

# Chapter 13

## Data Replication

As we discussed in previous chapters, distributed databases are typically replicated. The purposes of replication are multiple:

1. **System availability.** As discussed in Chapter 1, distributed DBMSs may remove single points of failure by replicating data, so that data items are accessible from multiple sites. Consequently, even when some sites are down, data may be accessible from other sites.
2. **Performance.** As we have seen previously, one of the major contributors to response time is the communication overhead. Replication enables us to locate the data closer to their access points, thereby localizing most of the access that contributes to a reduction in response time.
3. **Scalability.** As systems grow geographically and in terms of the number of sites (consequently, in terms of the number of access requests), replication allows for a way to support this growth with acceptable response times.
4. **Application requirements.** Finally, replication may be dictated by the applications, which may wish to maintain multiple data copies as part of their operational specifications.

Although data replication has clear benefits, it poses the considerable challenge of keeping different copies synchronized. We will discuss this shortly, but let us first consider the execution model in replicated databases. Each replicated data item  $x$  has a number of copies  $x_1, x_2, \dots, x_n$ . We will refer to  $x$  as the *logical data item* and to its copies (or *replicas*)<sup>1</sup> as *physical data items*. If replication transparency is to be provided, user transactions will issue read and write operations on the logical data item  $x$ . The replica control protocol is responsible for mapping these operations to reads and writes on the physical data items  $x_1, \dots, x_n$ . Thus, the system behaves as if there is a single copy of each data item – referred to as *single system image* or *one-copy equivalence*. The specific implementation of the Read and Write interfaces

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<sup>1</sup> In this chapter, we use the terms “replica”, “copy”, and “physical data item” interchangeably.

of the transaction monitor differ according to the specific replication protocol, and we will discuss these differences in the appropriate sections.

There are a number of decisions and factors that impact the design of replication protocols. Some of these were discussed in previous chapters, while others will be discussed here.

- **Database design.** As discussed in Chapter 3, a distributed database may be fully or partially replicated. In the case of a partially replicated database, the number of physical data items for each logical data item may vary, and some data items may even be non-replicated. In this case, transactions that access only non-replicated data items are *local transactions* (since they can be executed locally at one site) and their execution typically does not concern us here. Transactions that access replicated data items have to be executed at multiple sites and they are *global transactions*.
- **Database consistency.** When global transactions update copies of a data item at different sites, the values of these copies may be different at a given point in time. A replicated database is said to be in a *mutually consistent* state if all the replicas of each of its data items have identical values. What differentiates different mutual consistency criteria is how tightly synchronized replicas have to be. Some ensure that replicas are mutually consistent when an update transaction commits, thus, they are usually called *strong consistency* criteria. Others take a more relaxed approach, and are referred to as *weak consistency* criteria.
- **Where updates are performed.** A fundamental design decision in designing a replication protocol is where the database updates are first performed [Gray et al., 1996]. The techniques can be characterized as *centralized* if they perform updates first on a *master* copy, versus *distributed* if they allow updates over any replica. Centralized techniques can be further identified as *single master* when there is only one master database copy in the system, or *primary copy* where the master copy of each data item may be different<sup>2</sup>.
- **Update propagation.** Once updates are performed on a replica (master or otherwise), the next decision is how updates are propagated to the others. The alternatives are identified as *eager* versus *lazy* [Gray et al., 1996]. Eager techniques perform all of the updates within the context of the global transaction that has initiated the write operations. Thus, when the transaction commits, its updates will have been applied to all of the copies. Lazy techniques, on the other hand, propagate the updates sometime after the initiating transaction has committed. Eager techniques are further identified according to when they push each write to the other replicas – some push each write operation individually, others batch the writes and propagate them at the commit point.

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<sup>2</sup> Centralized techniques are referred to, in the literature, as *single master*, while distributed ones are referred to as *multi-master* or *update anywhere*. These terms, in particular “single master”, are confusing, since they refer to alternative architectures for implementing centralized protocols (more on this in Section 13.2.3). Thus, we prefer the more descriptive terms “centralized” and “distributed”.

- **Degree of replication transparency.** Certain replication protocols require each user application to know the master site where the transaction operations are to be submitted. These protocols provide only *limited replication transparency* to user applications. Other protocols provide *full replication transparency* by involving the Transaction Manager (TM) at each site. In this case, user applications submit transactions to their local TMs rather than the master site.

We discuss consistency issues in replicated databases in Section 13.1, and analyze centralized versus distributed update application as well as update propagation alternatives in Section 13.2. This will lead us to a discussion of the specific protocols in Section 13.3. In Section 13.4, we discuss the use of group communication primitives in reducing the messaging overhead of replication protocols. In these sections, we will assume that no failures occur so that we can focus on the replication protocols. We will then introduce failures and investigate how protocols are revised to handle failures (Section 13.5). Finally, in Section 13.6, we discuss how replication services can be provided in multidatabase systems (i.e., outside the component DBMSs).

## 13.1 Consistency of Replicated Databases

There are two issues related to consistency of a replicated database. One is mutual consistency, as discussed above, that deals with the convergence of the values of physical data items corresponding to one logical data item. The second is transaction consistency as we discussed in Chapter 11. Serializability, which we introduced as the transaction consistency criterion needs to be recast in the case of replicated databases. In addition, there are relationships between mutual consistency and transaction consistency. In this section we first discuss mutual consistency approaches and then focus on the redefinition of transaction consistency and its relationship to mutual consistency.

### 13.1.1 Mutual Consistency

As indicated earlier, mutual consistency criteria for replicated databases can either be strong or weak. Each is suitable for different classes of applications with different consistency requirements.

Strong mutual consistency criteria require that all copies of a data item have the same value at the end of the execution of an update transaction. This is achieved by a variety of means, but the execution of 2PC at the commit point of an update transaction is a common way to achieve strong mutual consistency.

Weak mutual consistency criteria do not require the values of replicas of a data item to be identical when an update transaction terminates. What is required is that, if the update activity ceases for some time, the values *eventually* become identical. This is commonly referred to as *eventual consistency*, which refers to the fact that

replica values may diverge over time, but will eventually converge. It is hard to define this concept formally or precisely, although the following definition is probably as precise as one can hope to get [Saito and Shapiro, 2005]:

“A replicated [data item] is *eventually consistent* when it meets the following conditions, assuming that all replicas start from the same initial state.

- At any moment, for each replica, there is a prefix of the [history] that is equivalent to a prefix of the [history] of every other replica. We call this a *committed prefix* for the replica.
- The committed prefix of each replica grows monotonically over time.
- All non-aborted operations in the committed prefix satisfy their preconditions.
- For every submitted operation  $\alpha$ , either  $\alpha$  or [its abort] will eventually be included in the committed prefix.”

It should be noted that this definition of eventual consistency is rather strong – in particular the requirements that history prefixes are the same at any given moment and that the committed prefix grows monotonically. Many systems that claim to provide eventual consistency would violate these requirements.

*Epsilon serializability* (ESR) [Pu and Leff, 1991; Ramamritham and Pu, 1995] allows a query to see inconsistent data while replicas are being updated, but requires that the replicas converge to a one-copy serializable state once the updates are propagated to all of the copies. It bounds the error on the read values by an epsilon ( $\epsilon$ ) value (hence the name), which is defined in terms of the number of updates (write operations) that a query “misses”. Given a read-only transaction (query)  $T_Q$ , let  $T_U$  be all the update transactions that are executing concurrently with  $T_Q$ . If  $RS(T_Q) \cap WS(T_U) \neq \emptyset$  ( $T_Q$  is reading some copy of some data items while  $T_U$  is updating (possibly a different) copy of those data items) then there is a read-write conflict and  $T_Q$  may be reading inconsistent data. The inconsistency is bounded by the changes performed by  $T_U$ . Clearly, ESR does not sacrifice database consistency, but only allows read-only transactions (queries) to read inconsistent data. For this reason, it has been claimed that ESR does not weaken database consistency, but “stretches” it [Wu et al., 1997].

Other looser bounds have also been discussed. It has even been suggested that users should be allowed to specify *freshness constraints* that are suitable for particular applications and the replication protocols should enforce these [Pacitti and Simon, 2000; Röhm et al., 2002b; Bernstein et al., 2006]. The types of freshness constraints that can be specified are the following:

- Time-bound constraints. Users may accept divergence of physical copy values up to a certain time:  $x_i$  may reflect the value of an update at time  $t$  while  $x_j$  may reflect the value at  $t - \Delta$  and this may be acceptable.
- Value-bound constraints. It may be acceptable to have values of all physical data items within a certain range of each other. The user may consider the database to be mutually consistent if the values do not diverge more than a certain amount (or percentage).

- Drift constraints on multiple data items. For transactions that read multiple data items, users may be satisfied if the time drift between the update timestamps of two data items is less than a threshold (i.e., they were updated within that threshold) or, in the case of aggregate computation, if the aggregate computed over a data item is within a certain range of the most recent value (i.e., even if the individual physical copy values may be more out of sync than this range, as long as a particular aggregate computation is within range, it may be acceptable).

An important criterion in analyzing protocols that employ criteria that allow replicas to diverge is *degree of freshness*. The degree of freshness of a given replica  $r_i$  at time  $t$  is defined as the proportion of updates that have been applied at  $r_i$  at time  $t$  to the total number of updates [Pacitti et al., 1998, 1999].

### 13.1.2 Mutual Consistency versus Transaction Consistency

Mutual consistency, as we have defined it here, and transactional consistency as we discussed in Chapter 11 are related, but different. Mutual consistency refers to the replicas converging to the same value, while transaction consistency requires that the global execution history be serializable. It is possible for a replicated DBMS to ensure that data items are mutually consistent when a transaction commits, but the execution history may not be globally serializable. This is demonstrated in the following example.

*Example 13.1.* Consider three sites (A, B, and C) and three data items ( $x, y, z$ ) that are distributed as follows: Site A hosts  $x$ , Site B hosts  $x, y$ , Site C hosts  $x, y, z$ . We will use site identifiers as subscripts on the data items to refer to a particular replica.

Now consider the following three transactions:

$T_1$ : $x \leftarrow 20$	$T_2$ : Read( $x$ )	$T_3$ : Read( $x$ )
Write( $x$ )	$y \leftarrow x + y$	Read( $y$ )
Commit	Write( $y$ )	$z \leftarrow (x * y) / 100$
	Commit	Write( $z$ )
		Commit

Note that  $T_1$ 's *Write* has to be executed at all three sites (since  $x$  is replicated at all three sites),  $T_2$ 's *Write* has to be executed at B and C, and  $T_3$ 's *Write* has to be executed only at C. We are assuming a transaction execution model where transactions can read their local replicas, but have to update all of the replicas.

