11 Spectrum of compact operators

We begin with some general results on the spectrum of continuous operators (11.1–11.5), where we always assume that X is a Banach space over \mathbb{C} (!), i.e. $\mathbb{K} = \mathbb{C}$, and that $T \in \mathscr{L}(X)$ (for the real case see 11.14). The main topic of this chapter is the Riesz-Schauder theory on the spectrum of compact operators (theorem 11.9).

11.1 Spectrum. We define the *resolvent set* of T by

$$\varrho(T) := \left\{ \lambda \in \mathbb{C} ; \ \mathscr{N}(\lambda \mathrm{Id} - T) = \{0\} \text{ and } \mathscr{R}(\lambda \mathrm{Id} - T) = X \right\}$$

and the **spectrum** of T by

$$\sigma(T) := \mathbb{C} \setminus \varrho(T) \,.$$

The spectrum can be decomposed into the *point spectrum*

$$\sigma_p(T) := \left\{ \lambda \in \sigma(T) \; ; \; \mathscr{N}(\lambda \mathrm{Id} - T) \neq \{0\} \right\} \; ,$$

the continuous spectrum

$$\sigma_c(T) := \left\{ \lambda \in \sigma(T) \; ; \; \mathscr{N}(\lambda \mathrm{Id} - T) = \{0\} \text{ and} \\ \mathscr{R}(\lambda \mathrm{Id} - T) \neq X, \; \text{ but } \overline{\mathscr{R}(\lambda \mathrm{Id} - T)} = X \right\}$$

and the $residual \ spectrum$

$$\sigma_r(T) := \left\{ \lambda \in \sigma(T) ; \ \mathscr{N}(\lambda \mathrm{Id} - T) = \{0\} \ \text{and} \ \overline{\mathscr{R}(\lambda \mathrm{Id} - T)} \neq X \right\}.$$

11.2 Remarks.

(1) It holds that $\lambda \in \rho(T)$ if and only if $\lambda \text{Id} - T : X \to X$ is bijective. The inverse mapping theorem 7.8 yields that this is equivalent to the existence of

$$R(\lambda;T) := (\lambda \mathrm{Id} - T)^{-1} \in \mathscr{L}(X).$$

The inverse $R(\lambda; T)$ is called the **resolvent** of T in λ and as a function of λ is called the **resolvent function**.

(2) $\lambda \in \sigma_p(T)$ is equivalent to:

There exists an
$$x \neq 0$$
 with $Tx = \lambda x$.

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 λ is then called an *eigenvalue* and x an *eigenvector* of T. If X is a function space, then x is also called an *eigenfunction*. The subspace $\mathscr{N}(\lambda \mathrm{Id} - T)$ is the *eigenspace* of T corresponding to the eigenvalue λ . The eigenspace is a T-invariant subspace. (A subspace $Y \subset X$ is called **T-invariant** if $T(Y) \subset Y$.)

11.3 Theorem. The resolvent set $\varrho(T)$ is open and the resolvent function $\lambda \mapsto R(\lambda;T)$ is a complex analytic map from $\varrho(T)$ to $\mathscr{L}(X)$. It holds that

$$||R(\lambda; T)||^{-1} \le \operatorname{dist}(\lambda, \sigma(T)) \quad \text{for } \lambda \in \varrho(T).$$

Remark: A map $F: D \to Y$, with $D \subset \mathbb{C}$ open and Y a Banach space, is called *complex analytic* if for every $\lambda_0 \in D$ there exists a ball $B_{r_0}(\lambda_0) \subset D$ such that $F(\lambda)$ for $\lambda \in B_{r_0}(\lambda_0)$ can be written as a power series in $\lambda - \lambda_0$ with coefficients in Y. Complex analytic maps are holomorphic (see A10.1).

Proof. Let $\lambda \in \varrho(T)$. Then we have for $\mu \in \mathbb{C}$ that

$$(\lambda - \mu)$$
Id $-T = (\lambda$ Id $-T) \underbrace{(Id - \mu R(\lambda; T))}_{=: S(\mu)}$.

It follows from 5.7 that $S(\mu)$ is invertible if

$$\|\mu\| \cdot \|R(\lambda;T)\| < 1,$$

and then $\lambda - \mu \in \rho(T)$, with

$$R(\lambda - \mu; T) = S(\mu)^{-1} R(\lambda; T) = \sum_{k=0}^{\infty} \mu^k R(\lambda; T)^{k+1}$$

Setting $d := \|R(\lambda;T)\|^{-1}$ yields that $B_d(\lambda) \subset \varrho(T)$, i.e. $\operatorname{dist}(\lambda, \sigma(T)) \geq d$.

11.4 Theorem. The spectrum $\sigma(T)$ is compact and nonempty (if $X \neq \{0\}$), with

$$\sup_{\lambda \in \sigma(T)} |\lambda| = \lim_{m \to \infty} \|T^m\|^{\frac{1}{m}} \le \|T\|.$$

This value is called the *spectral radius* of T.

Proof. Let $\lambda \neq 0$. We have from 5.7 that $\operatorname{Id} - \frac{T}{\lambda}$ is invertible if $\left\| \frac{T}{\lambda} \right\| < 1$, i.e. if $|\lambda| > ||T||$, and then

$$R(\lambda;T) = \frac{1}{\lambda} \left(\mathrm{Id} - \frac{T}{\lambda} \right)^{-1} = \sum_{k=0}^{\infty} \frac{T^k}{\lambda^{k+1}}$$

This shows that

$$r := \sup_{\lambda \in \sigma(T)} |\lambda| \le ||T||.$$

Since

$$\lambda^m \mathrm{Id} - T^m = (\lambda \mathrm{Id} - T)p_m(T) = p_m(T)(\lambda \mathrm{Id} - T)$$

with

$$p_m(T) := \sum_{i=0}^{m-1} \lambda^{m-1-i} T^i,$$

we conclude that

$$\begin{array}{lll} \lambda \in \sigma(T) & \Longrightarrow & \lambda^m \in \sigma(T^m) \\ & \Longrightarrow & |\lambda^m| \leq \|T^m\| & (\text{recall the bound established above}) \\ & \Longrightarrow & |\lambda| \leq \|T^m\|^{\frac{1}{m}} \,. \end{array}$$

