

Chapter 14

Semigroups of Steepest Descent for Differential Equations

The first problem in this chapter seeks to make the point that for a given linear transformation A on a finite-dimensional space to itself, an adjoint for A depends on a choice of inner products, one for the domain space and one for the range space.

Problem 204 Suppose that $A \in L(\mathbb{R}^2, \mathbb{R}^2)$ defined by

$$A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x + 2y \\ 3x + 4y \end{pmatrix}, \quad \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2.$$

Suppose also that in addition to the standard inner product $\langle \cdot, \cdot \rangle_{\mathbb{R}^2}$, one has a second inner product $\langle \cdot, \cdot \rangle_S$ defined by

$$\left\langle \begin{pmatrix} r \\ s \end{pmatrix}, \begin{pmatrix} u \\ v \end{pmatrix} \right\rangle_S = \left\langle \begin{pmatrix} r \\ s \end{pmatrix}, \begin{pmatrix} u \\ v \end{pmatrix} \right\rangle_{\mathbb{R}^2} + (r - s)(u - v), \quad \begin{pmatrix} u \\ v \end{pmatrix}, \begin{pmatrix} r \\ s \end{pmatrix} \in \mathbb{R}^2.$$

Find a linear transformation $B \in L(\mathbb{R}^2, \mathbb{R}^2)$ such that

$$\left\langle A \begin{pmatrix} u \\ v \end{pmatrix}, \begin{pmatrix} r \\ s \end{pmatrix} \right\rangle_{\mathbb{R}^2} = \left\langle \begin{pmatrix} u \\ v \end{pmatrix}, B \begin{pmatrix} r \\ s \end{pmatrix} \right\rangle_S, \quad \begin{pmatrix} u \\ v \end{pmatrix}, \begin{pmatrix} r \\ s \end{pmatrix} \in \mathbb{R}^2.$$

For the remainder of this chapter H denotes a Hilbert space. There are two objectives for the problems in this chapter. One is to describe an important class of semigroups. The other is to introduce a theory of steepest descent for partial differential equations.

Problem 205 Show that if f is a continuous linear function from H to \mathbb{R} (that is to say, a member of the dual space H^* of H), then there is a unique $y \in H$ so that

$$f(x) = \langle x, y \rangle_H, \quad x \in H. \tag{14.1}$$

Definition 15 Suppose that ϕ is a C^1 function from $H \rightarrow R$. The gradient of ϕ is the function $\nabla\phi : H \rightarrow R$ so that

$$\phi'(x)h = \langle h, (\nabla\phi)(x) \rangle_H, \quad x, h \in H.$$

For the rest of this chapter we suppose that the gradient $\nabla\phi$ is defined on all of H and $\nabla\phi$ is locally lipschitz, that is, if $x \in H$ there is $\delta, M > 0$ such that

$$\|(\nabla\phi)(w) - (\nabla\phi)(y)\|_H \leq M\|w - y\|_H$$

if $\|w - x\|, \|y - x\| \leq \delta$.

Problem 206 Suppose that $w > 0$, $x \in H$ and $z : [0, w] \rightarrow H$ so that

$$z(0) = x, \quad z'(t) = -(\nabla\phi)(z(t)), \quad t \in [0, w].$$

Show that

$$(\phi(z))'(t) = -\|(\nabla\phi)(z(t))\|^2, \quad t \in [0, w].$$

Problem 207 Show that, given $x \in H$, there is a unique function $z : [0, \infty) \rightarrow H$ such that

$$z(0) = x, \quad z'(t) = -(\nabla\phi)(z(t)), \quad t \in [0, \infty). \quad (14.2)$$

Denote by T_ϕ the semigroup generated by (14.2), i.e., if $x \in H$ and $s \geq 0$, then

$$T_\phi(s)x = z(s),$$

where z satisfies (14.2).