Assume that the following three local histories are generated at the sites:

$$H_A = \{W_1(x_A), C_1\}$$

$$H_B = \{W_1(x_B), C_1, R_2(x_B), W_2(y_B), C_2\}$$

$$H_C = \{W_2(y_C), C_2, R_3(x_C), R_3(y_C), W_3(z_C), C_3, W_1(x_C), C_1\}$$

The serialization order in  $H_B$  is  $T_1 \rightarrow T_2$  while in  $H_C$  it is  $T_2 \rightarrow T_3 \rightarrow T_1$ . Therefore, the global history is not serializable. However, the database is mutually consistent. Assume, for example, that initially  $x_A = x_B = x_C = 10, y_B = y_C = 15$ , and  $z_C = 7$ . With the above histories, the final values will be  $x_A = x_B = x_C = 20, y_B = y_C = 35, z_C = 3.5$ . All the physical copies (replicas) have indeed converged to the same value. ♦

Of course, it is possible for both the database to be mutually inconsistent, and the execution history to be globally non-serializable, as demonstrated in the following example.

*Example 13.2.* Consider two sites (A and B), and one data item ( $x$ ) that is replicated at both sites ( $x_A$  and  $x_B$ ). Further consider the following two transactions:

$T_1$ : Read( $x$ )	$T_2$ : Read( $x$ )
$x \leftarrow x + 5$	$x \leftarrow x * 10$
Write( $x$ )	Write( $x$ )
Commit	Commit

Assume that the following two local histories are generated at the two sites (again using the execution model of the previous example):

$$H_A = \{R_1(x_A), W_1(x_A), C_1, R_2(x_A), W_2(x_A), C_2\}$$

$$H_B = \{R_2(x_B), W_2(x_B), C_2, R_1(x_B), W_1(x_B), C_1\}$$

Although both of these histories are serial, they serialize  $T_1$  and  $T_2$  in reverse order; thus the global history is not serializable. Furthermore, the mutual consistency is violated as well. Assume that the value of  $x$  prior to the execution of these transactions was 1. At the end of the execution of these schedules, the value of  $x$  is 60 at site A while it is 15 at site B. Thus, in this example, the global history is non-serializable, **and** the databases are mutually inconsistent. ♦

Given the above observation, the transaction consistency criterion given in Chapter 11 is extended in replicated databases to define *one-copy serializability*. One-copy serializability (ISR) states that the effects of transactions on replicated data items should be the same as if they had been performed one at-a-time on a single set of data items. In other words, the histories are equivalent to some serial execution over non-replicated data items.

Snapshot isolation that we introduced in Chapter 11 has been extended for replicated databases [Lin et al., 2005] and used as an alternative transactional consistency criterion within the context of replicated databases [Plattner and Alonso, 2004; Daudjee and Salem, 2006]. Similarly, a weaker form of serializability, called *relaxed concurrency (RC-) serializability* has been defined that corresponds to “read committed” isolation level (Section 10.2.3) [Bernstein et al., 2006].

## 13.2 Update Management Strategies

As discussed earlier, the replication protocols can be classified according to when the updates are propagated to copies (eager versus lazy) and where updates are allowed to occur (centralized versus distributed). These two decisions are generally referred to as *update management* strategies. In this section, we discuss these alternatives before we present protocols in the next section.

### 13.2.1 Eager Update Propagation

The eager update propagation approaches apply the changes to all the replicas within the context of the update transaction. Consequently, when the update transaction commits, all the copies have the same value. Typically, eager propagation techniques use 2PC at commit point, but, as we will see later, alternatives are possible to achieve agreement. Furthermore, eager propagation may use *synchronous* propagation of each update by applying it on all the replicas at the same time (when the *Write* is issued), or *deferred* propagation whereby the updates are applied to one replica when they are issued, but their application on the other replicas is batched and deferred to the end of the transaction. Deferred propagation can be implemented by including the updates in the “Prepare-to-Commit” message at the start of 2PC execution.

Eager techniques typically enforce strong mutual consistency criteria. Since all the replicas are mutually consistent at the end of an update transaction, a subsequent read can read from any copy (i.e., one can map a  $Read(x)$  to  $Read(x_i)$  for any  $x_i$ ). However, a  $Write(x)$  has to be applied to all  $x_i$  (i.e.,  $Write(x_i), \forall x_i$ ). Thus, protocols that follow eager update propagation are known as *read-one/write-all* (ROWA) protocols.

The advantages of eager update propagation are threefold. First, they typically ensure that mutual consistency is enforced using 1SR; therefore, there are no transactional inconsistencies. Second, a transaction can read a local copy of the data item (if a local copy is available) and be certain that an up-to-date value is read. Thus, there is no need to do a remote read. Finally, the changes to replicas are done atomically; thus recovery from failures can be governed by the protocols we have already studied in the previous chapter.

The main disadvantage of eager update propagation is that a transaction has to update all the copies before it can terminate. This has two consequences. First, the response time performance of the update transaction suffers, since it typically has to participate in a 2PC execution, and because the update speed is restricted by the slowest machine. Second, if one of the copies is unavailable, then the transaction cannot terminate since all the copies need to be updated. As discussed in Chapter 12, if it is possible to differentiate between site failures and network failures, then one can terminate the transaction as long as only one replica is unavailable (recall that more than one site unavailability causes 2PC to be blocking), but it is generally not possible to differentiate between these two types of failures.

### 13.2.2 Lazy Update Propagation

In lazy update propagation the replica updates are not all performed within the context of the update transaction. In other words, the transaction does not wait until its updates are applied to all the copies before it commits – it commits as soon as one replica is updated. The propagation to other copies is done *asynchronously* from the original transaction, by means of *refresh transactions* that are sent to the replica sites some time after the update transaction commits. A refresh transaction carries the sequence of updates of the corresponding update transaction.

Lazy propagation is used in those applications for which strong mutual consistency may be unnecessary and too restrictive. These applications may be able to tolerate some inconsistency among the replicas in return for better performance. Examples of such applications are Domain Name Service (DNS), databases over geographically widely distributed sites, mobile databases, and personal digital assistant databases [Saito and Shapiro, 2005]. In these cases, usually weak mutual consistency is enforced.

The primary advantage of lazy update propagation techniques is that they generally have lower response times for update transactions, since an update transaction can commit as soon as it has updated one copy. The disadvantages are that the replicas are not mutually consistent and some replicas may be out-of-date, and, consequently, a local read may read stale data and does not guarantee to return the up-to-date value. Furthermore, under some scenarios that we will discuss later, transactions may not see their own writes, i.e.,  $Read_i(x)$  of an update transaction  $T_i$  may not see the effects of  $Write_i(x)$  that was executed previously. This has been referred to as *transaction inversion*. Strong one-copy serializability (strong 1SR) [Daudjee and Salem, 2004] and strong snapshot isolation (strong SI) [Daudjee and Salem, 2006] prevent all transaction inversions at 1SR and SI isolation levels, respectively, but are expensive to provide. The weaker guarantees of 1SR and global SI, while being much less expensive to provide than their stronger counterparts, do not prevent transaction inversions. Session-level transactional guarantees at the 1SR and SI isolation levels have been proposed that address these shortcomings by preventing transaction inversions within a client session but not necessarily across sessions [Daudjee and Salem, 2004, 2006]. These session-level guarantees are less costly to provide than their strong counterparts while preserving many of the desirable properties of the strong counterparts.

### 13.2.3 Centralized Techniques

Centralized update propagation techniques require that updates are first applied at a master copy and then propagated to other copies (which are called *slaves*). The site that hosts the master copy is similarly called the *master site*, while the sites that host the slave copies for that data item are called *slave sites*.



In some techniques, there is a single master for all replicated data. We refer to these as *single master* centralized techniques. In other protocols, the master copy for each data item may be different (i.e., for data item  $x$ , the master copy may be  $x_i$  stored at site  $S_i$ , while for data item  $y$ , it may be  $y_j$  stored at site  $S_j$ ). These are typically known as *primary copy* centralized techniques.

The advantages of centralized techniques are two-fold. First, application of the updates is easy since they happen at only the master site, and they do not require synchronization among multiple replica sites. Second, there is the assurance that at least one site – the site that holds the master copy – has up-to-date values for a data item. These protocols are generally suitable in data warehouses and other applications where data processing is centralized at one or a few master sites.

The primary disadvantage is that, as in any centralized algorithm, if there is one central site that hosts all of the masters, this site can be overloaded and can become a bottleneck. Distributing the master site responsibility for each data item as in primary copy techniques is one way of reducing this overhead, but it raises consistency issues, in particular with respect to maintaining global serializability in lazy replication techniques since the refresh transactions have to be executed at the replicas in the same serialization order. We discuss these further in relevant sections.

### ***13.2.4 Distributed Techniques***

Distributed techniques apply the update on the local copy at the site where the update transaction originates, and then the updates are propagated to the other replica sites. These are called distributed techniques since different transactions can update different copies of the same data item located at different sites. They are appropriate for collaborative applications with distributive decision/operation centers. They can more evenly distribute the load, and may provide the highest system availability if coupled with lazy propagation techniques.

A serious complication that arises in these systems is that different replicas of a data item may be updated at different sites (masters) concurrently. If distributed techniques are coupled by eager propagation methods, then the distributed concurrency control methods can adequately address the concurrent updates problem. However, if lazy propagation methods are used, then transactions may be executed in different orders at different sites causing non-1SR global history. Furthermore, various replicas will get out of sync. To manage these problems, a reconciliation method is applied involving undoing and redoing transactions in such a way that transaction execution is the same at each site. This is not an easy issue since the reconciliation is generally application dependent.

## 13.3 Replication Protocols

In the previous section, we discussed two dimensions along which update management techniques can be classified. These dimensions are orthogonal; therefore four combinations are possible: eager centralized, eager distributed, lazy centralized, and lazy distributed. We discuss each of these alternatives in this section. For simplicity of exposition, we assume a fully replicated database, which means that all update transactions are global. We further assume that each site implements a 2PL-based concurrency control technique.

### 13.3.1 Eager Centralized Protocols

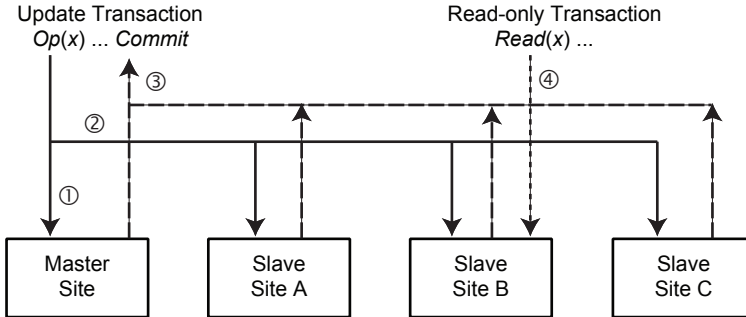
In eager centralized replica control, a master site controls the operations on a data item. These protocols are coupled with strong consistency techniques, so that updates to a logical data item are applied to all of its replicas within the context of the update transaction, which is committed using the 2PC protocol (although non-2PC alternatives exist as we discuss shortly). Consequently, once the update transaction completes, all replicas have the same values for the updated data items (i.e., mutually consistent), and the resulting global history is 1SR.