This proves that

$$r \le \liminf_{m \to \infty} \|T^m\|^{\frac{1}{m}}.$$

Next we show that

$$r \ge \limsup_{m \to \infty} \|T^m\|^{\frac{1}{m}} \,.$$

We recall from 11.3 that $R(\cdot; T)$ is a complex analytic map in $\mathbb{C} \setminus \overline{\mathbb{B}_r(0)}$ (if $\sigma(T)$ is empty, in \mathbb{C}). Hence, by Cauchy's integral theorem (see A10.1),

$$\frac{1}{2\pi \mathrm{i}} \int_{\partial \mathrm{B}_{s}(0)} \lambda^{j} R(\lambda; T) \,\mathrm{d}\lambda$$

is independent of s for $j \ge 0$ and s > r. However, if we choose s > ||T||, then we obtain with the help of the representation of $R(\lambda; T)$ at the beginning of the proof that this integral is equal to

$$= \frac{1}{2\pi \mathrm{i}} \int_{\partial \mathrm{B}_{s}(0)} \sum_{k=0}^{\infty} \lambda^{j-k-1} T^{k} \,\mathrm{d}\lambda = \frac{1}{2\pi} \sum_{k=0}^{\infty} s^{j-k} \left(\int_{0}^{2\pi} e^{\mathrm{i}\theta(j-k)} \,\mathrm{d}\theta \right) T^{k}$$
$$= \sum_{k=0}^{\infty} s^{j-k} \delta_{j,k} T^{k} = T^{j} \,.$$

Hence, for $j \ge 0$ and s > r,

$$\left\|T^{j}\right\| = \frac{1}{2\pi} \left\| \int_{\partial \mathcal{B}_{s}(0)} \lambda^{j} R(\lambda; T) \,\mathrm{d}\lambda \right\| \le s^{j+1} \sup_{|\lambda|=s} \left\|R(\lambda; T)\right\|.$$

Consequently we obtain for s > r and every subsequence $j \to \infty$ that

$$\left\|T^{j}\right\|^{\frac{1}{j}} \leq s \cdot \left(s \sup_{|\lambda|=s} \left\|R(\lambda;T)\right\|\right)^{\frac{1}{j}} \longrightarrow s \text{ or } 0,$$

and hence

$$\limsup_{j \to \infty} \left\| T^j \right\|^{\frac{1}{j}} \le s$$

As this holds for all s > r, we obtain the desired result on the spectral radius. In addition, if $\sigma(T)$ was empty, we would obtain for j = 0 and as $s \searrow 0$ that

$$\|\mathrm{Id}\| \leq s \cdot \sup_{|\lambda| \leq 1} \|R(\lambda;T)\| \longrightarrow 0,$$

i.e. Id = 0, and so $X = \{0\}$.

11.5 Remarks.

(1) If dim $X < \infty$, then $\sigma(T) = \sigma_p(T)$.

(2) If dim $X = \infty$ and $T \in \mathscr{K}(X)$, then $0 \in \sigma(T)$. But in general 0 is not an eigenvalue.

Proof (1). If $\lambda \in \sigma(T)$, then $\lambda \operatorname{Id} - T$ is not bijective, and so, as dim $X < \infty$, it is also not injective, i.e. $\lambda \in \sigma_p(T)$.

Proof (2). Let $T \in \mathscr{K}(X)$ and assume that $0 \in \varrho(T)$. Then (see 11.2(1)) $T^{-1} \in \mathscr{L}(X)$, and (see 10.3) so $\mathrm{Id} = T^{-1}T \in \mathscr{K}(X)$, which on recalling 4.10 implies that X is finite-dimensional.

Example without eigenvalue 0: The operator $T: C^0([0,1]) \to C^1([0,1])$ in 5.6(3) is injective. As an operator in $\mathscr{L}(C^0([0,1]))$ it is a compact operator in $\mathscr{K}(C^0([0,1]))$, by theorem 10.6.

In the following we are interested in the point spectrum $\sigma_p(T)$ of an operator $T \in \mathscr{L}(X)$, i.e. we consider the *eigenvalue problem* corresponding to T: For a given $y \in X$ we look for all solutions $\lambda \in \mathbb{K}$ and $x \in X$ to

$$Tx - \lambda x = y.$$

If $\lambda \in \varrho(T)$, then there exists a uniquely determined solution x to this equation. If $\lambda \in \sigma_p(T)$, then the solution, if one exists, is not unique, i.e. on setting $A_{\lambda} := \lambda \operatorname{Id} - T$ we see that adding an element from $\mathscr{N}(A_{\lambda})$ to a solution yields another solution (for $T \in \mathscr{K}(X)$ see also 11.11). On the other hand, the condition $y \in \mathscr{R}(A_{\lambda})$ needs to be satisfied for a solution to the eigenvalue problem to exist at all. An important class of operators A_{λ} are those operators for which both the number of degrees of freedom for the solution x and the number of side conditions on y are finite:

11.6 Fredholm operators. A map $A \in \mathscr{L}(X;Y)$ is called a *Fredholm operator* if:

- (1) $\dim \mathcal{N}(A) < \infty$,
- (2) $\mathscr{R}(A)$ is closed,
- (3) $\operatorname{codim} \mathscr{R}(A) < \infty$.

The *index* of a Fredholm operator is defined by

$$\operatorname{ind}(A) := \dim \mathscr{N}(A) - \operatorname{codim} \mathscr{R}(A).$$

Remark: The *codimension* of the image of A being finite means that $Y = \mathscr{R}(A) \oplus Y_0$ for a finite-dimensional subspace $Y_0 \subset Y$. Then $\operatorname{codim} \mathscr{R}(A) := \dim Y_0$ is independent of the choice of Y_0 : indeed, if $Y_1 \subset Y$ is a subspace with $\mathscr{R}(A) \cap Y_1 = \{0\}$, then Y_1 is finite-dimensional with $\dim Y_1 \leq \dim Y_0$, with equality if and only if $Y = \mathscr{R}(A) \oplus Y_1$.