Problem 208 Show that if $x \in H$ and

$$u = \lim_{t \rightarrow \infty} T_\phi(t)x \text{ exists,} \quad (14.3)$$

then

$$(\nabla\phi)(u) = 0.$$

The study of limits in (14.3) is very important in the theory of semigroups. For many problems in the theory of differential equations in variational form (represented by a function ϕ) the critical points of ϕ are the solutions to the problem. In the notes in the last chapter there are additional references to applications. If a system of equations does not arise from a conventional variational form, one may often construct a function ϕ such that its zeros are solutions. This is illustrated by means of the following sequence of problems devoted to one of the simplest possible examples cast into a variational form: Find u with domain $[0, 1]$ so that

$$u' - u = 0. \quad (14.4)$$

We know that u satisfies (14.4) if and only if there is $c \in R$ such that

$$u(t) = ce^t, \quad t \in [0, 1]$$

but it is good to study a new method in a simple known case.

We can try to place (14.4) in a variational form by introducing ϕ such that

$$\phi(u) = \frac{1}{2} \int_0^1 (u' - u)^2, \quad u \in H. \quad (14.5)$$

But how do we choose H ?

Problem 209 Show that if $H = L_2([0, 1])$, then ϕ has as its domain a linear set only dense in H . In addition, show that ϕ is nowhere continuous.

Problem 210 What do you think about the choice $H = L_2([0, 1])$ for a space on which to try to minimize Φ ? Would a useful gradient be forthcoming if this choice is made?

The next problems introduce a Sobolev space which will serve us well. It is the simplest example of a Sobolev space, but the ideas in these problems carry over to very general cases. This provides an alternate, but equivalent, definition for $H^{1,2}([0, 1])$ given in Chapter 7.

Denote by G_1 the set

$$\left\{ \begin{pmatrix} u \\ u' \end{pmatrix} : u \in C^1([0, 1]) \right\}.$$

Problem 211 Show that G_1 is a linear subspace of $L_2([0, 1])^2$ with norm

$$\left\| \begin{pmatrix} f \\ g \end{pmatrix} \right\|_{L_2([0, 1])^2} = (\|f\|^2 + \|g\|^2)^{1/2}, \quad f, g \in C^1([0, 1]). \quad (14.6)$$

Problem 212 Denote by G_2 the closure, in $L_2([0, 1])^2$, of G_1 . Show that there are not two members of G_2 with the same first term.

Definition 16

$$H = H^{1,2}([0, 1])$$

denotes the space of all first terms of members of G_2 . If $f \in H$ with $\begin{pmatrix} f \\ g \end{pmatrix} \in G_2$, write f' for g and say that g is the generalized derivative of f . For norm in this space H take

$$\|f\|_H = (\|f\|_{L_2([0, 1])}^2 + \|f'\|_{L_2([0, 1])}^2)^{1/2}.$$

Problem 213 Can one justify defining g in the above definition as f' ? Show that if $f \in C^1([0, 1])$, then this definition is consistent with the usual one.

Problem 214 Show that if $f \in H^{1,2}$, then for some number c ,

$$f(x) = c + \int_0^x f', \quad x \in [0, 1].$$

Problem 215 Show that ϕ in (14.5) is continuous on H .

Problem 216 Find ϕ' for ϕ as in (14.5).

We want to find an expression for $\nabla\phi$ where ϕ is defined in (14.5).

Problem 217 Show that if

$$\begin{pmatrix} w \\ v \end{pmatrix} \in (L_2([0, 1]))^2$$

and

$$\left\langle \begin{pmatrix} u \\ u' \end{pmatrix}, \begin{pmatrix} w \\ v \end{pmatrix} \right\rangle_{L_2([0,1])^2} = 0, \quad \begin{pmatrix} u \\ u' \end{pmatrix} \in G_2,$$

then

$$v \in H, \quad w = v' \quad \text{and} \quad v(0) = 0 = v(1).$$

Problem 218 Construct the projection P of all of $L_2([0, 1])^2$ onto

$$\left\{ \begin{pmatrix} u \\ u' \end{pmatrix} : u \in H \right\}.$$

To do this, take $\begin{pmatrix} f \\ g \end{pmatrix} \in L_2([0, 1])^2$. Seek $u \in H$ such that

