, F.: A multi-stage algorithm for a capacitated vehicle routing problem with time constraints. Algorithms 11(5) (2018). https://doi.org/10.3390/a11050069. http://www.mdpi.com/ 1999-4893/11/5/69
- Chen, X., Kong, Y., Dang, L., Hou, Y., Ye, X.: Exact and metaheuristic approaches for a bi-objective school bus scheduling problem. PLOS ONE 10(7), 1–20 (2015). https://doi.org/10.1371/journal.pone.0132600
- Dantzig, G., Ramser, J.: The truck dispatching problem. Manag. Sci. 6, 80–91 (1959)
- Das, A., Mathieu, C.: A quasipolynomial time approximation scheme for Euclidean capacitated vehicle routing. Algorithmica 73, 115–142 (2015). https://doi.org/10. 1007/s00453-014-9906-4
- 11. Gschwind, T., Irnich, S.: Effective handling of dynamic time windows and its application to solving the dial-a-ride problem. Transp. Sci. **49**(2), 335–354 (2015)
- Haimovich, M., Rinnooy Kan, A.H.G.: Bounds and heuristics for capacitated routing problems. Math. Oper. Res. 10(4), 527–542 (1985). https://doi.org/10.1287/moor.10.4.527
- Hashimoto, H., Yagiura, M.: A path relinking approach with an adaptive mechanism to control parameters for the vehicle routing problem with time windows. In: van Hemert, J., Cotta, C. (eds.) EvoCOP 2008. LNCS, vol. 4972, pp. 254–265. Springer, Heidelberg (2008). https://doi.org/10.1007/978-3-540-78604-7_22
- Khachai, M.Y., Dubinin, R.D.: Approximability of the vehicle routing problem in finite-dimensional Euclidean spaces. Proc. Steklov Inst. Math. 297(1), 117–128 (2017). https://doi.org/10.1134/S0081543817050133
- Khachai, M., Ogorodnikov, Y.: Polynomial time approximation scheme for the capacitated vehicle routing problem with time windows. Trudy instituta matematiki i mekhaniki UrO RAN 24(3), 233–246 (2018). https://doi.org/10.21538/0134-4889-2018-24-3-233-246
- Khachay, M., Ogorodnikov, Y.: Efficient PTAS for the Euclidean CVRP with time windows. In: van der Aalst, W.M.P., et al. (eds.) AIST 2018. LNCS, vol. 11179, pp. 318–328. Springer, Cham (2018). https://doi.org/10.1007/978-3-030-11027-7_30
- Khachay, M., Ogorodnikov, Y.: Improved polynomial time approximation scheme for capacitated vehicle routing problem with time windows. In: Evtushenko, Y., Jaćimović, M., Khachay, M., Kochetov, Y., Malkova, V., Posypkin, M. (eds.) OPTIMA 2018. CCIS, vol. 974, pp. 155–169. Springer, Cham (2019). https:// doi.org/10.1007/978-3-030-10934-9_12
- Khachay, M., Dubinin, R.: PTAS for the Euclidean capacitated vehicle routing problem in R^d. In: Kochetov, Y., Khachay, M., Beresnev, V., Nurminski, E., Pardalos, P. (eds.) DOOR 2016. LNCS, vol. 9869, pp. 193–205. Springer, Cham (2016). https://doi.org/10.1007/978-3-319-44914-2_16
- Khachay, M., Zaytseva, H.: Polynomial time approximation scheme for single-depot Euclidean capacitated vehicle routing problem. In: Lu, Z., Kim, D., Wu, W., Li, W., Du, D.-Z. (eds.) COCOA 2015. LNCS, vol. 9486, pp. 178–190. Springer, Cham (2015). https://doi.org/10.1007/978-3-319-26626-8_14
- Kumar, S., Panneerselvam, R.: A survey on the vehicle routing problem and its variants. Intell. Inf. Manag. 4, 66–74 (2012). https://doi.org/10.4236/iim.2012.43010
- Nalepa, J., Blocho, M.: Adaptive memetic algorithm for minimizing distance in the vehicle routing problem with time windows. Soft Comput. 20(6), 2309–2327 (2016). https://doi.org/10.1007/s00500-015-1642-4

- Necula, R., Breaban, M., Raschip, M.: Tackling dynamic vehicle routing problem with time windows by means of ant colony system. In: 2017 IEEE Congress on Evolutionary Computation (CEC), pp. 2480–2487 (2017). https://doi.org/10.1109/ CEC.2017.7969606
- Pace, S., Turky, A., Moser, I., Aleti, A.: Distributing fibre boards: a practical application of the heterogeneous fleet vehicle routing problem with time windows and three-dimensional loading constraints. Procedia Comput. Sci. 51, 2257–2266 (2015). https://doi.org/10.1016/j.procs.2015.05.382. International Conference on Computational Science, ICCS 2015
- Papadimitriou, C.: Euclidean TSP is NP-complete. Theor. Comput. Sci. 4, 237–244 (1977)
- Savelsbergh, M., van Woensel, T.: 50th anniversary invited article city logistics: challenges and opportunities. Transp. Sci. 50(2), 579–590 (2016). https://doi.org/ 10.1287/trsc.2016.0675
- Shen, L., Tao, F., Wang, S.: Multi-depot open vehicle routing problem with time windows based on carbon trading. Int. J. Environ. Res. Public Health 15(9), 2025 (2018). https://doi.org/10.3390/ijerph15092025
- Song, L., Huang, H.: The Euclidean vehicle routing problem with multiple depots and time windows. In: Gao, X., Du, H., Han, M. (eds.) COCOA 2017. LNCS, vol. 10628, pp. 449–456. Springer, Cham (2017). https://doi.org/10.1007/978-3-319-71147-8_31
- Song, L., Huang, H., Du, H.: Approximation schemes for Euclidean vehicle routing problems with time windows. J. Comb. Optim. **32**(4), 1217–1231 (2016). https:// doi.org/10.1007/s10878-015-9931-5
- Ting, C.K., Liao, X.L., Huang, Y.H., Liaw, R.T.: Multi-vehicle selective pickup and delivery using metaheuristic algorithms. Inf. Sci. 406–407, 146–169 (2017). https://doi.org/10.1016/j.ins.2017.04.001. http://www.sciencedirect.com/science/ article/pii/S0020025517306436
- Toth, P., Vigo, D.: Vehicle Routing: Problems, Methods, and Applications. MOS-SIAM Series on Optimization, 2nd edn. SIAM, Philadelphia (2014)
- 31. Vidal, T., Crainic, T.G., Gendreau, M., Prins, C.: A hybrid genetic algorithm with adaptive diversity management for a large class of vehicle routing problems with time-windows. Comput. Oper. Res. 40(1), 475–489 (2013). https://doi.org/ 10.1016/j.cor.2012.07.018