Proof. We have from (2) and 4.9, respectively, that $Z := \mathscr{R}(A)$ and Y_0 are closed subspaces. Now let $P \in \mathscr{P}(Y)$ be the projection onto Y_0 with $Z = \mathscr{N}(P)$, as in 9.15. Then

 $S := P|_{Y_1} : Y_1 \to Y_0$ is linear and injective,

because if $y \in Y_1$ with P(y) = 0, then $y \in Z \cap Y_1 = \{0\}$. As Y_0 is finite-dimensional, it follows that Y_1 is also finite-dimensional, with dim $Y_1 \leq \dim Y_0$.

If $Y = Z \oplus Y_1$, then it follows as above (interchange Y_0 and Y_1) that dim $Y_0 \leq \dim Y_1$, and so dim $Y_1 = \dim Y_0$. Conversely, if this holds, then Sis bijective. For $x \in Y$ we then have that $y := S^{-1}Px \in Y_1$ with $Py = SS^{-1}Px = Px$, and so $x - y \in \mathcal{N}(P) = Z$, which proves that $Y = Z \oplus Y_1$.

11.7 Example. Let $X = W^{1,2}(\Omega)$ and $Y = W^{1,2}(\Omega)'$. Then $A: W^{1,2}(\Omega) \to W^{1,2}(\Omega)'$, defined by

$$\langle v, Au \rangle_{W^{1,2}} := \int_{\Omega} \sum_{i,j} \partial_i v \cdot a_{ij} \partial_j u \, \mathrm{dL}^n \quad \text{for } u, v \in W^{1,2}(\Omega)$$

is a weak elliptic differential operator with Neumann boundary conditions. (We consider the homogeneous case in 6.5(2) with $h_i = 0$ and b = 0.) We have from 8.18(2) (where the symmetry $a_{ij} = a_{ji}$ was assumed) that:

The null space $\mathscr{N}(A)$ consists of the constant functions, and therefore $\dim \mathscr{N}(A) = 1$. The image of A is $\mathscr{R}(A) = \{F \in Y; \langle 1, F \rangle_{W^{1,2}} = 0\}$, and so it is closed, with $\operatorname{codim} \mathscr{R}(A) = 1$. It holds that

$$Y = \mathscr{R}(A) \oplus \operatorname{span}\{F_0\}, \quad \text{where} \quad \langle v, F_0 \rangle_{W^{1,2}} := \int_{\Omega} v \, \mathrm{dL}^n$$

Hence A is a Fredholm operator with index 0.

Observe: For the homogeneous Dirichlet problem (see 10.14(2)) the operator $A: W_0^{1,2}(\Omega) \to W_0^{1,2}(\Omega)'$ is an isomorphism.

A large class of Fredholm operators with Y = X is given by compact perturbations of the identity (see also 12.8):

11.8 Theorem. Let $T \in \mathscr{K}(X)$. Then A := Id - T is a Fredholm operator with index 0. We prove this in several steps:

- (1) $\dim \mathcal{N}(A) < \infty$,
- (2) $\mathscr{R}(A)$ is closed,
- (3) $\mathcal{N}(A) = \{0\} \implies \mathscr{R}(A) = X,$
- (4) $\operatorname{codim} \mathscr{R}(A) \leq \dim \mathscr{N}(A),$
- (5) $\dim \mathcal{N}(A) \leq \operatorname{codim} \mathcal{R}(A)$.

Proof (1). On noting that Ax = 0 is equivalent to x = Tx, we have that $B_1(0) \cap \mathcal{N}(A) \subset T(B_1(0))$, i.e. the unit ball in $\mathcal{N}(A)$ is precompact, and so 4.10 yields that $\mathcal{N}(A)$ is finite-dimensional.

Proof (2). Let $x \in \overline{\mathscr{R}(A)}$ and let $Ax_n \to x$ as $n \to \infty$. We may assume without loss of generality that

 $||x_n|| \le 2 d_n$ with $d_n := \operatorname{dist}(x_n, \mathcal{N}(A)),$

because otherwise we choose $a_n \in \mathcal{N}(A)$ with $||x_n - a_n|| \leq 2 \operatorname{dist}(x_n, \mathcal{N}(A))$ and then proceed with $\tilde{x}_n := x_n - a_n$, where

$$\operatorname{dist}(\widetilde{x}_n, \mathcal{N}(A)) = \operatorname{dist}(x_n, \mathcal{N}(A)).$$

First we assume that $d_n \to \infty$ for a subsequence $n \to \infty$. Setting

$$y_n := \frac{x_n}{d_n}$$
 it holds that $Ay_n = \frac{Ax_n}{d_n} \to 0$

as $n \to \infty$. Noting that the y_n are bounded and recalling that T is compact yields that there exists a subsequence such that $Ty_n \to y$ as $n \to \infty$. It follows that

$$y_n = Ay_n + Ty_n \to y_1$$

and so, by the continuity of A,

$$Ay = \lim_{n \to \infty} Ay_n = 0.$$

Hence $y \in \mathcal{N}(A)$, which implies that

$$||y_n - y|| \ge \operatorname{dist}(y_n, \mathscr{N}(A)) = \operatorname{dist}\left(\frac{x_n}{d_n}, \mathscr{N}(A)\right) = \frac{\operatorname{dist}(x_n, \mathscr{N}(A))}{d_n} = 1,$$

a contradiction. This shows that the d_n are bounded, and so are the x_n . For a subsequence we then have that $Tx_n \to z$ as $n \to \infty$, and so

$$x \leftarrow Ax_n = A(Ax_n + Tx_n) \longrightarrow A(x+z),$$

which means that $x \in \mathscr{R}(A)$.