$$\left\| \begin{pmatrix} u \\ u' \end{pmatrix} - \begin{pmatrix} f \\ g \end{pmatrix} \right\|_{L_2([0,1])}^2$$

is minimum, that is, seek $u, v \in H$ such that

$$\begin{pmatrix} u \\ u' \end{pmatrix} + \begin{pmatrix} v' \\ v \end{pmatrix} = \begin{pmatrix} f \\ g \end{pmatrix} \quad \text{and} \quad v(0) = 0 = v(1). \quad (14.7)$$

In the notes there are references which contain extensive information on projections which one encounters in the construction of Sobolev gradients.

Problem 219 Solve the system (14.7). Note that, thanks to Problem 217, there is only one pair (u, v) which satisfies (14.7). Define

$$S(t) = \sinh(t); \quad C(t) = \cosh(t), \quad t \in R,$$

show that

$$u(t) = [C(1-t) \int_0^t (C(r)f(r) + S(r)g(r)) dr + C(t) \int_t^1 (C(1-r)f(r) - S(1-r)g(r)) dr] / S(1), \quad t \in [0, 1].$$

Problem 220 With ϕ as in (14.5), P as in Problem 218 and

$$\pi : L_2([0, 1])^2 \rightarrow L_2([0, 1])$$

defined by

$$\pi \begin{pmatrix} f \\ g \end{pmatrix} = f, \quad \begin{pmatrix} f \\ g \end{pmatrix} \in L_2([0, 1])^2,$$

show that

$$(\nabla\phi)(y) = \pi P \begin{pmatrix} y - y' \\ y' - y \end{pmatrix}, \quad y \in H. \quad (14.8)$$

Problem 221 Find a simple form for $\nabla\phi$ in Problem 220.

Problem 222 Search for an expression for the solution z of (14.2) using the gradient in Problem 221 and search for a form for u in (14.3).

Problem 223 Show that in Problem 221 a limit depends on the selection of $z(0)$ in (14.2).

Problem 224 Show that a limit u in Problem 221 is the nearest element to $z(0)$ in the norm of $H^{1,2}([0, 1])$ where z is as in (14.2).

Usually one cannot find an explicit form for the Sobolev gradient for ϕ . For many cases one can use the above ideas to try to prove that the limit u in (14.3) exists and is a zero of ϕ . In addition, one may try to follow a trajectory z numerically. Some of the problems which follow deal with existence of the limit u in (14.3).

Definition 17 Suppose ϕ is a function from a Hilbert space H into $[0, \infty)$ of class C^1 with a locally lipschitzian gradient and $\Omega \subset H$. One says that ϕ satisfies a gradient inequality on Ω if there is $c > 0$ such that

$$\|(\nabla\phi)(x)\|_H \geq c(\phi(x))^{1/2}, \quad \text{if } x \in \Omega. \quad (14.9)$$

Problem 225 Suppose H is a Hilbert space, ϕ a function from H to $[0, \infty)$ such that $\nabla\phi$ is locally lipschitz, $x \in H$, and z the unique solution of

$$z(0) = x, \quad z'(t) = -(\nabla\phi)(z(t)), \quad t \geq 0.$$

Suppose also that $\Omega \subset H$ is such that ϕ satisfies a gradient inequality (14.9) in Ω with constant c . Show that if

$$\text{range}(z) \subset \Omega,$$

then

$$(\phi(z))'(t) \leq -c^2\phi(z(t)), \quad t \geq 0. \quad (14.10)$$

Problem 226 Show that if (14.10) holds, then

$$\phi(z(t)) \leq \phi(z(a))e^{-c^2(t-a)}, \quad t \geq a.$$

Problem 227 Show that for z as in Problem 225,

$$u = \lim_{t \rightarrow \infty} z(t) \text{ exists}$$

and

$$\phi(u) = 0.$$