The two design parameters that we discussed earlier determine the specific implementation of eager centralized replica protocols: where updates are performed, and degree of replication transparency. The first parameter, which was discussed in Section 13.2.3, refers to whether there is a single master site for all data items (single master), or different master sites for each, or, more likely, for a group of data items (primary copy). The second parameter indicates whether each application knows the location of the master copy (limited application transparency) or whether it can rely on its local TM for determining the location of the master copy (full replication transparency).

#### 13.3.1.1 Single Master with Limited Replication Transparency

The simplest case is to have a single master for the entire database (i.e., for all data items) with limited replication transparency so that user applications know the master site. In this case, global update transactions (i.e., those that contain at least one  $Write(x)$  operation where  $x$  is a replicated data item) are submitted directly to the master site – more specifically, to the transaction manager (TM) at the master site. At the master, each  $Read(x)$  operation is performed on the master copy (i.e.,  $Read(x)$  is converted to  $Read(x_M)$ , where  $M$  signifies master copy) and executed as follows: a read lock is obtained on  $x_M$ , the read is performed, and the result is returned to the user. Similarly, each  $Write(x)$  causes an update of the master copy (i.e., executed as  $Write(x_M)$ ) by first obtaining a write lock and then performing the write operation. The master TM then forwards the  $Write$  to the slave sites either

synchronously or in a deferred fashion (Figure 13.1). In either case, it is important to propagate updates such that conflicting updates are executed at the slaves in the same order they are executed at the master. This can be achieved by timestamping or by some other ordering scheme.



**Fig. 13.1** Eager Single Master Replication Protocol Actions. (1) A *Write* is applied on the master copy; (2) *Write* is then propagated to the other replicas; (3) Updates become permanent at commit time; (4) Read-only transaction's *Read* goes to any slave copy.

The user application may submit a read-only transaction (i.e., all operations are *Read*) to any slave site. The execution of read-only transactions at the slaves can follow the process of centralized concurrency control algorithms, such as C2PL (Algorithms 11.1-11.3), where the centralized lock manager resides at the master replica site. Implementations within C2PL require minimal changes to the TM at the non-master sites, primarily to deal with the *Write* operations as described above, and its consequences (e.g., in the processing of *Commit* command). Thus, when a slave site receives a *Read* operation (from a read-only transaction), it forwards it to the master site to obtain a read lock. The *Read* can then be executed at the master and the result returned to the application, or the master can simply send a “lock granted” message to the originating site, which can then execute the *Read* on the local copy.

It is possible to reduce the load on the master by performing the *Read* on the local copy without obtaining a read lock from the master site. Whether synchronous or deferred propagation is used, the local concurrency control algorithm ensures that the local read-write conflicts are properly serialized, and since the *Write* operations can only be coming from the master as part of update propagation, local write-write conflicts won't occur as the propagation transactions are executed in each slave in the order dictated by the master. However, a *Read* may read data item values at a slave either before an update is installed or after. The fact that a read transaction at one slave site may read the value of one replica before an update while another read transaction reads another replica at another slave after the same update is inconsequential from the perspective of ensuring global ISR histories. This is demonstrated by the following example.

*Example 13.3.* Consider a data item  $x$  whose master site is at Site A with slaves at sites B and C. Consider the following three transactions:

$T_1$ : Write( $x$ ) Commit	$T_2$ : Read( $x$ ) Commit	$T_3$ : Read( $x$ ) Commit
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Assume that  $T_2$  is sent to slave at Site B and  $T_3$  to slave at Site C. Assume that  $T_2$  reads  $x$  at B [ $Read(x_B)$ ] before  $T_1$ 's update is applied at B, while  $T_3$  reads  $x$  at C [ $Read(x_C)$ ] after  $T_1$ 's update at C. Then the histories generated at the two slaves will be as follows:

$$H_B = \{R_2(x), C_2, W_1(x), C_1\}$$

$$H_C = \{W_1(x), C_1, R_3(x), C_3\}$$

The serialization order at Site B is  $T_2 \rightarrow T_1$ , while at Site C it is  $T_1 \rightarrow T_3$ . The global serialization order, therefore, is  $T_2 \rightarrow T_1 \rightarrow T_3$ , which is fine. Therefore the history is 1SR. ◆

Consequently, if this approach is followed, read transactions may read data that are concurrently updated at the master, but the global history will still be 1SR.

In this alternative protocol, when a slave site receives a  $Read(x)$ , it obtains a local read lock, reads from its local copy (i.e.,  $Read(x_i)$ ) and returns the result to the user application; this can only come from a read-only transaction. When it receives a  $Write(x)$ , if the  $Write$  is coming from the master site, then it performs it on the local copy (i.e.,  $Write(x_i)$ ). If it receives a  $Write$  from a user application, then it rejects it, since this is obviously an error given that update transactions have to be submitted to the master site.

These alternatives of a single master eager centralized protocol are simple to implement. One important issue to address is how one recognizes a transaction as “update” or “read-only” – it may be possible to do this by explicit declaration within the `Begin.Transaction` command.

### 13.3.1.2 Single Master with Full Replication Transparency

Single master eager centralized protocols require each user application to know the master site, and they put significant load on the master that has to deal with (at least) the *Read* operations within update transactions as well as acting as the coordinator for these transactions during 2PC execution. These issues can be addressed, to some extent, by involving, in the execution of the update transactions, the TM at the site where the application runs. Thus, the update transactions are not submitted to the master, but to the TM at the site where the application runs (since they don't need to know the master). This TM can act as the coordinating TM for both update and read-only transactions. Applications can simply submit their transactions to their local TM, providing full transparency.

There are alternatives to implementing full transparency – the coordinating TM may only act as a “router”, forwarding each operation directly to the master site. The master site can then execute the operations locally (as described above) and return the results to the application. Although this alternative implementation provides full

transparency and has the advantage of being simple to implement, it does not address the overloading problem at the master. An alternative implementation may be as follows.

1. The coordinating TM sends each operation, as it gets it, to the central (master) site. This requires no change to the C2PL-TM algorithm (Algorithm 11.1).
2. If the operation is a  $Read(x)$ , then the centralized lock manager (C2PL-LM in Algorithm 11.2) can proceed by setting a read lock on its copy of  $x$  (call it  $x_M$ ) on behalf of this transaction and informs the coordinating TM that the read lock is granted. The coordinating TM can then forward the  $Read(x)$  to any slave site that holds a replica of  $x$  (i.e., converts it to a  $Read(x_i)$ ). The read can then be carried out by the data processor (DP) at that slave.
3. If the operation is a  $Write(x)$ , then the centralized lock manager (master) proceeds as follows:
  - (a) It first sets a write lock on its copy of  $x$ .
  - (b) It then calls its local DP to perform the  $Write$  on its own copy of  $x$  (i.e., converts the operation to  $Write(x_M)$ ).
  - (c) Finally, it informs the coordinating TM that the write lock is granted.

The coordinating TM, in this case, sends the  $Write(x)$  to all the slaves where a copy of  $x$  exists; the DPs at these slaves apply the  $Write$  to their local copies.

The fundamental difference in this case is that the master site does not deal with *Reads* or with the coordination of the updates across replicas. These are left to the TM at the site where the user application runs.

It is straightforward to see that this algorithm guarantees that the histories are 1SR since the serialization orders are determined at a single master (similar to centralized concurrency control algorithms). It is also clear that the algorithm follows the ROWA protocol, as discussed above – since all the copies are ensured to be up-to-date when an update transaction completes, a *Read* can be performed on any copy.

To demonstrate how eager algorithms combine replica control and concurrency control, we show how the Transaction Management algorithm for the coordinating TM (Algorithm 13.1) and the Lock Management algorithm for the master site (Algorithm 13.2). We show only the revisions to the centralized 2PL algorithms (Algorithms 11.1 and 11.2 in Chapter 11).

Note that in the algorithm fragments that we have given, the LM simply sends back a “Lock granted” message and not the result of the update operation. Consequently, when the update is forwarded to the slaves by the coordinating TM, they need to execute the update operation themselves. This is sometimes referred to as *operation transfer*. The alternative is for the “Lock granted” message to include the result of the update computation, which is then forwarded to the slaves who simply need to apply the result and update their logs. This is referred to as *state transfer*. The distinction may seem trivial if the operations are simply in the form  $Write(x)$ , but recall that this

---

**Algorithm 13.1:** Eager Single Master Modifications to C2PL-TM
 

---

```

begin
  ⋮
  if lock request granted then
    if op.Type = W then
      |  $S \leftarrow$  set of all sites that are slaves for the data item
    else
      |  $S \leftarrow$  any one site which has a copy of data item
      |  $DP_S(op)$  {send operation to all sites in set  $S$ }
    else
      | inform user about the termination of transaction
  ⋮
end

```

---



---

**Algorithm 13.2:** Eager Single Master Modifications to C2PL-LM
 

---

```

begin
  ⋮
  switch op.Type do
    case R or W {lock request; see if it can be granted}
      | find the lock unit  $lu$  such that  $op.arg \subseteq lu$ ;
      | if lu is unlocked or lock mode of lu is compatible with op.Type
      | then
      | | set lock on  $lu$  in appropriate mode on behalf of transaction
      | |  $op.tid$ ;
      | | if op.Type = W then
      | | |  $DP_M(op)$  {call local DP (M for “master”) with operation}
      | | | send “Lock granted” to coordinating TM of transaction
      | else
      | | put  $op$  on a queue for  $lu$ 
    ⋮
  end

```

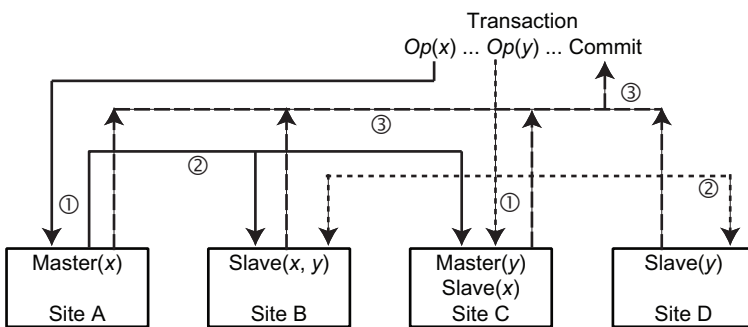
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*Write* operation is an abstraction; each update operation may require the execution of an SQL expression, in which case the distinction is quite important.

The above implementation of the protocol relieves some of the load on the master site and alleviates the need for user applications to know the master. However, its implementation is more complicated than the first alternative we discussed. In particular, now the TM at the site where transactions are submitted has to act as the 2PC coordinator and the master site becomes a participant. This requires some care in revising the algorithms at these sites.

### 13.3.1.3 Primary Copy with Full Replication Transparency

Let us now relax the requirement that there is one master for all data items; each data item can have a different master. In this case, for each replicated data item, one of the replicas is designated as the *primary copy*. Consequently, there is no single master to determine the global serialization order, so more care is required. In the case of fully replicated databases, any replica can be primary copy for a data item, however for partially replicated databases, limited replication transparency option only makes sense if an update transaction accesses only data items whose primary sites are at the same site. Otherwise, the application program cannot forward the update transactions to one master; it will have to do it operation-by-operation, and, furthermore, it is not clear which primary copy master would serve as the coordinator for 2PC execution. Therefore, the reasonable alternative is the full transparency support, where the TM at the application site acts as the coordinating TM and forwards each operation to the primary site of the data item that it acts on. Figure 13.2 depicts the sequence of operations in this case where we relax our previous assumption of fully replication. Site A is the master for data item *x* and sites B and C hold replicas (i.e., they are slaves); similarly data item *y*'s master is site C with slave sites B and D.