Proof (3). Assume that there exists an $x \in X \setminus \mathscr{R}(A)$. Then

$$A^n x \in \mathscr{R}(A^n) \setminus \mathscr{R}(A^{n+1}) \quad \text{ for all } n \ge 0,$$

because otherwise $A^n x = A^{n+1}y$ for some y, then $A^n(x - Ay) = 0$, and from $\mathcal{N}(A) = \{0\}$ it then would follow (inductively) that x - Ay = 0, i.e $x \in \mathscr{R}(A)$, a contradiction. In addition $\mathscr{R}(A^{n+1})$ is closed, on noting that

$$A^{n+1} = (\mathrm{Id} - T)^{n+1} = \mathrm{Id} + \underbrace{\sum_{k=1}^{n+1} \binom{n+1}{k} (-T)^k}_{\in \mathscr{K}(X) \text{ on recalling 10.3}},$$

and so (2) yields that $\mathscr{R}(A^{n+1})$ is closed. Hence there exists an $a_{n+1} \in \mathscr{R}(A^{n+1})$ with

$$0 < ||A^{n}x - a_{n+1}|| \le 2 \operatorname{dist}(A^{n}x, \mathscr{R}(A^{n+1})).$$

Now consider

$$x_n := \frac{A^n x - a_{n+1}}{\|A^n x - a_{n+1}\|} \in \mathscr{R}(A^n) \,.$$

We have that

$$\operatorname{dist}(x_n, \mathscr{R}(A^{n+1})) \ge \frac{1}{2}, \qquad (11-4)$$

because for $y \in \mathscr{R}(A^{n+1})$

$$||x_n - y|| = \frac{||A^n x - (a_{n+1} + ||A^n x - a_{n+1}||y)||}{||A^n x - a_{n+1}||}$$

$$\geq \frac{\operatorname{dist}(A^n x, \mathscr{R}(A^{n+1}))}{||A^n x - a_{n+1}||} \geq \frac{1}{2}.$$

For m > n, we have $Ax_n + x_m - Ax_m \in \mathscr{R}(A^{n+1})$, and hence (11-4) implies that

$$||Tx_n - Tx_m|| = ||x_n - (Ax_n + x_m - Ax_m)|| \ge \frac{1}{2}$$

Hence $(Tx_n)_{n \in \mathbb{N}}$ contains no convergent subsequence, even though $(x_n)_{n \in \mathbb{N}}$ is a bounded sequence. This is a contradiction to the compactness of T.

Proof (4). By (1), the number $n := \dim \mathcal{N}(A)$ is finite. Let $\{x_1, \ldots, x_n\}$ be an arbitrary basis of $\mathcal{N}(A)$. If we assume that the claimed inequality is false, then there exist linearly independent vectors y_1, \ldots, y_n , such that $\operatorname{span}\{y_1, \ldots, y_n\} \oplus \mathscr{R}(A)$ is a proper subspace of X. Moreover, 9.16(1) yields the existence of $x'_1, \ldots, x'_n \in X'$ with

$$\langle x_l, x'_k \rangle = \delta_{k,l}$$
 for $k, l = 1, \dots, n$.

Setting

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$$\widetilde{T}x := Tx + \sum_{k=1}^{n} \langle x, x'_k \rangle y_k$$

then defines an operator $\widetilde{T} \in \mathscr{K}(X)$, indeed, T is compact and $\widetilde{T} - T$ has a finite-dimensional image. In addition, $\mathscr{N}(\widetilde{A}) = \{0\}$, where $\widetilde{A} := \mathrm{Id} - \widetilde{T}$, because $\widetilde{A}x = 0$ implies, on recalling the choice of the y_k , that Ax = 0 and $\langle x, x'_k \rangle = 0$ for $k = 1, \ldots, n$. Therefore $x \in \mathscr{N}(A)$, and hence there exists a representation

$$x = \sum_{k=1}^{n} \alpha_k x_k$$
, and so $0 = \langle x, x'_l \rangle = \sum_{k=1}^{n} \alpha_k \langle x_k, x'_l \rangle = \alpha_l$

for l = 1, ..., n, which yields that x = 0. On applying (3) to the operator A, it follows that $\mathscr{R}(\widetilde{A}) = X$. On noting that $\widetilde{A}x_l = -y_l$ for l = 1, ..., n and that

$$\widetilde{A}\left(x - \sum_{l=1}^{n} \langle x, x_{l}' \rangle x_{l}\right) = Ax \quad \text{for all } x \in X,$$

we conclude that $X = \mathscr{R}(\widetilde{A}) \subset \operatorname{span}\{y_1, \ldots, y_n\} \oplus \mathscr{R}(A)$, a contradiction to the above property.

Proof (5). We have from (4) that $m := \operatorname{codim} \mathscr{R}(A) \le n := \dim \mathscr{N}(A)$.

First we reduce the claim to the case m = 0. To this end, choose x_1, \ldots, x_n and x'_1, \ldots, x'_n as in the proof of (4) and y_1, \ldots, y_m with

$$X = \operatorname{span}\{y_1, \ldots, y_m\} \oplus \mathscr{R}(A)$$
 .

As in the proof of (4), the operator

$$x \longmapsto \widetilde{T}x := Tx + \sum_{k=1}^{m} \langle x, x'_k \rangle y_k$$

is compact and $\widetilde{A} := \operatorname{Id} - \widetilde{T}$ is surjective with $\mathscr{N}(\widetilde{A}) = \operatorname{span}\{x_i; m < i \leq n\}$. We need to show that $\mathscr{N}(\widetilde{A}) = \{0\}$. Hence the claim is reduced to the case m = 0.

In the case m = 0 it holds that $\mathscr{R}(A) = X$. We assume that there exists an $x_1 \in \mathscr{N}(A) \setminus \{0\}$. The surjectivity of A then yields that we can inductively choose $x_k \in X$, $k \ge 2$, with $Ax_k = x_{k-1}$. Then $x_k \in \mathscr{N}(A^k) \setminus \mathscr{N}(A^{k-1})$. It follows from the theorem on the almost orthogonal element that there exists a $z_k \in \mathscr{N}(A^k)$ with $||z_k|| = 1$ and $dist(z_k, \mathscr{N}(A^{k-1})) \ge \frac{1}{2}$. For l < k this implies that $Az_k + z_l - Az_l \in \mathscr{N}(A^{k-1})$, and so the choice of z_k yields that

$$||Tz_k - Tz_l|| = ||z_k - (Az_k + z_l - Az_l)|| \ge \frac{1}{2}.$$

This shows that $\{Tz_k; k \in \mathbb{N}\}$ contains no convergent subsequence. This is a contradiction to the sequence $\{z_k; k \in \mathbb{N}\}$ being bounded and the operator T being compact.