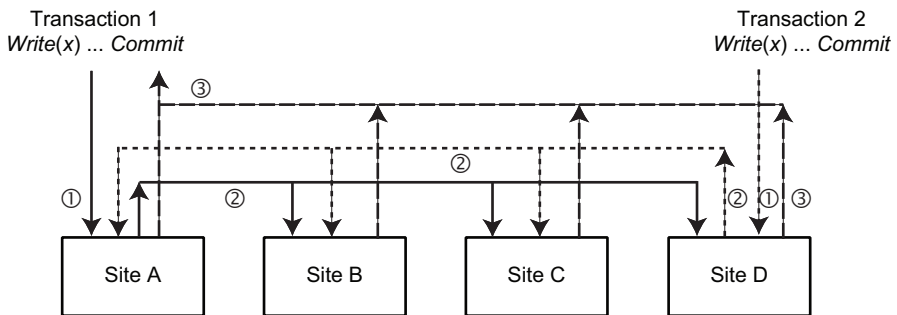
**Fig. 13.2** Eager Primary Copy Replication Protocol Actions. (1) Operations (*Read* or *Write*) for each data item are routed to that data item's master and a *Write* is first applied at the master; (2) *Write* is then propagated to the other replicas; (3) Updates become permanent at commit time.

Recall that this version still applies the updates to all the replicas within transactional boundaries, requiring integration with concurrency control techniques. A very early proposal is the *primary copy two-phase locking* (PC2PL) algorithm proposed for the prototype distributed version of INGRES [Stonebraker and Neuhold, 1977]. PC2PL is a straightforward extension of the single master protocol discussed above in an attempt to counter the latter’s potential performance problems. Basically, it implements lock managers at a number of sites and makes each lock manager responsible for managing the locks for a given set of lock units for which it is the master site. The transaction managers then send their lock and unlock requests to the lock managers that are responsible for that specific lock unit. Thus the algorithm treats one copy of each data item as its primary copy.

As a combined replica control/concurrency control technique, primary copy approach demands a more sophisticated directory at each site, but it also improves the previously discussed approaches by reducing the load of the master site without causing a large amount of communication among the transaction managers and lock managers.

### 13.3.2 Eager Distributed Protocols

In eager distributed replica control, the updates can originate anywhere, and they are first applied on the local replica, then the updates are propagated to other replicas. If the update originates at a site where a replica of the data item does not exist, it is forwarded to one of the replica sites, which coordinates its execution. Again, all of these are done within the context of the update transaction, and when the transaction commits, the user is notified and the updates are made permanent. Figure 13.3 depicts the sequence of operations for one logical data item  $x$  with copies at sites A, B, C and D, and where two transactions update two different copies (at sites A and D).



**Fig. 13.3** Eager Distributed Replication Protocol Actions. (1) Two *Write* operations are applied on two local replicas of the same data item; (2) The *Write* operations are independently propagated to the other replicas; (3) Updates become permanent at commit time (shown only for Transaction 1).



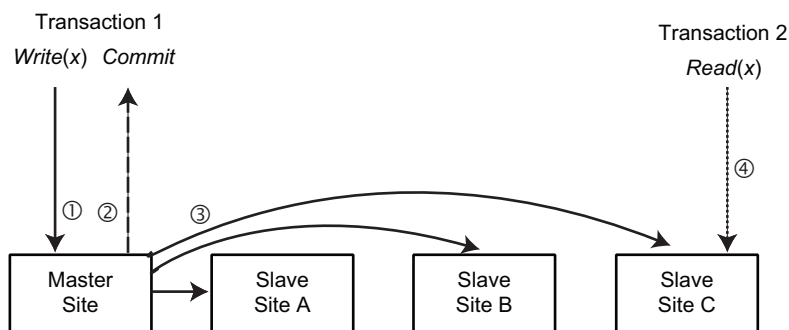
As can be clearly seen, the critical issue is to ensure that concurrent conflicting *Writes* initiated at different sites are executed in the same order at every site where they execute together (of course, the local executions at each site also have to be serializable). This is achieved by means of the concurrency control techniques that are employed at each site. Consequently, read operations can be performed on any copy, but writes are performed on all copies within transactional boundaries (e.g., ROWA) using a concurrency control protocol.

### 13.3.3 Lazy Centralized Protocols

Lazy centralized replication algorithms are similar to eager centralized replication ones in that the updates are first applied to a master replica and then propagated to the slaves. The important difference is that the propagation does not take place within the update transaction, but after the transaction commits as a separate refresh transaction. Consequently, if a slave site performs a *Read(x)* operation on its local copy, it may read stale (non-fresh) data, since  $x$  may have been updated at the master, but the update may not have yet been propagated to the slaves.

#### 13.3.3.1 Single Master with Limited Transparency

In this case, the update transactions are submitted and executed directly at the master site (as in the eager single master); once the update transaction commits, the refresh transaction is sent to the slaves. The sequence of execution steps are as follows: (1) an update transaction is first applied to the master replica, (2) the transaction is committed at the master, and then (3) the refresh transaction is sent to the slaves (Figure 13.4).



**Fig. 13.4** Lazy Single Master Replication Protocol Actions. (1) Update is applied on the local replica; (2) Transaction commit makes the updates permanent at the master; (3) Update is propagated to the other replicas in refresh transactions; (4) Transaction 2 reads from local copy.

When a slave (secondary) site receives a  $Read(x)$ , it reads from its local copy and returns the result to the user. Notice that, as indicated above, its own copy may not be up-to-date if the master is being updated and the slave has not yet received and executed the corresponding refresh transaction. A  $Write(x)$  received by a slave is rejected (and the transaction aborted), as this should have been submitted directly to the master site. When a slave receives a refresh transaction from the master, it applies the updates to its local copy. When it receives a  $Commit$  or  $Abort$  ( $Abort$  can happen for only locally submitted read-only transactions), it locally performs these actions.

The case of primary copy with limited transparency is similar, so we don't discuss it in detail. Instead of going to a single master site,  $Write(x)$  is submitted to the primary copy of  $x$ ; the rest is straightforward.

How can it be ensured that the refresh transactions can be applied at all of the slaves in the same order? In this architecture, since there is a single master copy for all data items, the ordering can be established by simply using timestamps. The master site would attach a timestamp to each refresh transaction according to the commit order of the actual update transaction, and the slaves would apply the refresh transactions in timestamp order.

A similar approach may be followed in the primary copy, limited transparency case. In this case, a site contains slave copies of a number of data items, causing it to get refresh transactions from multiple masters. The execution of these refresh transactions need to be ordered the same way at all of the involved slaves to ensure that the database states eventually converge. There are a number of alternatives that can be followed.

One alternative is to assign timestamps such that refresh transactions issued from different masters have different timestamps (by appending the site identifier to a monotonic counter at each site). Then the refresh transactions at each site can be executed in their timestamp order. However, those that come out of order cause difficulty. In traditional timestamp-based techniques discussed in Chapter 11, these transactions would be aborted; however in lazy replication, this is not possible since the transaction has already been committed at the primary copy site. The only possibility is to run a compensating transaction (which, effectively, aborts the transaction by rolling back its effects) or to perform update reconciliation that will be discussed shortly. The issue can be addressed by a more careful study of the resulting histories. An approach proposed by Breitbart and Korth [1997] uses a serialization graph approach that builds a *replication graph* whose nodes consist of transactions ( $T$ ) and sites ( $S$ ) and an edge  $\langle T_i, S_j \rangle$  exists in the graph if and only if  $T_i$  performs a  $Write$  on a (replicated) physical copy that is stored at  $S_j$ . When an operation ( $op_k$ ) is submitted, the appropriate nodes ( $T_k$ ) and edges are inserted into the replication graph, which is checked for cycles. If there is no cycle, then the execution can proceed. If a cycle is detected and it involves a transaction that has committed at the master, but whose refresh transactions have not yet committed at all of the involved slaves, then the current transaction ( $T_k$ ) is aborted (to be restarted later) since its execution would cause the history to be non-ISR. Otherwise,  $T_k$  can wait until the other transactions in the cycle are completed (i.e., they are committed at their masters and their refresh transactions are committed at all of the slaves). When a transaction

is completed in this manner, the corresponding node and all of its incident edges are removed from the replication graph. This protocol is proven to produce 1SR histories. An important issue is the maintenance of the replication graph. If it is maintained by a single site, then this becomes a centralized algorithm. We leave the distributed construction and maintenance of the replication graph as an exercise.

Another alternative is to rely on the group communication mechanism provided by the underlying communication infrastructure (if it can provide it). We discuss this alternative in Section 13.4.

Recall from Section 13.3.1 that, in the case of partially replicated databases, eager primary copy with limited replication transparency approach makes sense if the update transactions access only data items whose master sites are the same, since the update transactions are run completely at a master. The same problem exists in the case of lazy primary copy, limited replication approach. The issue that arises in both cases is how to design the distributed database so that meaningful transactions can be executed. This problem has been studied within the context of lazy protocols [Chundi et al., 1996] and a primary site selection algorithm was proposed that, given a set of transactions, a set of sites, and a set of data items, finds a primary site assignment to these data items (if one exists) such that the set of transactions can be executed to produce a 1SR global history.

### 13.3.3.2 Single Master or Primary Copy with Full Replication Transparency

We now turn to alternatives that provide full transparency by allowing (both read and update) transactions to be submitted at any site and forwarding their operations to either the single master or to the appropriate primary master site. This is tricky and involves two problems: the first is that, unless one is careful, 1SR global history may not be guaranteed; the second problem is that a transaction may not see its own updates. The following two examples demonstrate these problems.

*Example 13.4.* Consider the single master scenario and two sites M and B where M holds the master copies of  $x$  and  $y$  and B holds their slave copies. Now consider the following two transactions:  $T_1$  submitted at site B, while transaction  $T_2$  submitted at site M:

$T_1$ : Read( $x$ )	$T_2$ : Write( $x$ )
Write( $y$ )	Write( $y$ )
Commit	Commit

One way these would be executed under full transparency is as follows.  $T_2$  would be executed at site M since it contains the master copies of both  $x$  and  $y$ . Sometime after it commits, refresh transactions for its *Writes* are sent to site B to update the slave copies. On the other hand,  $T_1$  would read the local copy of  $x$  at site B, but its *Write*( $x$ ) would be forwarded to  $x$ 's master copy, which is at site M. Some time after *Write*<sub>1</sub>( $x$ ) is executed at the master site and commits there, a refresh transaction

would be sent back to site B to update the slave copy. The following is a possible sequence of steps of execution (Figure 13.5):

1.  $Read_1(x)$  is submitted at site B, where it is performed;
2.  $Write_2(x)$  is submitted at site M, and it is executed;
3.  $Write_2(y)$  is submitted at site M, and it is executed;
4.  $T_2$  submits its *Commit* at site M and commits there;
5.  $Write_1(x)$  is submitted at site B; since the master copy of  $x$  is at site M, the *Write* is forwarded to M;
6.  $Write_1(x)$  is executed at site M and the confirmation is sent back to site B;
7.  $T_1$  submits *Commit* at site B, which forwards it to site M; it is executed there and B is informed of the commit where  $T_1$  also commits;
8. Site M now sends refresh transaction for  $T_2$  to site B where it is executed and commits;
9. Site M finally sends refresh transaction for  $T_1$  to site B (this is for  $T_1$ 's *Write* that was executed at the master), it is executed at B and commits.

The following two histories are now generated at the two sites where the superscript  $r$  on operations indicate that they are part of a refresh transaction:

$$H_M = \{W_2(x_M), W_2(y_M), C_2, W_1(y_M), C_1\}$$

$$H_B = \{R_1(x_B), C_1, W_2^r(x_B), W_2^r(y_B), C_2^r, W_1^r(x_B), C_1^r\}$$

The resulting global history over the *logical* data items  $x$  and  $y$  is non-1SR.   ◆

*Example 13.5.* Again consider a single master scenario, where site M holds the master copy of  $x$  and site D holds its slave. Consider the following simple transaction:

$T_3$ : Write( $x$ )  
 Read( $x$ )  
 Commit

Following the same execution model as in Example 13.4, the sequence of steps would be as follows:

1.  $Write_3(x)$  is submitted at site D, which forwards it to site M for execution;
2. The *Write* is executed at M and the confirmation is sent back to site D;
3.  $Read_3(x)$  is submitted at site D and is executed on the local copy;
4.  $T_3$  submits commit at D, which is forwarded to M, executed there and a notification is sent back to site D, which also commits the transaction;
5. Site M sends a refresh transaction to site D for the  $W_3(x)$  operation;
6. Site D executes the refresh transaction and commits it.

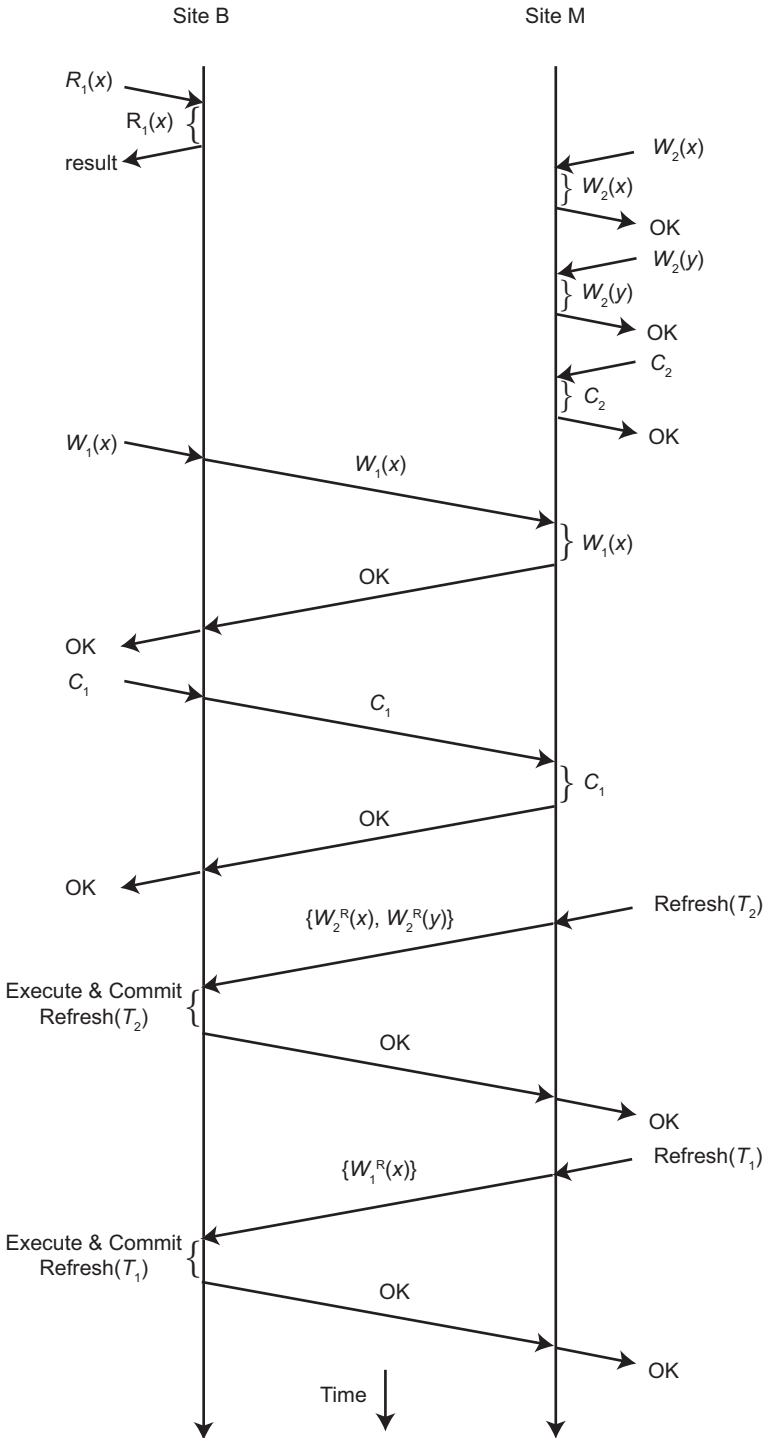


Fig. 13.5 Time sequence of executions of transactions

Note that, since the refresh transaction is sent to site D sometime after  $T_3$  commits at site M, at step 3 when it reads the value of  $x$  at site D, it reads the old value and does not see the value of its own *Write* that just precedes *Read*. ♦

Because of these problems, there are not too many proposals for full transparency in lazy replication algorithms. A notable exception is that by Bernstein et al. [2006] that considers the single master case and provides a method for validity testing by the master site, at commit point, similar to optimistic concurrency control. The fundamental idea is the following. Consider a transaction  $T$  that writes a data item  $x$ . At commit time of transaction  $T$ , the master generates a timestamp for it and uses this timestamp to set a timestamp for the master copy of  $x$  ( $x_M$ ) that records the timestamp of the last transaction that updated it ( $last\_modified(x_M)$ ). This is appended to refresh transactions as well. When refresh transactions are received at slaves they also set their copies to this same value, i.e.,  $last\_modified(x_i) \leftarrow last\_modified(x_M)$ . The timestamp generation for  $T$  at the master follows the following rule:

The timestamp for transaction  $T$  should be greater than all previously issued timestamps and should be less than the *last\_modified* timestamps of the data items it has accessed. If such a timestamp cannot be generated, then  $T$  is aborted.<sup>3</sup>

This test ensures that read operations read correct values. For example, in Example 13.4, master site M would not be able to assign an appropriate timestamp to transaction  $T_1$  when it commits, since the  $last\_modified(x_M)$  would reflect the update performed by  $T_2$ . Therefore,  $T_1$  would be aborted.

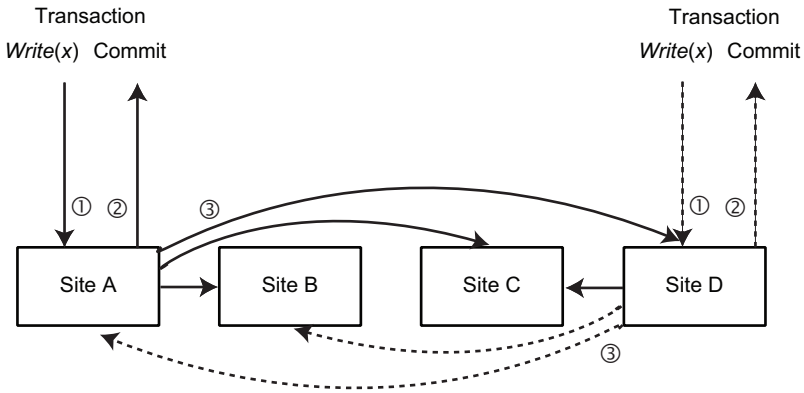
Although this algorithm handles the first problem we discussed above, it does not automatically handle the problem of a transaction not seeing its own writes (what we referred to as transaction inversion earlier). To address this issue, it has been suggested that a list be maintained of all the updates that a transaction performs and this list is consulted when a *Read* is executed. However, since only the master knows the updates, the list has to be maintained at the master and all the *Reads* (as well as *Writes*) have to be executed at the master.

### 13.3.4 Lazy Distributed Protocols

Lazy distributed replication protocols are the most complex ones owing to the fact that updates can occur on any replica and they are propagated to the other replicas lazily (Figure 13.6).

The operation of the protocol at the site where the transaction is submitted is straightforward: both *Read* and *Write* operations are executed on the local copy, and the transaction commits locally. Sometime after the commit, the updates are propagated to the other sites by means of refresh transactions.

<sup>3</sup> The original proposal handles a wide range of freshness constraints, as we discussed earlier; therefore, the rule is specified more generically. However, since our discussion primarily focuses on ISR behavior, this (more strict) recasting of the rule is appropriate.



**Fig. 13.6** Lazy Distributed Replication Protocol Actions. (1) Two updates are applied on two local replicas; (2) Transaction commit makes the updates permanent; (3) The updates are independently propagated to the other replicas.

The complications arise in processing these updates at the other sites. When the refresh transactions arrive at a site, they need to be locally scheduled, which is done by the local concurrency control mechanism. The proper serialization of these refresh transactions can be achieved using the techniques discussed in previous sections. However, multiple transactions can update different copies of the same data item concurrently at different sites, and these updates may conflict with each other. These changes need to be reconciled, and this complicates the ordering of refresh transactions. Based on the results of reconciliation, the order of execution of the refresh transactions is determined and updates are applied at each site.

The critical issue here is reconciliation. One can design a general purpose reconciliation algorithm based on heuristics. For example, updates can be applied in timestamp order (i.e., those with later timestamps will always win) or one can give preference to updates that originate at certain sites (perhaps there are more important sites). However, these are ad hoc methods and reconciliation is really dependent upon application semantics. Furthermore, whatever reconciliation technique is used, some of the updates are lost. Note that timestamp-based ordering will only work if timestamps are based on local clocks that are synchronized. As we discussed earlier, this is hard to achieve in large-scale distributed systems. Simple timestamp-based approach, which concatenates a site number and local clock, gives arbitrary preference between transactions that may have no real basis in application logic. The reason timestamps work well in concurrency control and not in this case is because in concurrency control we are only interested in determining *some* order; here we are interested in determining a *particular* order that is consistent with application semantics.