A second possible proof for m = 0 is as follows: We start with a decomposition $X = \widetilde{X} \oplus \mathcal{N}(A)$ with a closed subspace \widetilde{X} (this follows from (1) and 9.16(2) for $Y = \{0\}$). Then $A : \widetilde{X} \to X$ is bijective, and so 7.8 yields that $\widetilde{A} := (A|_{\widetilde{X}})^{-1} : X \to \widetilde{X}$ is continuous. Now consider \widetilde{A} as an element in $\mathscr{L}(X)$. Then $\widetilde{T} := \mathrm{Id} - \widetilde{A} \in \mathscr{K}(X)$, because if $\{x_k; k \in \mathbb{N}\}$ is bounded in X, then so is $\{\widetilde{A}x_k; k \in \mathbb{N}\}$, and hence there exists a subsequence with $T\widetilde{A}x_k \to x$ as $k \to \infty$. On the other hand,

$$T\widetilde{A}x_k = (\mathrm{Id} - A)\widetilde{A}x_k = \widetilde{A}x_k - x_k = -\widetilde{T}x_k.$$

Now (3) implies that $\mathscr{R}(\widetilde{A}) = X$, i.e. $\mathscr{N}(A) = \{0\}$.

A further possible proof of (5) will be given in 12.7.

The fundamental theorem of this chapter is the

11.9 Spectral theorem for compact operators (Riesz-Schauder). For every operator $T \in \mathcal{K}(X)$ it holds that:

(1) The set $\sigma(T) \setminus \{0\}$ consists of countably (finitely or infinitely) many eigenvalues with 0 as the only possible cluster point. So if $\sigma(T)$ contains infinitely many elements, then $\sigma(T) = \sigma_p(T) \cup \{0\}$, hence 0 is a cluster point of $\sigma(T)$.

(2) For $\lambda \in \sigma(T) \setminus \{0\}$

$$1 \le n_{\lambda} := \max \left\{ n \in \mathbb{N} ; \mathcal{N}\left((\lambda \mathrm{Id} - T)^{n-1} \right) \ne \mathcal{N}\left((\lambda \mathrm{Id} - T)^{n} \right) \right\} < \infty.$$

The number $n_{\lambda} \in \mathbb{N}$ is called the *order* (or *index*) of λ and dim $\mathcal{N}(\lambda \mathrm{Id} - T)$ is called the *multiplicity* of λ .

(3) *Riesz decomposition.* For $\lambda \in \sigma(T) \setminus \{0\}$

$$X = \mathscr{N}\left((\lambda \mathrm{Id} - T)^{n_{\lambda}}\right) \oplus \mathscr{R}\left((\lambda \mathrm{Id} - T)^{n_{\lambda}}\right).$$

Both subspaces are closed and T-invariant, and the *characteristic sub*space $\mathcal{N}((\lambda \mathrm{Id} - T)^{n_{\lambda}})$ is finite-dimensional.

(4) For $\lambda \in \sigma(T) \setminus \{0\}$ it holds that $\sigma(T|_{\mathscr{R}((\lambda \operatorname{Id} - T)^{n_{\lambda}})}) = \sigma(T) \setminus \{\lambda\}$.

(5) If E_{λ} for $\lambda \in \sigma(T) \setminus \{0\}$ denotes the projection onto $\mathscr{N}((\lambda \mathrm{Id} - T)^{n_{\lambda}})$ corresponding to the decomposition in (3), then

$$E_{\lambda}E_{\mu} = \delta_{\lambda,\mu}E_{\lambda} \quad \text{for } \lambda, \mu \in \sigma(T) \setminus \{0\}.$$

Proof (1). Let $0 \neq \lambda \notin \sigma_p(T)$. Then $\mathscr{N}(\mathrm{Id} - \frac{T}{\lambda}) = \{0\}$, and so $\mathscr{R}(\mathrm{Id} - \frac{T}{\lambda}) = X$ (recall 11.8(3)), i.e. $\lambda \in \varrho(T)$. This shows that

$$\sigma(T) \setminus \{0\} \subset \sigma_p(T) \,.$$

If $\sigma(T) \setminus \{0\}$ is not finite, then we choose $\lambda_n \in \sigma(T) \setminus \{0\}$, $n \in \mathbb{N}$, pairwise distinct and eigenvectors $e_n \neq 0$ to λ_n and define

$$X_n := \operatorname{span}\{e_1, \ldots, e_n\}.$$

The eigenvectors e_k , k = 1, ..., n, are linearly independent, because if there exists (this is an inductive proof) $1 < k \leq n$ with

$$e_k = \sum_{i=1}^{k-1} \alpha_i e_i$$

with already linearly independent vectors e_1, \ldots, e_{k-1} , then it follows that

$$0 = Te_k - \lambda_k e_k = \sum_{i=1}^{k-1} \alpha_i (Te_i - \lambda_k e_i) = \sum_{i=1}^{k-1} \alpha_i \underbrace{(\lambda_i - \lambda_k)}_{\neq 0} e_i,$$

and so $\alpha_i = 0$ for i = 1, ..., k - 1, i.e. $e_k = 0$, a contradiction. This shows that X_{n-1} is a proper subspace of X_n . Hence the theorem on the almost orthogonal element (see 4.5) yields the existence of an $x_n \in X_n$ with

$$||x_n|| = 1$$
 and $\operatorname{dist}(x_n, X_{n-1}) \ge \frac{1}{2}$. (11-5)

On noting that $x_n = \alpha_n e_n + \tilde{x}_n$ with certain $\alpha_n \in \mathbb{C}$ and $\tilde{x}_n \in X_{n-1}$, it follows from the *T*-invariance of the subspace X_{n-1} that $Tx_n - \lambda_n x_n = T\tilde{x}_n - \lambda_n \tilde{x}_n \in X_{n-1}$, and so it holds for m < n that

$$\frac{1}{\lambda_n}(Tx_n - \lambda_n x_n) - \frac{1}{\lambda_m}Tx_m \in X_{n-1}.$$

Hence it follows from (11-5) that

$$\left\|T\left(\frac{x_n}{\lambda_n}\right) - T\left(\frac{x_m}{\lambda_m}\right)\right\| = \left\|x_n + \frac{1}{\lambda_n}(Tx_n - \lambda_n x_n) - \frac{1}{\lambda_m}Tx_m\right\| \ge \frac{1}{2}$$