## 13.4 Group Communication

As discussed in the previous section, the overhead of replication protocols can be high – particularly in terms of message overhead. A very simple cost model for the replication algorithms is as follows. If there are  $n$  replicas and each transaction consists of  $m$  update operations, then each transaction issues  $n * m$  messages (if multicast communication is possible,  $m$  messages would be sufficient). If the system wishes to maintain a throughput of  $k$  transactions-per-second, this results in  $k * n * m$  messages per second (or  $k * m$  in the case of multicasting). One can add sophistication to this cost function by considering the execution time of each operation (perhaps based on system load) to get a cost function in terms of time. The problem with many of the replication protocols discussed above (in particular the distributed ones) is that their message overhead is high.

A critical issue in efficient implementation of these protocols is to reduce the message overhead. Solutions have been proposed that use group communication protocols [Chockler et al., 2001] together with non-traditional techniques for processing local transactions [Stanoi et al., 1998; Kemme and Alonso, 2000a,b; Patiño-Martínez et al., 2000; Jiménez-Peris et al., 2002]. These solutions introduce two modifications: they do not employ 2PC at commit time, but rely on the underlying group communication protocols to ensure agreement, and they use deferred update propagation rather than synchronous.

Let us first review the group communication idea. A group communication system enables a node to multicast a message to all nodes of a group with a delivery guarantee, i.e., the message is eventually delivered to all nodes. Furthermore, it can provide multicast primitives with different delivery orders only one of which is important for our discussion: total order. In total ordered multicast, all messages sent by different nodes are delivered in the same total order at all nodes. This is important in understanding the following discussion.

We will demonstrate the use of group communication by considering two protocols. The first one is an alternative eager distributed protocol [Kemme and Alonso, 2000a], while the second one is a lazy centralized protocol [Pacitti et al., 1999].

The group communication-based eager distributed protocol due to Kemme and Alonso [2000a] uses a local processing strategy where *Write* operations are carried out on local shadow copies where the transaction is submitted and utilizes total ordered group communication to multicast the set of write operations of the transaction to all the other replica sites. Total ordered communication guarantees that all sites receive the write operations in exactly the same order, thereby ensuring identical serialization order at every site. For simplicity of exposition, in the following discussion, we assume that the database is fully replicated and that each site implements a 2PL concurrency control algorithm.

The protocol executes a transaction  $T_i$  in four steps (local concurrency control actions are not indicated):

1. **Local processing phase.** A  $Read_i(x)$  operation is performed at the site where it is submitted (this is the master site for this transaction). A  $Write_i(x)$  op-



eration is also performed at the master site, but on a shadow copy (see the previous chapter for a discussion of shadow paging).

- II. **Communication phase.** If  $T_i$  consists only of *Read* operations, then it can be committed at the master site. If it involves *Write* operations (i.e., if it is an update transaction), then the TM at  $T_i$ 's master site (i.e., the site where  $T_i$  is submitted) assembles the writes into one *write message*  $WM_i$ <sup>4</sup> and multicasts it to all the replica sites (including itself) using total ordered group communication.
- III. **Lock phase.** When  $WM_i$  is delivered at a site  $S_j$ , it requests all locks in  $WM_i$  in an atomic step. This can be done by acquiring a latch (lighter form of a lock) on the lock table that is kept until all the locks are granted or requests are enqueued. The following actions are performed:
  1. For each  $Write(x)$  in  $WM_i$  (let  $x_j$  refer to the copy of  $x$  that exists at site  $S_j$ ), the following are performed:
    - (a) If there are no other transactions that have locked  $x_j$ , then the write lock on  $x_j$  is granted.
    - (b) Otherwise a conflict test is performed:
      - If there is a local transaction  $T_k$  that has already locked  $x_j$ , but is in its local read or communication phases, then  $T_k$  is aborted. Furthermore, if  $T_k$  is in its communication phase, a final decision message *Abort* is multicast to all the sites. At this stage, read/write conflicts are detected and local read transactions are simply aborted. Note that only local read operations obtain locks during the local execution phase, since local writes are only executed on shadow copies. Therefore, there is no need to check for write/write conflicts at this stage.
      - Otherwise,  $W_i(x_j)$  lock request is put on queue for  $x_j$ .
  2. If  $T_i$  is a local transaction (recall that the message is also sent to the site where  $T_i$  originates, in which case  $j = i$ ), then the site can commit the transaction, so it multicasts a *Commit* message. Note that the commit message is sent as soon as the locks are requested and not after writes; thus this is not a 2PC execution.
- IV. **Write phase.** When a site is able to obtain the write lock, it applies the corresponding update (for the master site, this means that the shadow copy is made the valid version). The site where  $T_i$  is submitted can commit and release all the locks. Other sites have to wait for the decision message and terminate accordingly.

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<sup>4</sup> What is being sent are the updated data items (i.e., state transfer).

Note that in this protocol, the important thing is to ensure that the lock phases of the concurrent transactions are executed in the same order at each site; that is what total ordered multicasting achieves. Also note that there is no ordering requirement on the decision messages (step III.2) and these may be delivered in any order, even before the delivery of the corresponding *WM*. If this happens, then the sites that receive the decision message before *WM* simply register the decision, but do not take any action. When *WM* message arrives, they can execute the lock and write phases and terminate the transaction according to the previously delivered decision message.

This protocol is significantly better, in terms of performance, than the naive one discussed in Section 13.3.2. For each transaction, the master site sends two messages: one when it sends the *WM* and the second one when it communicates the decision. Thus, if we wish to maintain a system throughput of  $k$  transactions-per-second, the total number of messages is  $2k$  rather than  $k * m$ , as is the case with the naive protocol (assuming multicast in both cases). Furthermore, system performance is improved by the use of deferred eager propagation since synchronization among replica sites for all *Write* operations is done once at the end rather than throughout the transaction execution.

The second example of the use of group communication that we will discuss is in the context of lazy centralized algorithms. Recall that an important issue in this case is to ensure that the refresh transactions are ordered the same way at all the involved slaves so that the database states converge. If totally ordered multicasting is available, the refresh transactions sent by different master sites would be delivered in the same order at all the slaves. However, total order multicast has high messaging overhead which may limit its scalability. It is possible to relax the ordering requirement of the communication system and let the replication protocol take responsibility for ordering the execution of refresh transactions. We will demonstrate this alternative by means of a proposal due to Pacitti et al. [1999]. The protocol assumes FIFO ordered multicast communication with a bounded delay for communication (call it *Max*), and assumes that the clocks are loosely synchronized so that they may only be out of sync by up to  $\epsilon$ . It further assumes that there is an appropriate transaction management functionality at each site. The result of the replication protocol at each slave is to maintain a “running queue” that holds an ordered list of refresh transactions, which is the input to the transaction manager for local execution. Thus, the protocol ensures that the orders in the running queues at each slave site where a set of refresh transactions run are the same.

At each slave site, a “pending queue” is maintained for each master site of this slave (i.e., if the slave site has replicas of  $x$  and  $y$  whose master sites are *Site*<sub>1</sub> and *Site*<sub>2</sub>, respectively, then there are two pending queues,  $q_1$  and  $q_2$ , corresponding to master sites *Site*<sub>1</sub> and *Site*<sub>2</sub>, respectively). When a refresh transaction  $RT_i^k$  is created at a master site *Site* <sub>$k$</sub> , it is assigned a timestamp  $ts(RT_i)$  that corresponds to the real time value at the commit time of the corresponding update transaction  $T_i$ . When  $RT_i$  arrives at a slave, it is put on queue  $q_k$ . At each message arrival the top elements of all pending queues are scanned and the one with the lowest timestamp is chosen as the new *RT* (*new\_RT*) to be handled. If the *new\_RT* has changed since the last cycle (i.e., a new *RT* arrived with a lower timestamp than what was chosen in the

previous cycle), then the one with the lower timestamp becomes the *new\_RT* and is considered for scheduling.

When a refresh transaction is chosen as the *new\_RT*, it is not immediately put on the “running queue” for the transaction manager; the scheduling of a refresh transaction takes into account the maximum delay and the possible drift in local clocks. This is done to ensure that any refresh transaction that may be delayed has a chance of reaching the slave. The time when an  $RT_i$  is put into the “running queue” at a slave site is  $delivery\_time = ts(new\_RT) + Max + \epsilon$ . Since the communication system guarantees an upper bound of *Max* for message delivery and since the maximum drift in local clocks (that determine timestamps) is  $\epsilon$ , a refresh transaction cannot be delayed by more than the *delivery\_time* before reaching all of the intended slaves. Thus, the protocol guarantees that a refresh transaction is scheduled for execution at a slave when the following hold: (1) all the write operations of the corresponding update transaction are performed at the master, (2) according to the order determined by the timestamp of the refresh transaction (which reflects the commit order of the update transaction), and (3) at the earliest at real time equivalent to its *delivery\_time*. This ensures that the updates on secondary copies at the slave sites follow the same chronological order in which their primary copies were updated and this order will be the same at all of the involved slaves, assuming that the underlying communication infrastructure can guarantee *Max* and  $\epsilon$ . This is an example of a lazy algorithm that ensures 1SR global history, but weak mutual consistency, allowing the replica values to diverge by up to a predetermined time period.

## 13.5 Replication and Failures

Up to this point, we have focused on replication protocols in the absence of any failures. What happens to mutual consistency concerns if there are system failures? The handling of failures differs between eager replication and lazy replication approaches.

### 13.5.1 Failures and Lazy Replication

Let us first consider how lazy replication techniques deal with failures. This case is relatively easy since these protocols allow divergence between the master copies and the replicas. Consequently, when communication failures make one or more sites unreachable (the latter due to network partitioning), the sites that are available can simply continue processing. Even in the case of network partitioning, one can allow operations to proceed in multiple partitions independently and then worry about the convergence of the database states upon repair using the conflict resolution techniques discussed in Section 13.3.4. Before the merge, databases at multiple partitions diverge, but they are reconciled at merge time.

### 13.5.2 Failures and Eager Replication

Let us now focus on eager replication, which is considerably more involved. As we noted earlier, all eager techniques implement some sort of ROWA protocol, ensuring that, when the update transaction commits, all of the replicas have the same value. ROWA family of protocols is attractive and elegant. However, as we saw during the discussion of commit protocols, it has one significant drawback. Even if one of the replicas is unavailable, then the update transaction cannot be terminated. So, ROWA fails in meeting one of the fundamental goals of replication, namely providing higher availability.

An alternative to ROWA which attempts to address the low availability problem is the Read-One/Write-All Available (ROWA-A) protocol. The general idea is that the write commands are executed on all the available copies and the transaction terminates. The copies that were unavailable at the time will have to “catch up” when they become available.

There have been various versions of this protocol [Helal et al., 1997], two of which will be discussed here. The first one is known as the *available copies protocol* [Bernstein and Goodman, 1984; Bernstein et al., 1987]. The coordinator of an update transaction  $T_i$  (i.e., the master where the transaction is executing) sends each  $W_i(x)$  to all the slave sites where replicas of  $x$  reside, and waits for confirmation of execution (or rejection). If it times out before it gets acknowledgement from all the sites, it considers those which have not replied as unavailable and continues with the update on the available sites. The unavailable slave sites update their databases to the latest state when they recover. Note, however, that these sites may not even be aware of the existence of  $T_i$  and the update to  $x$  that  $T_i$  has made if they had become unavailable before  $T_i$  started.