This shows that the sequence $\left(T\left(\frac{x_n}{\lambda_n}\right)\right)_{n\in\mathbb{N}}$ has no cluster point. As T is compact, this implies that $\left(\frac{x_n}{\lambda_n}\right)_{n\in\mathbb{N}}$ contains no bounded subsequences, which yields that

$$\frac{1}{|\lambda_n|} = \left\| \frac{x_n}{\lambda_n} \right\| \longrightarrow \infty \quad \text{as } n \to \infty,$$

i.e. $\lambda_n \to 0$ as $n \to \infty$. Hence we have shown that 0 is the only cluster point of $\sigma(T) \setminus \{0\}$. In particular, it then holds that $\sigma(T) \setminus B_r(0)$ is finite for every r > 0, and so $\sigma(T) \setminus \{0\}$ is countable. \Box

Proof (2). Let $A := \lambda \text{Id} - T$. Then $\mathscr{N}(A^{n-1}) \subset \mathscr{N}(A^n)$ for all n. First we assume that:

$$\mathscr{N}(A^{n-1})$$
 is a proper subset of $\mathscr{N}(A^n)$ for all $n \ge 1$.

Similarly to the proof of (1), and on recalling the theorem on the almost orthogonal element, we choose an $x_n \in \mathcal{N}(A^n)$ with

$$||x_n|| = 1$$
 and $\operatorname{dist}(x_n, \mathscr{N}(A^{n-1})) \ge \frac{1}{2}$. (11-6)

Then it follows for m < n that

$$Ax_n + \lambda x_m - Ax_m \in \mathscr{N}(A^{n-1})$$

and so with (11-6) that

$$||Tx_n - Tx_m|| = ||\lambda x_n - (Ax_n + \lambda x_m - Ax_m)|| \ge \frac{|\lambda|}{2} > 0.$$

On the other hand, $\{x_n; n \in \mathbb{N}\}\$ is a bounded sequence. This contradicts the compactness of T. Hence we can find an $n \in \mathbb{N}$ with $\mathscr{N}(A^{n-1}) = \mathscr{N}(A^n)$. This implies for m > n that

$$\begin{aligned} x \in \mathscr{N}(A^m) &\implies A^{m-n}x \in \mathscr{N}(A^n) = \mathscr{N}(A^{n-1}) \\ &\implies A^{n-1+m-n}x = 0 \\ &\implies x \in \mathscr{N}(A^{m-1}), \end{aligned}$$

and so $\mathcal{N}(A^m) = \mathcal{N}(A^{m-1})$, and it follows inductively that $\mathcal{N}(A^m) = \mathcal{N}(A^n)$ for all $m \ge n$. Hence we have shown that $n_\lambda < \infty$. Since $\mathcal{N}(A) \ne \{0\}$ it holds that $n_\lambda \ge 1$.

Proof (3). Let $A := \lambda \text{Id} - T$ as before. Then

 $\mathscr{N}(A^{n_{\lambda}}) \oplus \mathscr{R}(A^{n_{\lambda}}) \subset X \,,$

because if $x \in \mathcal{N}(A^{n_{\lambda}}) \cap \mathscr{R}(A^{n_{\lambda}})$, then $A^{n_{\lambda}}x = 0$ and $x = A^{n_{\lambda}}y$ for a $y \in X$. Then $A^{2n_{\lambda}}y = 0$, and so $y \in \mathcal{N}(A^{2n_{\lambda}}) = \mathcal{N}(A^{n_{\lambda}})$ and hence $x = A^{n_{\lambda}}y = 0$. Now $A^{n_{\lambda}}$ can be written as

$$A^{n_{\lambda}} = \lambda^{n_{\lambda}} \mathrm{Id} + \underbrace{\sum_{k=1}^{n_{\lambda}} \binom{n_{\lambda}}{k} \lambda^{n_{\lambda}-k} (-T)^{k}}_{\in \mathscr{K}(X) \text{ by 10.3}} .$$
(11-7)

Hence $\operatorname{codim} \mathscr{R}(A^{n_{\lambda}}) \leq \dim \mathscr{N}(A^{n_{\lambda}}) < \infty$ (recall 11.8(4) and 11.8(1)), which yields that

$$X = \mathscr{N}(A^{n_{\lambda}}) \oplus \mathscr{R}(A^{n_{\lambda}}).$$

As T commutes with A, i.e. TA = AT, T also commutes with $A^{n_{\lambda}}$, and so both subspaces are T-invariant.

Proof (4). We denote by T_{λ} the restriction of T to $\mathscr{R}(A^{n_{\lambda}})$, where $A^{n_{\lambda}}$ has been computed in (11-7). Then $T_{\lambda} \in \mathscr{K}(\mathscr{R}(A^{n_{\lambda}}))$, where $\mathscr{R}(A^{n_{\lambda}})$ is a closed subspace (recall 11.8(2)), and so a Banach space. Here we have used the fact that T and $A^{n_{\lambda}}$ commute. Moreover, we have that

$$\mathscr{N}(\lambda \mathrm{Id} - T_{\lambda}) = \mathscr{N}(A) \cap \mathscr{R}(A^{n_{\lambda}}) = \{0\},\$$

and hence $\mathscr{R}(\lambda \mathrm{Id} - T_{\lambda}) = \mathscr{R}(A^{n_{\lambda}})$ (apply 11.8(3) to T_{λ}), which shows that $\lambda \in \varrho(T_{\lambda})$. It remains to show that

$$\sigma(T_{\lambda}) \setminus \{\lambda\} = \sigma(T) \setminus \{\lambda\}.$$

Let $\mu \in \mathbb{C} \setminus \{\lambda\}$. We recall from above that $\mathscr{N}(A^{n_{\lambda}})$ is invariant under $\mu \operatorname{Id} - T$. Moreover, $\mu \operatorname{Id} - T$ is injective on this subspace. To see this, note that $x \in \mathscr{N}(\mu \operatorname{Id} - T)$ implies that $(\lambda - \mu)x = Ax$. If in addition $A^m x = 0$ for some $m \geq 1$, it follows that

$$(\lambda - \mu)A^{m-1}x = A^{m-1}((\lambda - \mu)x) = A^m x = 0,$$

and since $\lambda \neq \mu$ this means that $A^{m-1}x = 0$. Inductively (for decreasing m) this yields that $x = A^0x = 0$. Hence we have shown that

$$\mathscr{N}(\mu \mathrm{Id} - T) \cap \mathscr{N}(A^m) = \{0\} \text{ for all } m \ge 1.$$

Setting $m = n_{\lambda}$ yields the injectivity of $\mu \operatorname{Id} - T$ on $\mathscr{N}(A^{n_{\lambda}})$. As this space is finite-dimensional, we have that $\mu \operatorname{Id} - T$ is also bijective on $\mathscr{N}(A^{n_{\lambda}})$. But this means that $\mu \in \varrho(T)$ if and only if $\mu \in \varrho(T_{\lambda})$. This shows that by removing the (finite-dimensional) characteristic subspace corresponding to the eigenvalue λ we obtain a remaining operator T_{λ} for which $\sigma(T_{\lambda}) = \sigma(T) \setminus \{\lambda\}$. \Box

Proof (5). Let $\lambda, \mu \in \sigma(T) \setminus \{0\}$ be distinct, and let $A_{\lambda} := \lambda \operatorname{Id} - T$ and $A_{\mu} := \mu \operatorname{Id} - T$. Now every $x \in \mathcal{N}(A_{\mu}^{n_{\mu}})$, corresponding to the Riesz decomposition of X into $\mathcal{N}(A_{\lambda}^{n_{\lambda}}) \oplus \mathscr{R}(A_{\lambda}^{n_{\lambda}})$, has a representation x = z + y. As both subspaces are invariant under T, and hence also under A_{μ} , it follows that

$$0 = A^{n_{\mu}}_{\mu}x = \underbrace{A^{n_{\mu}}_{\mu}z}_{\in \mathscr{N}(A^{n_{\lambda}}_{\lambda})} + \underbrace{A^{n_{\mu}}_{\mu}y}_{\in \mathscr{R}(A^{n_{\lambda}}_{\lambda})}$$

and so $0 = A_{\mu}^{n_{\mu}} z$. On recalling from the above proof that A_{μ} is bijective on $\mathcal{N}(A_{\lambda}^{n_{\lambda}})$, and hence also $A_{\mu}^{n_{\mu}}$, it follows that z = 0, i.e. $x \in \mathscr{R}(A_{\lambda}^{n_{\lambda}})$. Therefore we have shown that

$$\mathscr{N}(A^{n_{\mu}}_{\mu}) \subset \mathscr{R}(A^{n_{\lambda}}_{\lambda}),$$

in other words

$$\mathscr{R}(E_{\mu}) \subset \mathscr{N}(E_{\lambda}),$$

and hence $E_{\lambda}E_{\mu} = 0$.

11.10 Corollary. If $T \in \mathscr{K}(X)$ and $\lambda \in \sigma(T) \setminus \{0\}$, then the resolvent function $\mu \mapsto R(\mu; T)$ has an *(isolated) pole* of *order* n_{λ} in λ , i.e. the function $\mu \mapsto (\mu - \lambda)^{n_{\lambda}} R(\mu; T)$ can be complex analytically extended to the point λ , and the value at the point λ is different from the null operator.

Proof. Consider the decomposition

$$X = \underbrace{\mathscr{N}\left((\lambda \mathrm{Id} - T)^{n_{\lambda}}\right)}_{=\mathscr{R}(E_{\lambda})} \oplus \underbrace{\mathscr{R}\left((\lambda \mathrm{Id} - T)^{n_{\lambda}}\right)}_{=\mathscr{N}(E_{\lambda})}$$

and the restrictions

$$T_0 := T$$
 to $\mathscr{R}(E_\lambda)$, $T_1 := T$ to $\mathscr{N}(E_\lambda)$.

Since λ is an isolated point of $\sigma(T)$, there exists an r > 0 with $B_r(\lambda) \setminus \{\lambda\} \subset \rho(T)$. Then $B_r(\lambda) \setminus \{\lambda\} \subset \rho(T_0)$ and we have from 11.9(4) that $B_r(\lambda) \subset \rho(T_1)$, and it holds for $0 < |\mu| < r$ that

$$R(\lambda + \mu; T) = R(\lambda + \mu; T_0)E_{\lambda} + R(\lambda + \mu; T_1)(\mathrm{Id} - E_{\lambda}).$$

It follows from 11.3 that $R(\lambda + \cdot; T_1)$ is complex analytic in $B_r(0)$, and so it remains to show that $R(\lambda + \cdot; T_0)$ has a pole of order n_{λ} in 0. Consider

$$S(\mu) := \sum_{k=1}^{n_{\lambda}} \mu^{-k} (T_0 - \lambda \mathrm{Id})^{k-1} \quad \text{for } \mu \neq 0.$$

It holds that

$$S(\mu)((\lambda+\mu)\mathrm{Id} - T_0) = \sum_{k=1}^{n_{\lambda}} \mu^{1-k} (T_0 - \lambda \mathrm{Id})^{k-1} - \sum_{k=1}^{n_{\lambda}} \mu^{-k} (T_0 - \lambda \mathrm{Id})^k$$
$$= \mathrm{Id} - \mu^{-n_{\lambda}} (T_0 - \lambda \mathrm{Id})^{n_{\lambda}} = \mathrm{Id}$$

and similarly $((\lambda + \mu) \operatorname{Id} - T_0) S(\mu) = \operatorname{Id}$, i.e. $R(\lambda + \mu; T_0) = S(\mu)$.

The assertion $\sigma(T) \setminus \{0\} \subset \sigma_p(T)$ in 11.9(1) can also be formulated as follows:

11.11 Fredholm alternative. If $T \in \mathscr{K}(X)$ and $\lambda \neq 0$, then it holds that:

Either the equation $Tx - \lambda x = y$ is uniquely solvable for every $y \in X$,

or the equation $Tx - \lambda x = 0$ has nontrivial solutions.

Note: See also theorem 12.8.