There are two complications that need to be addressed. The first one is the possibility that the sites that the coordinator thought were unavailable were in fact up and running and may have already updated  $x$  but their acknowledgement may not have reached the coordinator before its timer ran out. Second, some of these sites may have been unavailable when  $T_i$  started and may have recovered since then and have started executing transactions. Therefore, the coordinator undertakes a validation procedure before committing  $T_i$ :

1. The coordinator checks to see if all the sites it thought were unavailable are still unavailable. It does this by sending an inquiry message to every one of these sites. Those that are available reply. If the coordinator gets a reply from one of these sites, it aborts  $T_i$  since it does not know the state that the previously unavailable site is in: it could have been that the site was available all along and had performed the original  $W_i(x)$  but its acknowledgement was delayed (in which case everything is fine), or it could be that it was indeed unavailable when  $T_i$  started but became available later on and perhaps even executed  $W_j(x)$  on behalf of another transaction  $T_j$ . In the latter case, continuing with  $T_i$  would make the execution schedule non-serializable.

2. If the coordinator of  $T$  does not get any response from any of the sites that it thought were unavailable, then it checks to make sure that all the sites that were available when  $W_i(x)$  executed are still available. If they are, then  $T$  can proceed to commit. Naturally, this second step can be integrated into a commit protocol.

The second ROWA-A variant that we will discuss is the distributed ROWA-A protocol. In this case, each site  $S$  maintains a set,  $V_S$ , of sites that it believes to be available; this is the “view” that  $S$  has of the system configuration. In particular, when a transaction  $T_i$  is submitted, its coordinator’s view reflects all the sites that the coordinator knows to be available (let us denote this as  $V_C(T_i)$  for simplicity). A  $R_i(x)$  is performed on any replica in  $V_C(T_i)$  and a  $W_i(x)$  updates all copies in  $V_C(T_i)$ . The coordinator checks its view at the end of  $T_i$ , and if the view has changed since  $T_i$ ’s start, then  $T_i$  is aborted. To modify  $V$ , a special atomic transaction is run at all sites, ensuring that no concurrent views are generated. This can be achieved by assigning timestamps to each  $V$  when it is generated and ensuring that a site only accepts a new view if its version number is greater than the version number of that site’s current view.

The ROWA-A class of protocols are more resilient to failures, including network partitioning, than the simple ROWA protocol.

Another class of eager replication protocols are those based on voting. The fundamental characteristics of voting were presented in the previous chapter when we discussed network partitioning in non-replicated databases. The general ideas hold in the replicated case. Fundamentally, each read and write operation has to obtain a sufficient number of votes to be able to commit. These protocols can be pessimistic or optimistic. In what follows we discuss only pessimistic protocols. An optimistic version compensates transactions to recover if the commit decision cannot be confirmed at completion [Davidson, 1984]. This version is suitable wherever compensating transactions are acceptable (see Chapter 10).

The initial voting algorithm was proposed by Thomas [1979] and an early suggestion to use quorum-based voting for replica control is due to Gifford [1979]. Thomas’s algorithm works on fully replicated databases and assigns an equal vote to each site. For any operation of a transaction to execute, it must collect affirmative votes from a majority of the sites. Gifford’s algorithm, on the other hand, works with partially replicated databases (as well as with fully replicated ones) and assigns a vote to each copy of a replicated data item. Each operation then has to obtain a *read quorum* ( $V_r$ ) or a *write quorum* ( $V_w$ ) to read or write a data item, respectively. If a given data item has a total of  $V$  votes, the quorums have to obey the following rules:

1.  $V_r + V_w > V$
2.  $V_w > V/2$

As the reader may recall from the preceding chapter, the first rule ensures that a data item is not read and written by two transactions concurrently (avoiding the read-write conflict). The second rule, on the other hand, ensures that two write operations

from two transactions cannot occur concurrently on the same data item (avoiding write-write conflict). Thus the two rules ensure that serializability and one-copy equivalence are maintained.

In the case of network partitioning, the quorum-based protocols work well since they basically determine which transactions are going to terminate based on the votes that they can obtain. The vote allocation and threshold rules given above ensure that two transactions that are initiated in two different partitions and access the same data cannot terminate at the same time.

The difficulty with this version of the protocol is that transactions are required to obtain a quorum even to read data. This significantly and unnecessarily slows down read access to the database. We describe below another quorum-based voting protocol that overcomes this serious performance drawback [Abbadi et al., 1985].

The protocol makes certain assumptions about the underlying communication layer and the occurrence of failures. The assumption about failures is that they are “clean.” This means two things:

1. Failures that change the network’s topology are detected by all sites instantaneously.
2. Each site has a view of the network consisting of all the sites with which it can communicate.

Based on the presence of a communication network that can ensure these two conditions, the replica control protocol is a simple implementation of the ROWA-A principle. When the replica control protocol attempts to read or write a data item, it first checks if a majority of the sites are in the same partition as the site at which the protocol is running. If so, it implements the ROWA rule within that partition: it reads any copy of the data item and writes all copies that are in that partition.

Notice that the read or the write operation will execute in only one partition. Therefore, this is a pessimistic protocol that guarantees one-copy serializability, *but only within that partition*. When the partitioning is repaired, the database is recovered by propagating the results of the update to the other partitions.

A fundamental question with respect to implementation of this protocol is whether or not the failure assumptions are realistic. Unfortunately, they may not be, since most network failures are not “clean.” There is a time delay between the occurrence of a failure and its detection by a site. Because of this delay, it is possible for one site to think that it is in one partition when in fact subsequent failures have placed it in another partition. Furthermore, this delay may be different for various sites. Thus two sites that were in the same partition but are now in different partitions may proceed for a while under the assumption that they are still in the same partition. The violations of these two failure assumptions have significant negative consequences on the replica control protocol and its ability to maintain one-copy serializability.

The suggested solution is to build on top of the physical communication layer another layer of abstraction which hides the “unclean” failure characteristics of the physical communication layer and presents to the replica control protocol a communication service that has “clean” failure properties. This new layer of abstraction

provides *virtual partitions* within which the replica control protocol operates. A virtual partition is a group of sites that have agreed on a common view of who is in that partition. Sites join and depart from virtual partitions under the control of this new communication layer, which ensures that the clean failure assumptions hold.

The advantage of this protocol is its simplicity. It does not incur any overhead to maintain a quorum for read accesses. Thus the reads can proceed as fast as they would in a non-partitioned network. Furthermore, it is general enough so that the replica control protocol does not need to differentiate between site failures and network partitions.

Given alternative methods for achieving fault-tolerance in the case of replicated databases, a natural question is what the relative advantages of these methods are. There have been a number of studies that analyze these techniques, each with varying assumptions. A comprehensive study suggests that ROWA-A implementations achieve better scalability and availability than quorum techniques [Jiménez-Peris et al., 2003].

## 13.6 Replication Mediator Service

The replication protocols we have covered so far are suitable for tightly integrated distributed database systems where we can insert the protocols into each component DBMS. In multidatabase systems, replication support has to be supported outside the DBMSs by mediators. In this section we discuss how to provide replication support at the mediator level by means of an example protocol called NODO [Patiño-Martínez et al., 2000].

The NODO (NON-Disjoint conflict classes and Optimistic multicast) protocol is a hybrid between distributed and primary copy – it permits transactions to be submitted at any site, but it does have the notion of a primary copy for a data item. It uses group communications and optimistic delivery to reduce latency. The optimistic delivery technique delivers a message optimistically as soon as it is received without guaranteeing any order among messages. The message is said to be “opt-delivered”. When the total order of the message is established, then the message is to-delivered. Although optimistic delivery does not guarantee any order, most of the time the order will be the same as total ordering. This fact is exploited by NODO to overlap the total ordering of the transaction request with the transaction execution at the master node, thus masking the latency of total ordering. The protocol also executes transactions optimistically (see Section 11.5), and may abort them if necessary.

In the following discussion, we will assume a fully replicated database for simplicity. This allows us to ignore issues such as finding the primary copy site, how to execute a transaction over a set of data items that have different primary copies, etc. In the fully replicated environment, all of the sites in the system form a multicast group.

It is assumed that the data items are grouped into disjoint sets and each set has a primary copy. Each transaction accesses a particular set of items, and, as in all

primary copy techniques, it first executes at the primary copy site, and its writes are then propagated to the slave sites. The transaction is said to be *local* to its primary copy site.

Each set of data items is called a *conflict class*, and the protocol exploits the knowledge of transactions' conflict classes to increase concurrency. Two transactions that access the same conflict class have a high probability of conflict, while two transactions that access different conflict classes can run in parallel. A transaction can access several conflict classes and this must be statically known before execution (e.g., by analyzing the transaction code). Thus, conflict classes are further abstracted into conflict class groups. Each conflict class group has a single primary copy (i.e., the primary copy of one of the individual conflict classes in the group) where all transactions on that conflict class group must be executed. The same individual conflict class can be in different conflict class groups. For instance, if  $S_i$  be the primary copy site of  $\{C_x, C_y\}$  and  $S_j$  be the primary copy site of  $\{C_y\}$ , transactions  $T_1$  on  $\{C_x, C_y\}$  and  $T_2$  on  $\{C_y\}$  are executed at  $S_i$  and  $S_j$ , respectively.

Each transaction is associated with a single conflict class group, and therefore, it has a single primary copy. Each site manages a number of queues for its incoming transactions, one per individual conflict class (not one per conflict class group). The processing of a transaction proceeds in the following way:

1. A transaction is submitted by an application at a site.
2. That site multicasts the transaction to the multicast group (which is the entire set of sites since we are assuming full replication).
3. When the transaction is opt-delivered at a site, it is appended to the queue of all the individual classes included in its conflict class group.
4. At the primary copy site, when the transaction becomes the first in the queue of all the individual conflict classes of its conflict class group, it is optimistically executed.
5. When the transaction is to-delivered at a site, it is checked whether its optimistic ordering was the same as the total ordering. If the optimistic order was wrong, the transaction is reordered in all the queues according to the total order. The primary copy site, in addition, aborts the transaction (if it was already executed) and re-executes it when it again gets to the head of all the relevant queues. If the optimistic ordering was correct, the primary copy site extracts the resulting write set of the transaction and multicasts (without total ordering) it to the multicast group.
6. When the write set is received at the primary copy site (remember that in this case the primary copy site is also in the multicast group, so it receives its own transmission), it commits the transaction. When the write set is received at a slave site and the transaction becomes the first in all the relevant queues, its write set is applied, and then the transaction commits.