11.12 Finite-dimensional case. Let X be a finite-dimensional vector space over \mathbb{C} and let $T : X \to X$ be linear. Then there exist pairwise distinct $\lambda_1, \ldots, \lambda_m \in \mathbb{C}$, where $1 \leq m \leq \dim X$, such that

$$\sigma(T) = \sigma_p(T) = \{\lambda_1, \dots, \lambda_m\},\$$

and orders n_{λ_i} with the properties in 11.9(2) - 11.9(5), so that

$$X = \mathscr{N}((\lambda_1 \mathrm{Id} - T)^{n_{\lambda_1}}) \oplus \cdots \oplus \mathscr{N}((\lambda_m \mathrm{Id} - T)^{n_{\lambda_m}}).$$

Proof. We equip X with an arbitrary norm. Then $T \in \mathscr{K}(X)$ (see 10.2(3)), and similarly $T_{\mu} := T - \mu \operatorname{Id}$ for $\mu \in \mathbb{C}$. Now apply 11.9 to e.g. T_0 and T_1 . \Box

11.13 Jordan normal form. Let $T \in \mathscr{K}(X)$ and let $\lambda \in \sigma_p(T)$ be as in 11.9 or 11.12, respectively. Set $A := \lambda \mathrm{Id} - T$. Then:

(1) For $n = 1, ..., n_{\lambda}$ there exist subspaces E_n with $\mathcal{N}(A^{n-1}) \oplus E_n \subset \mathcal{N}(A^n)$ such that

$$\mathscr{N}(A^{n_{\lambda}}) = \bigoplus_{k=1}^{n_{\lambda}} N_k$$
, where $N_k := \bigoplus_{l=0}^{k-1} A^l(E_k)$.

(2) The subspaces N_k, k = 1,..., n_λ, are T-invariant and the dimensions d_k := dim A^l(E_k) are independent of l ∈ {0,..., k − 1}.
(3) If {e_{k,j}; j = 1,..., d_k} are bases of E_k, then

$$\{A^l e_{k,j}; \ 0 \le l < k \le n_j, \ 1 \le j \le d_k\}$$

is a basis of $\mathcal{N}(A^{n_{\lambda}})$ and with

$$x = \sum_{k,j,l} \alpha_{k,j,l} \ A^l e_{k,j} \quad \text{and} \quad y = \sum_{k,j,l} \beta_{k,j,l} \ A^l e_{k,j}$$

it holds that Tx = y is equivalent to

$$\begin{bmatrix} \beta_{k,j,0} \\ \vdots \\ \vdots \\ \beta_{k,j,k-1} \end{bmatrix} = \begin{bmatrix} \lambda & -1 & 0 \\ 0 & \ddots & \ddots \\ & \ddots & \ddots & -1 \\ & & 0 & \lambda \end{bmatrix} \begin{bmatrix} \alpha_{k,j,0} \\ \vdots \\ \vdots \\ \alpha_{k,j,k-1} \end{bmatrix},$$

i.e. the matrix representing T with respect to this basis has a **Jordan normal** form.

Proof. If E is a subspace with $\mathcal{N}(A^{n-1}) \oplus E \subset \mathcal{N}(A^n)$, then

$$\mathscr{N}(A^{n-l-1}) \oplus A^l(E) \subset \mathscr{N}(A^{n-l}) \quad \text{ for } 0 \leq l < n,$$

and A^l is injective on E. To see this, note that if $x \in E$ with $A^l x = 0$, then also $A^{n-1}x = 0$ because $l \leq n-1$, and so $x \in \mathcal{N}(A^{n-1}) \cap E = \{0\}$. Based on this observation we inductively choose E_n for $n = n_{\lambda}, \ldots, 1$ such that

$$\mathcal{N}(A^n) = \mathcal{N}(A^{n-1}) \oplus \bigoplus_{l=0}^{n_{\lambda}-n} A^l(E_{n+l})$$

This yields the desired results.

11.14 Real case. If X is a Banach space over \mathbb{R} and if $T \in \mathscr{K}(X)$, then the spectral theorem can be applied to their *complexification*, i.e. let

$$\widetilde{X} := X \times X$$

and for $x = (x_1, x_2) \in \widetilde{X}$, $\alpha = a + ib$ with $a, b \in \mathbb{R}$, let

$$\alpha x := (ax_1 - bx_2, ax_2 + bx_1), \quad \overline{x} := (x_1, -x_2).$$

With the above \widetilde{X} becomes a vector space over \mathbb{C} . On setting

$$\|x\|_{\widetilde{X}} := \sup_{\theta' \in \mathbb{R}} \left(\|\cos(\theta')x_1 - \sin(\theta')x_2\|_X^2 + \|\sin(\theta')x_1 + \cos(\theta')x_2\|_X^2 \right)^{\frac{1}{2}}$$

it holds that $\|e^{i\theta}x\|_{\widetilde{X}} = \|x\|_{\widetilde{X}}$ for $x \in \widetilde{X}$ and $\theta \in \mathbb{R}$, and equipped with this norm \widetilde{X} becomes a Banach space over \mathbb{C} . Then

$$\widetilde{T}x := (Tx_1, Tx_2)$$

defines the corresponding operator $\widetilde{T} \in \mathscr{K}(\widetilde{X})$, so that theorem 11.9 can now be applied.

Now if $\lambda \in \sigma_p(\widetilde{T})$ with eigenvector e, then

$$\widetilde{T}\overline{e} = \overline{\widetilde{T}e} = \overline{\lambda}\overline{e} = \overline{\lambda}\overline{e},$$

and so $\overline{\lambda} \in \sigma_p(\widetilde{T})$ with eigenvector \overline{e} . If $\lambda \in \mathbb{R}$, then the vectors $e_{k,j}$ in 11.13(3) can be chosen to satisfy $\overline{e_{k,j}} = e_{k,j}$. If $\lambda \notin \mathbb{R}$ and $e_{k,j}$ as in 11.13(3), then the vectors $\overline{e_{k,j}}$ have the properties in 11.13(3) with respect to $\overline{\lambda}$. *Remark:* In the case when X is a Hilbert space, the above norm satisfies

$$||x||_{\widetilde{X}} = \left(||x_1||_X^2 + ||x_2||_X^2\right)^{\frac{1}{2}}.$$