*Example 13.6.* Let site  $S_i$ , respectively  $S_j$ , be the master of the conflict class group  $\{C_x, C_y\}$ , respectively  $\{C_x\}$  and  $\{C_y\}$ . Let transaction  $T_1$  be on  $\{C_x, C_y\}$ ,  $T_2$  on  $\{C_y\}$  and  $T_3$  on  $\{C_x\}$ . Thus,  $T_1$  is local to  $S_i$  while  $T_2$  and  $T_3$  are local to  $S_j$ . At  $S_i$  and  $S_j$ , let transaction  $T_i$  be the  $i$ -th in the total order (i.e., the total order is  $T_1 \rightarrow T_2 \rightarrow T_3$ ). Consider the following state of the queues  $C_x$  and  $C_y$  at  $S_i$  and  $S_j$  after the transactions have been opt-delivered.

$$S_i : C_x = [T_1, T_3]; C_y = [T_1, T_2]$$

$$S_j : C_x = [T_3, T_1]; C_y = [T_1, T_2]$$

At  $S_i$   $T_1$  is the first in the queues  $C_x$  and  $C_y$  and thus it is executed. Similarly, at  $S_j$   $T_3$  is at the head of  $C_x$  and thus, executed. When  $S_i$  to-delivers  $T_1$ , since the optimistic ordering was correct, it extracts  $T_1$ 's write set and multicasts it. Upon delivering the write set of  $T_1$  at  $S_i$ ,  $T_1$  is committed. Upon delivering  $T_1$ 's write set at  $S_j$ , it is realized that  $T_1$  was wrongly ordered after  $T_3$ , and  $T_1$  is reordered before  $T_3$  and  $T_3$  is aborted since its optimistic ordering was wrong.  $T_1$ 's write set is then applied and committed. At both  $S_i$  and  $S_j$ ,  $T_1$  is removed from all the queues. Now  $T_2$  and  $T_3$  are first of their queues at  $S_j$ , their primary copy site, and both are executed in parallel. Since they are in disjoint conflict class groups, their relative ordering is irrelevant. Now  $T_2$  is to-delivered and since its optimistic delivery was correct, its write set is extracted and multicast. Upon delivery of the  $T_2$ 's write set,  $S_j$  commits  $T_2$ , while  $S_i$  applies the write set and commits it. Finally,  $T_3$  is to-delivered and since its execution was performed according to the total order,  $S_j$  extracts  $T_3$ 's write set and multicasts it. Upon delivery of the  $T_3$ 's writeset,  $S_j$  commits  $T_3$ . Similarly,  $S_i$  applies the write set and commits  $T_3$ . The final ordering is  $T_1 \rightarrow T_2 \rightarrow T_3$  at both nodes.  $\blacklozenge$

Interestingly, there are many cases where, in spite of an ordering mismatch between opt and to-delivery, it is possible to commit transactions consistently by using the optimistic rather than total ordering, thus minimizing the number of aborts due to optimism failures. This fact is exploited by the REORDERING protocol [Patiño-Martínez et al., 2005].

The implementation of the NODO protocol combines concurrency control with group communication primitives and what has been traditionally done inside the DBMS. This solution can be implemented outside a DBMS without a negligible overhead, and thus supports DBMS autonomy [Jiménez-Peris et al. [2002]]. Similar eager replication protocols have been proposed to support *partial replication*, where copies can be stored at subsets of nodes [Sousa et al., 2001; Serrano et al., 2007]. Unlike full replication, partial replication increases access locality and reduces the number of messages for propagating updates to replicas.

## 13.7 Conclusion

In this chapter we discussed different approaches to data replication and presented protocols that are appropriate under different circumstances. Each of the alterna-

tive protocols we have discussed have their advantages and disadvantages. Eager centralized protocols are simple to implement, they do not require update coordination across sites, and they are guaranteed to lead to one-copy serializable histories. However, they put a significant load on the master sites, potentially causing them to become bottlenecks. Consequently, they are harder to scale, in particular in the single master site architecture – primary copy versions have better scalability properties since the master responsibilities are somewhat distributed. These protocols result in long response times (the longest among the four alternatives), since the access to any data has to wait until the commit of any transaction that is currently updating it (using 2PC, which is expensive). Furthermore, the local copies are used sparingly, only for read operations. Thus, if the workload is update-intensive, eager centralized protocols are likely to suffer from bad performance.

Eager distributed protocols also guarantee one-copy serializability and provide an elegant symmetric solution where each site performs the same function. However, unless there is communication system support for efficient multicasting, they result in very high number of messages that increase network load and result in high transaction response times. This also constrains their scalability. Furthermore, naive implementations of these protocols will cause significant number of deadlocks since update operations are executed at multiple sites concurrently.

Lazy centralized protocols have very short response times since transactions execute and commit at the master, and do not need to wait for completion at the slave sites. There is also no need to coordinate across sites during the execution of an update transaction, thus reducing the number of messages. On the other hand, mutual consistency (i.e., freshness of data at all copies) is not guaranteed as local copies can be out of date. This means that it is not possible to do a local read and be assured that the most up-to-date copy is read.

Finally, lazy multi-master protocols have the shortest response times and the highest availability. This is because each transaction is executed locally, with no distributed coordination. Only after they commit are the other replicas updated through refresh transactions. However, this is also the shortcoming of these protocols – different replicas can be updated by different transactions, requiring elaborate reconciliation protocols and resulting in lost updates.

Replication has been studied extensively within the distributed computing community as well as the database community. Although there are considerable similarities in the problem definition in the two environments, there are also important differences. Perhaps the two more important differences are the following. Data replication focuses on data, while replication of computation is equally important in distributed computing. In particular, concerns about data replication in mobile environments that involve disconnected operation have received considerable attention. Secondly, database and transaction consistency is of paramount importance in data replication; in distributed computing, consistency concerns are not as high on the list of priorities. Consequently, considerably weaker consistency criteria have been defined.

Replication has been studied within the context of parallel database systems, in particular within parallel database clusters. We discuss these separately in Chapter 14.

## 13.8 Bibliographic Notes

Replication and replica control protocols have been the subject of significant investigation since early days of distributed database research. This work is summarized very well in [Helal et al., 1997]. Replica control protocols that deal with network partitioning are surveyed in [Davidson et al., 1985].

A landmark paper that defined a framework for various replication algorithms and argued that eager replication is problematic (thus opening up a torrent of activity on lazy techniques) is [Gray et al., 1996]. The characterization that we use in this chapter is based on this framework. A more detailed characterization is given in [Wiesmann et al., 2000]. A recent survey on optimistic (or lazy) replication techniques is [Saito and Shapiro, 2005]. The entire topic is discussed at length in [Kemme et al., 2010].

Freshness, in particular for lazy techniques, have been a topic of some study. Alternative techniques to ensure “better” freshness are discussed in [Pacitti et al., 1998; Pacitti and Simon, 2000; Röhm et al., 2002a; Pape et al., 2004; Akal et al., 2005].

There are many different versions of quorum-based protocols. Some of these are discussed in [Triantafillou and Taylor, 1995; Paris, 1986; Tanenbaum and van Renesse, 1988]. Besides the algorithms we have described here, some notable others are given in [Davidson, 1984; Eager and Sevcik, 1983; Herlihy, 1987; Minoura and Wiederhold, 1982; Skeen and Wright, 1984; Wright, 1983]. These algorithms are generally called *static* since the vote assignments and read/write quorums are fixed a priori. An analysis of one such protocol (such analyses are rare) is given in [Kumar and Segev, 1993]. Examples of *dynamic replication protocols* are in [Jajodia and Mutchler, 1987; Barbara et al., 1986, 1989] among others. It is also possible to change the way data are replicated. Such protocols are called *adaptive* and one example is described in [Wolfson, 1987].

An interesting replication algorithm based on economic models is described in [Sidell et al., 1996].

## Exercises

**Problem 13.1.** For each of the four replication protocols (eager centralized, eager distributed, lazy centralized, lazy distributed), give a scenario/application where the approach is more suitable than the other approaches. Explain why.

**Problem 13.2.** A company has several geographically distributed warehouses storing and selling products. Consider the following partial database schema:

ITEM(ID, ItemName, Price, ...)

STOCK(ID, Warehouse, Quantity, ...)

CUSTOMER(ID, CustName, Address, CreditAmt, ...)

CLIENT-ORDER(ID, Warehouse, Balance, ...)

ORDER(ID, Warehouse, CustID, Date)

ORDER-LINE(ID, ItemID, Amount, . . .)

The database contains relations with product information (ITEM contains the general product information, STOCK contains, for each product and for each warehouse, the number of pieces currently on stock). Furthermore, the database stores information about the clients/customers, e.g., general information about the clients is stored in the CUSTOMER table. The main activities regarding the clients are the ordering of products, the payment of bills and general information requests. There exist several tables to register the orders of a customer. Each order is registered in the ORDER and ORDER-LINE tables. For each order/purchase, one entry exists in the order table, having an ID, indicating the customer-id, the warehouse at which the order was submitted, the date of the order, etc. A client can have several orders pending at a warehouse. Within each order, several products can be ordered. ORDER-LINE contains an entry for each product of the order, which may include one or more products. CLIENT-ORDER is a summary table that lists, for each client and for each warehouse, the sum of all existing orders.

- (a) The company has a customer service group consisting of several employees that receive customers' orders and payments, query the data of local customers to write bills or register paychecks, etc. Furthermore, they answer any type of requests which the customers might have. For instance, ordering products changes (update/insert) the CLIENT-ORDER, ORDER, ORDER-LINE, and STOCK tables. To be flexible, each employee must be able to work with any of the clients. The workload is estimated to be 80% queries and 20% updates. Since the workload is query oriented, the management has decided to build a cluster of PCs each equipped with its own database to accelerate queries through fast local access. How would you replicate the data for this purpose? Which replica control protocol(s) would you use to keep the data consistent?
- (b) The company's management has to decide each fiscal quarter on their product offerings and sales strategies. For this purpose, they must continually observe and analyze the sales of the different products at the different warehouses as well as observe consumer behavior. How would you replicate the data for this purpose? Which replica control protocol(s) would you use to keep the data consistent?

**Problem 13.3 (\*)**. An alternative to ensuring that the refresh transactions can be applied at all of the slaves in the same order in lazy single master protocols with limited transparency is the use of a replication graph as discussed in Section 13.3.3. Develop a method for distributed management of the replication graph.

**Problem 13.4**. Consider data items  $x$  and  $y$  replicated across the sites as follows:

<u>Site 1</u>	<u>Site 2</u>	<u>Site 3</u>	<u>Site 4</u>
$x$	$x$		$x$
	$y$	$y$	$y$

- (a) Assign votes to each site and give the read and write quorum.
- (b) Determine the possible ways that the network can partition and for each specify in which group of sites a transaction that updates (reads and writes)  $x$  can be terminated and what the termination condition would be.
- (c) Repeat (b) for  $y$ .

**Problem 13.5 (\*\*).** In the NODO protocol, we have seen that each conflict class group has a master. However, this is not inherent to the protocol. Design a multi-master variation of NODO in which a transaction might be executed by any replica. What condition should be enforced to guarantee that each updated transaction is processed only by one replica?

**Problem 13.6 (\*\*).** In the NODO protocol, if the DBMS could provide additional introspection functionality, it would be possible to execute in certain circumstances transactions of the same conflict class in parallel. Determine which functionality would be needed from the DBMS. Also characterize formally under which circumstances concurrent execution of transactions in the same conflict class could be allowed to be executed in parallel whilst respecting 1-copy consistency. Extend the NODO protocol with this enhancement.